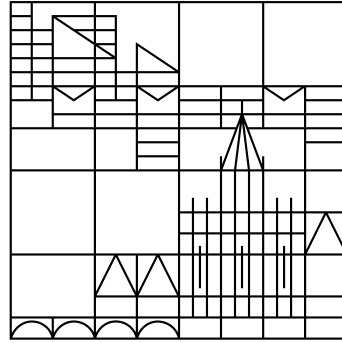


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Konstanz

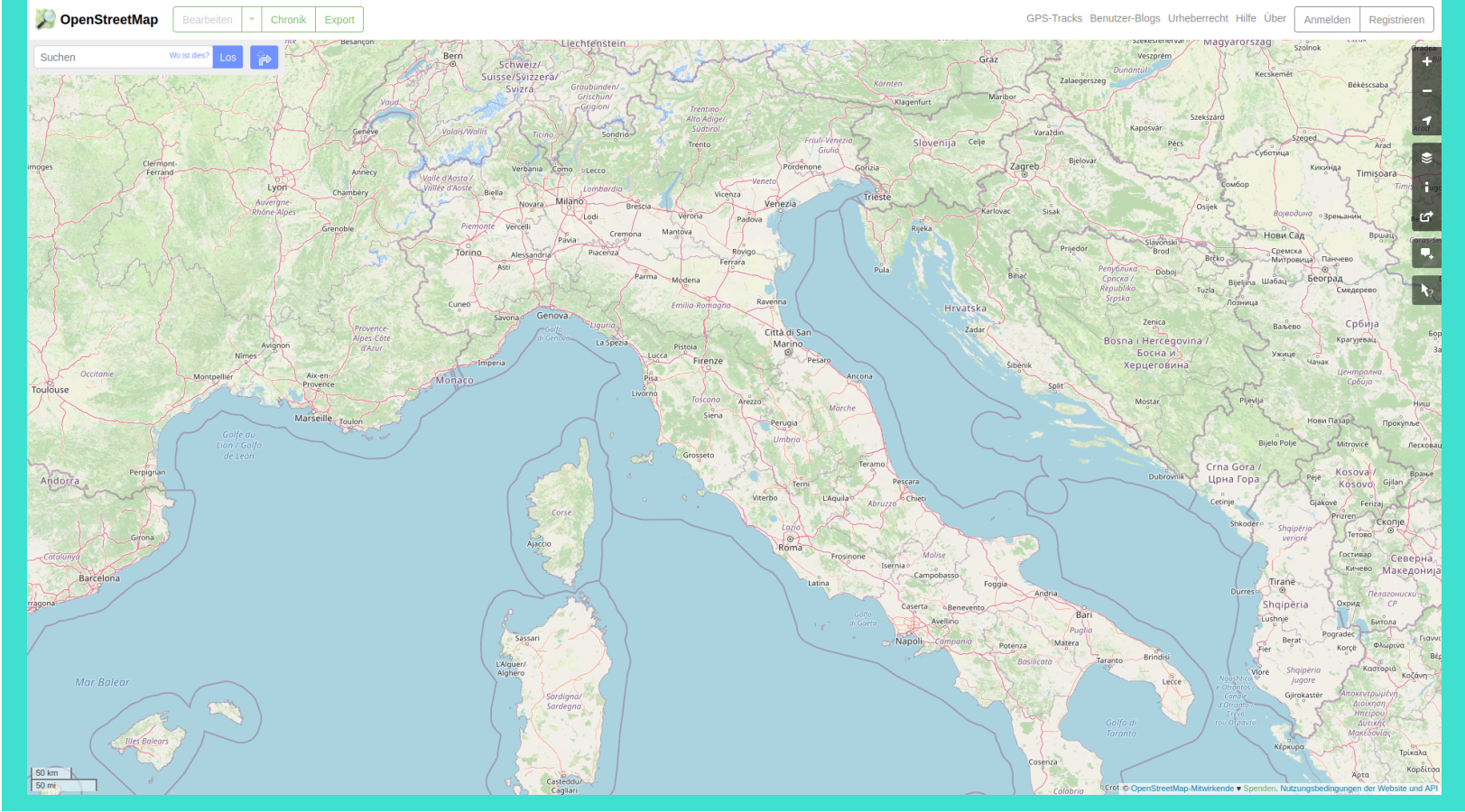


Local-Fréchet Polyline Simplification Has Subcubic Complexity in Two Dimensions

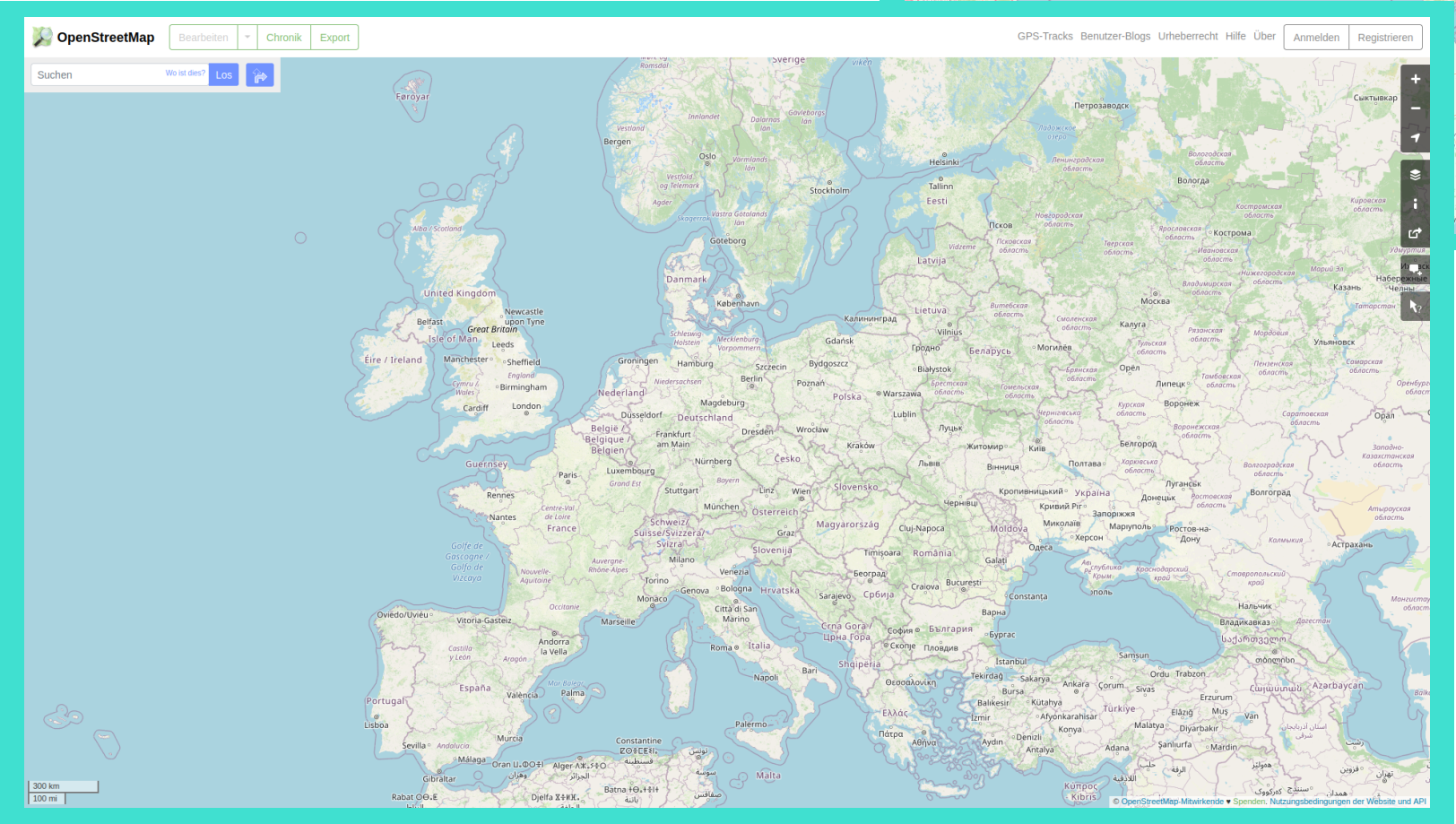
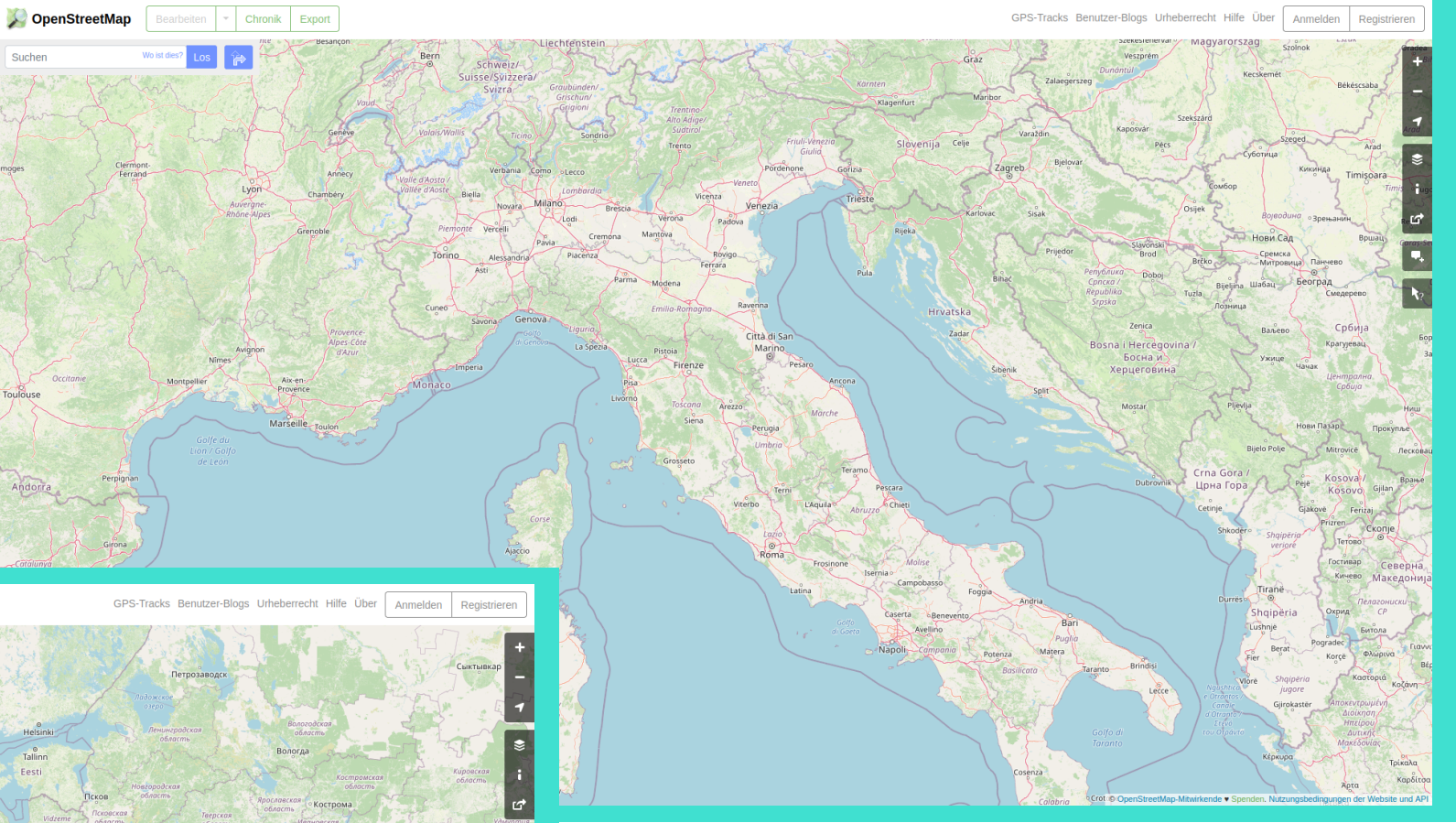
EuroCG 2022

Sabine Storandt and Johannes Zink

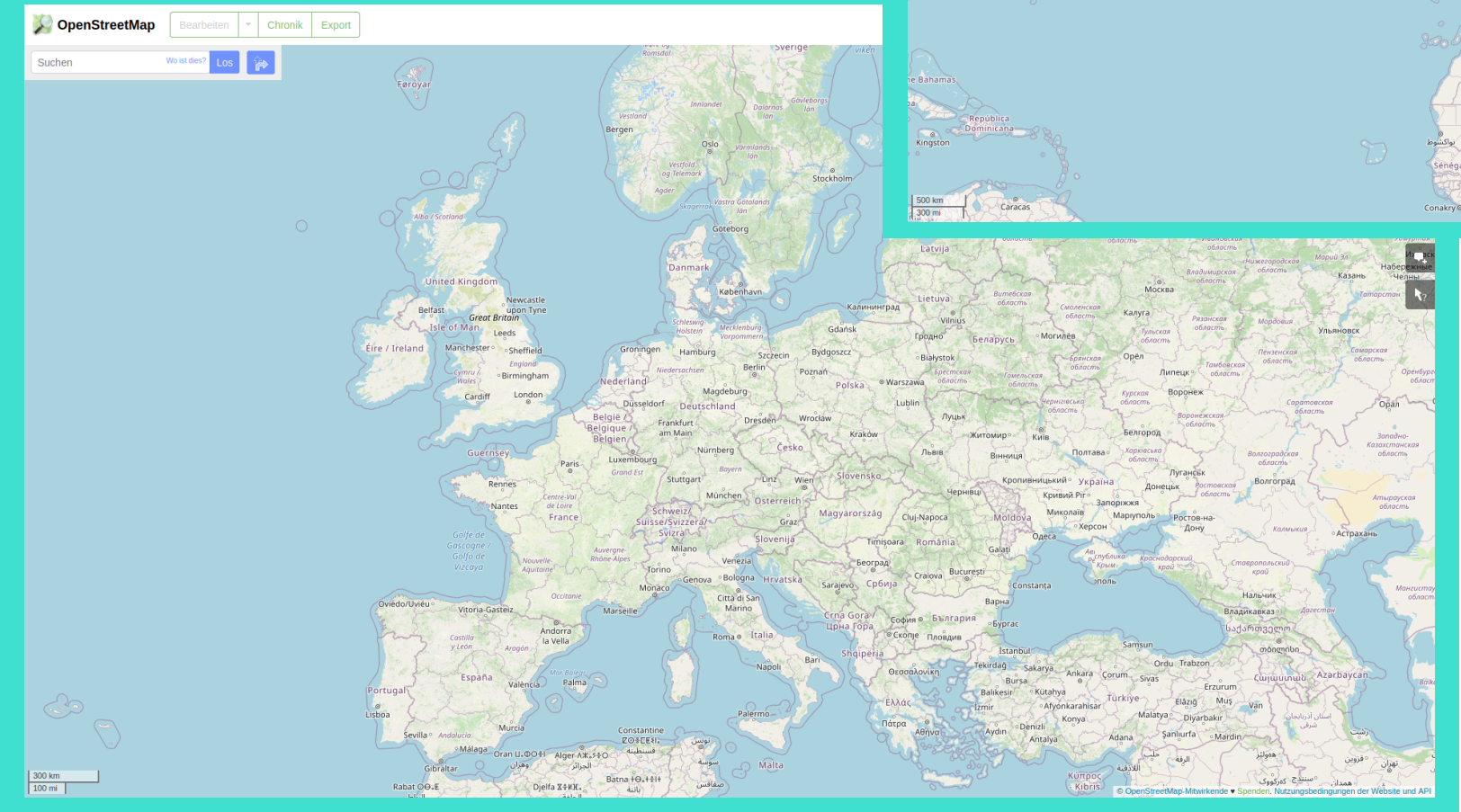
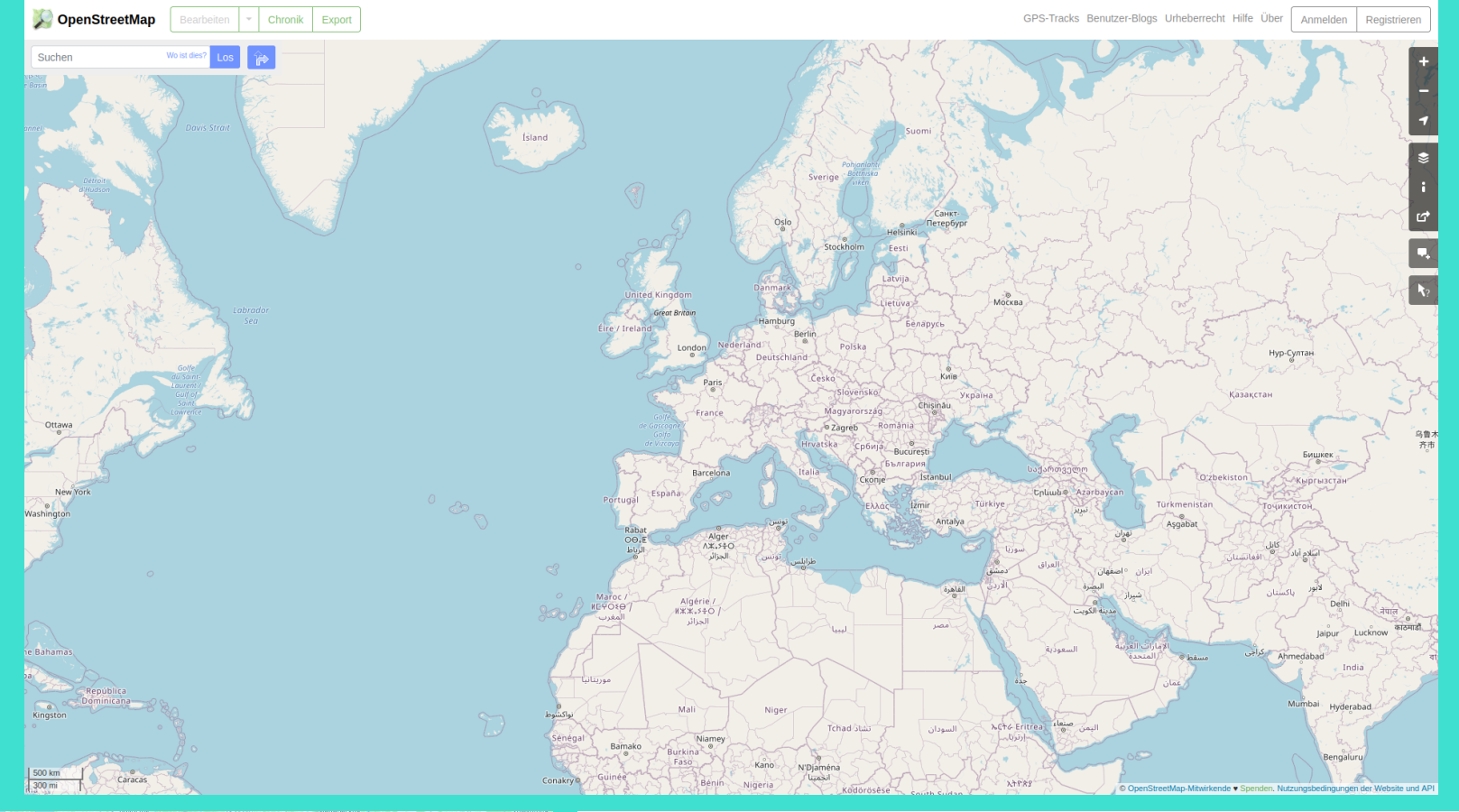
Motivation



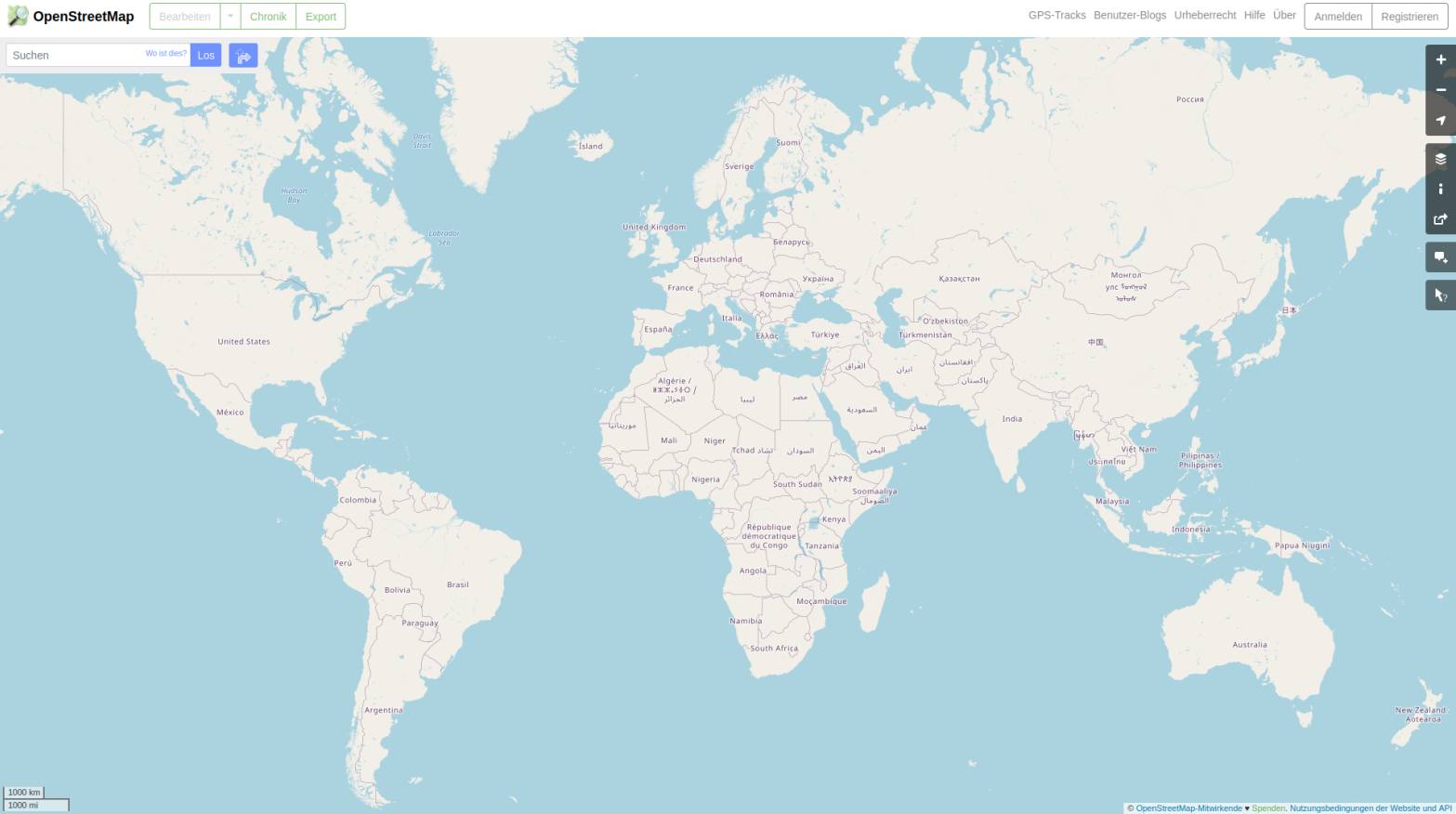
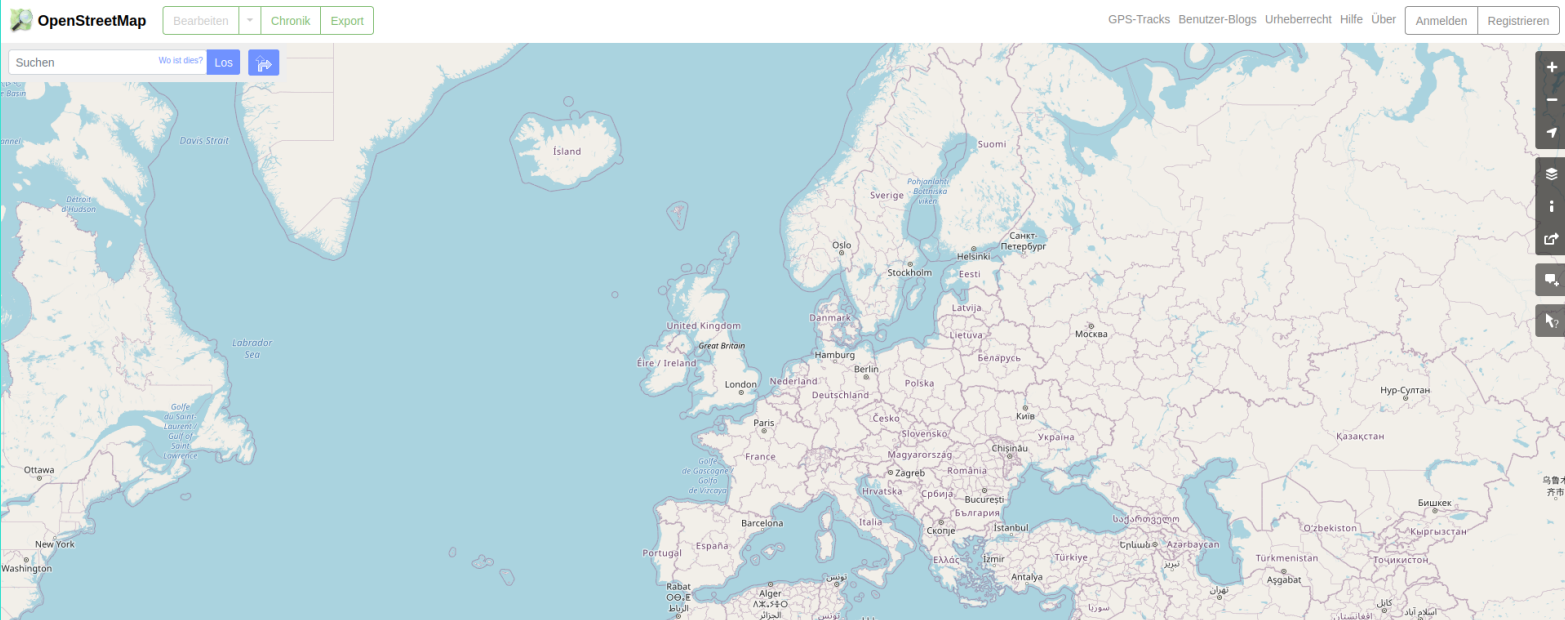
Motivation



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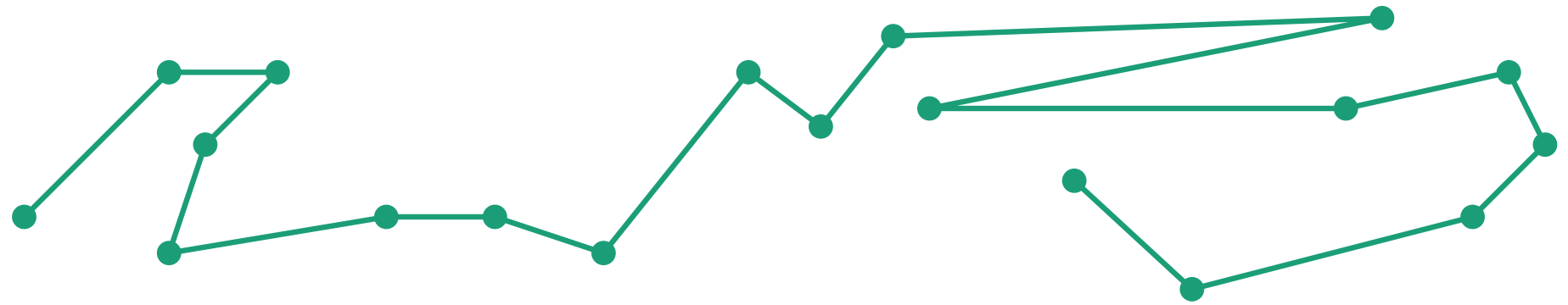
Definition: Polyline Simplification

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Given: ■ polyline P as a sequence of n points in the plane

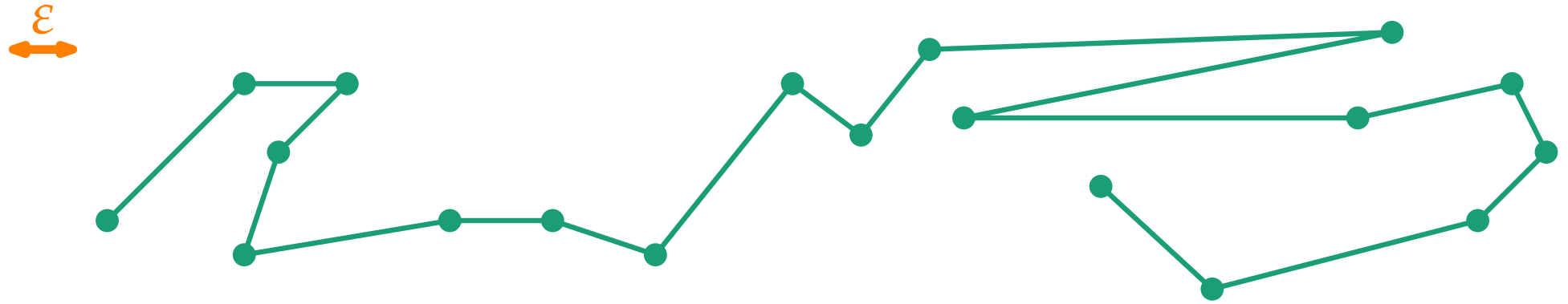
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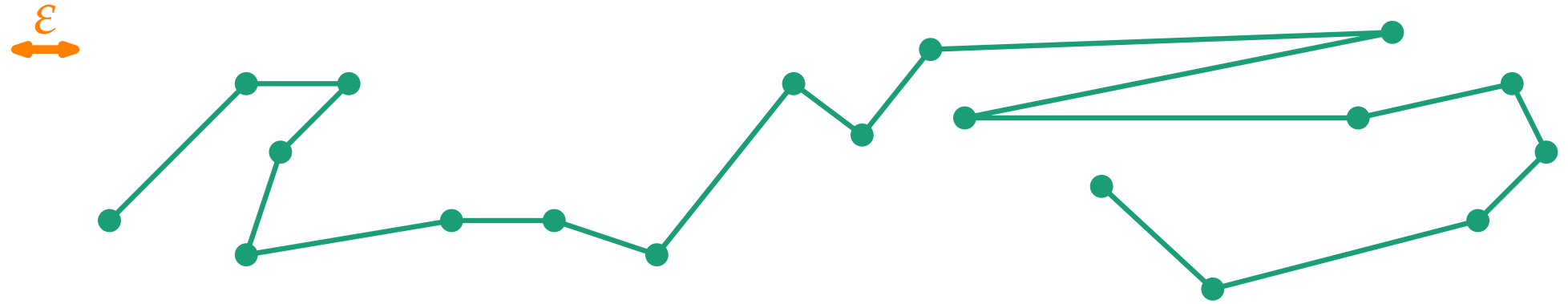
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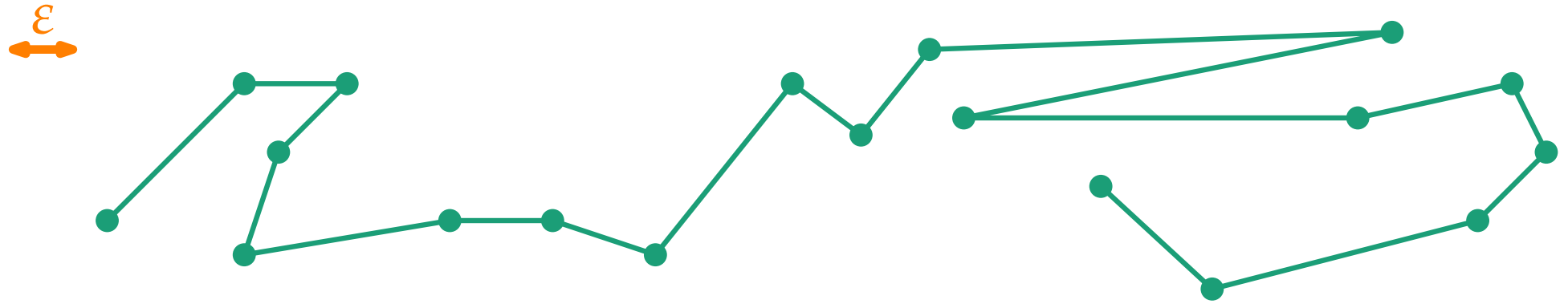
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distance measure
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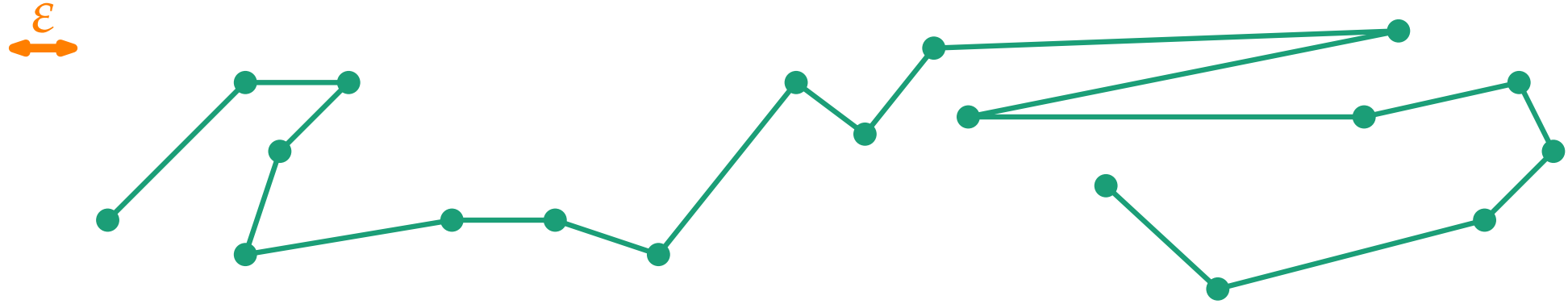
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measures d_X :



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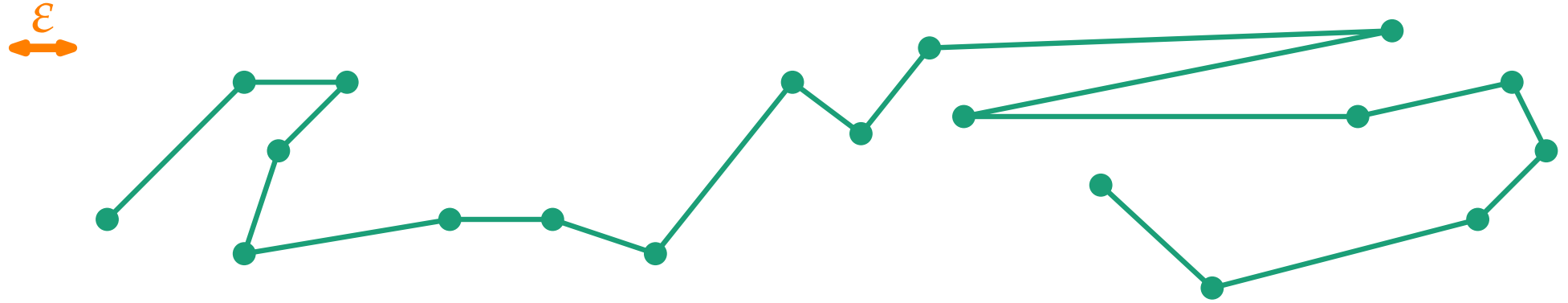
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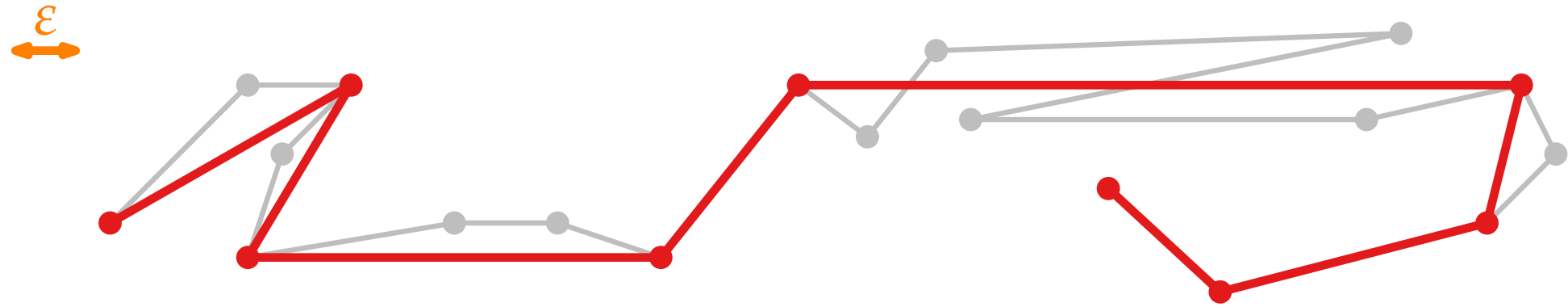
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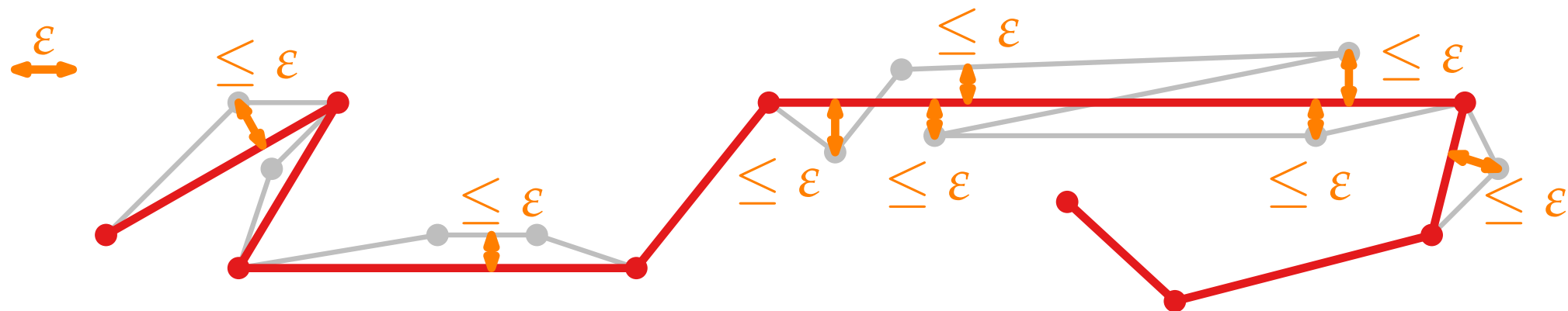
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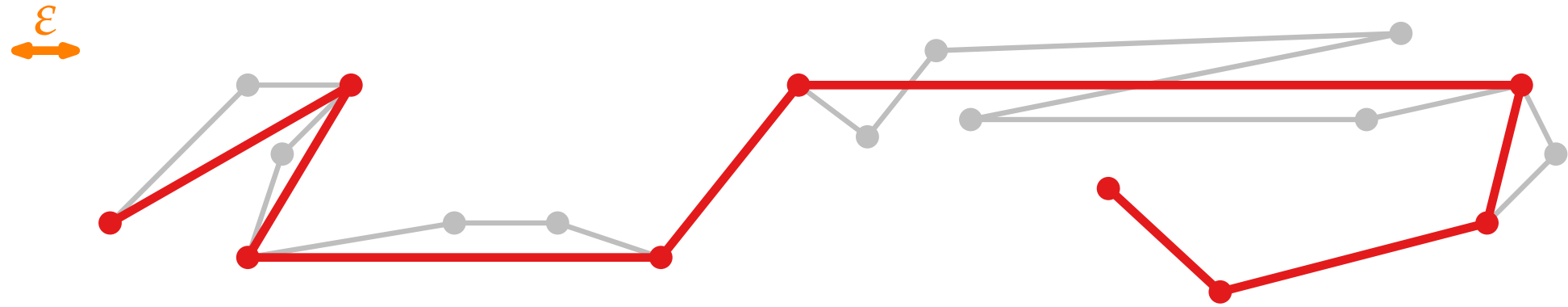
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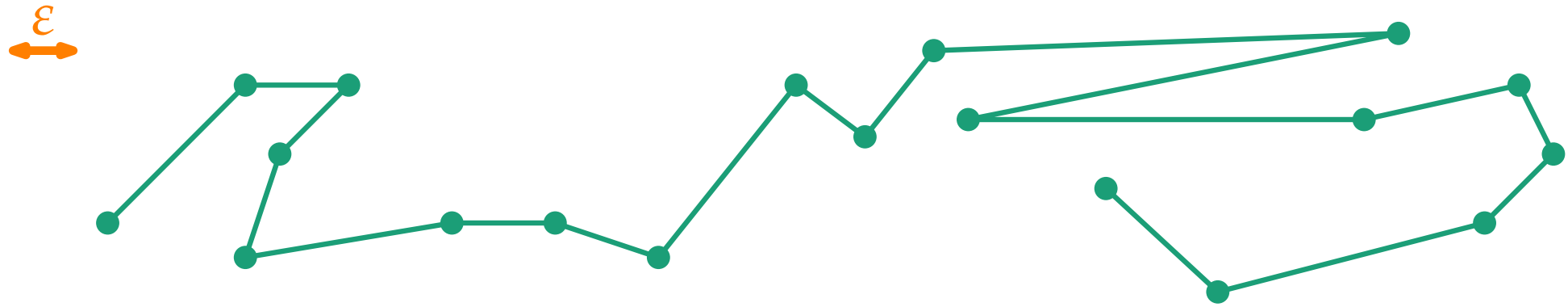
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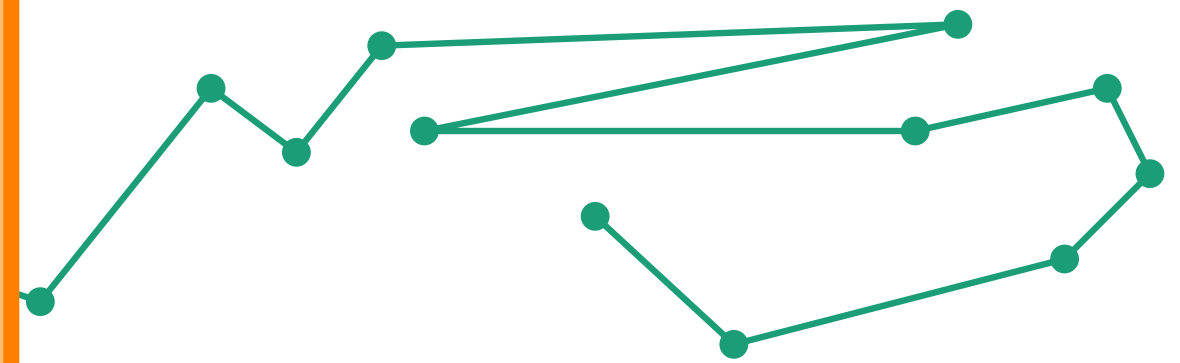
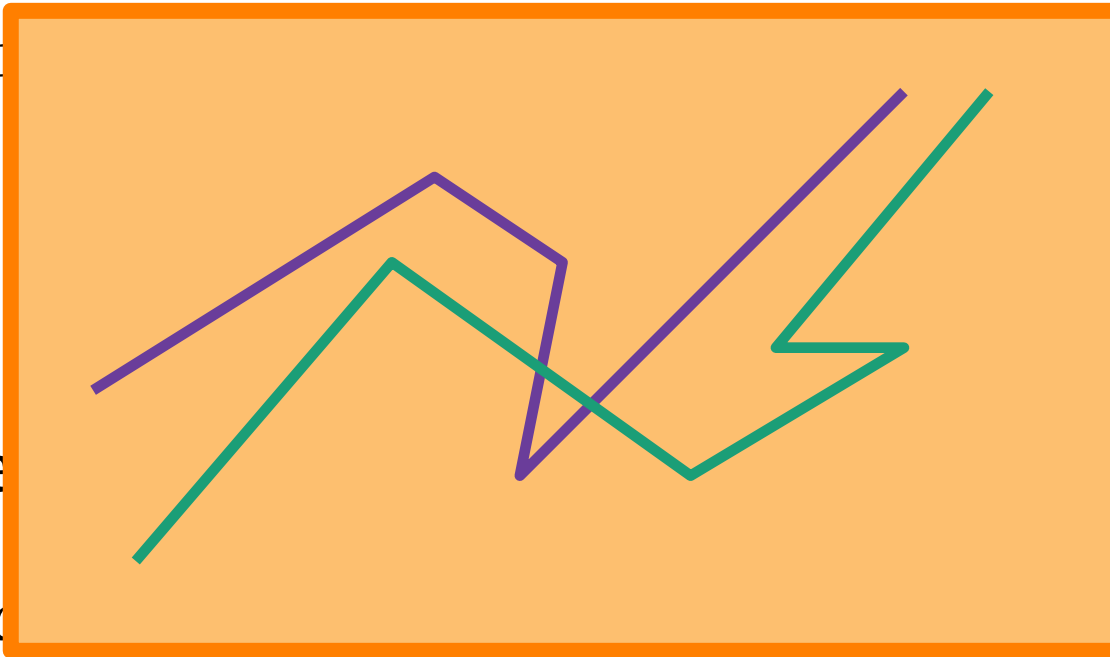
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Given:

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Typical
measure



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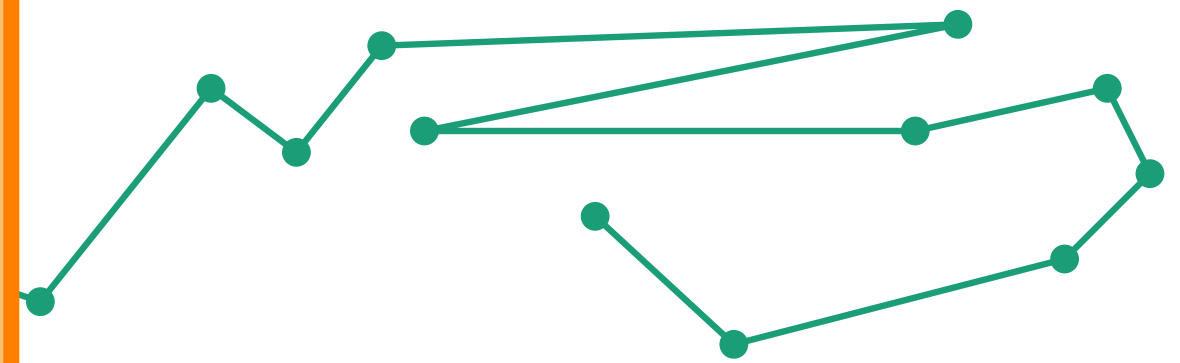
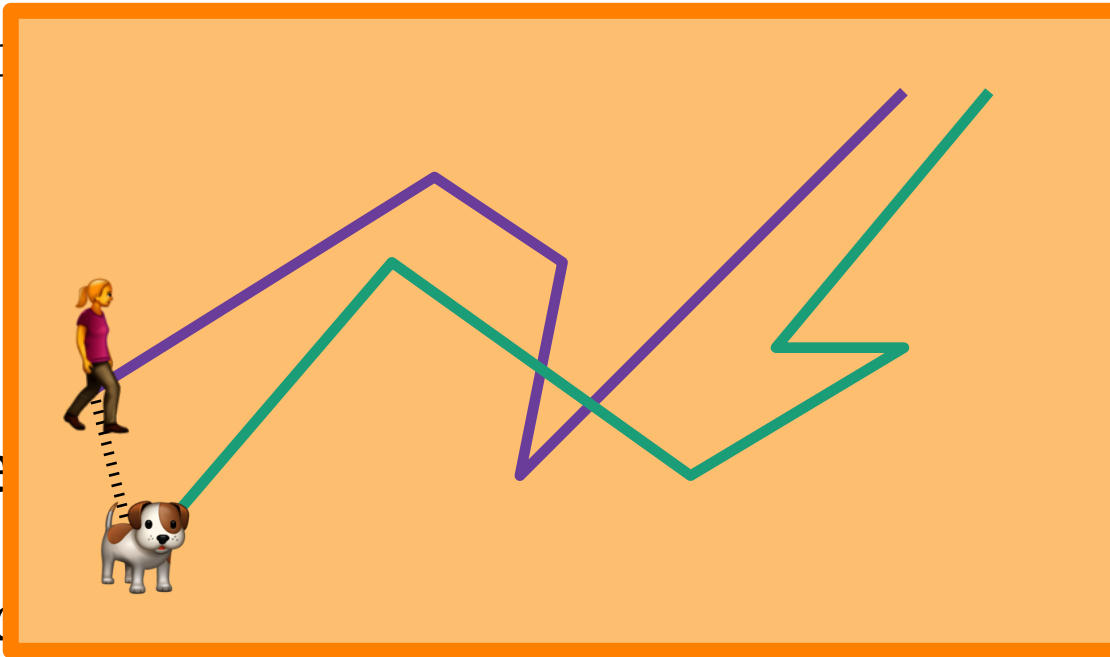
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Typical
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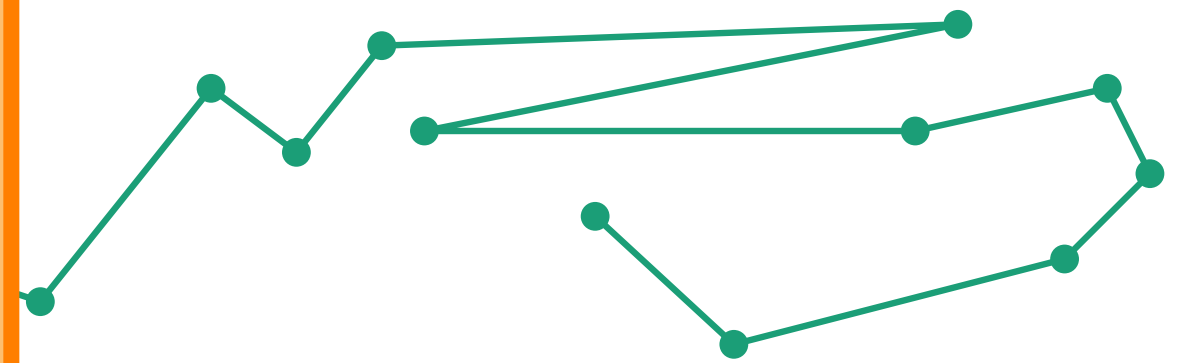
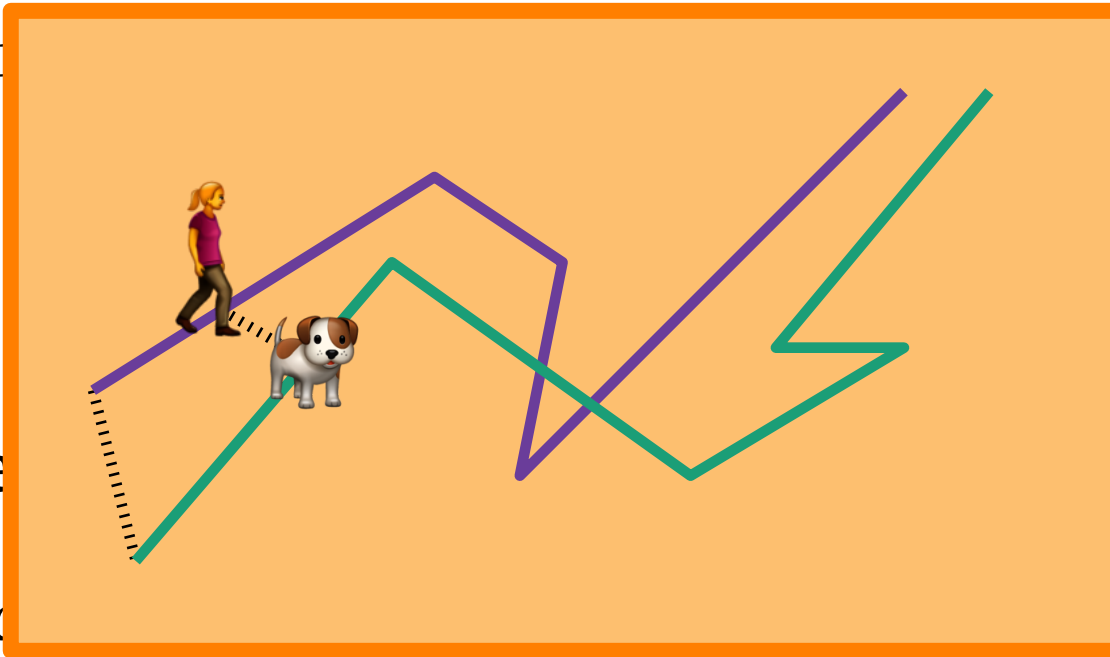
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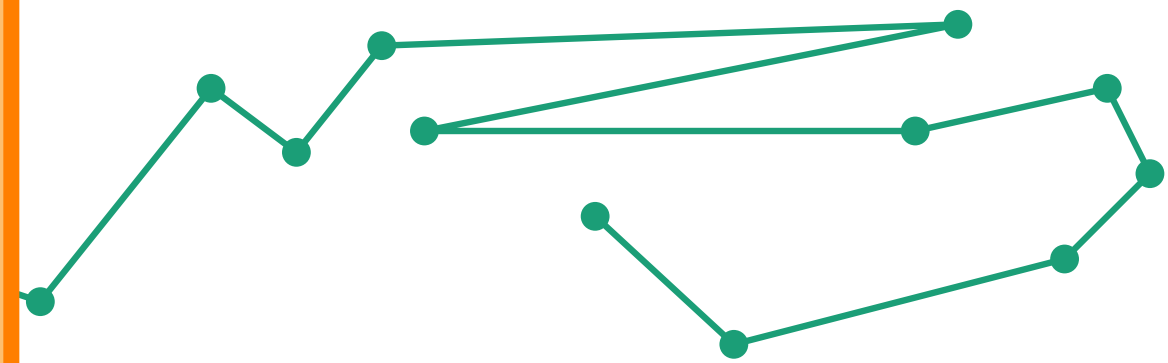
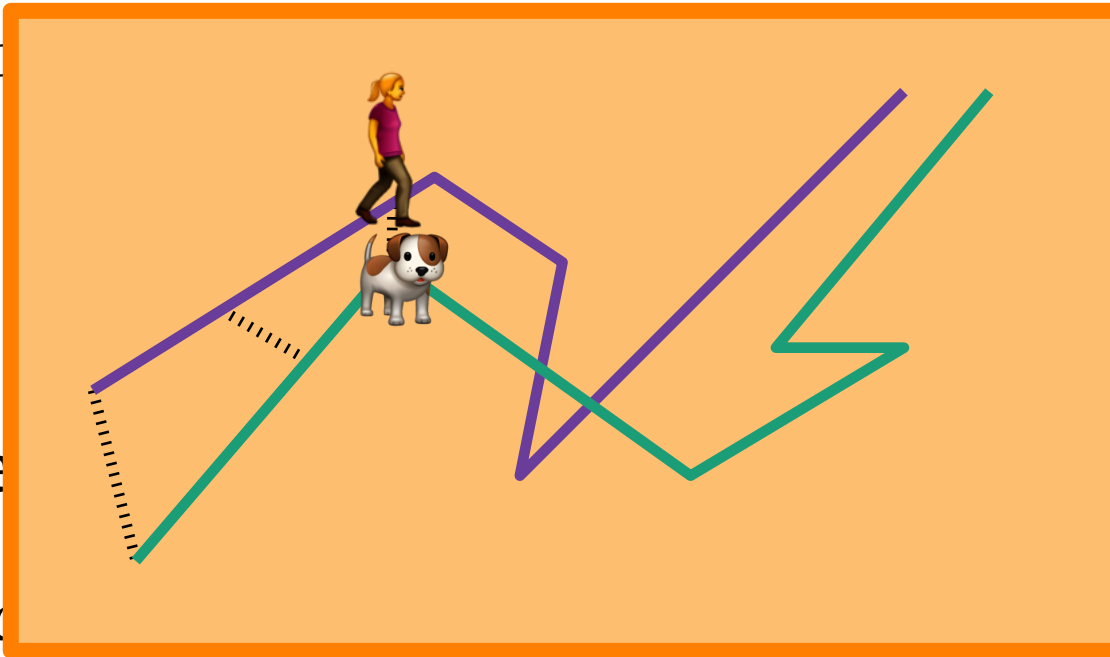
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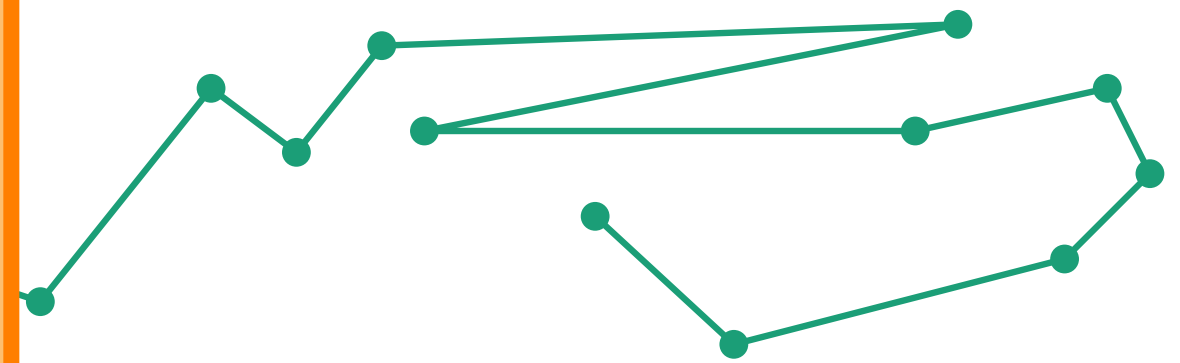
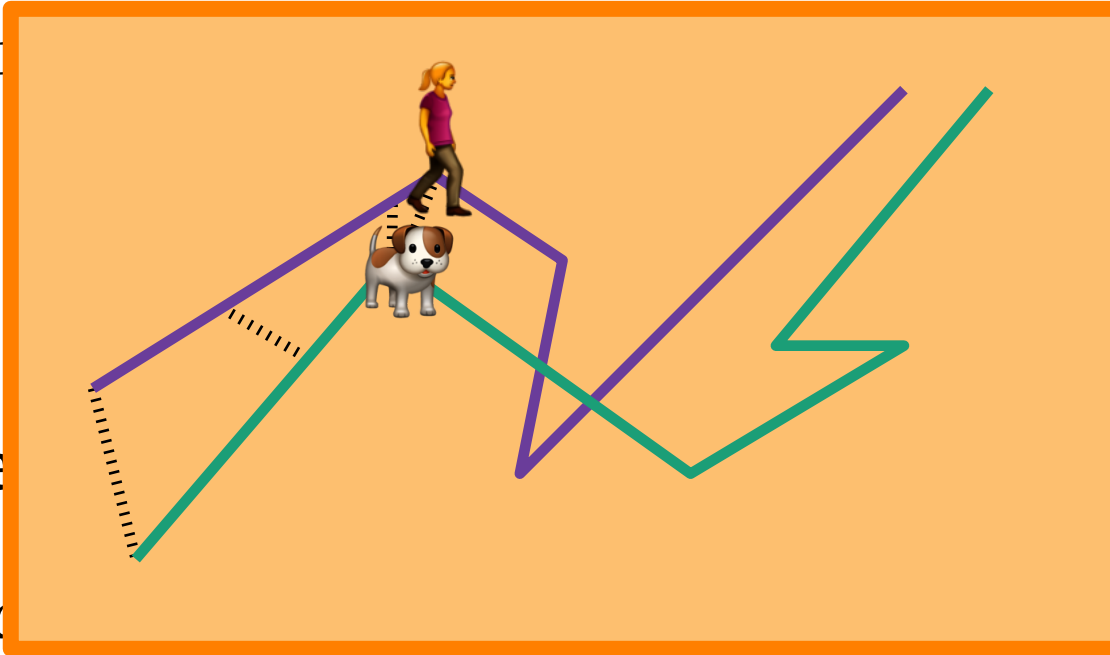
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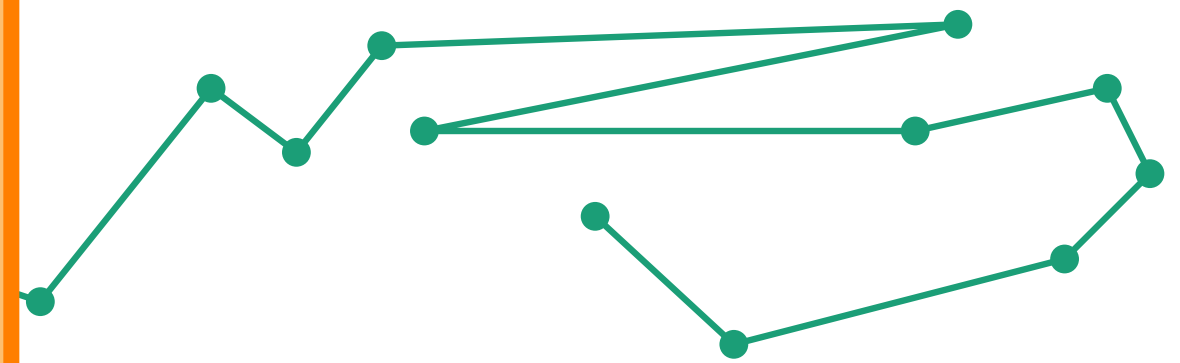
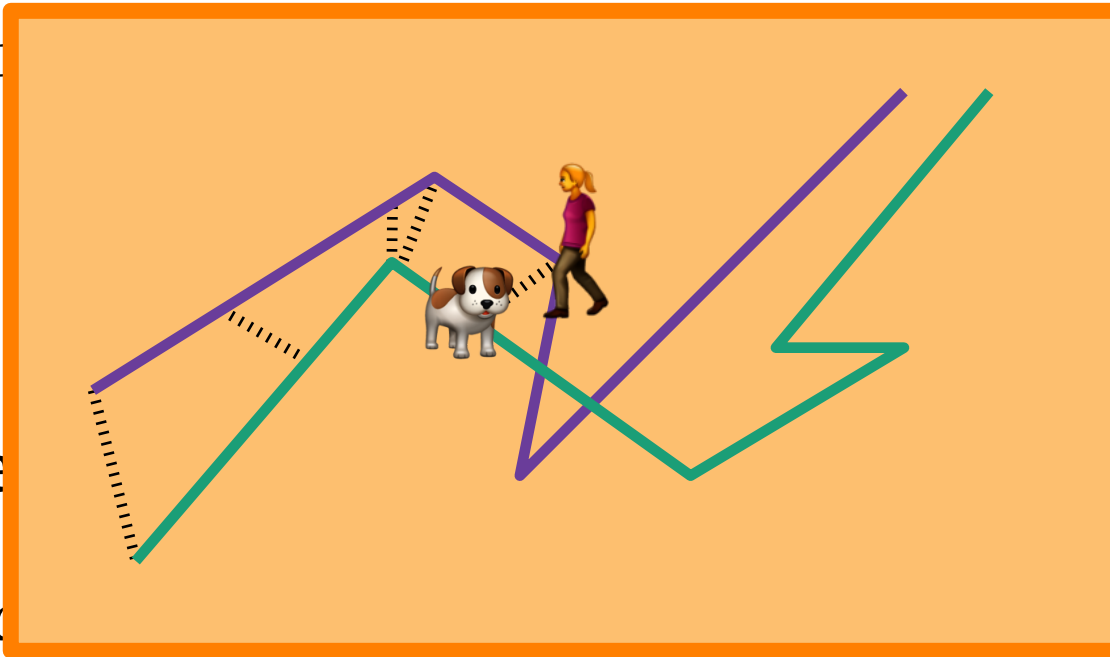
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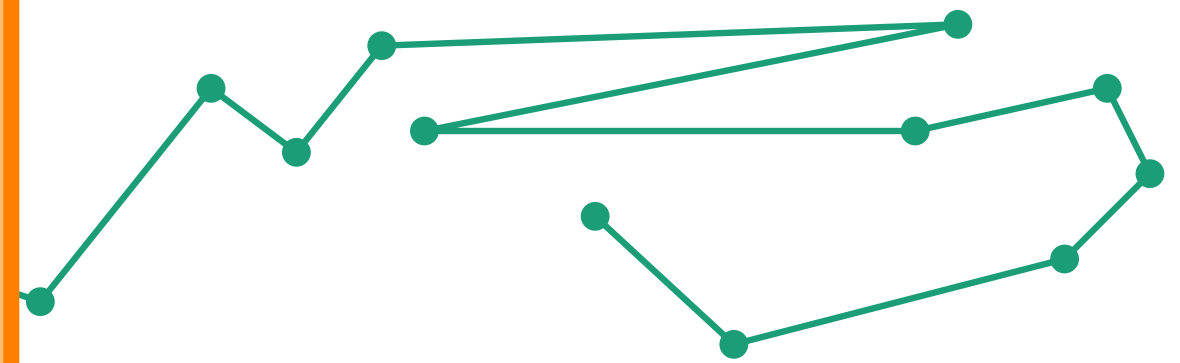
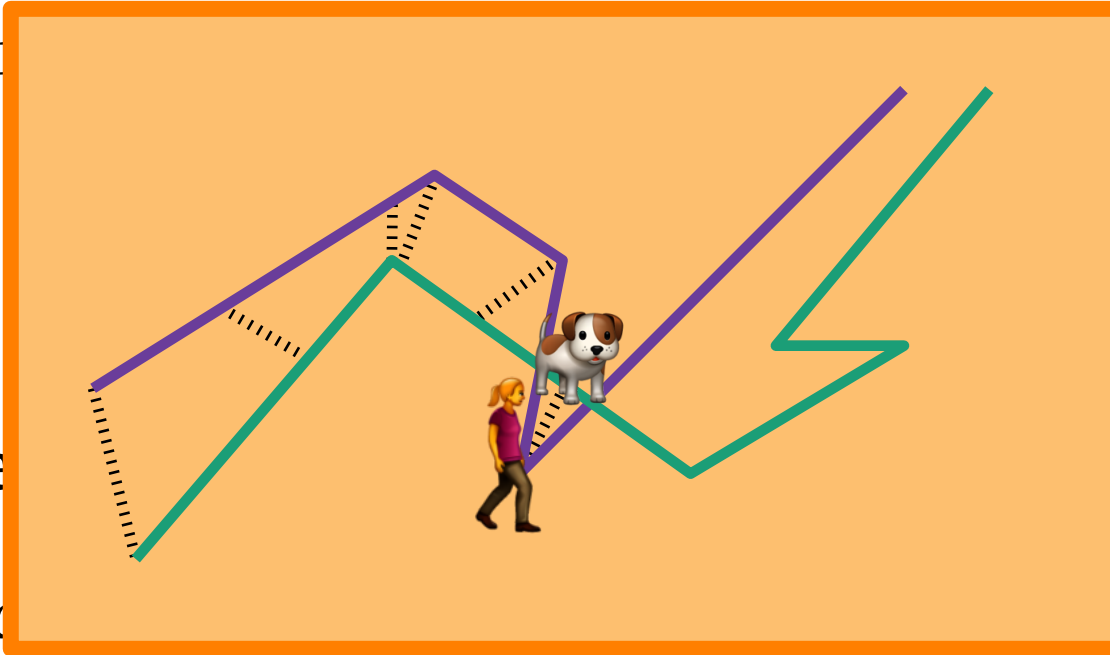
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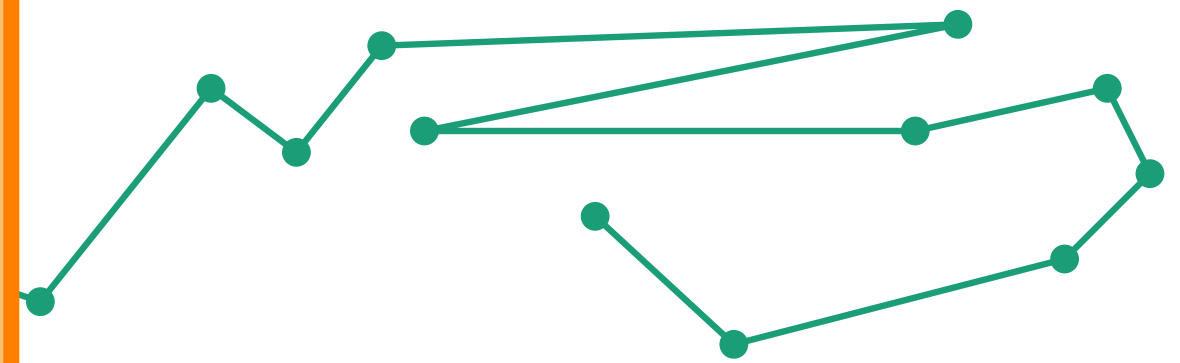
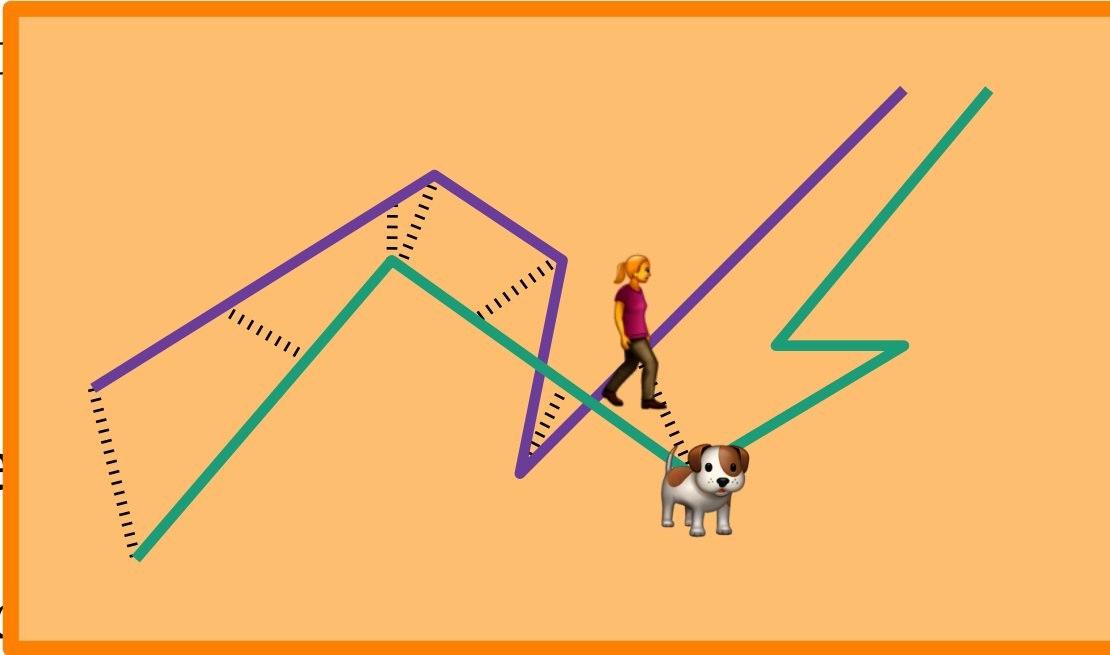
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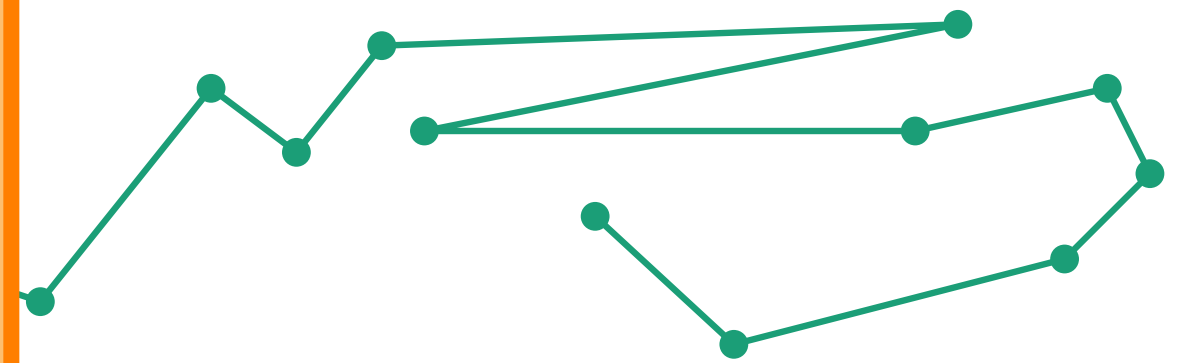
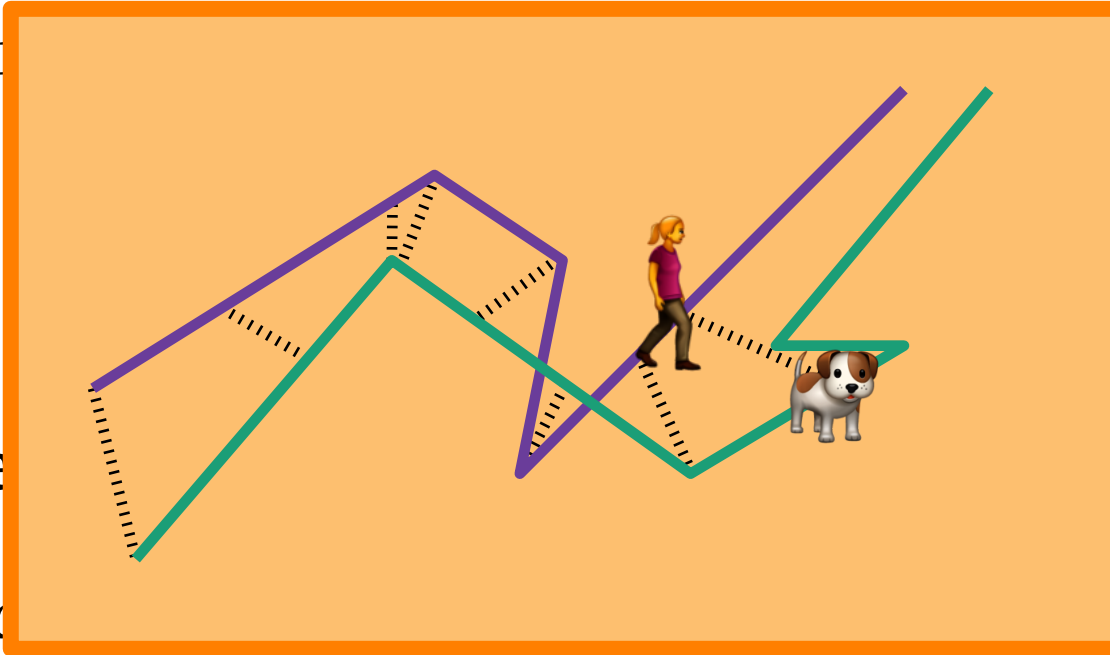
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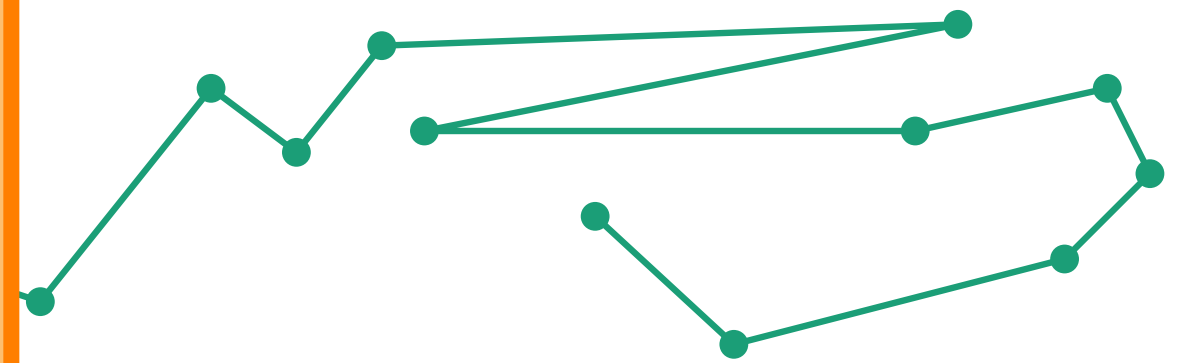
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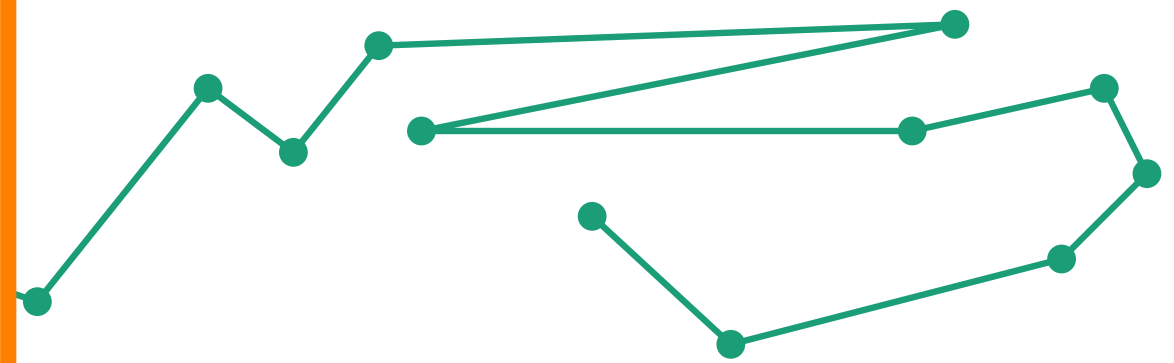
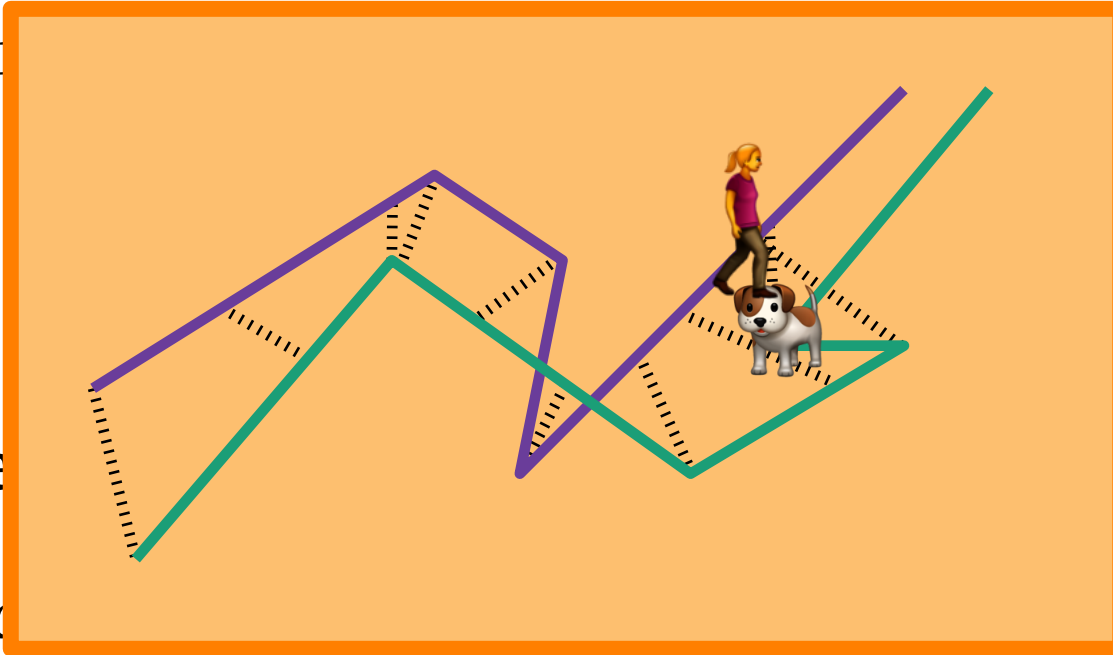
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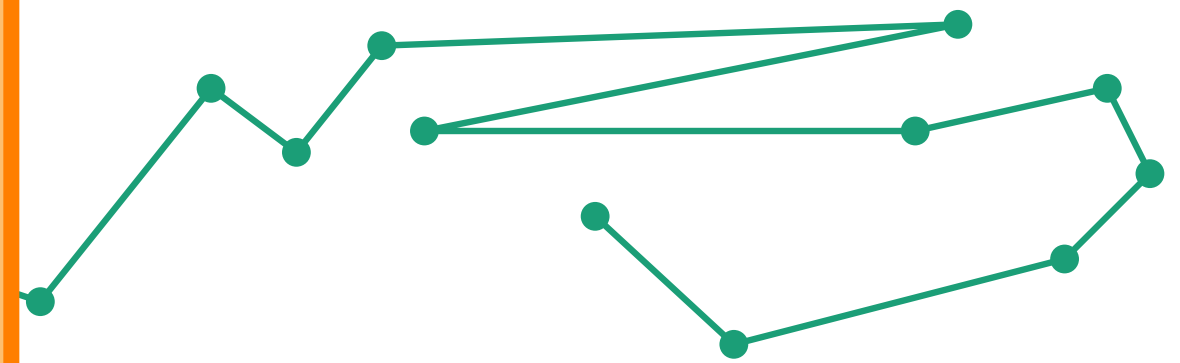
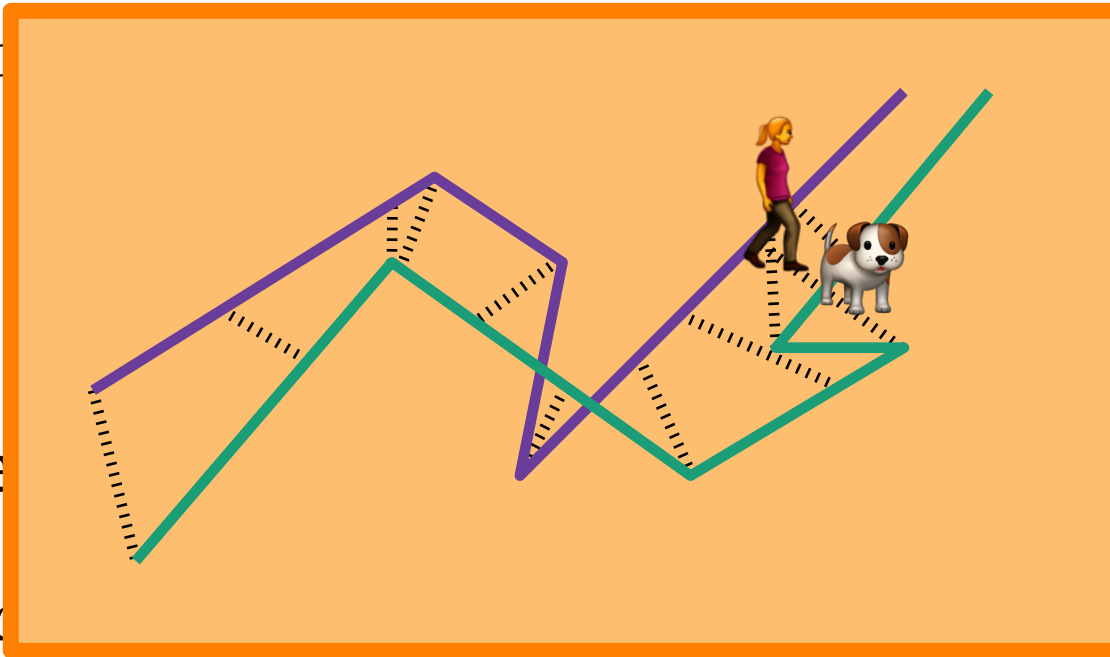
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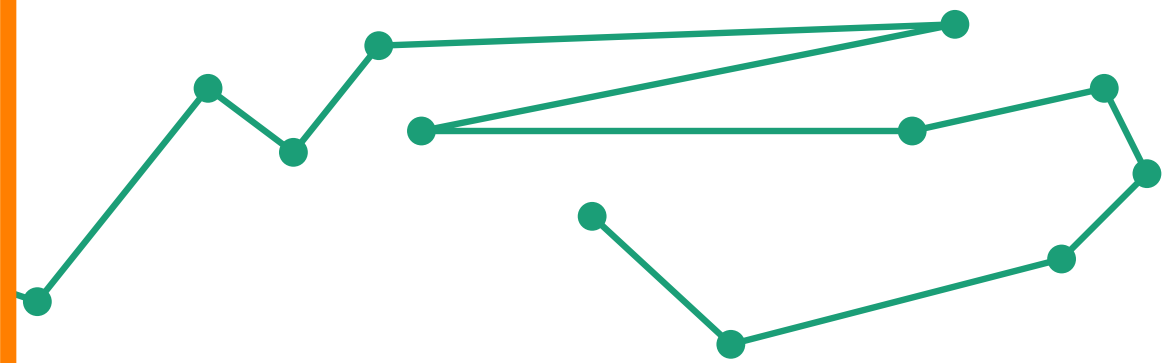
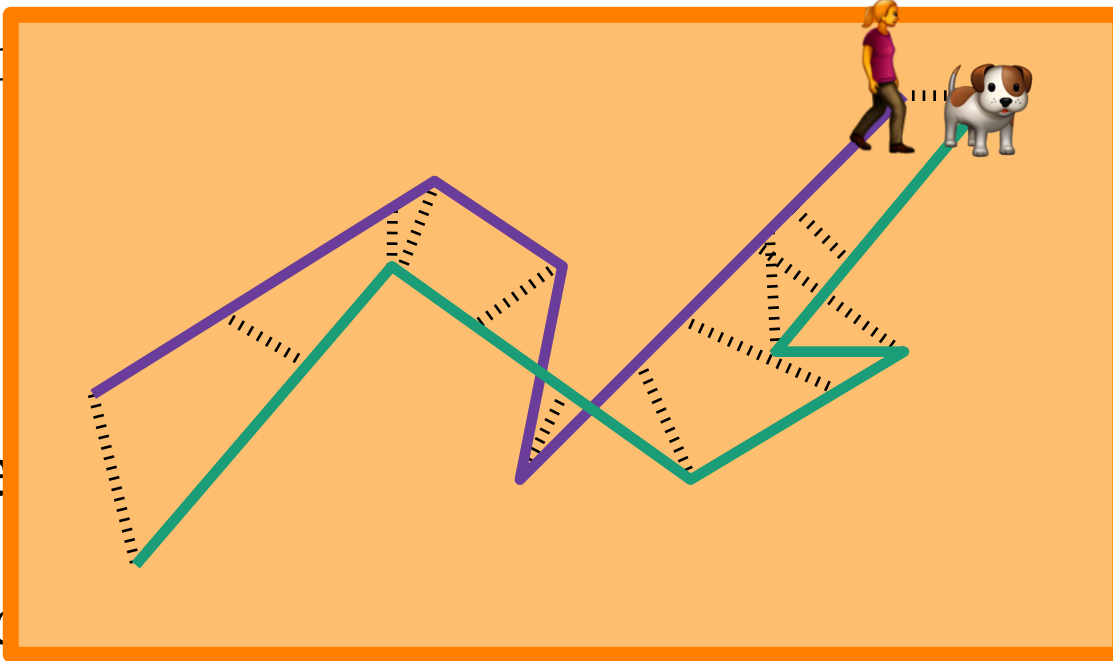
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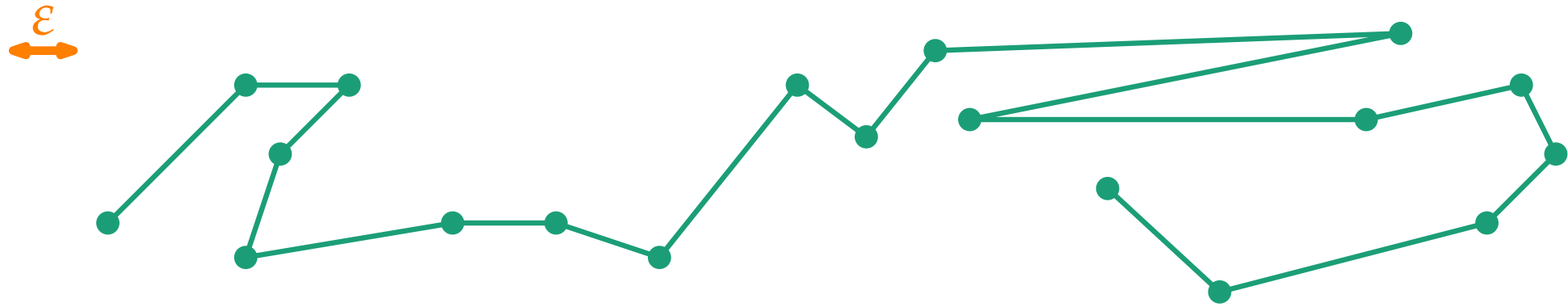
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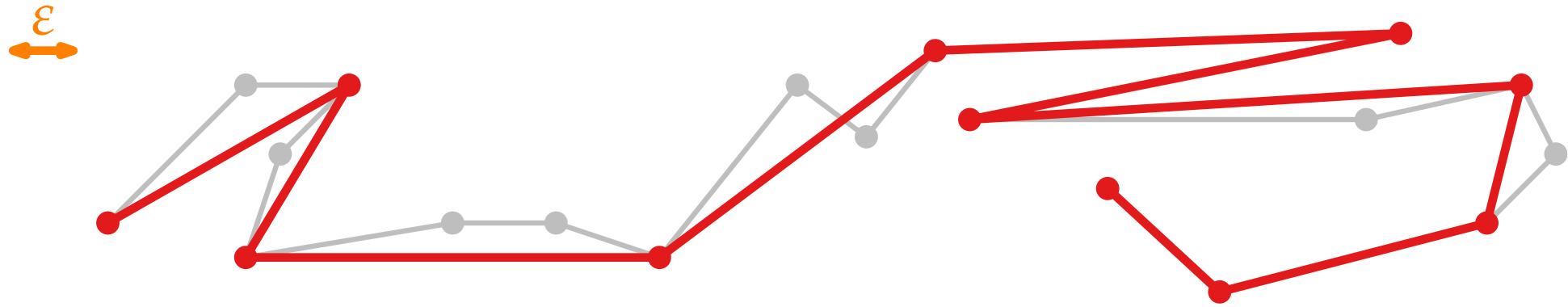
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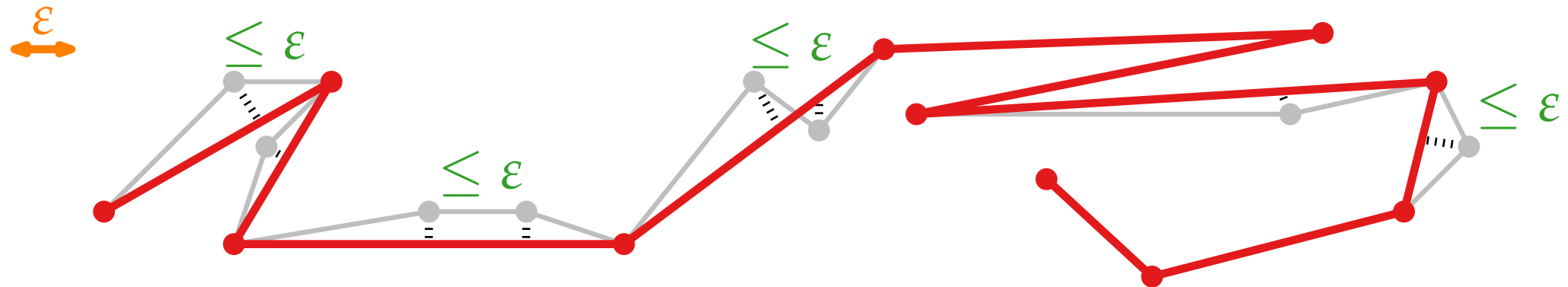
Definition: Polyline Simplification

Given:

- polyline P as a sequence of n points in the plane
- distance threshold ε

Find: Min. size subsequence P' of P , s.t. $d_X(P', P) \leq \varepsilon$ (keep start and end point).

Typical distance measures d_X :



- *Local Hausdorff distance*: for each line segment $\overline{uv} \in P'$: $d_H(\overline{uv}, P[u, v]) \leq \varepsilon$
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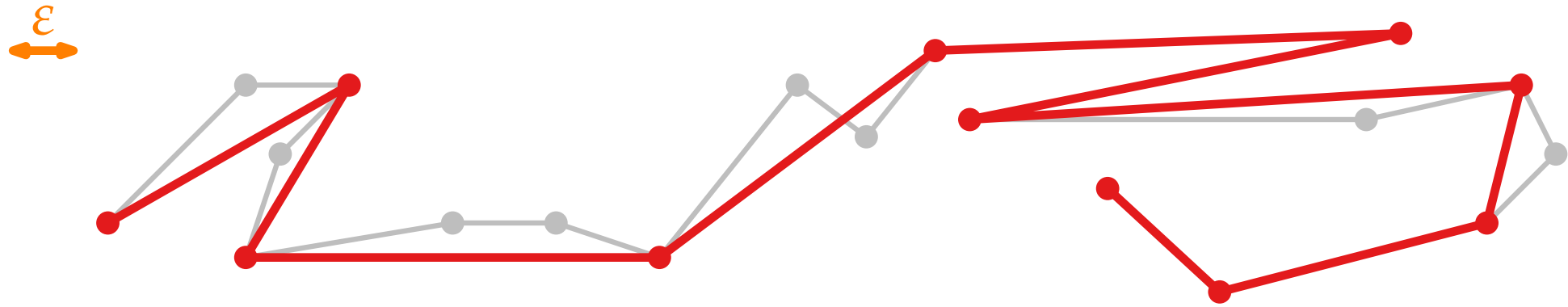
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Related Work & Contribution

Running time for finding an optimal polyline simplification ...

Related Work & Contribution

minimum size

Running time for finding an optimal polyline simplification ...

Related Work & Contribution

minimum size

Running time for finding an optimal polyline simplification ...

... under the local Hausdorff distance:

Related Work & Contribution

minimum size

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Related Work & Contribution

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Related Work & Contribution

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Algorithmica (2005) 42: 203–219
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Near-Linear Time Approximation Algorithms for Curve Simplification¹

Pankaj K. Agarwal,² Sarel Har-Peled,³ Nabil H. Mustafa,² and Yusu Wang²

5. Conclusions. In this paper we presented near-linear approximation algorithms for curve simplification under the Hausdorff and Fréchet error measures. We presented the first efficient approximation algorithm for Fréchet simplifications of a curve in dimension higher than two. Our experimental results demonstrate that our algorithms are efficient.

We conclude by mentioning a few open problems:

- (i) Does there exist a near-linear algorithm for computing an ε -simplification of size at most $c\kappa_M(\varepsilon, P)$ for a polygonal curve P , where $c \geq 1$ is a constant?
- (ii) Is it possible to compute the optimal ε -simplification under the Hausdorff error measure in near-linear time, or under the Fréchet error measure in subcubic time?
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2005

Related Work & Contribution

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2005

Polyline Simplification has Cubic Complexity

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35th International Symposium on Computational Geometry (SoCG 2019).
Editors: Gill Barequet and Yusu Wang; Article No. 18; pp. 18:1–18:16
Leibniz International Proceedings in Informatics
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The classic $\hat{O}(n^3)^1$ time algorithm by Imai and Iri [18] was designed for Local-Hausdorff simplification. By changing the distance computation in this algorithm for the Fréchet distance, one can obtain an $\hat{O}(n^3)$ -time algorithm for Local-Fréchet [15]. There are improvements for Local-Hausdorff simplification in small dimension d [19, 8, 6]; the fastest running times are $2^{O(d)}n^2$ for L_1 -norm, $\hat{O}(n^2)$ for L_∞ -norm, and $\hat{O}(n^{3-\Omega(1/d)})$ for L_2 -norm [6].

2019

Related Work & Contribution

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ON OPTIMAL POLYLINE SIMPLIFICATION USING THE HAUSDORFF AND FRÉCHET DISTANCE*

Marc van Kreveld,[†] Maarten Löffler,[†] and Lionov Wiratma^{†‡}

ABSTRACT. We revisit the classical polygonal line simplification problem and study it using the Hausdorff distance and Fréchet distance. Interestingly, no previous authors studied line simplification under these measures in its pure form, namely: for a given $\varepsilon > 0$, choose a minimum size subsequence of the vertices of the input such that the Hausdorff or Fréchet distance between the input and output polylines is at most ε .

Table 1: Algorithmic results.

	Douglas-Peucker	Imai-Iri	Optimal
Hausdorff distance	$O(n \log n)$ [19]	$O(n^2)$ [10]	NP-hard (this paper)
Fréchet distance	$O(n^2)$ (easy)	$O(n^3)$ [17]	$O(kn^5)$ (this paper)

n : vertices in the input polyline; k : output complexity of the simplified polyline

2005

2019

2020

Related Work & Contribution

minimum size

Running time for finding an optimal polyline simplification ...

... under the local Hausdorff distance:

... under the local Fréchet distance:

■ $O(n^3)$ [Imai, Iri '88]



■ $O(n^3)$ [Godau '91]



■ $O(n^2 \log n)$ [Melkman, O'Rourke '88]

■ ?



■ $O(n^2)$ time [Chan, Chin '96]

Related Work & Contribution

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our contribution

Related Work & Contribution

minimum size

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... under the local Hausdorff distance:

... under the local Fréchet distance:

L_2 norm

■ $O(n^3)$ [Imai, Iri '88]

■ $O(n^3)$ [Godau '91]

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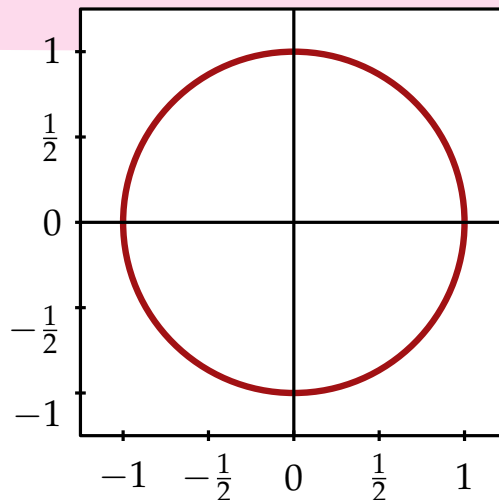
■ $O(n^2 \log n)$

■ $O(n^2)$ time [Chan, Chin '96]

our contribution

L_p :

$p = 2$



Related Work & Contribution

minimum size

Running time for finding an optimal polyline simplification ...

... under the local Hausdorff distance:

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L_1 norm

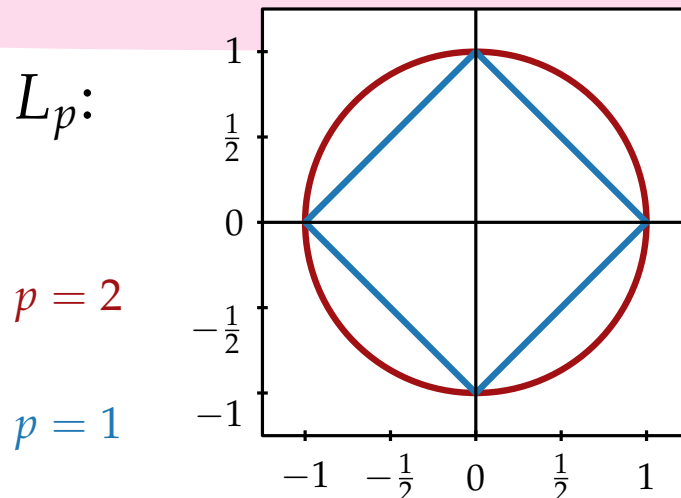
■ $O(n^3)$ [Godau '91]

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■ $O(n^2)$

our contribution



Related Work & Contribution

minimum size

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■ $O(n^2)$

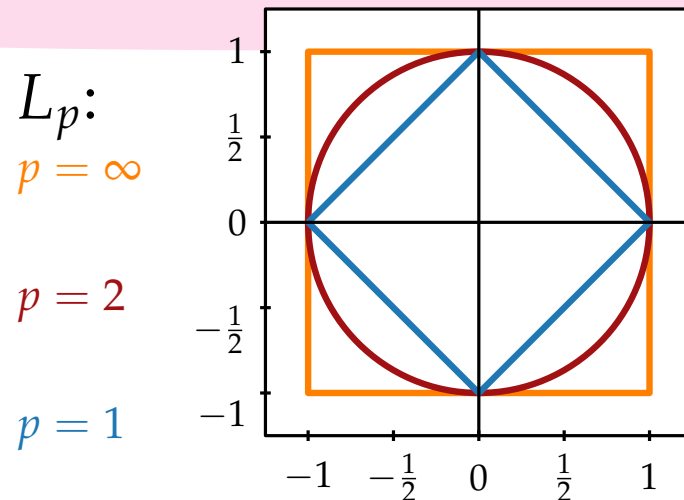


■ $O(n^2)$

L_1 norm

L_∞ norm

our contribution



Related Work & Contribution

minimum size

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■ $O(n^2 \log n)$

L_1 norm

■ $O(n^2)$

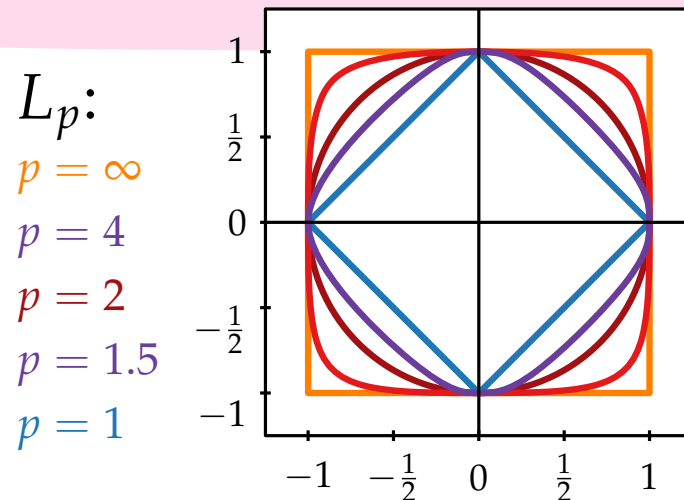
L_∞ norm

■ $O(n^2)$

$L_{p \in (1, \infty)}$ norm

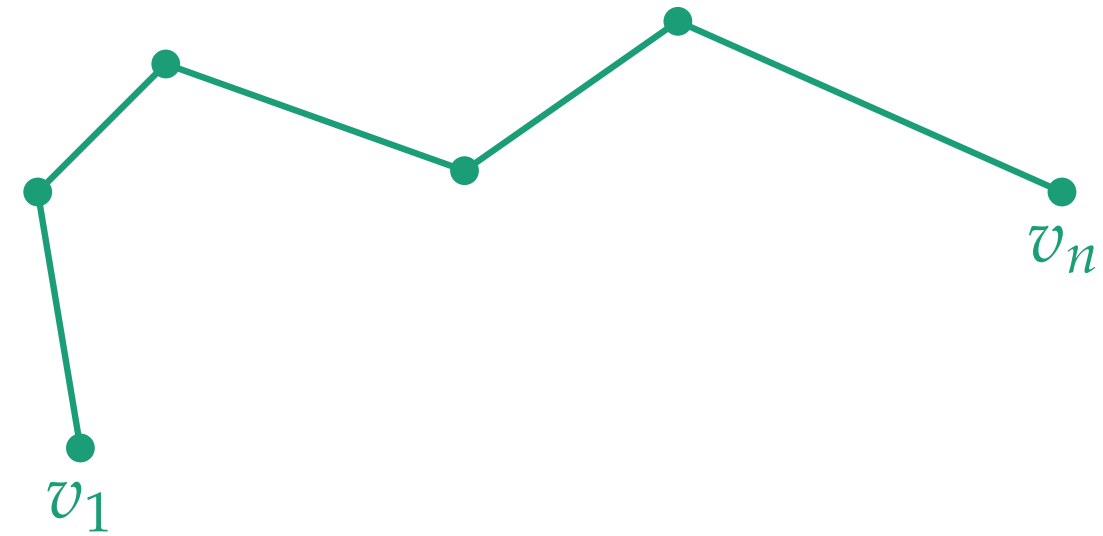
■ $O(n^2 \log n)$

our contribution



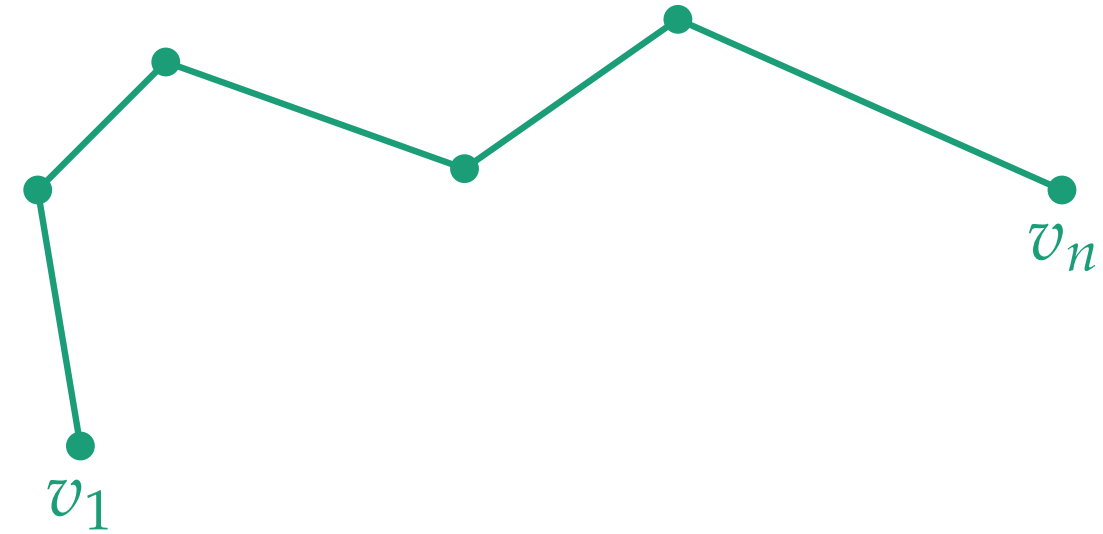
Algorithm by Imai and Iri

- proceeds in two phases



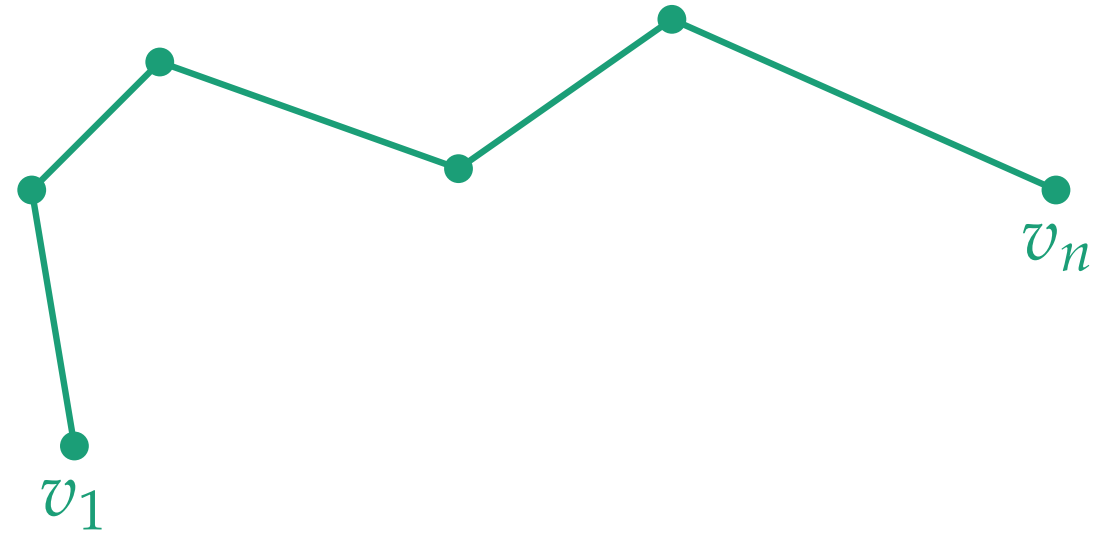
Algorithm by Imai and Iri

- proceeds in two phases
- First phase:



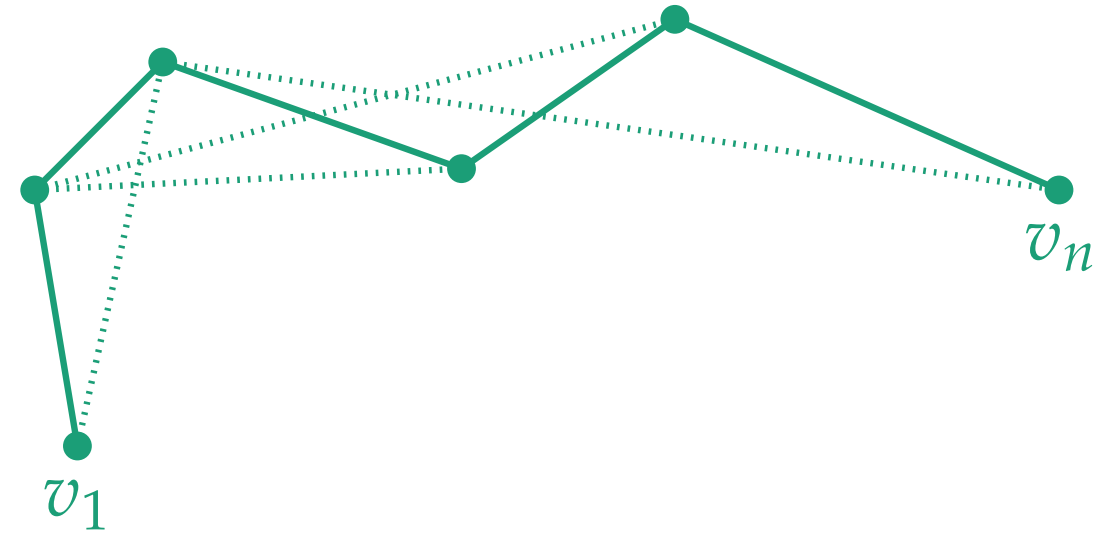
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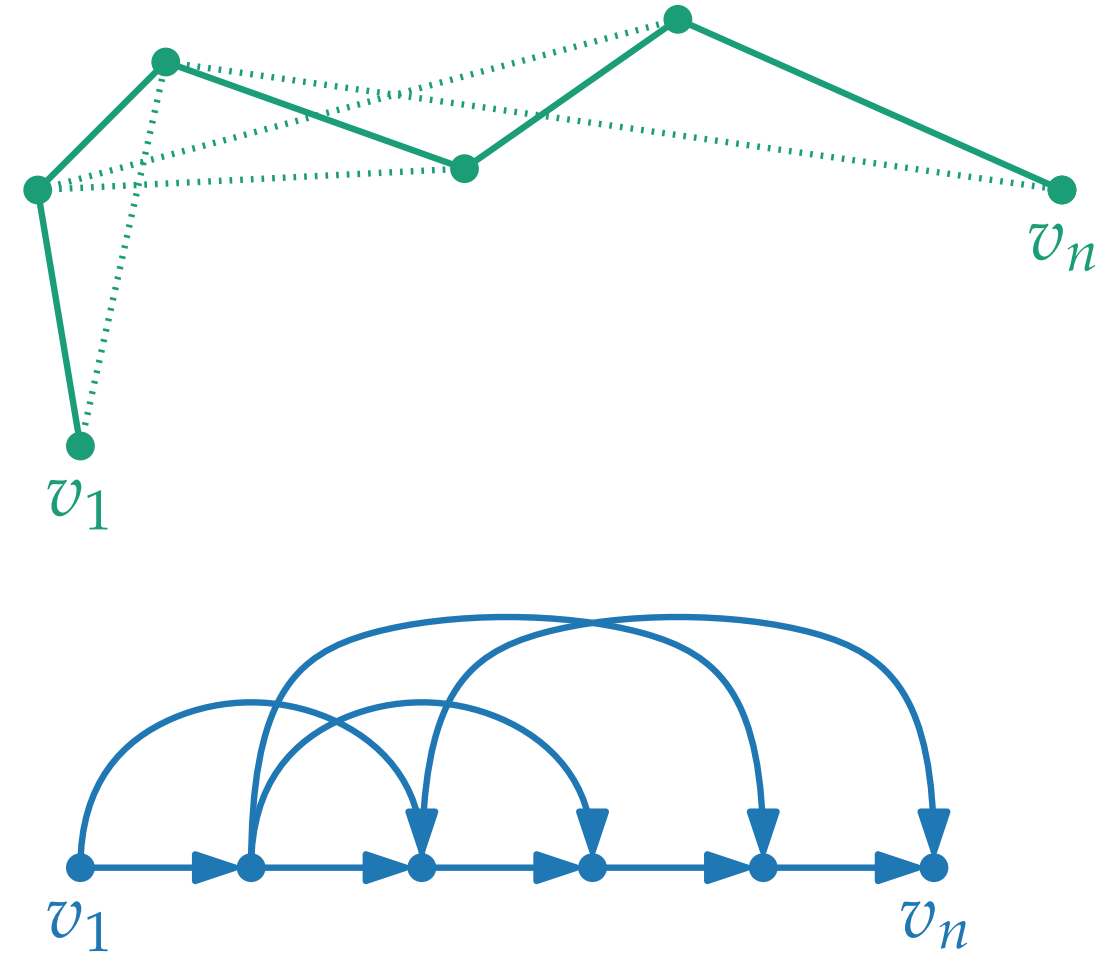
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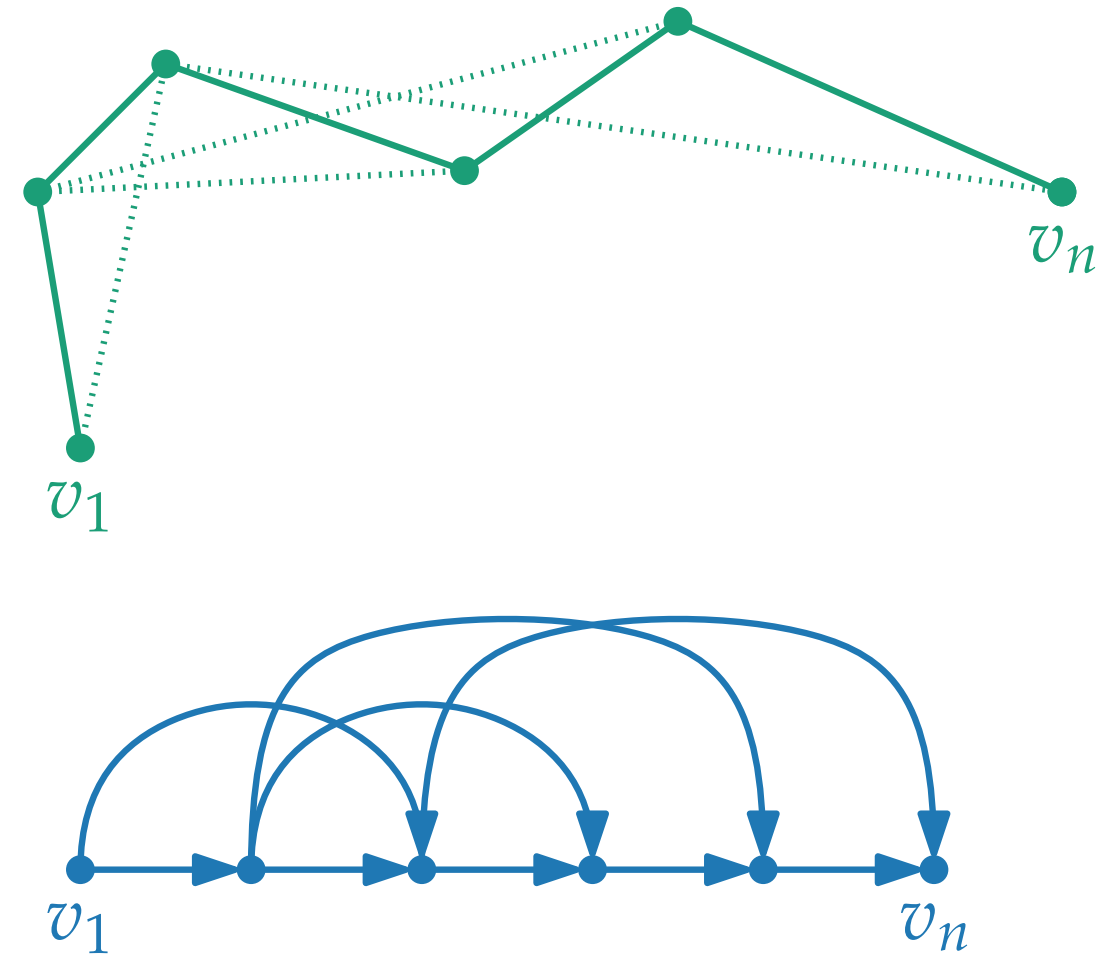
Algorithm by Imai and Iri

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 - build shortcut graph



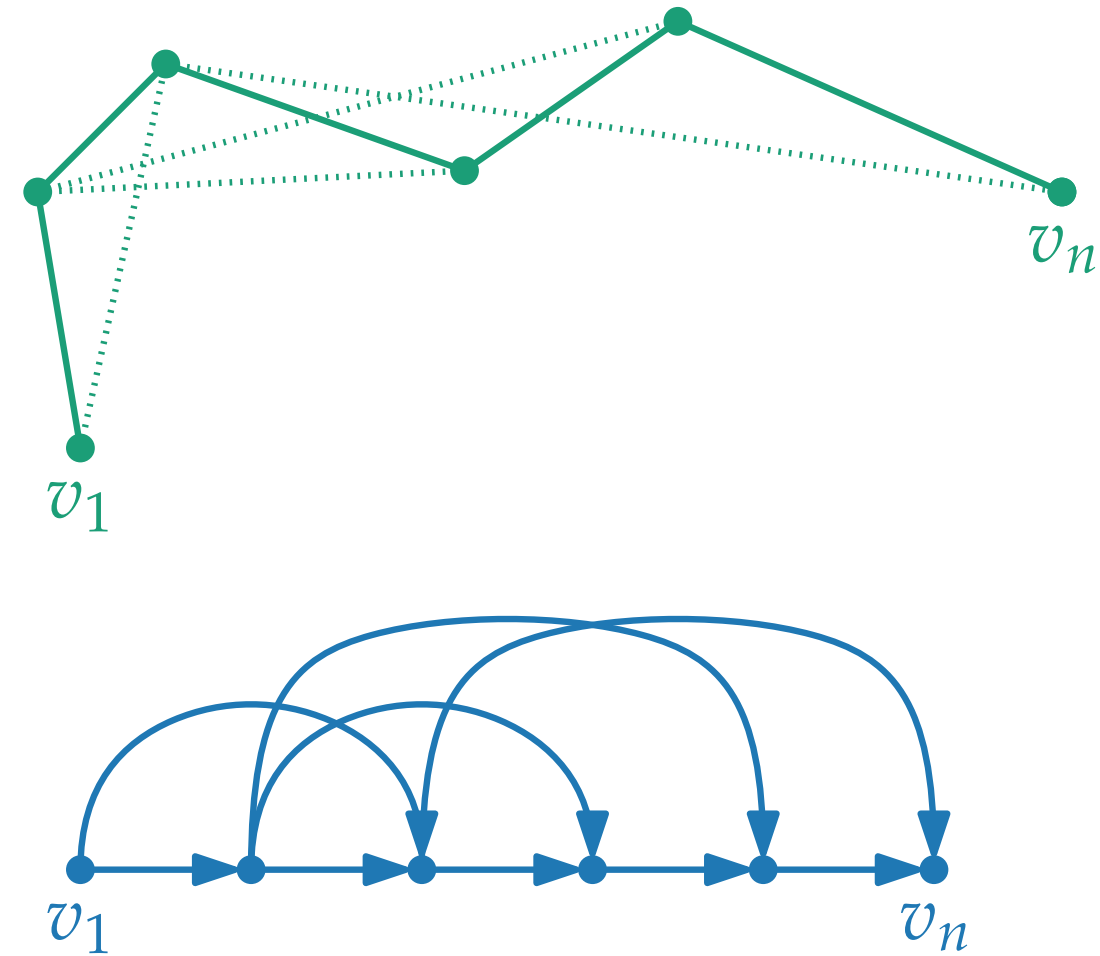
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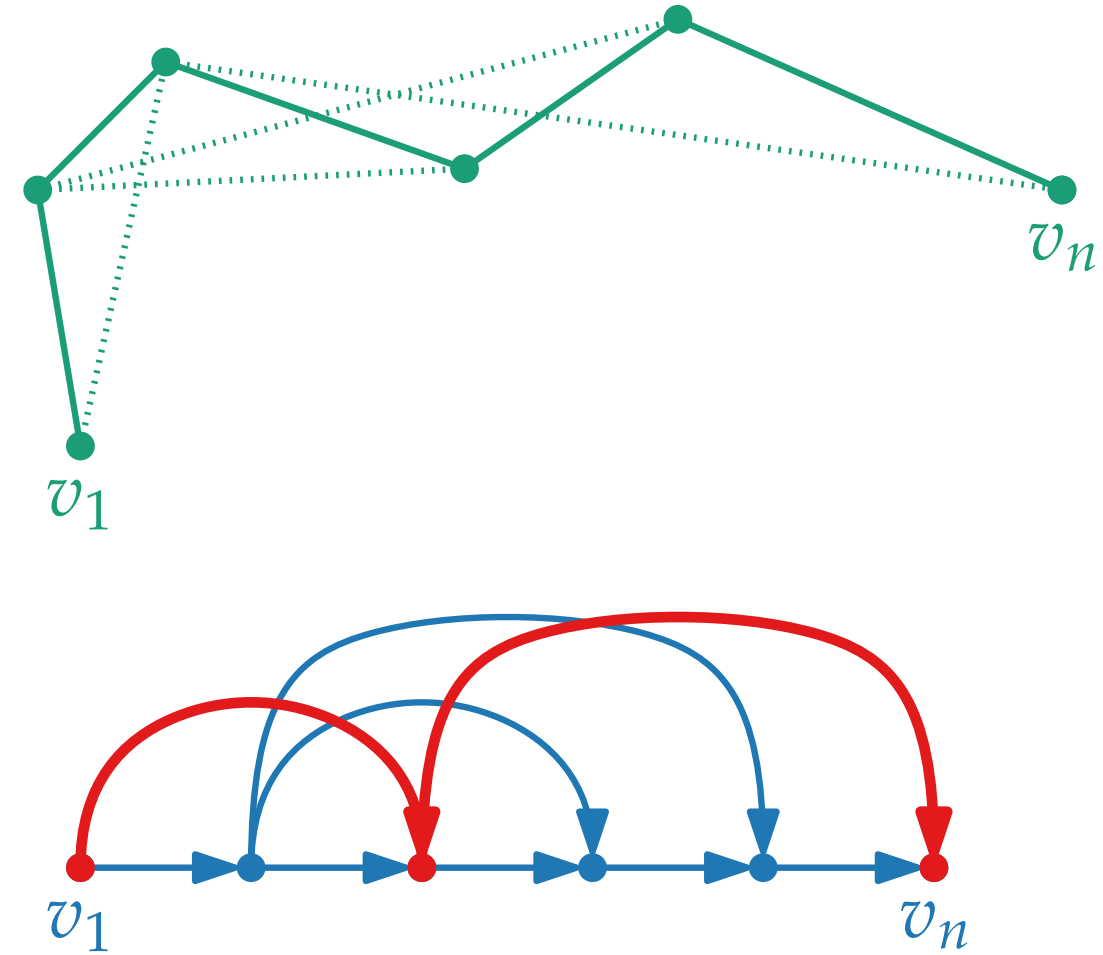
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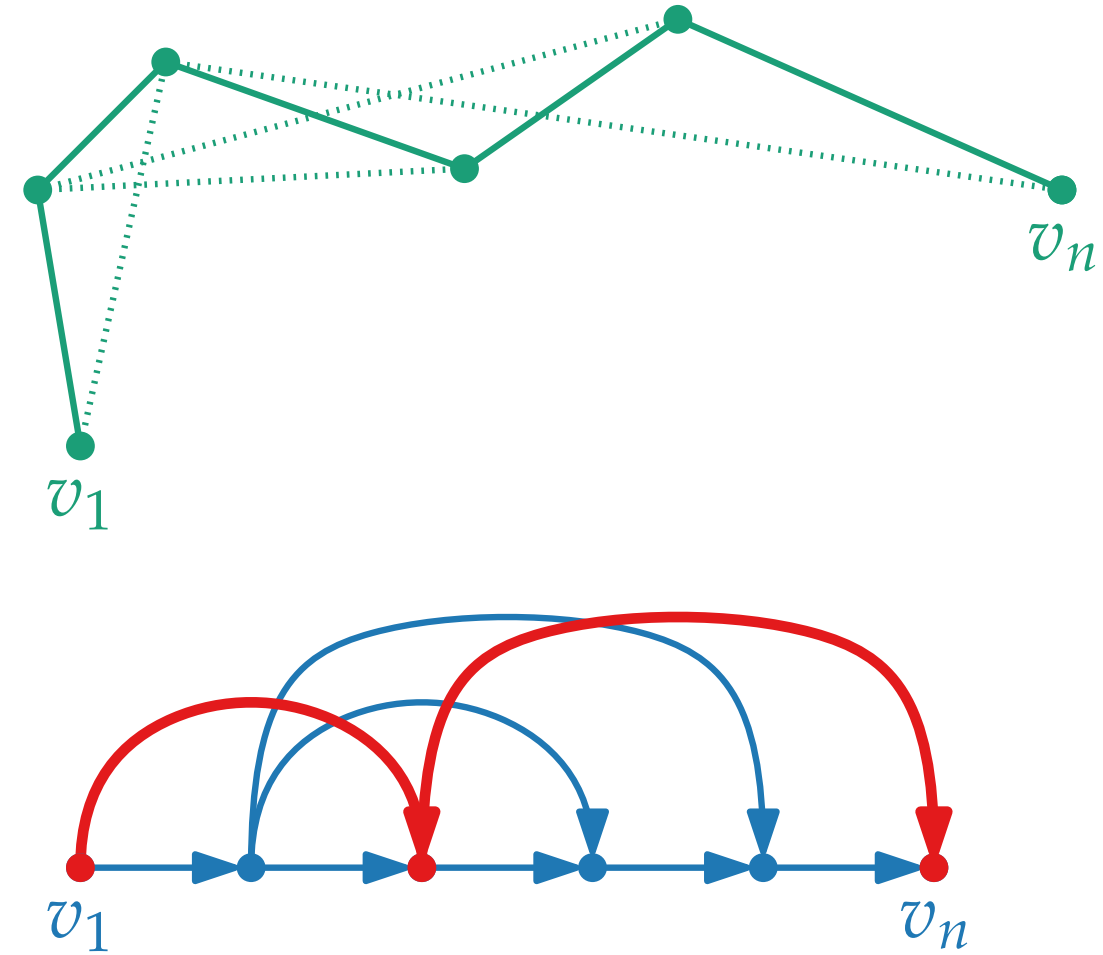
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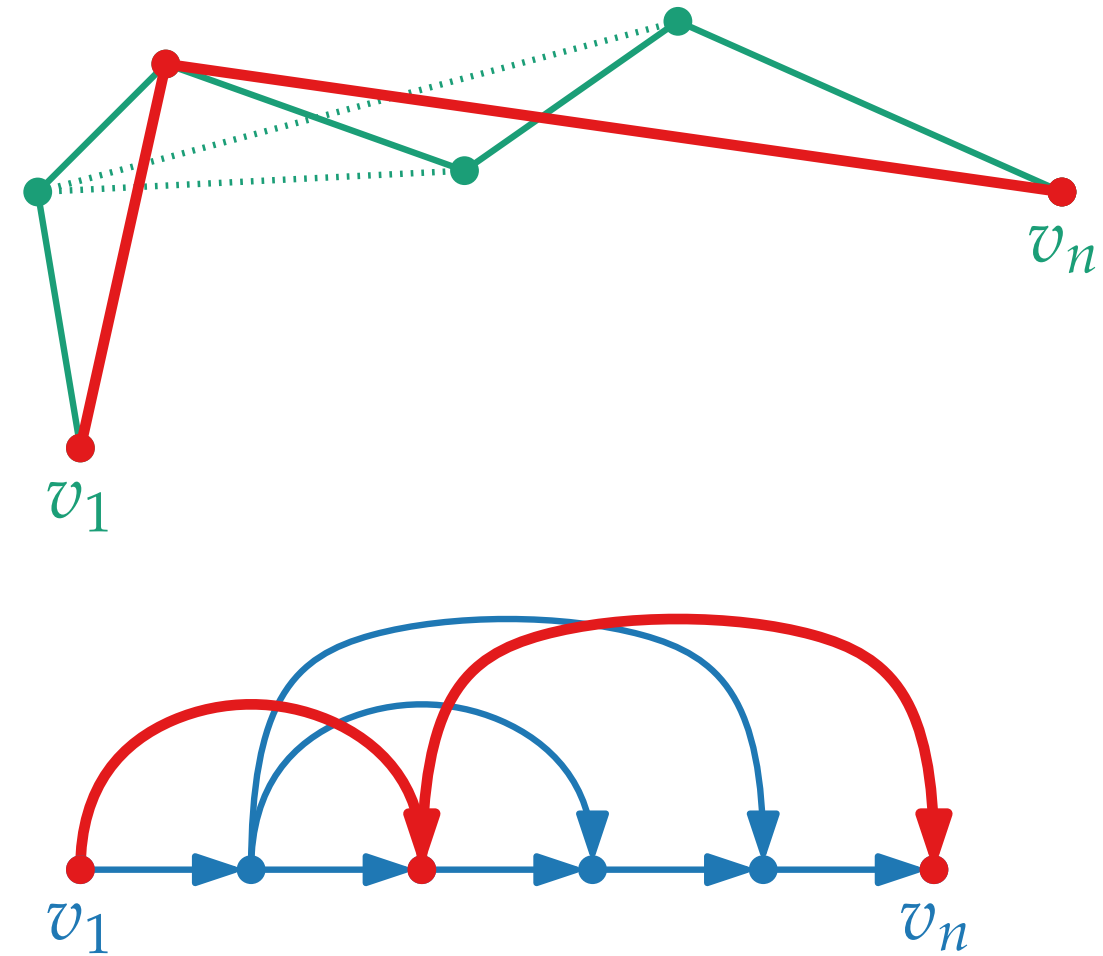
Algorithm by Imai and Iri

- proceeds in two phases
- First phase:
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 - build shortcut graph
- Second phase:
 - find shortest path in shortcut graph
 - return optimal simplification



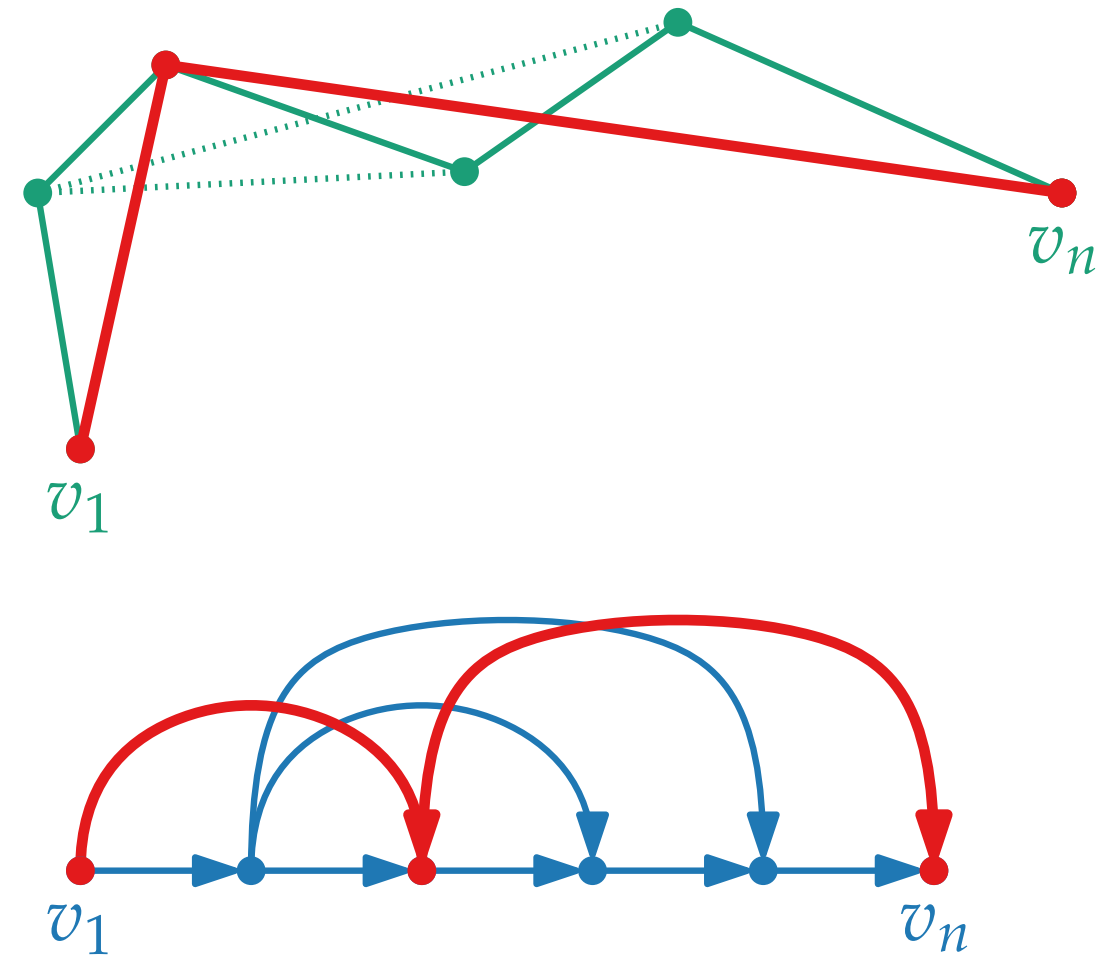
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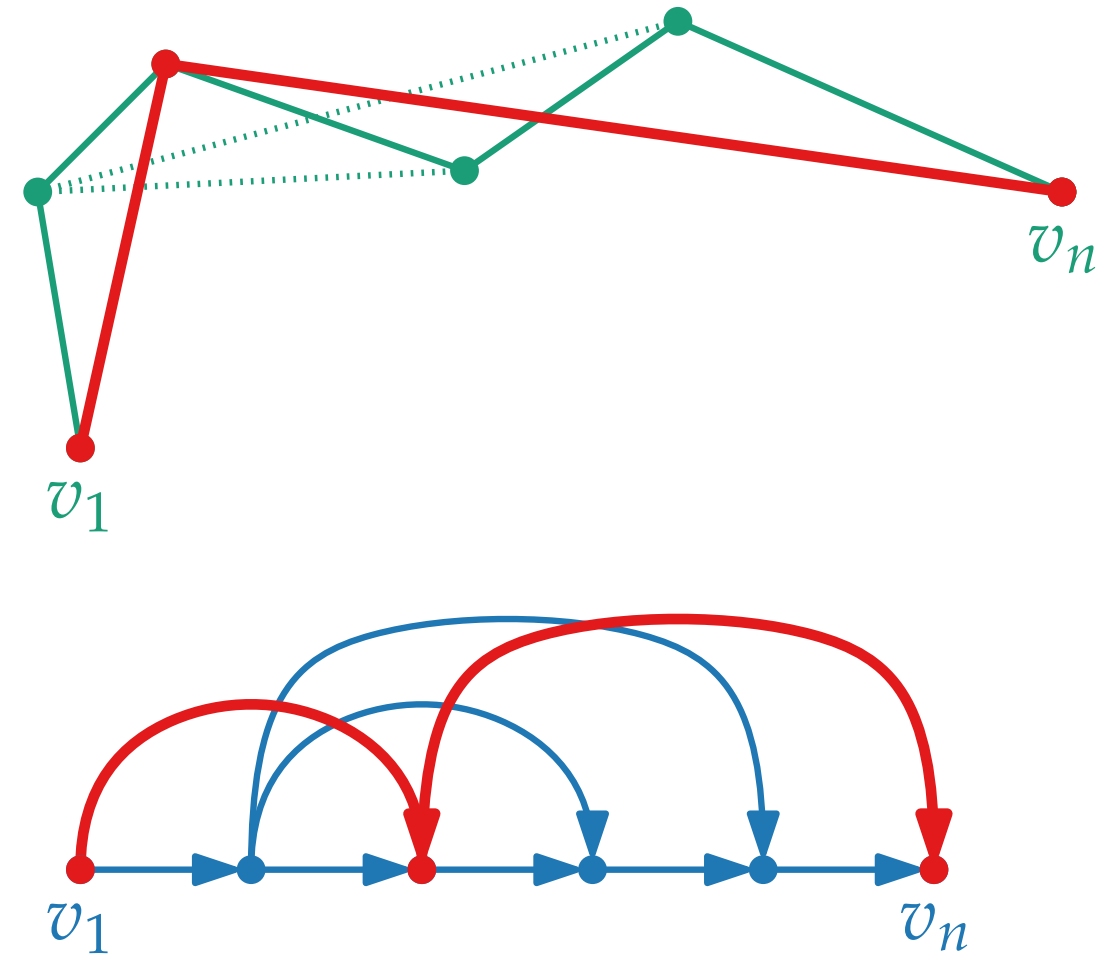
Algorithm by Imai and Iri

- proceeds in two phases
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 - build shortcut graph
- Second phase:
 - find shortest path in shortcut graph
 - return optimal simplification



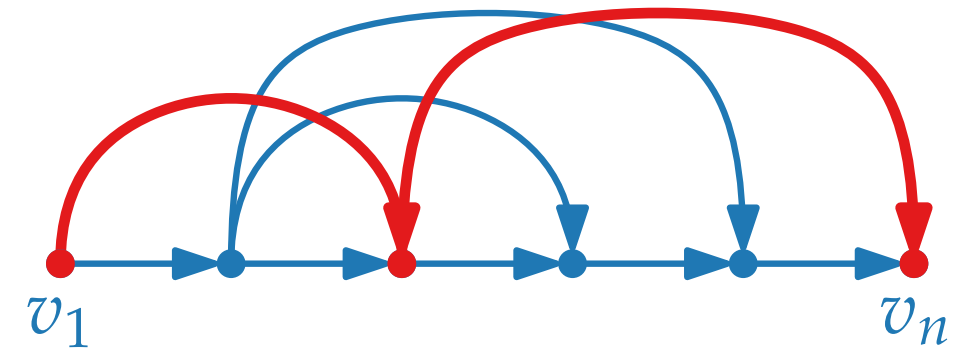
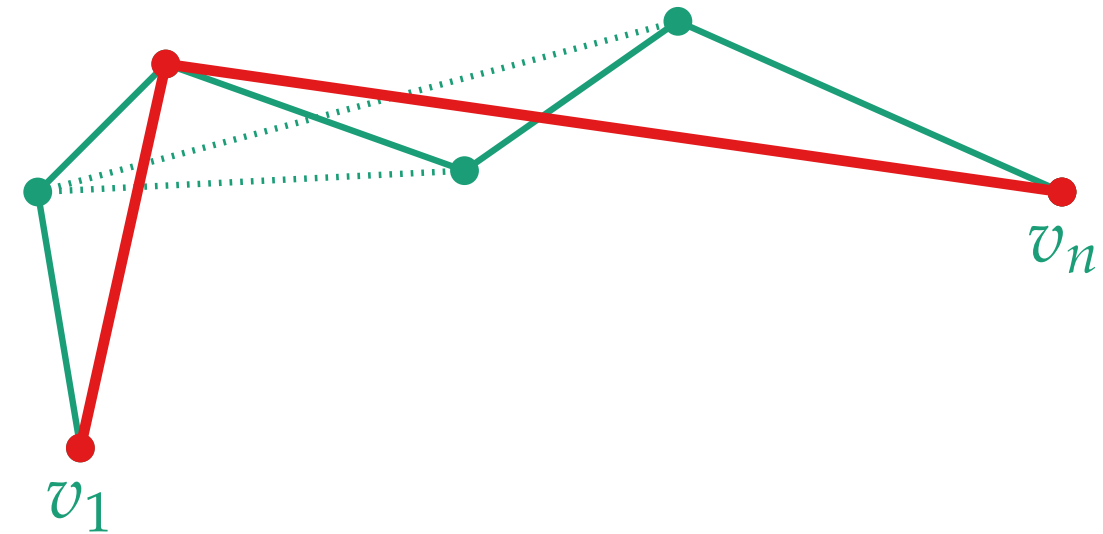
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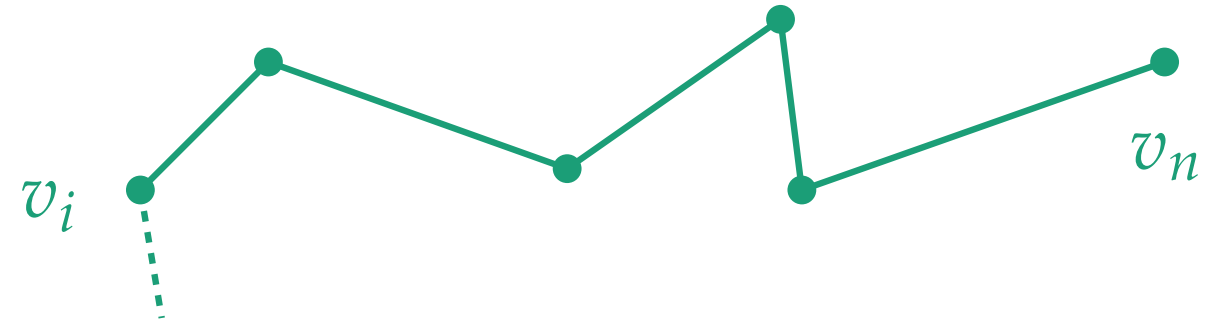


\Rightarrow total running time $O(n^3)$

Algorithm by Melkman & O'Rourke

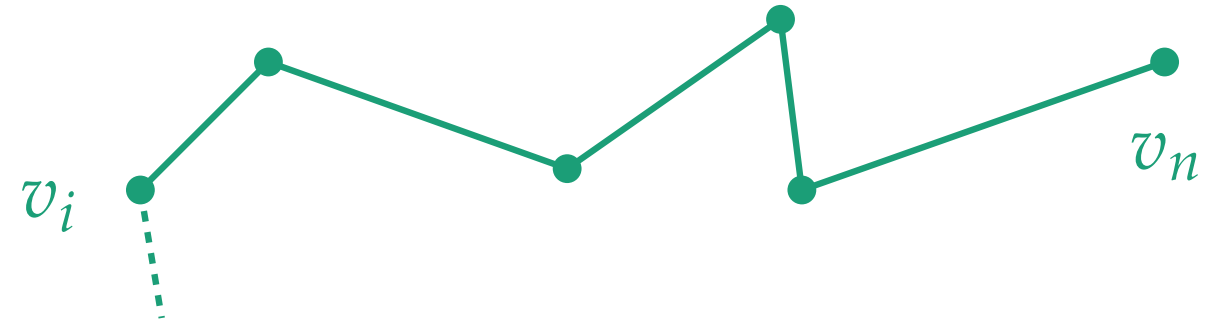
Algorithm by Melkman & O'Rourke

- Starting at each vertex v_i ($i \in \{1, \dots, n\}$),



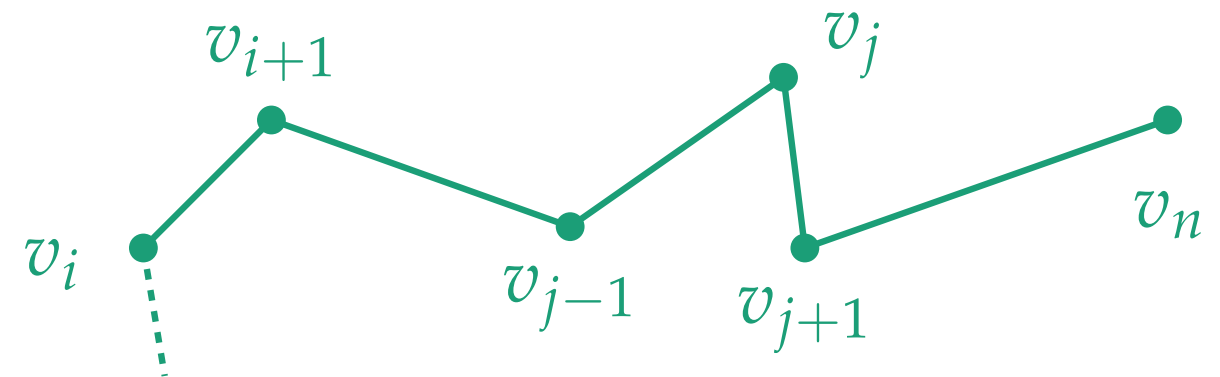
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- Starting at each vertex v_i ($i \in \{1, \dots, n\}$),
 - traverse each subsequent vertex v_j ($j \in \{i + 1, \dots, n\}$)



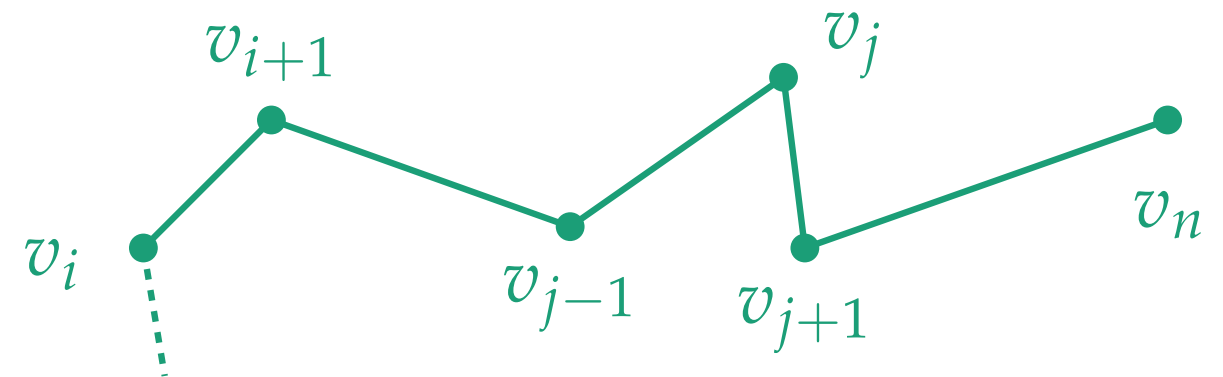
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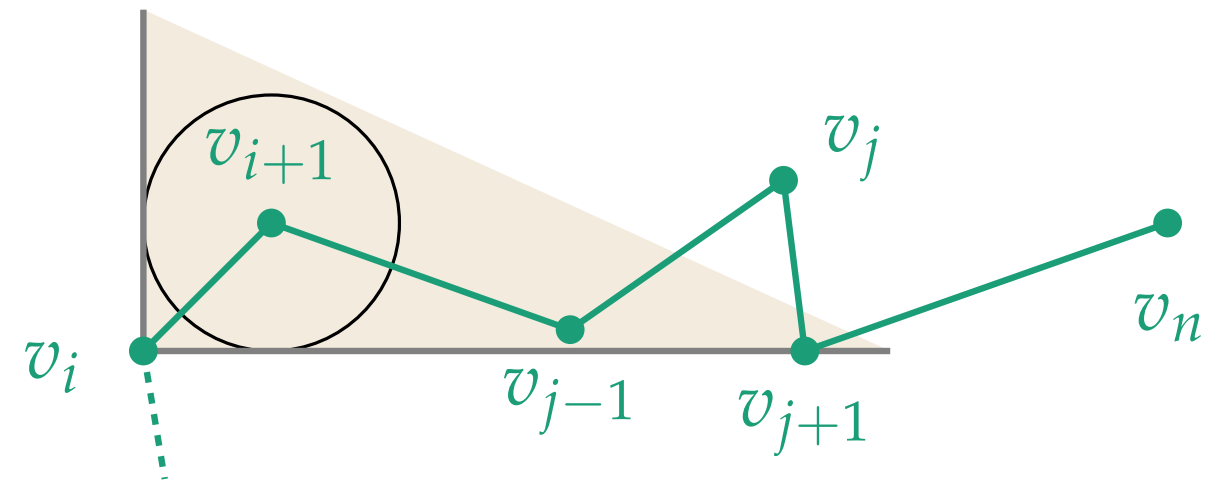
Algorithm by Melkman & O'Rourke

- Starting at each vertex v_i ($i \in \{1, \dots, n\}$),
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 - while maintaining a *cone*



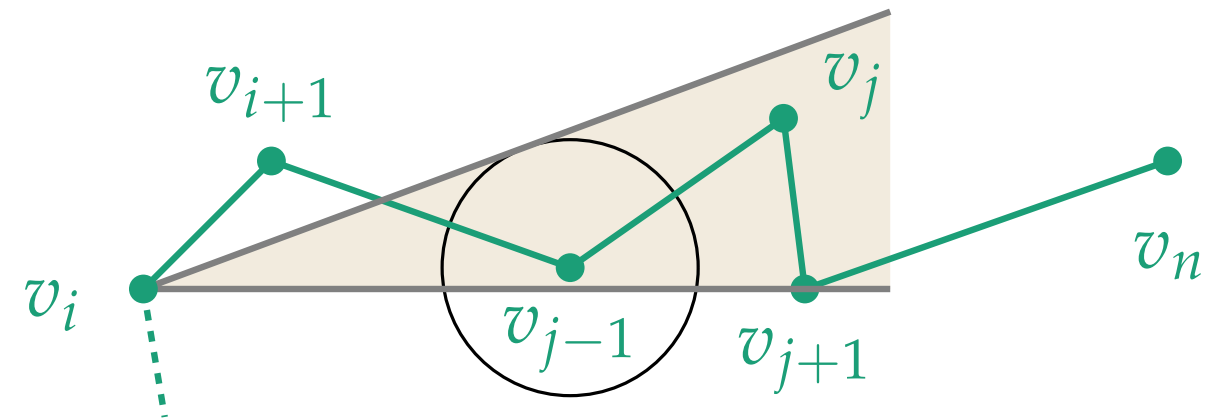
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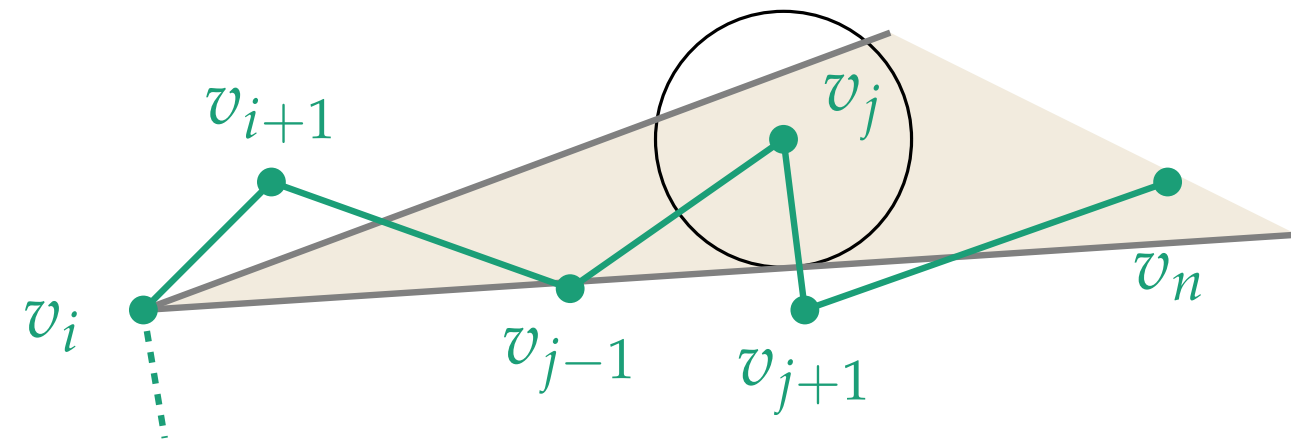
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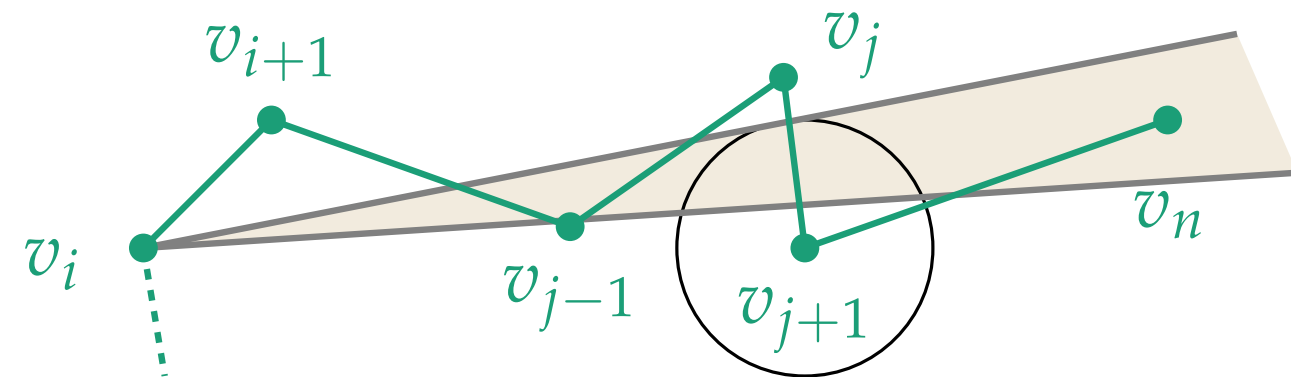
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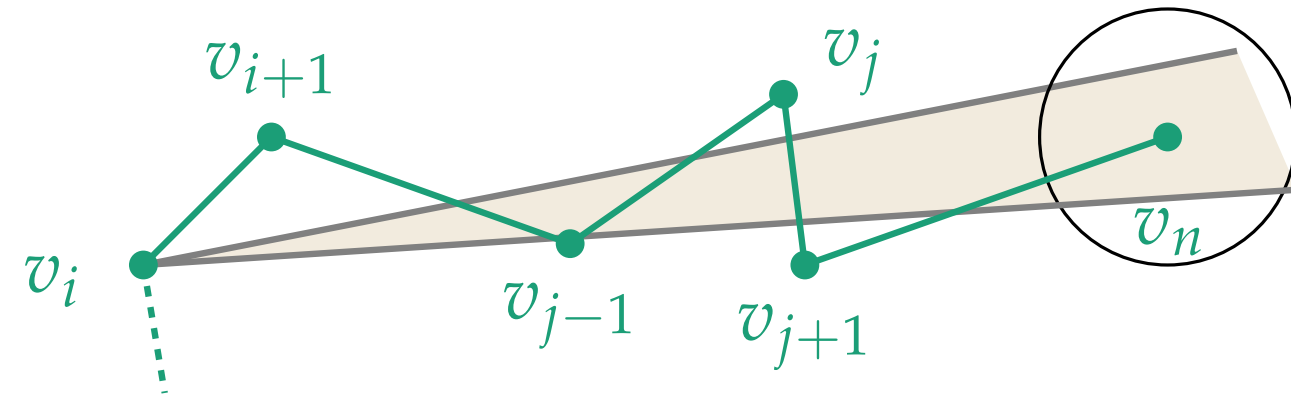
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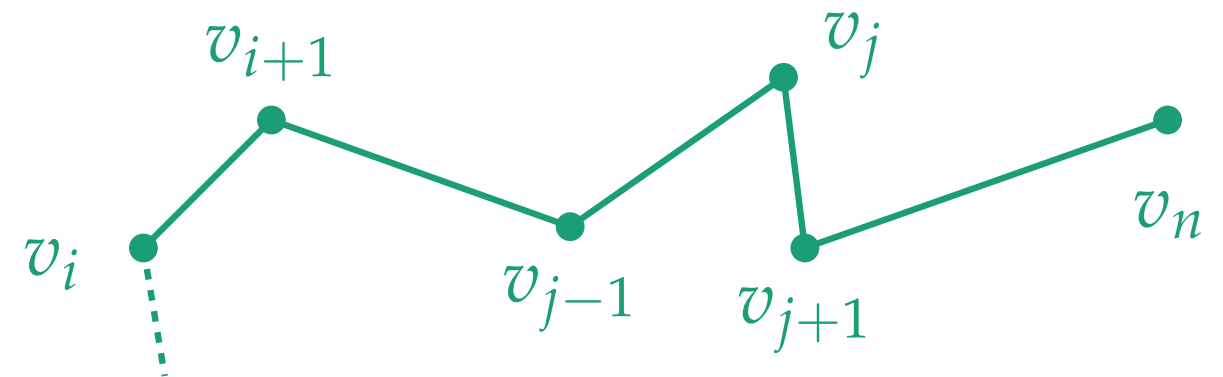
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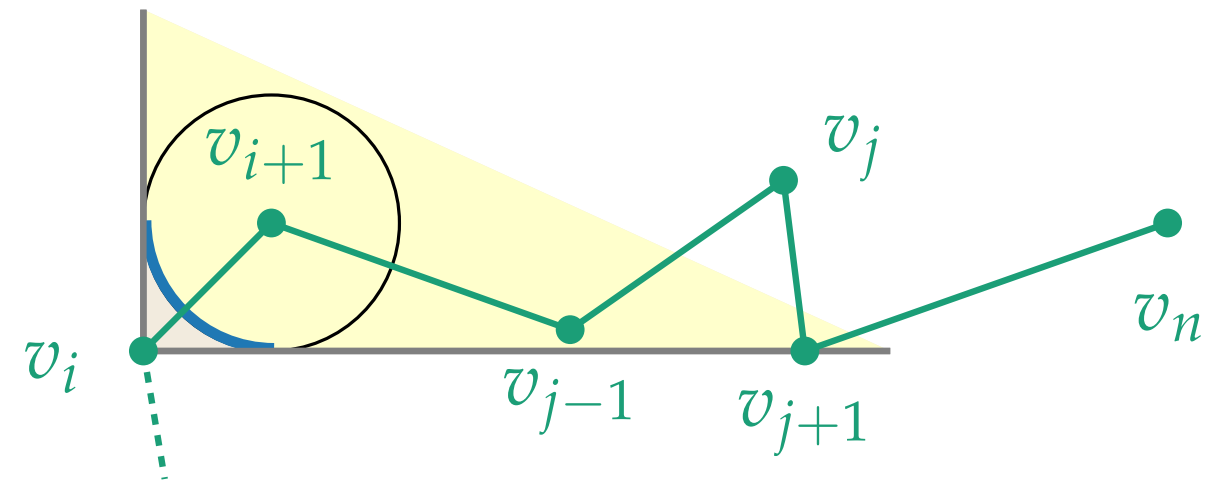
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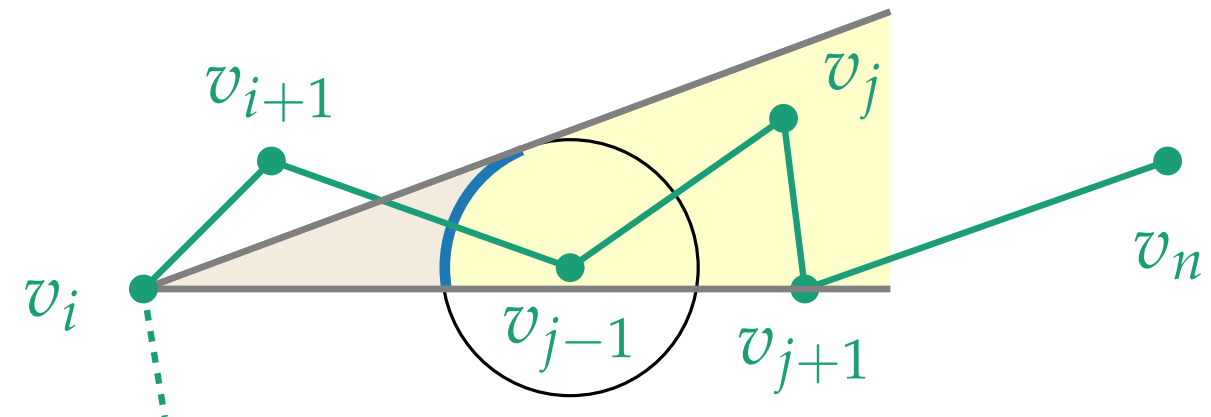
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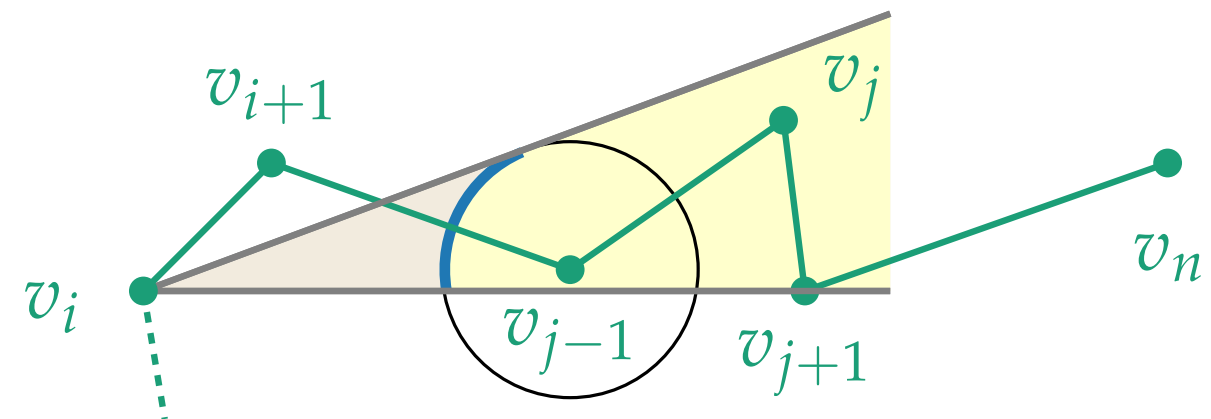
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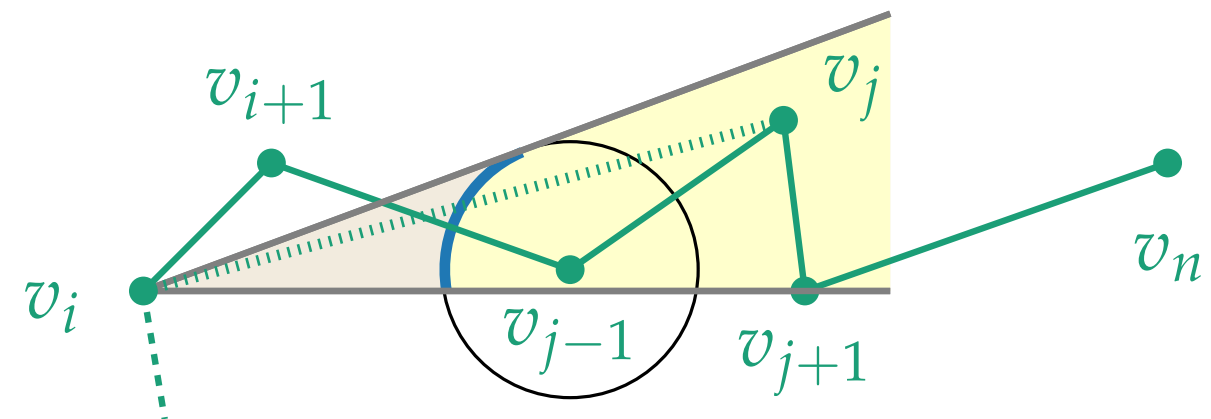
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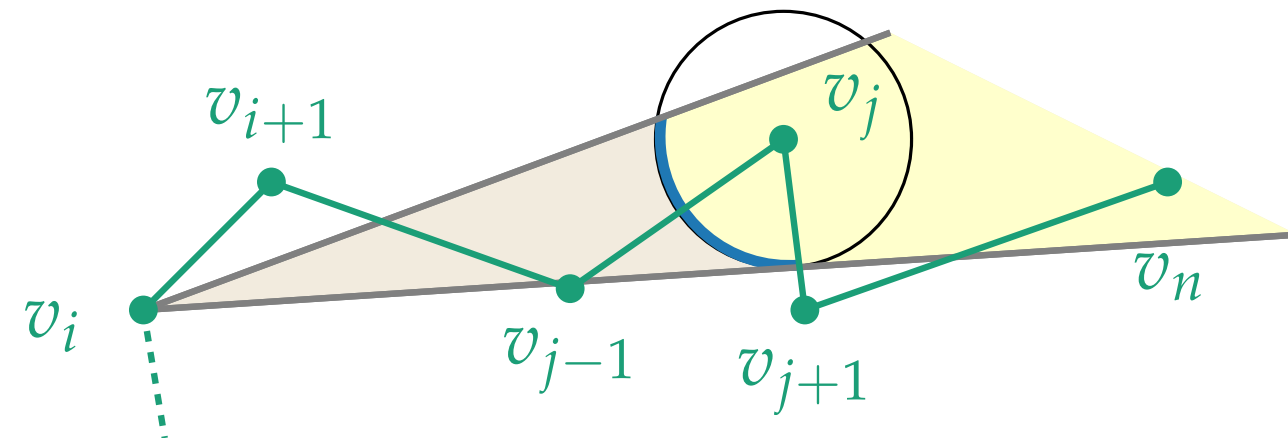
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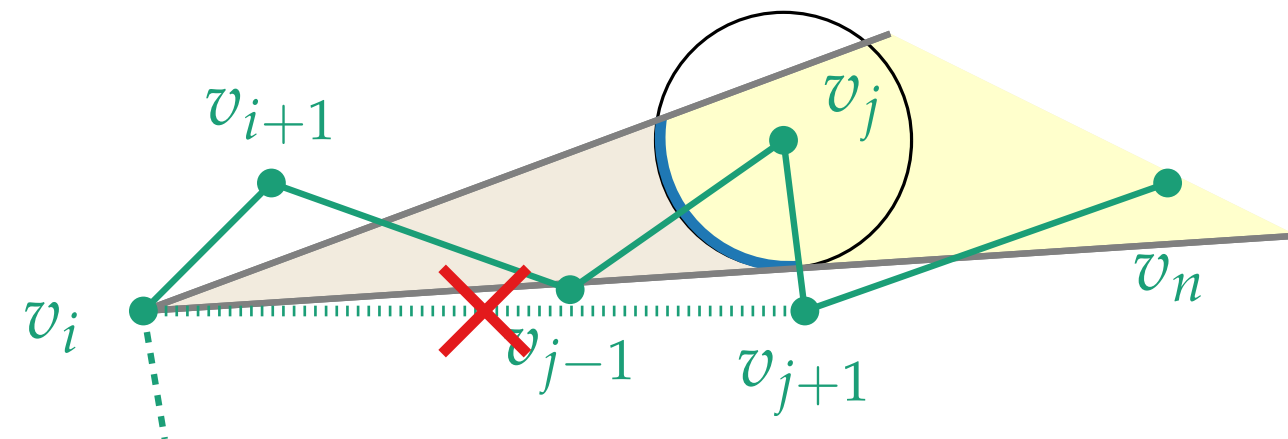
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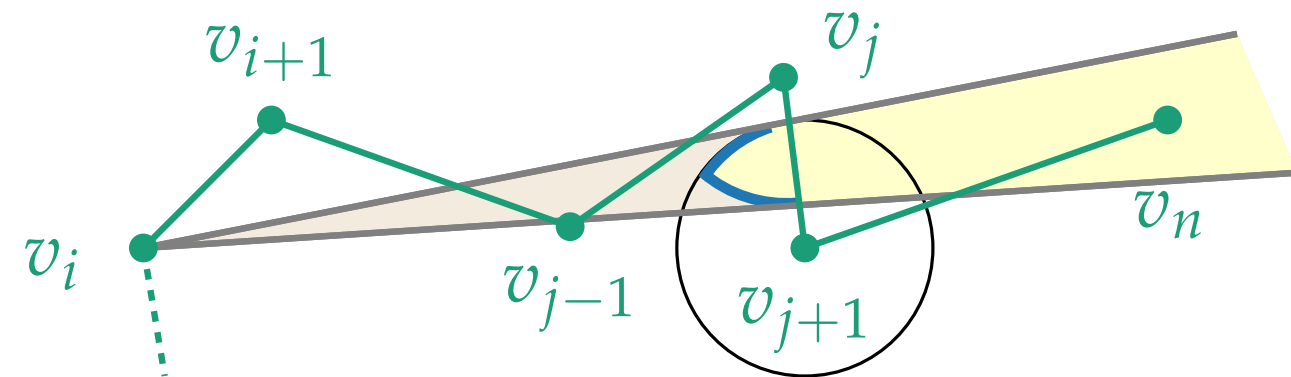
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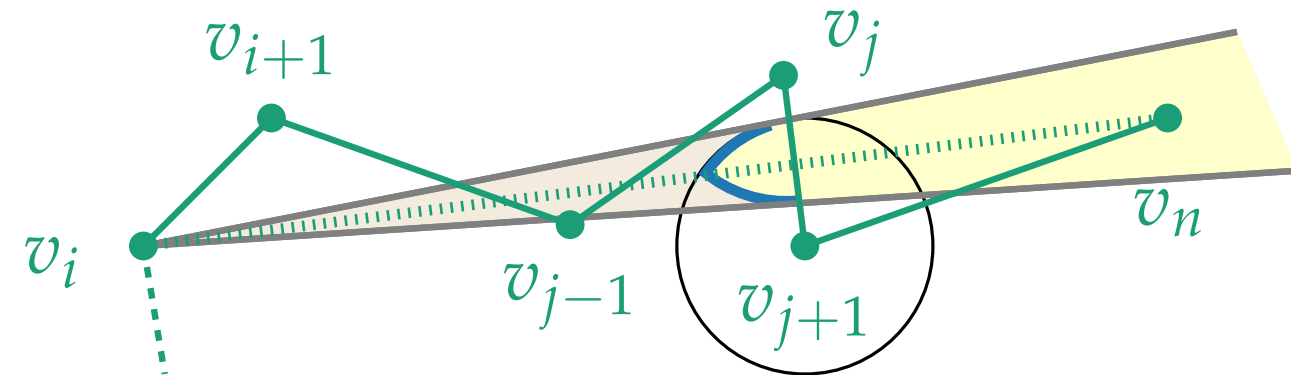
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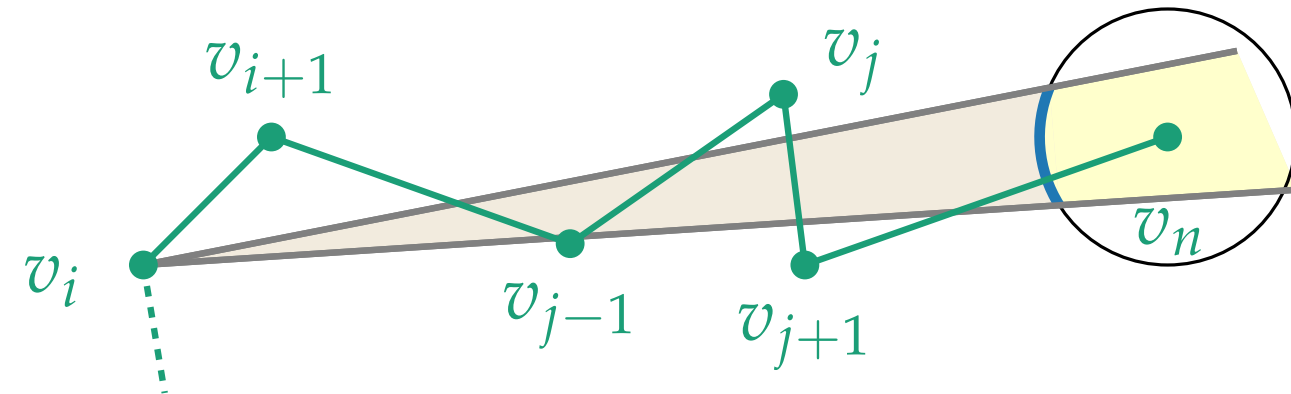
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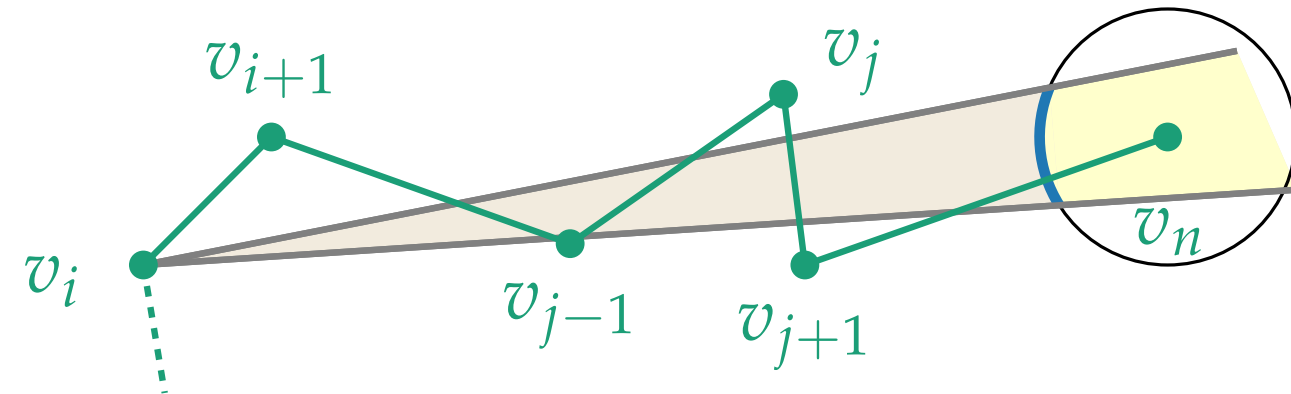
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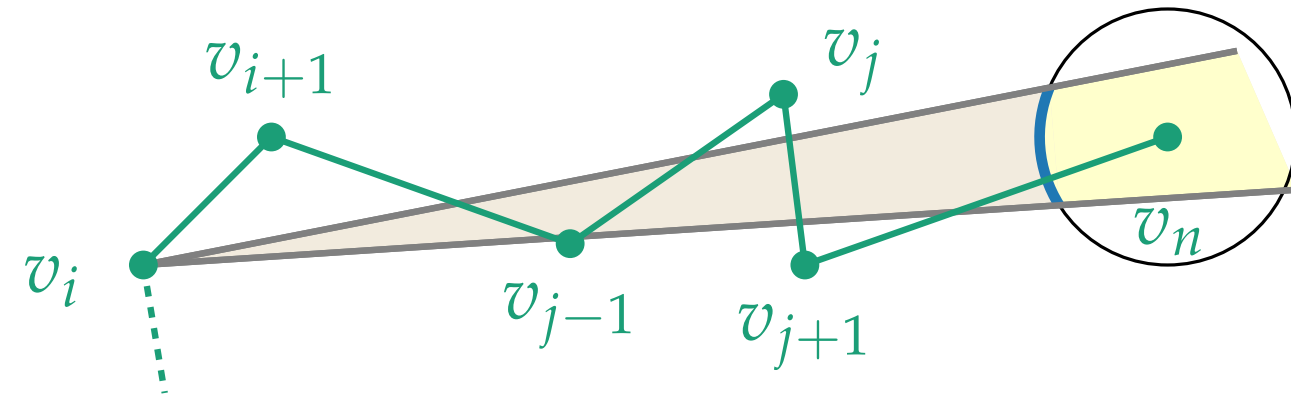
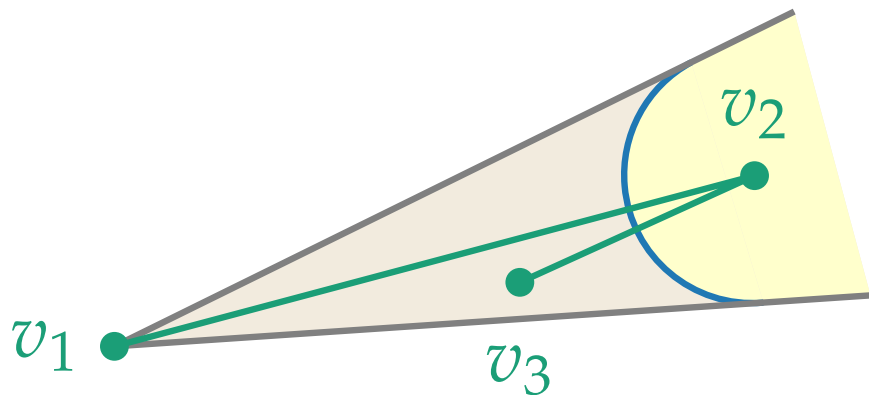
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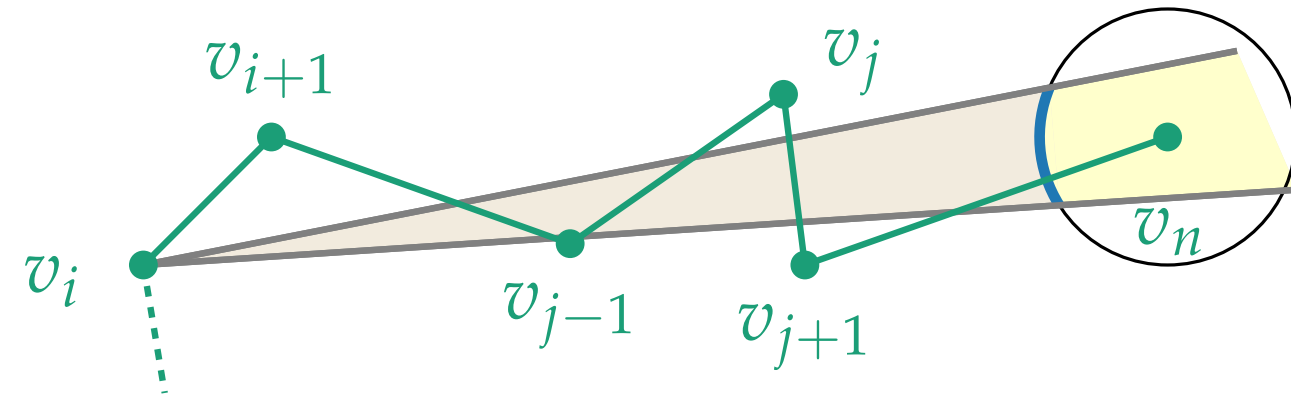
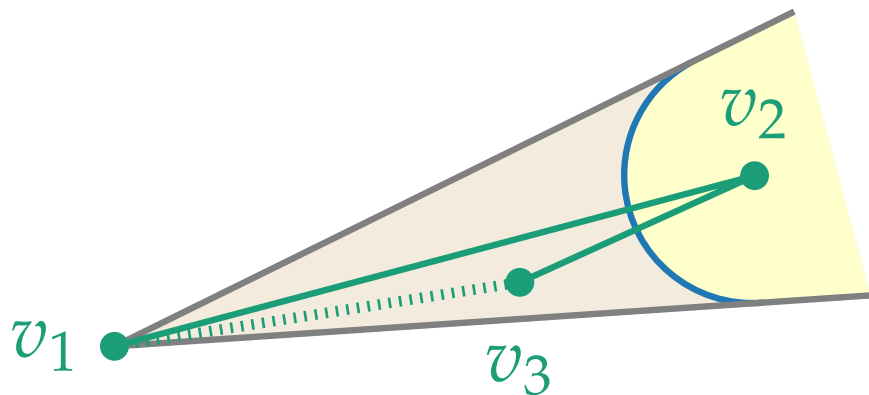
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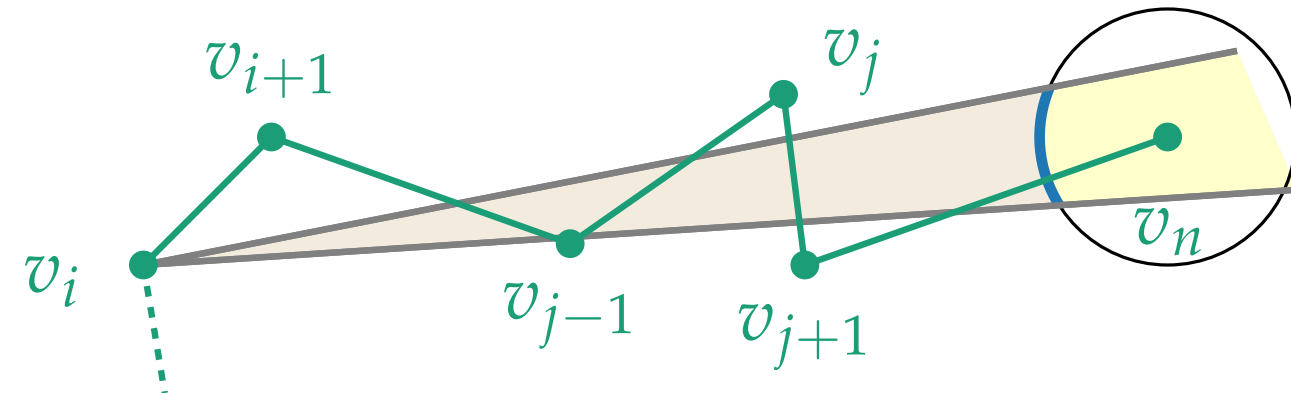
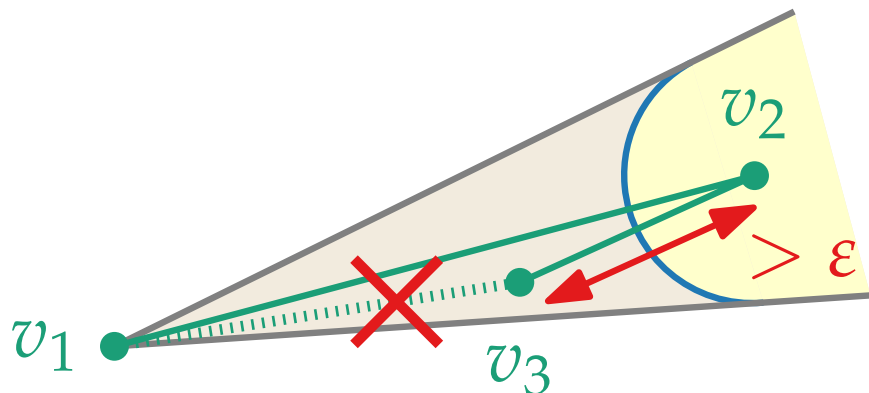
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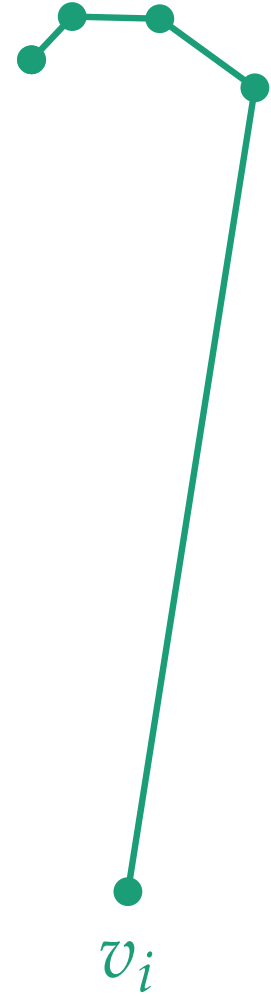
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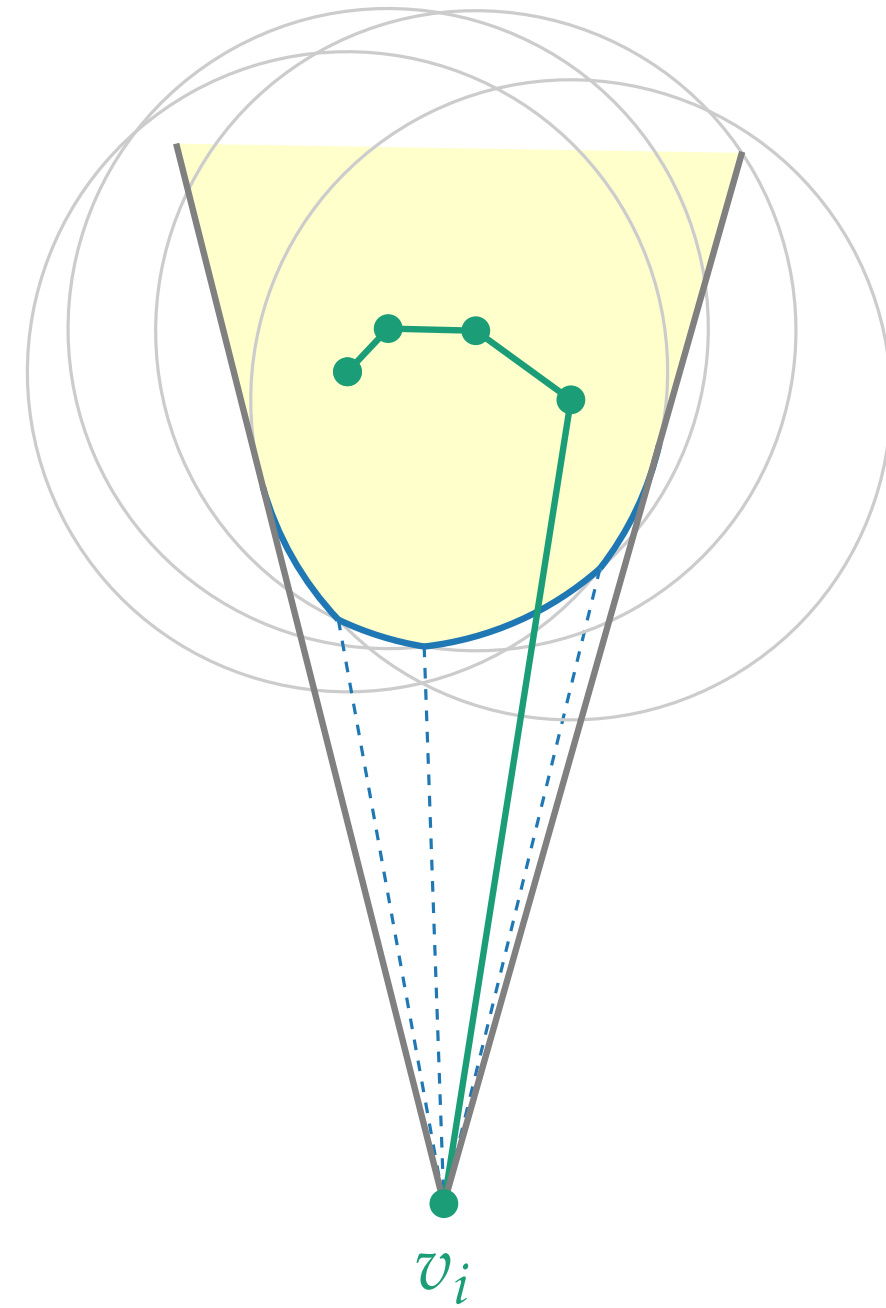


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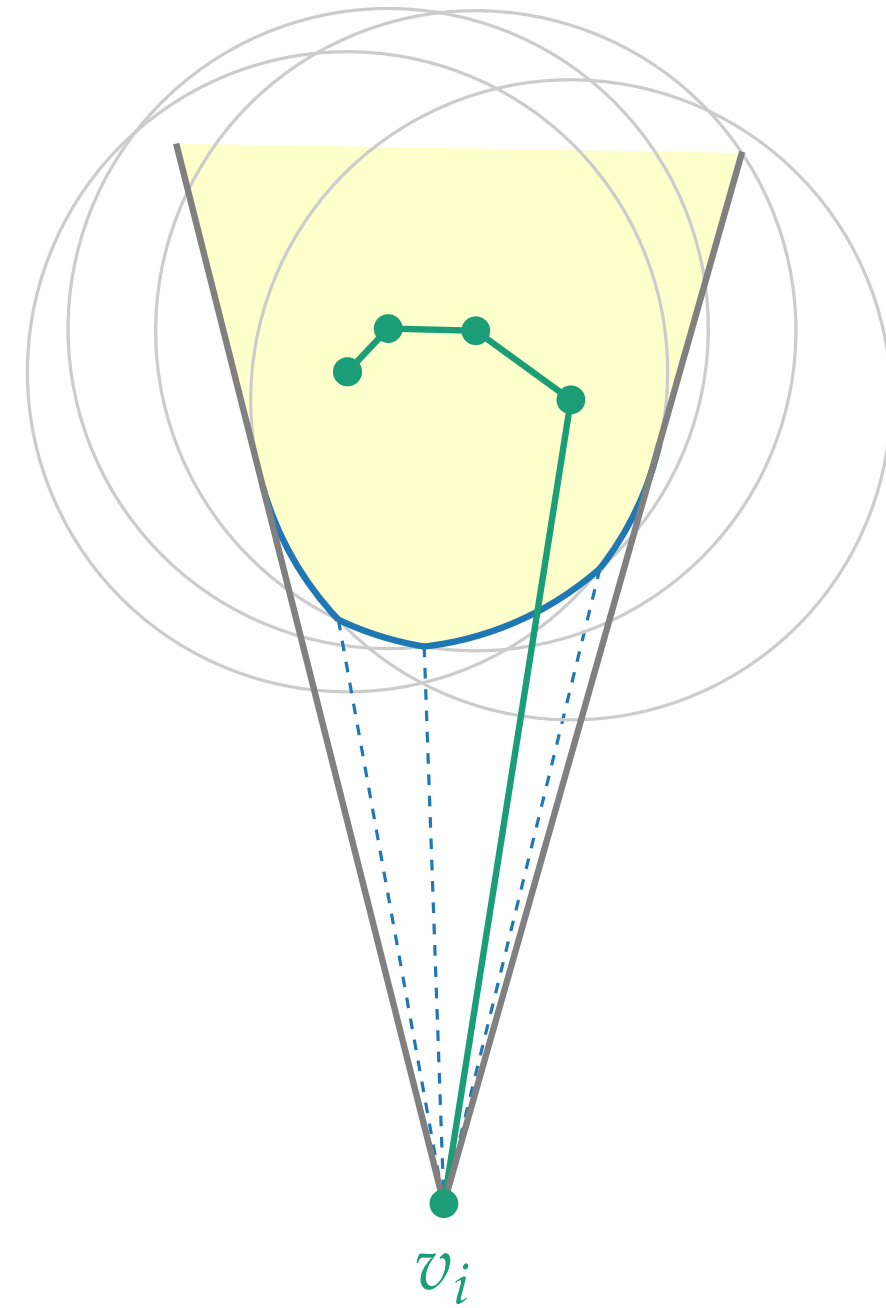
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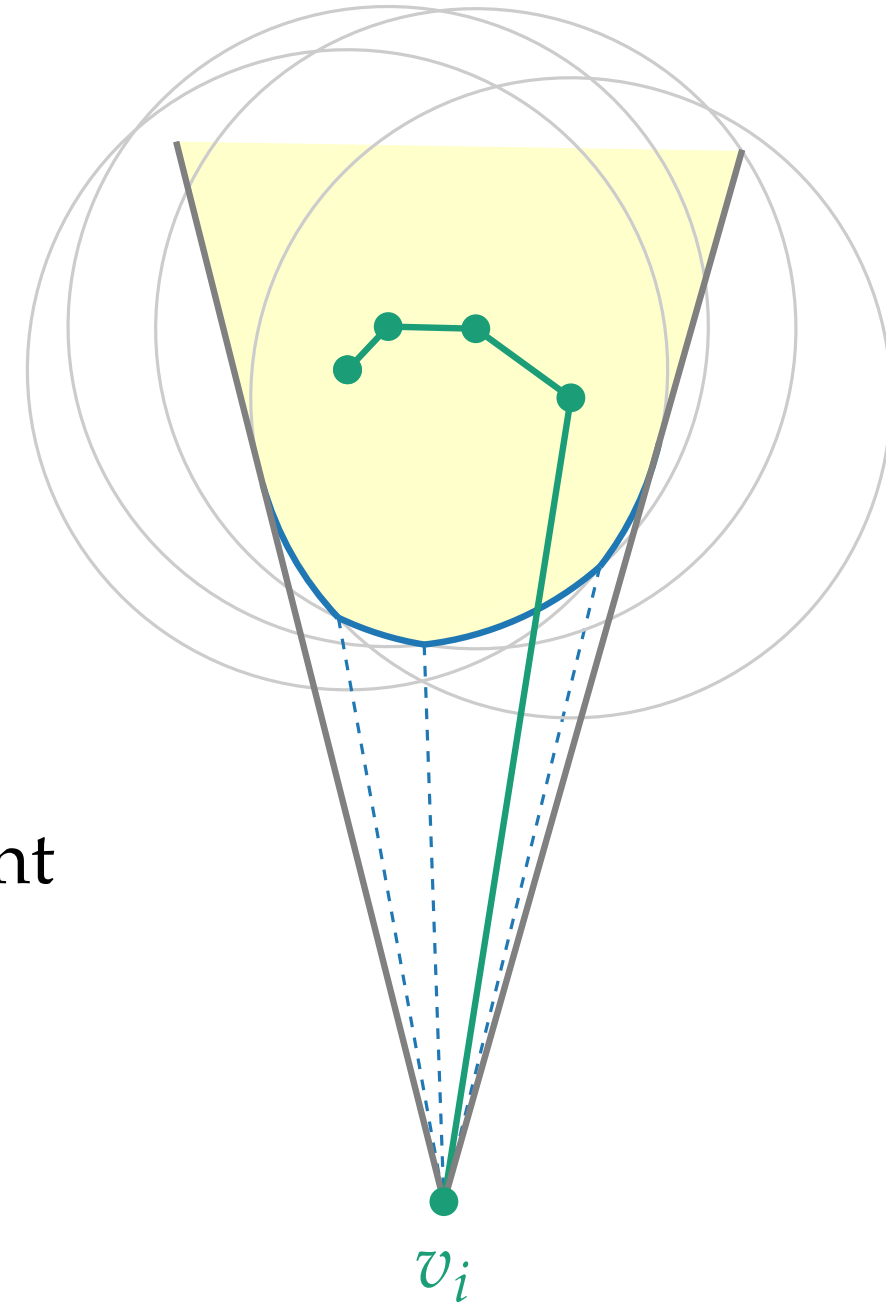
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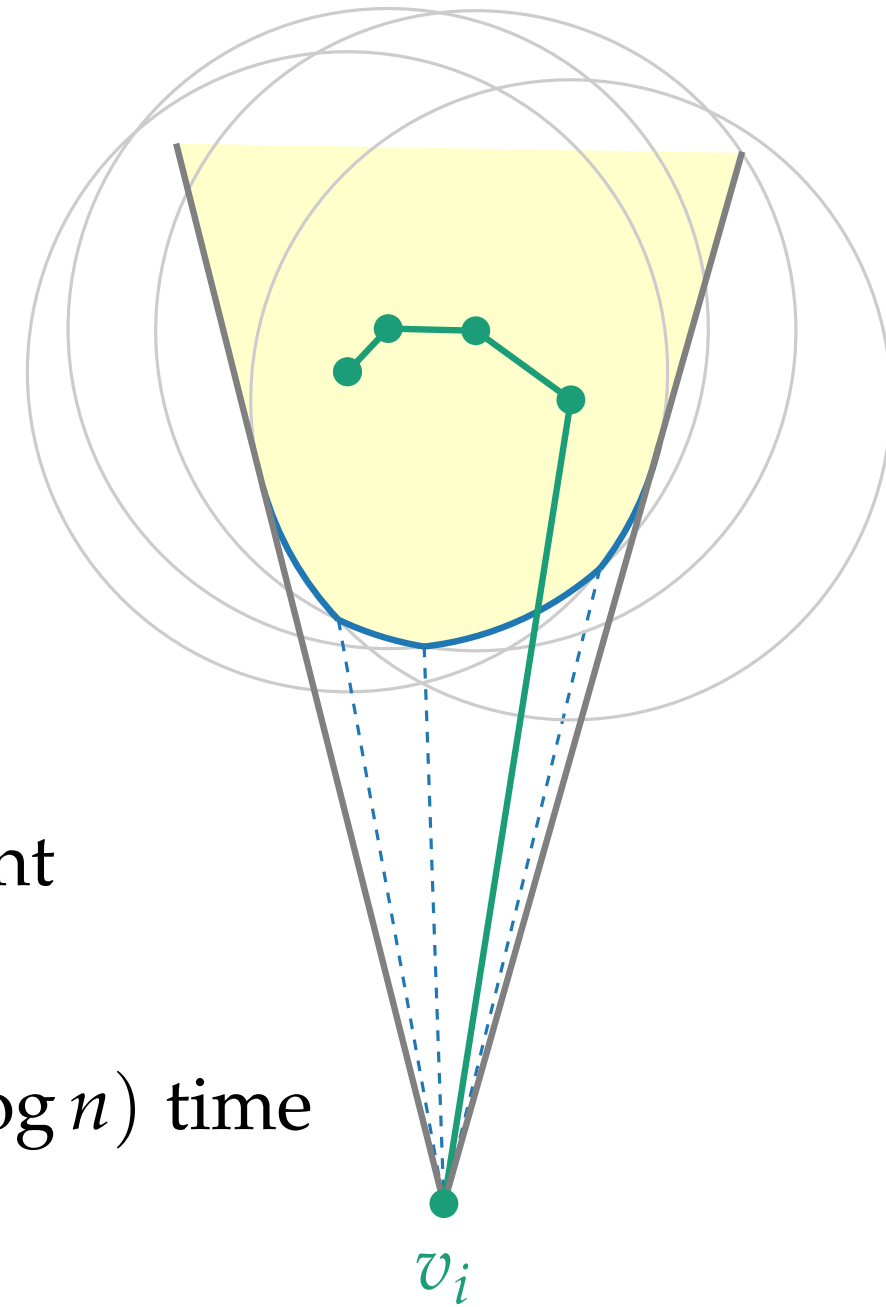
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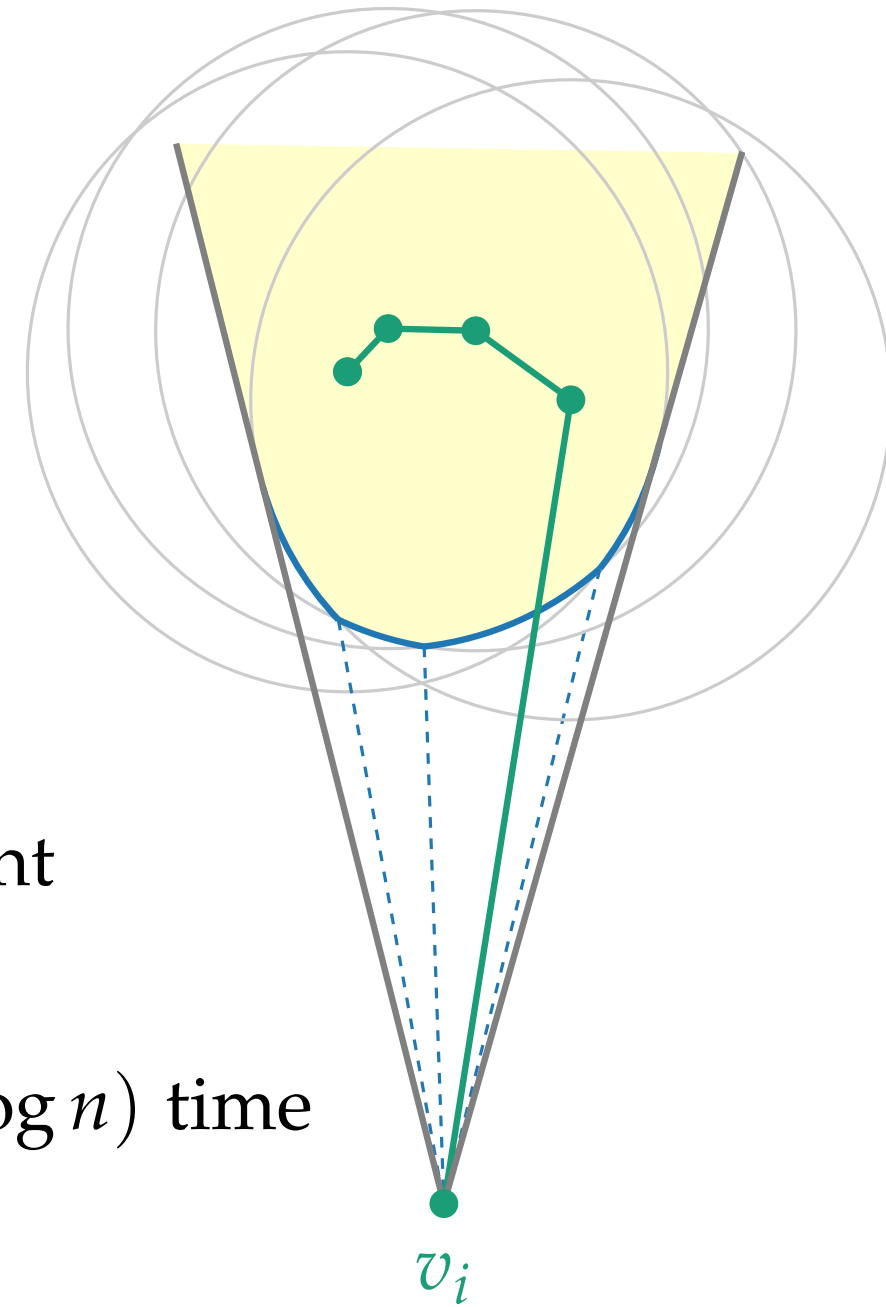
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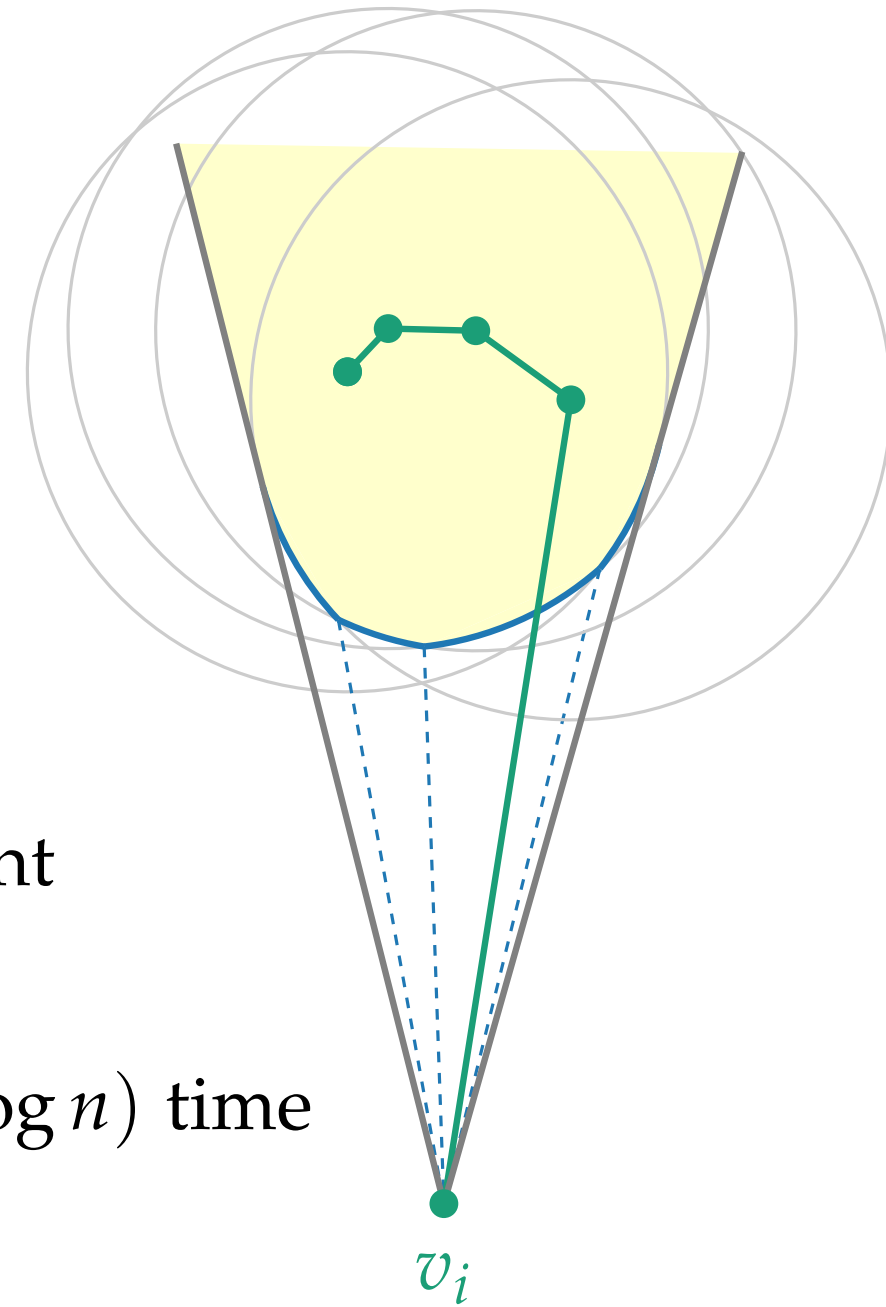
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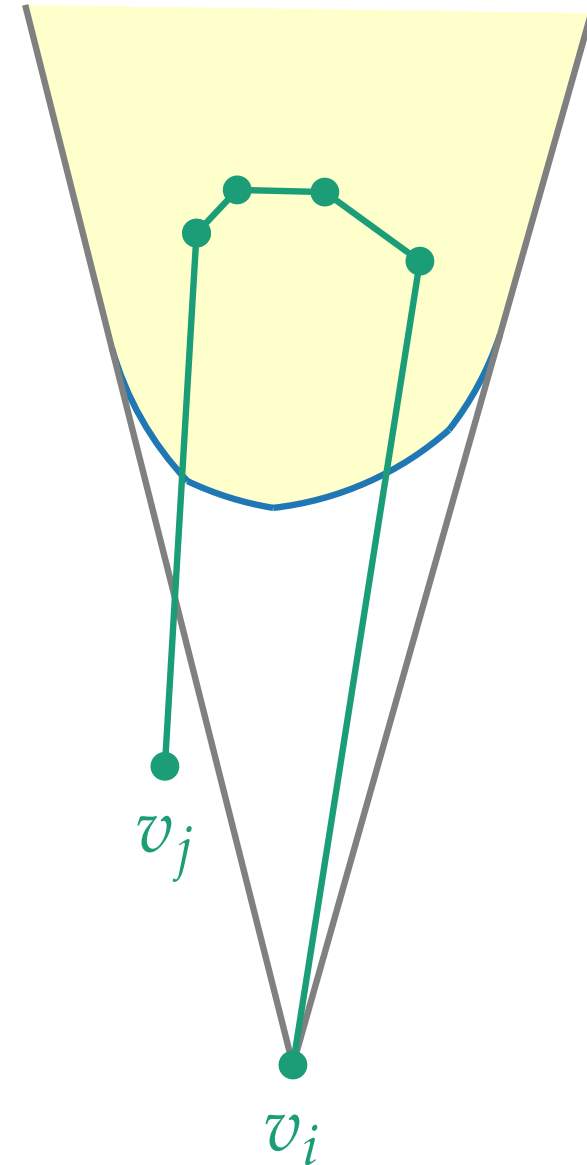
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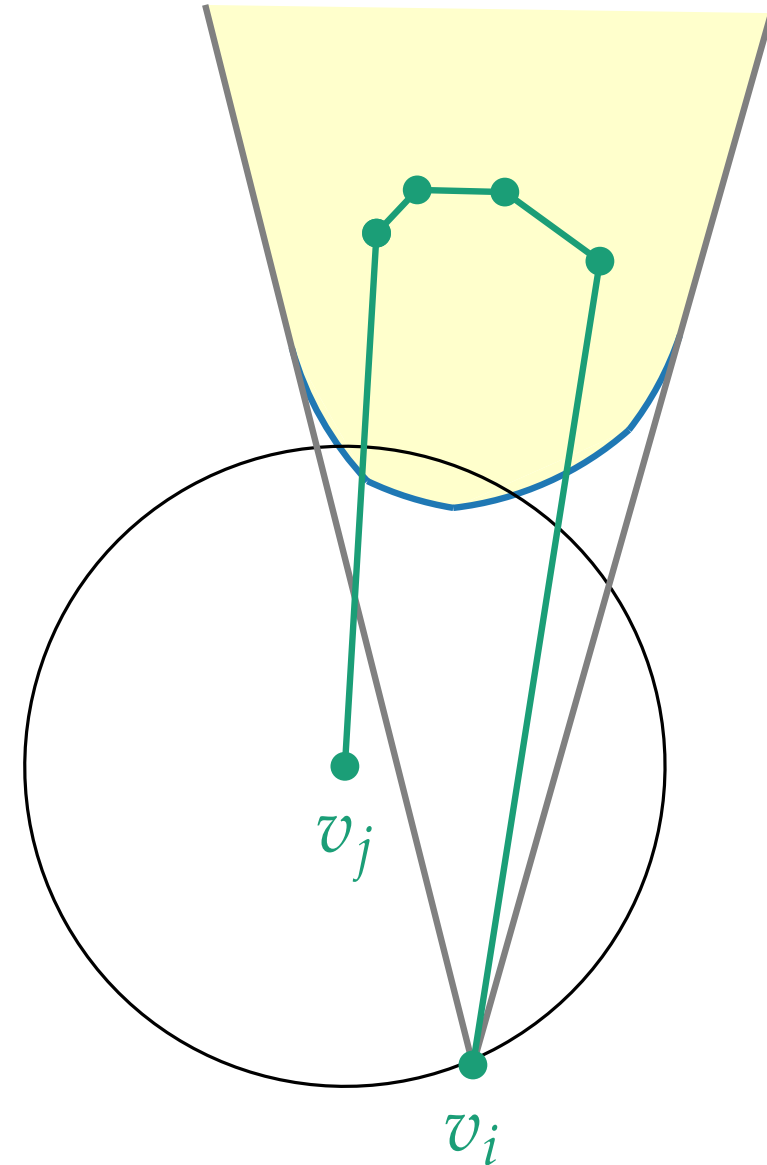
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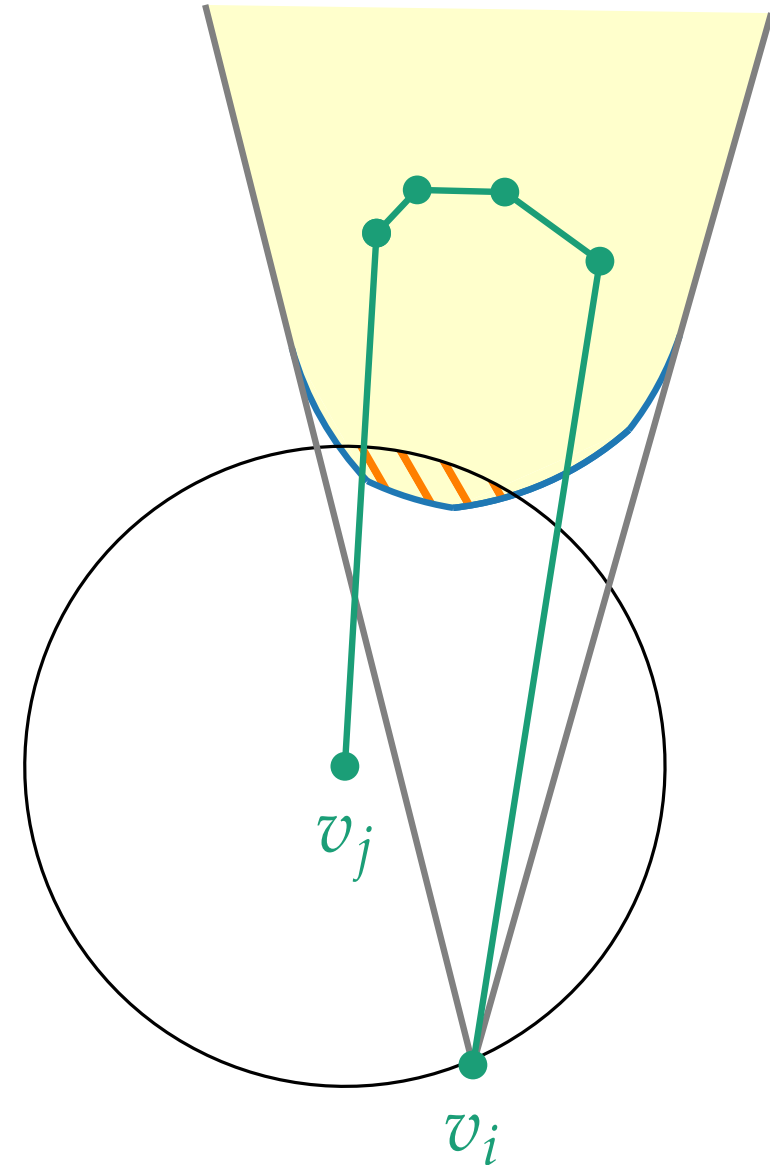
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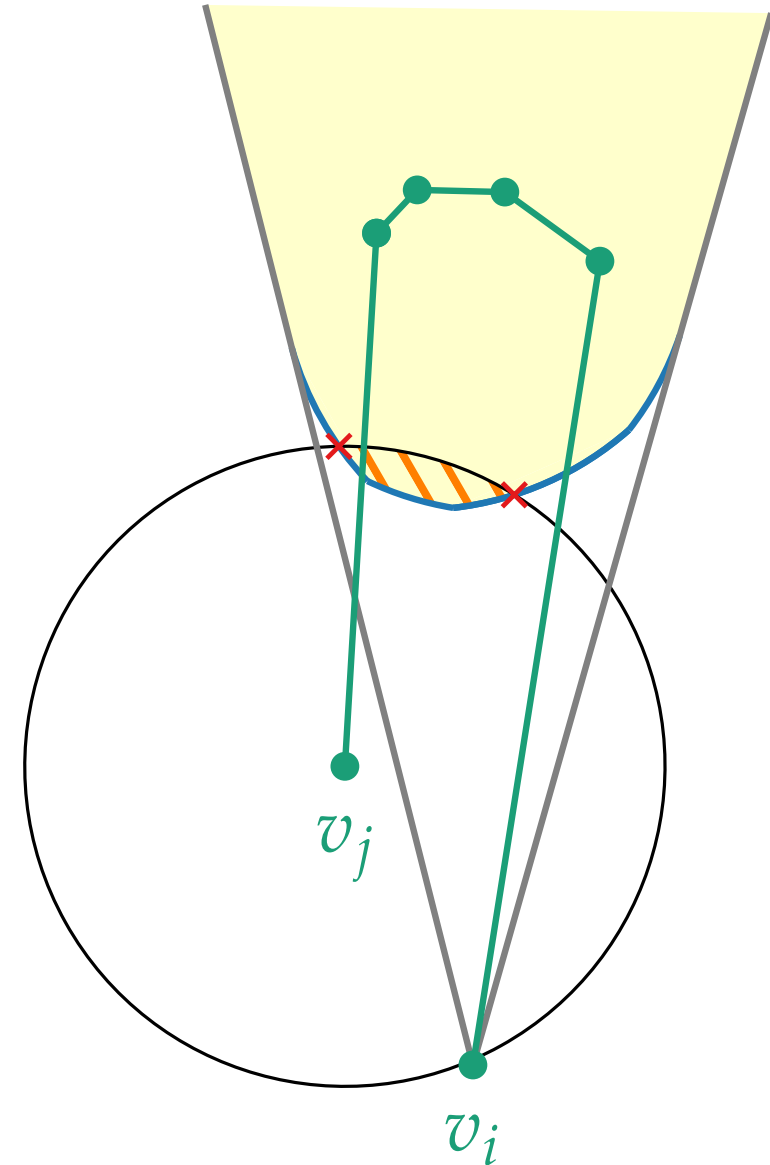


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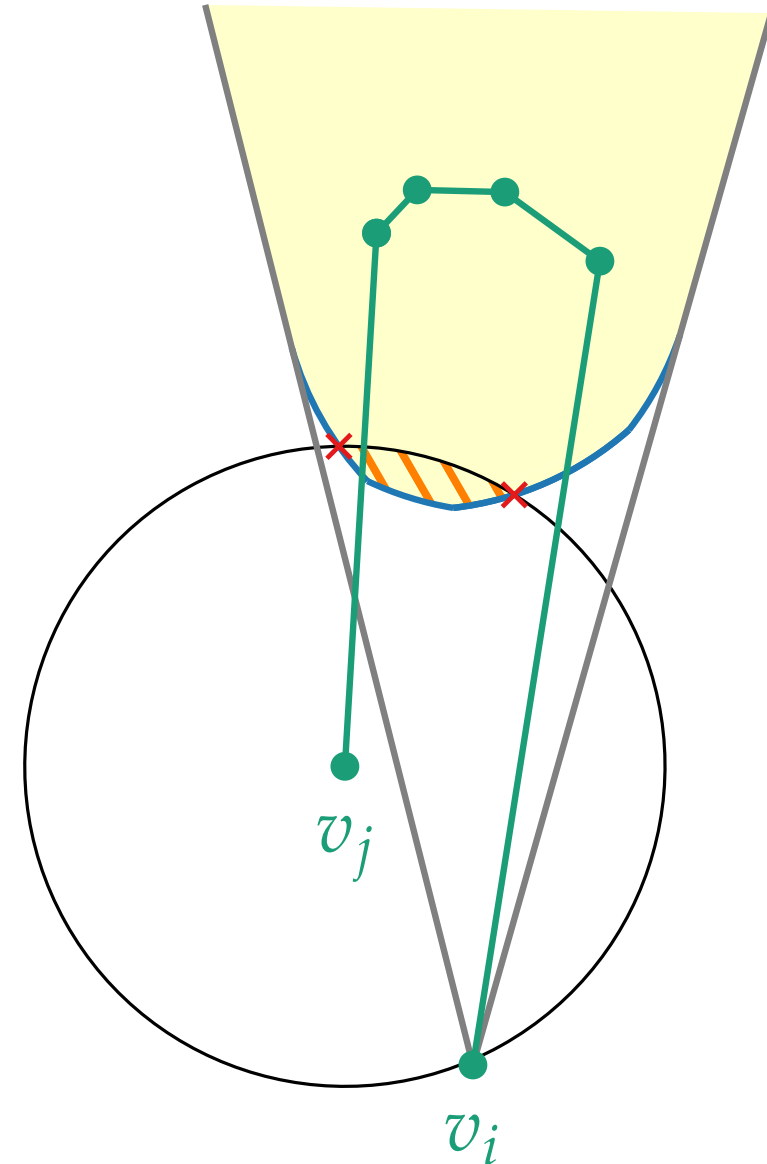
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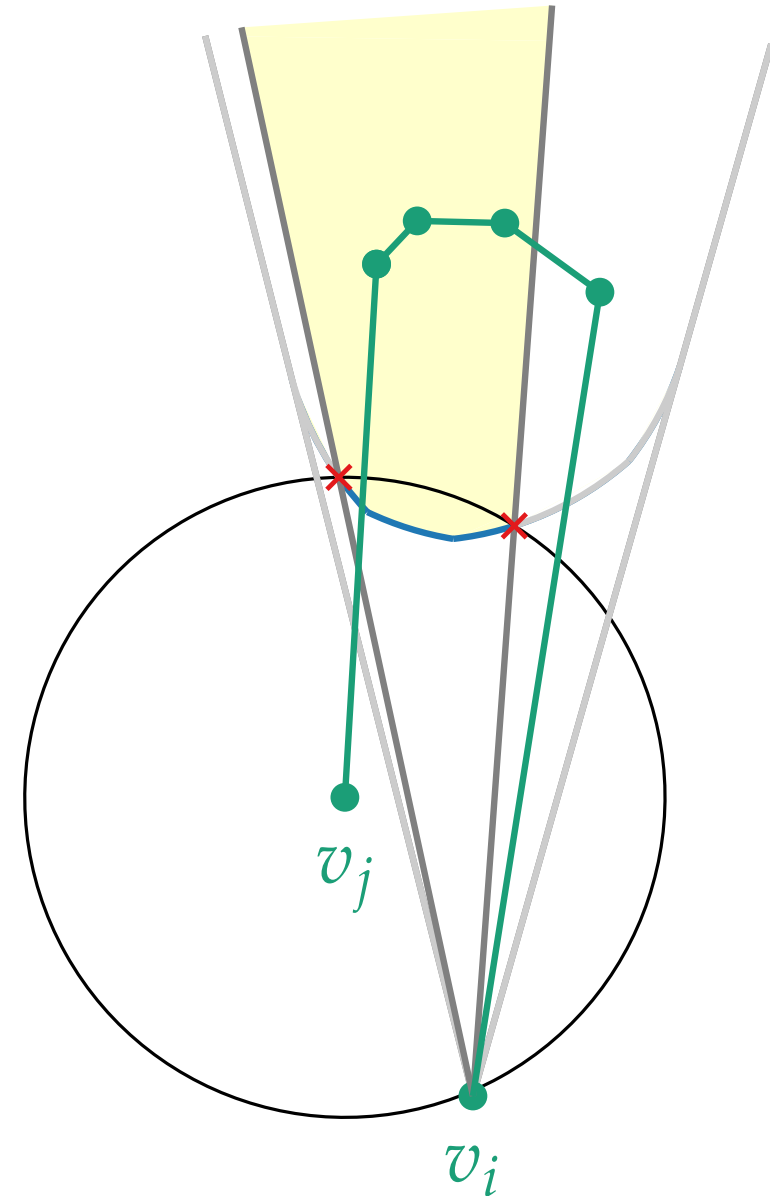
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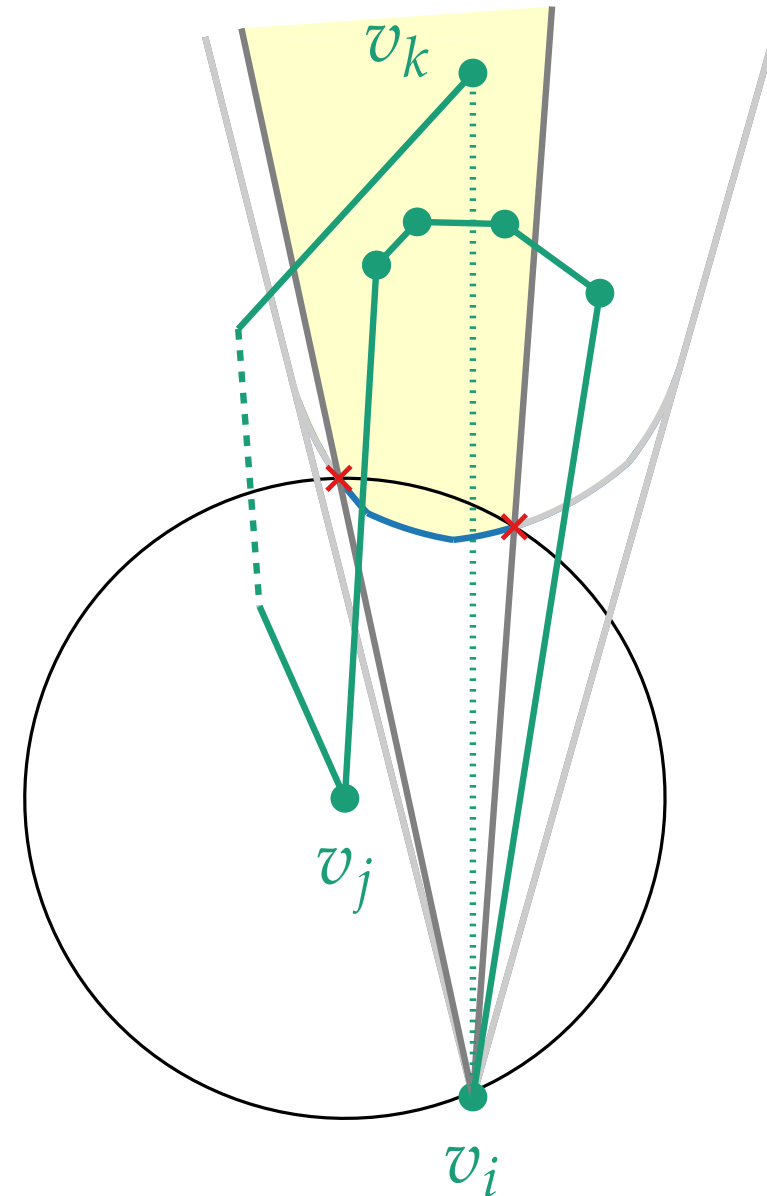
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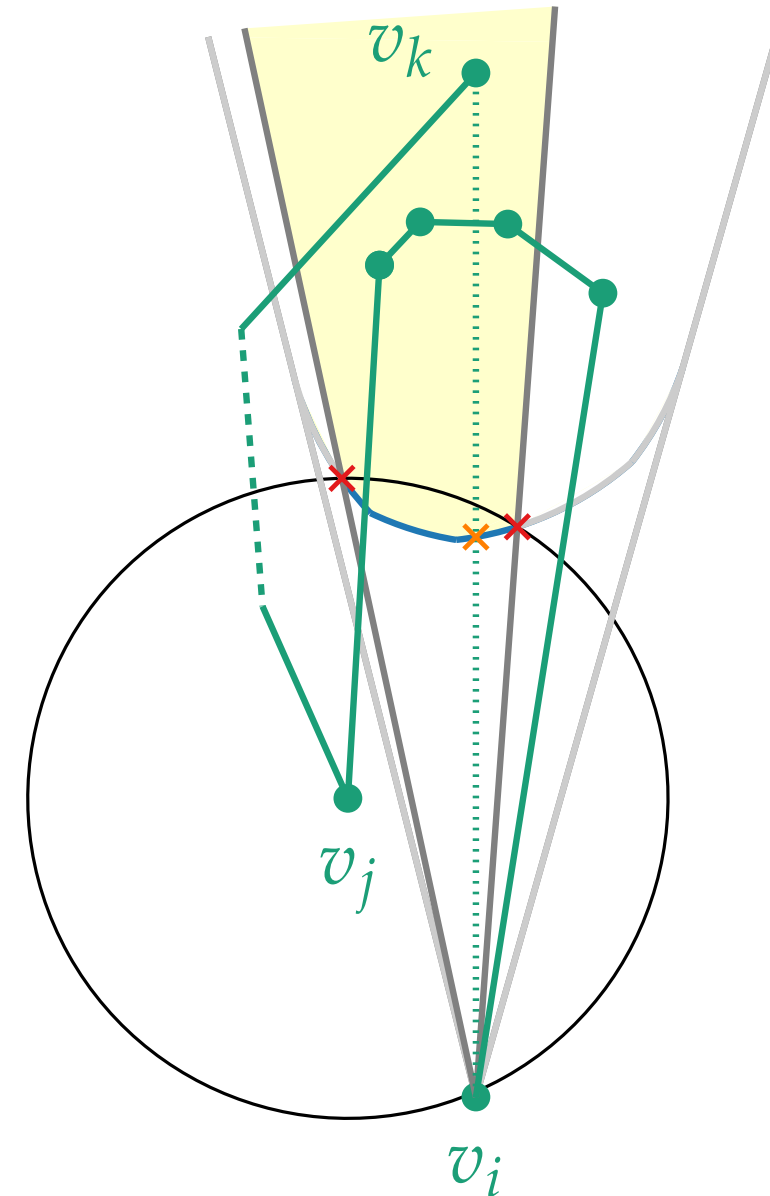
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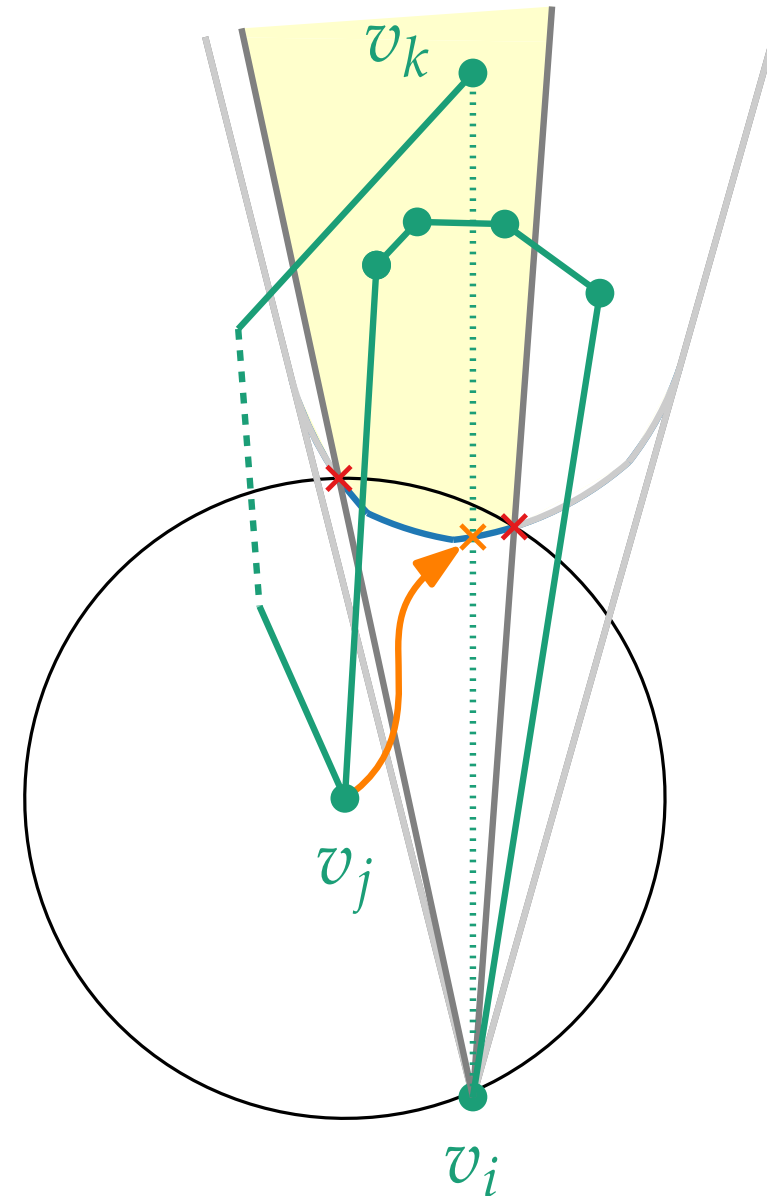
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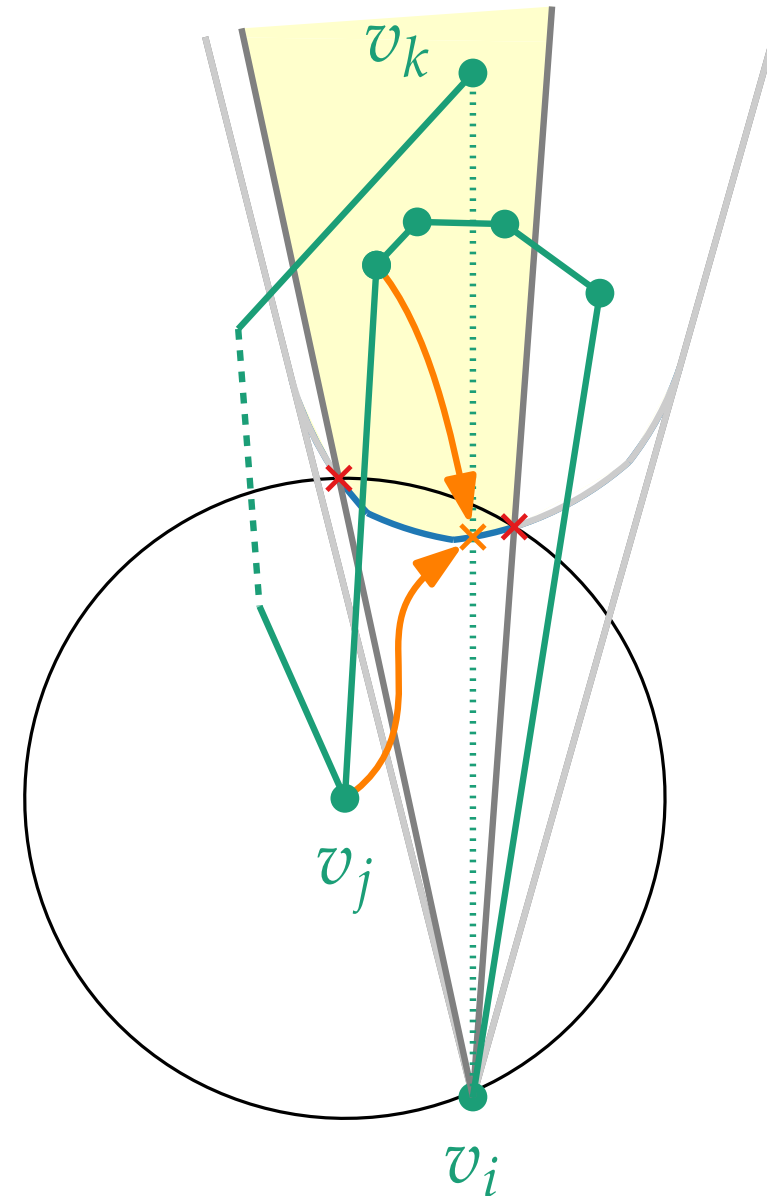


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Corollary: Polyline simplification under the local Fréchet distance can be done in $O(n^2 \log n)$ time in the L_p norm where $p \in [1, \infty]$.

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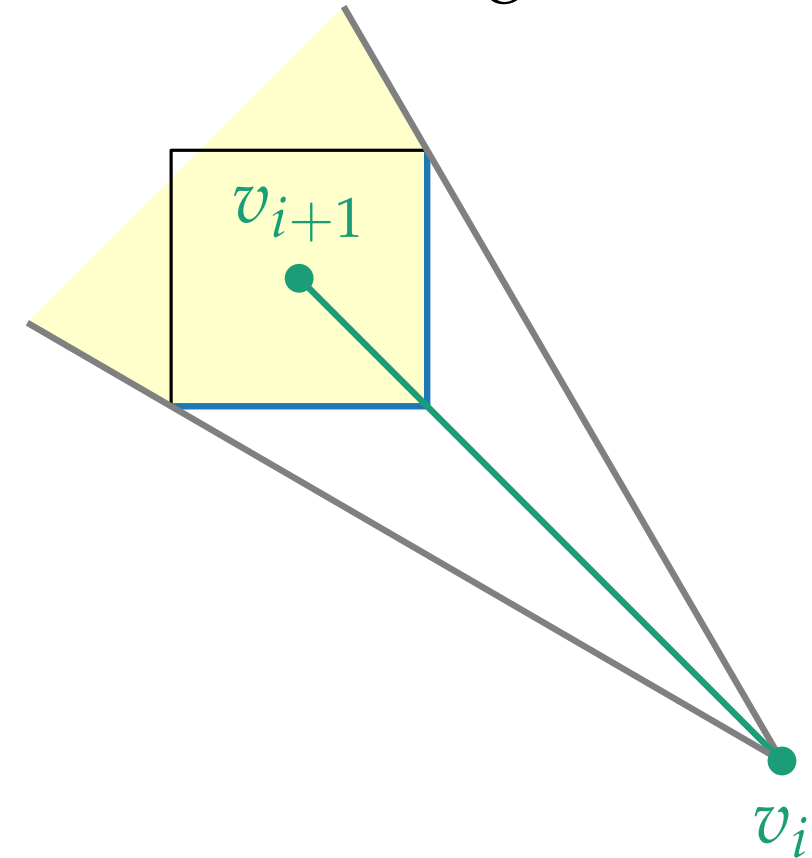
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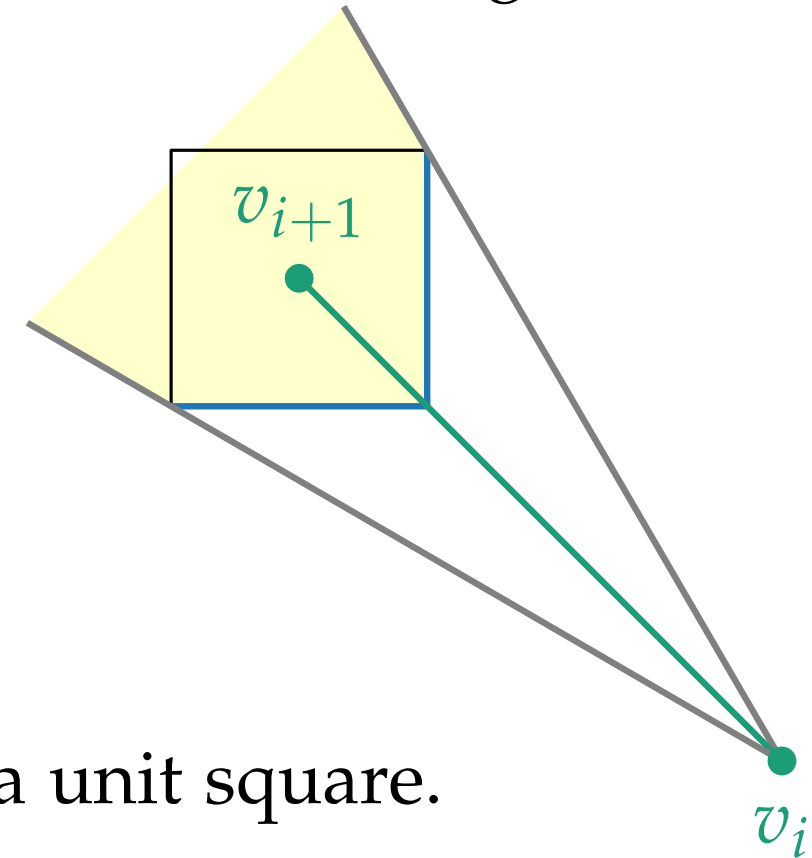
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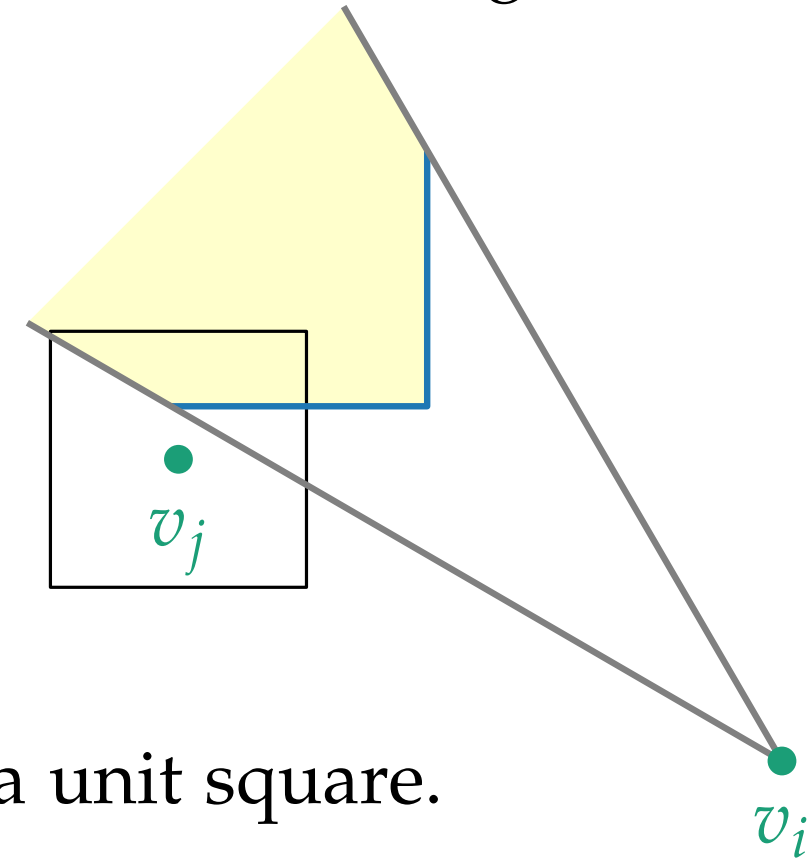
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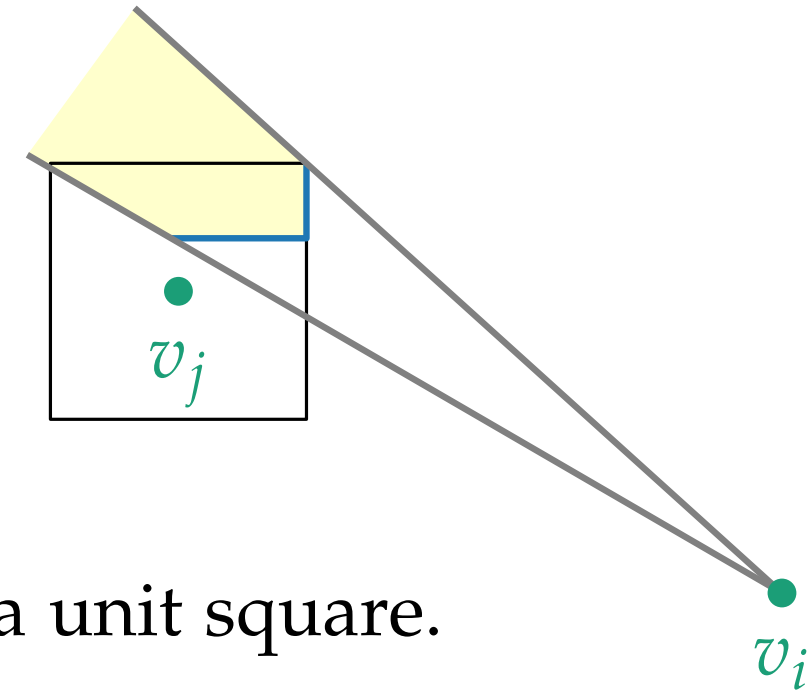
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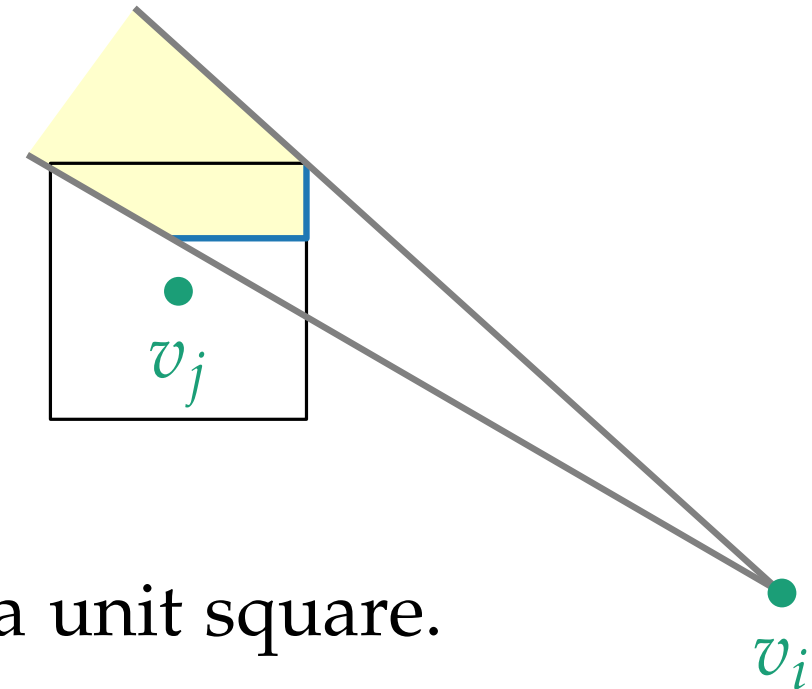
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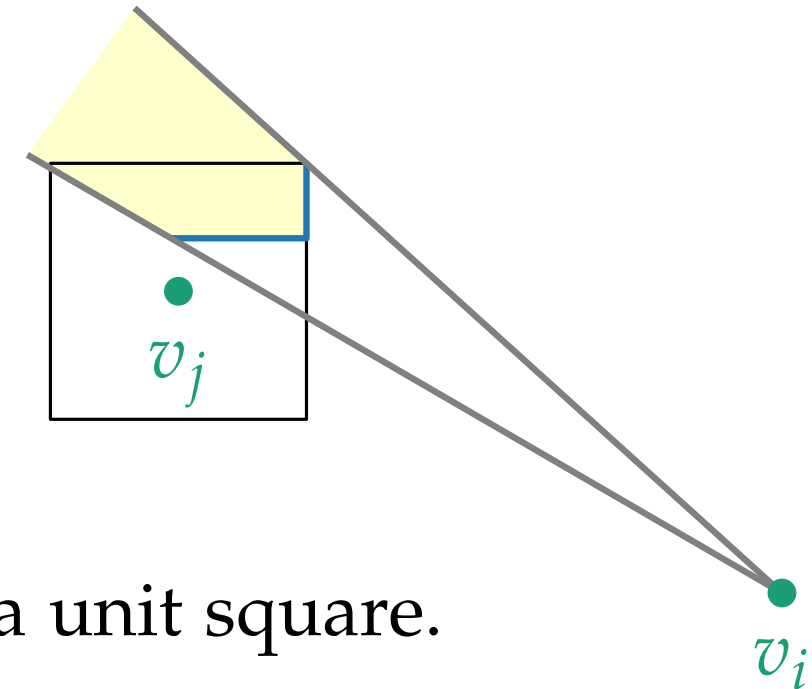
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- Using techniques from the algorithm by Melkman and O'Rourke, we have shown how to find an optimal simplification of a polyline under the local Fréchet distance in $O(n^2 \log n)$ (instead of $O(n^3)$) time in the L_2 norm.

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- The log-factor arises when the wave front has linear size.
However, this requires a special arrangement of the vertices of the polyline.

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- Our result generalizes to other L_p norms ($p \in [1, \infty]$).
In L_1 and L_∞ , the runtime improves to $O(n^2)$.

Future Work

- The log-factor arises when the wave front has linear size. However, this requires a special arrangement of the vertices of the polyline.
- Test experimentally that in a practical setting such arrangements don't occur.

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- Adjust the algorithm to handle such arrangements faster.