

Bounding and computing obstacle numbers of graphs

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Czech Republic



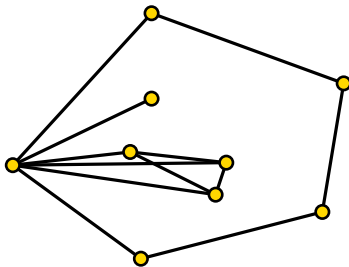
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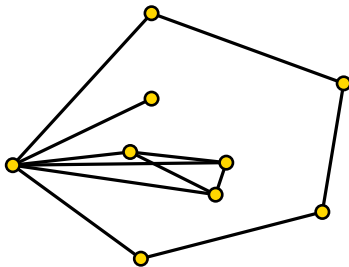
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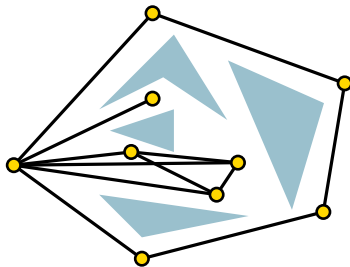
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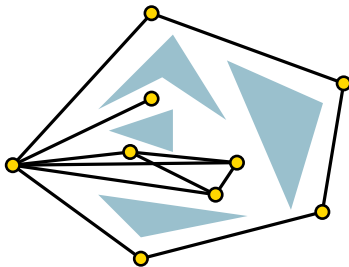
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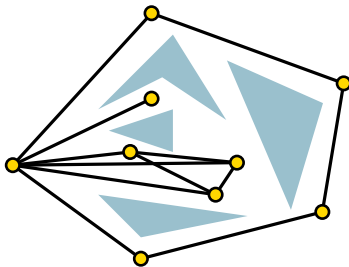
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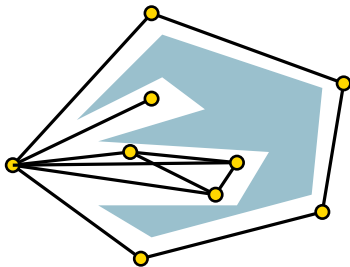
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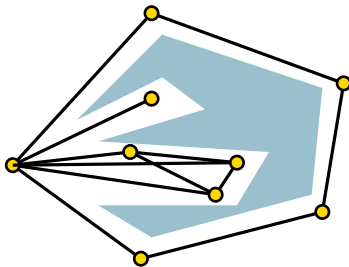
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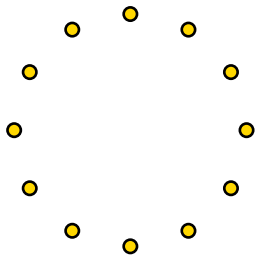
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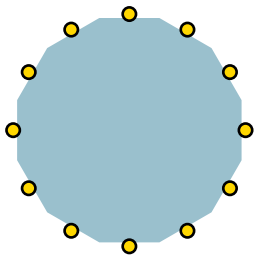
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- Similarly, the **convex obstacle number** $\text{obs}_c(G)$ of a graph G is the minimum number of *convex* obstacles in an obstacle representation of G .

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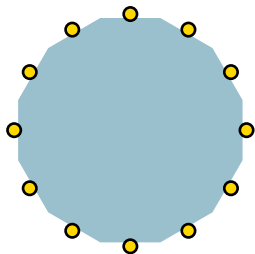


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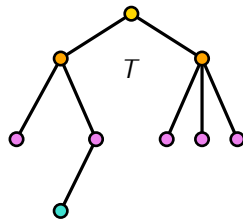


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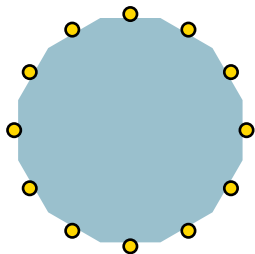
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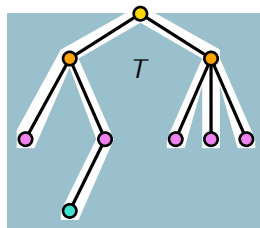
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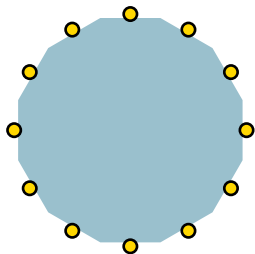


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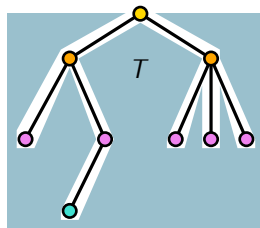
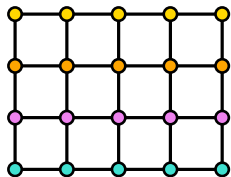


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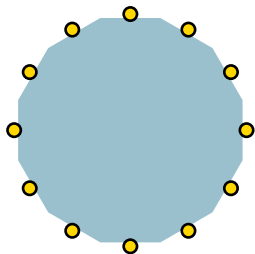


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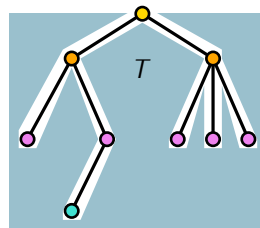


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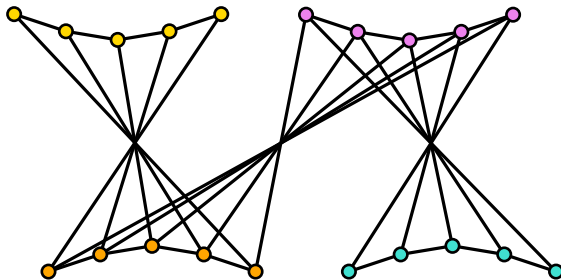
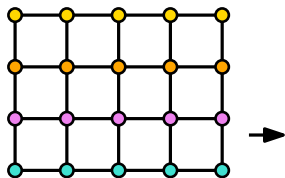
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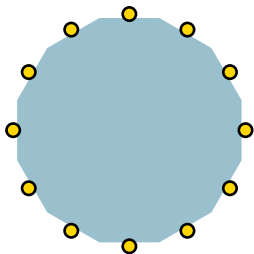
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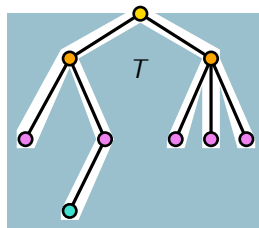
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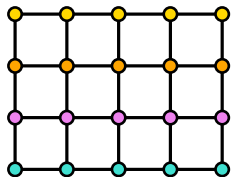
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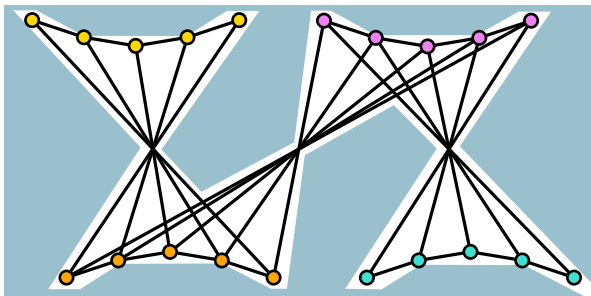


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$$\text{obs}(P_m \times P_n) = 1$$

(Fabrizio Frati)



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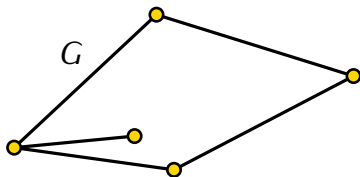
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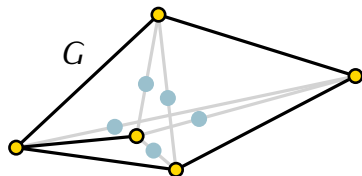
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$$\text{obs}(G) \leq \binom{n}{2} - |E(G)|$$

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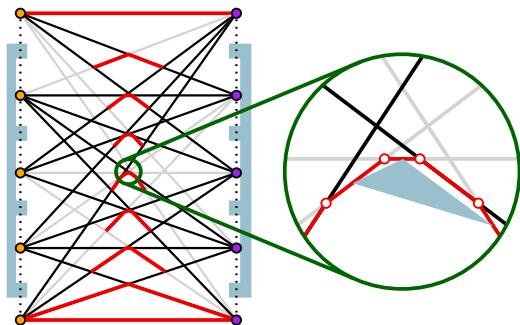
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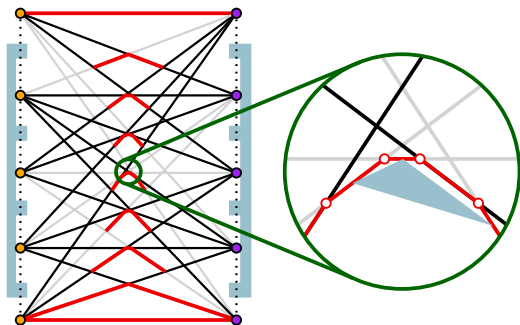
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- The bounds apply even if the obstacles are required to be convex.

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- The proofs are not constructive and follow from a counting argument.

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- This is asymptotically tight for $h < n$ as Balko, Cibulka, and Valtr showed $f_c(h, n) \in 2^{\Omega(hn)}$ for $0 < h < n$ and $f_c(1, n) \in 2^{\Omega(n \log n)}$.

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- The complexity of deciding whether a given graph has obstacle number 1 is still open.

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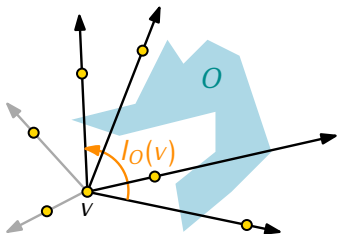
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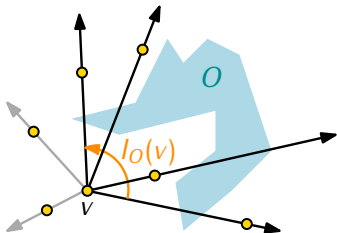
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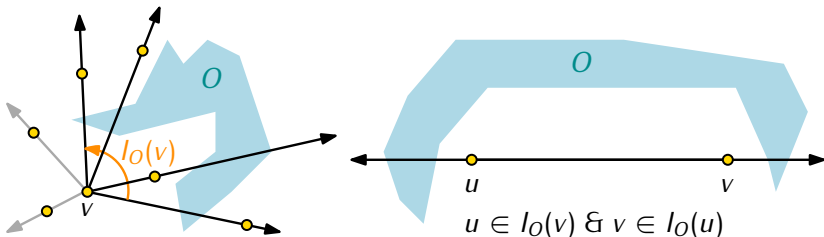
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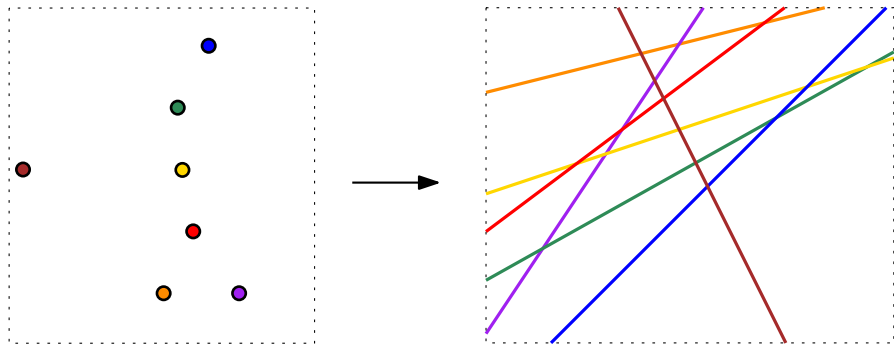
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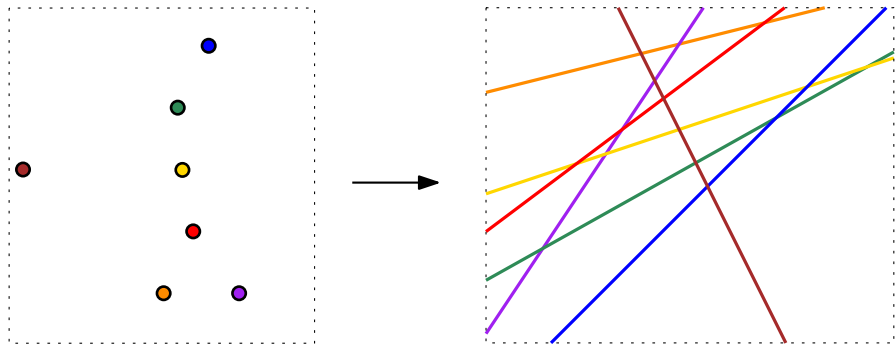
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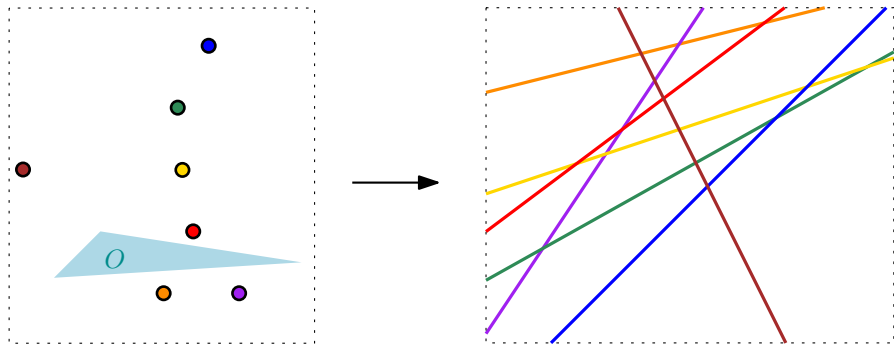
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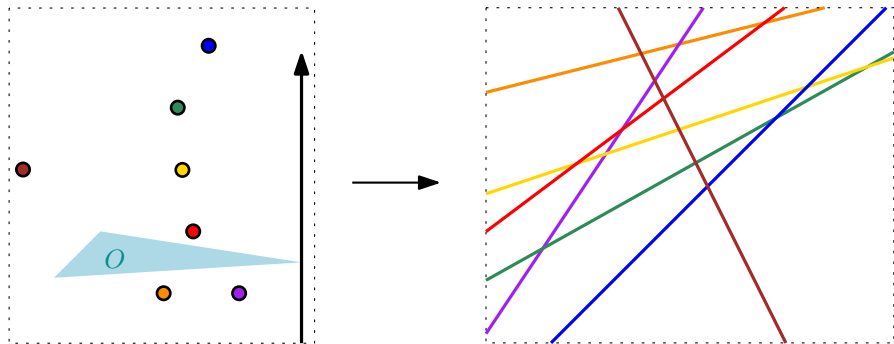
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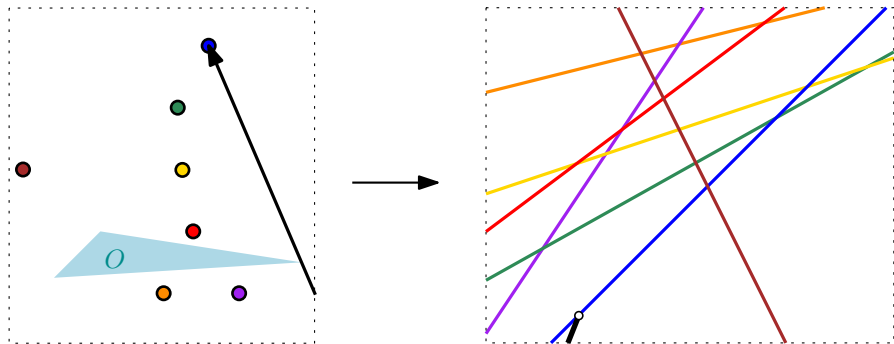
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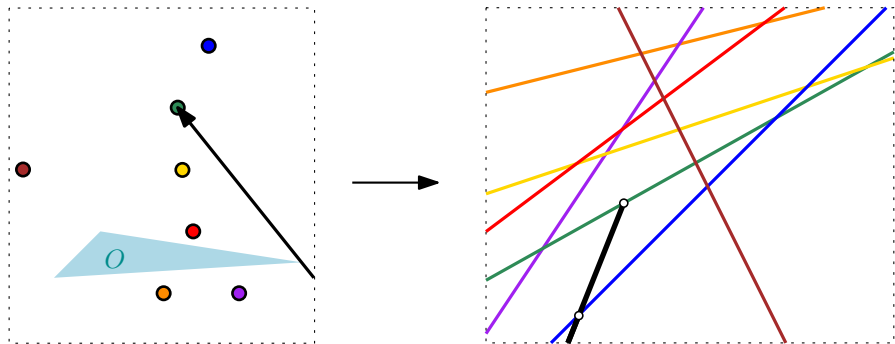
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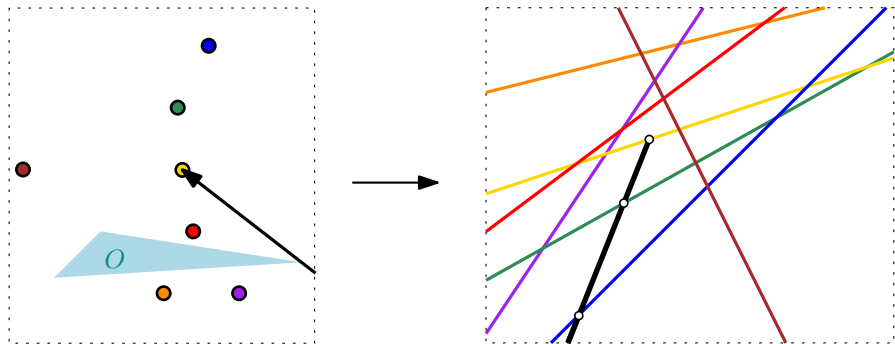
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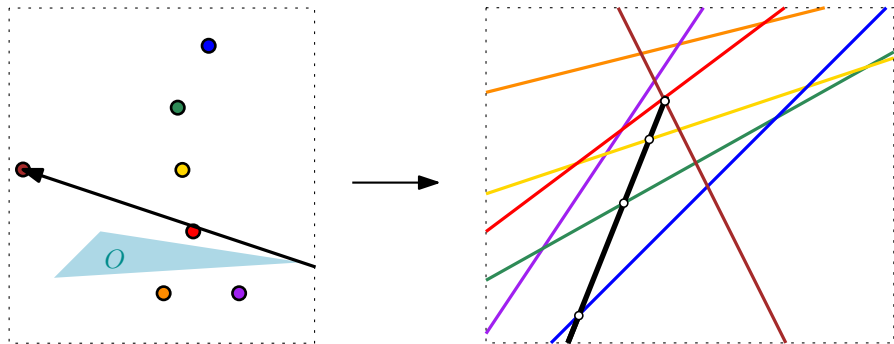
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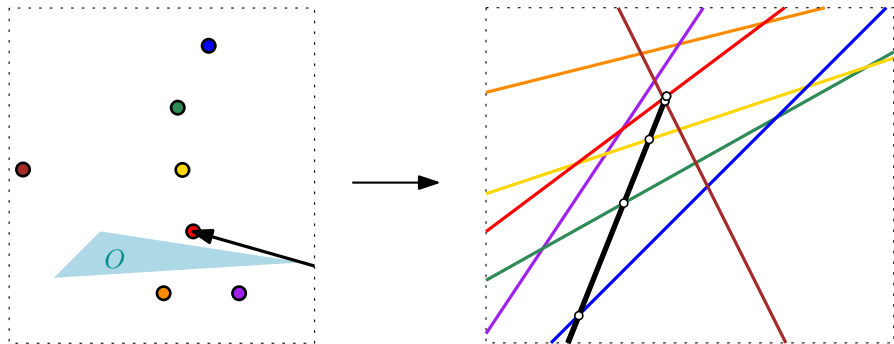
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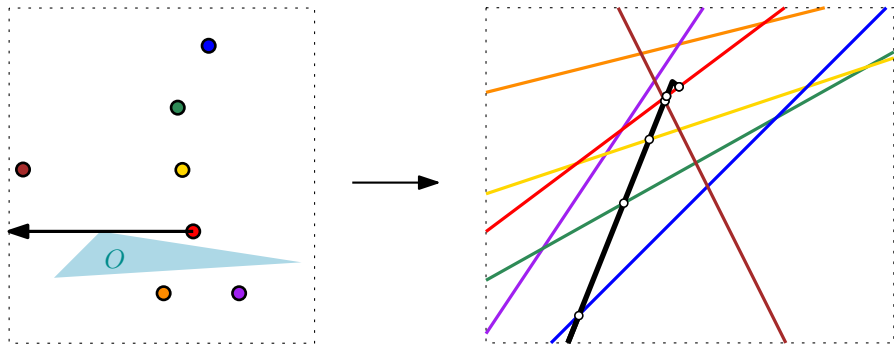
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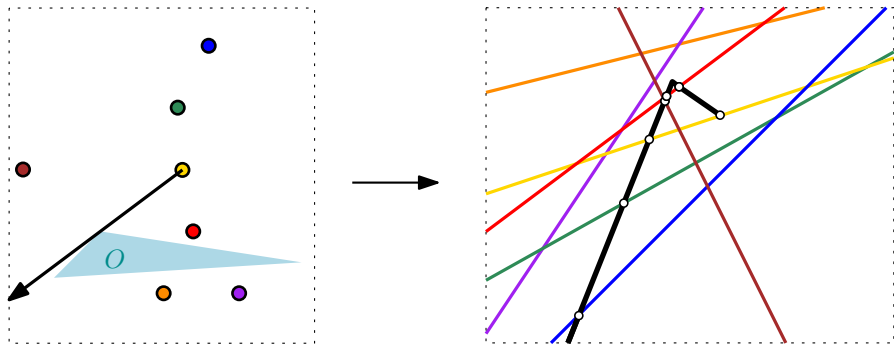
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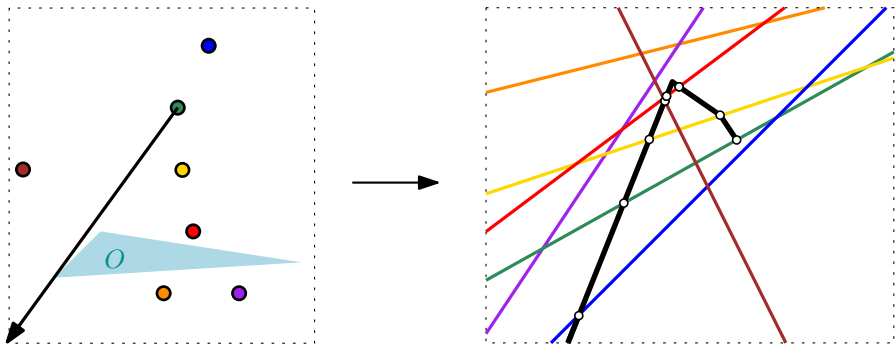
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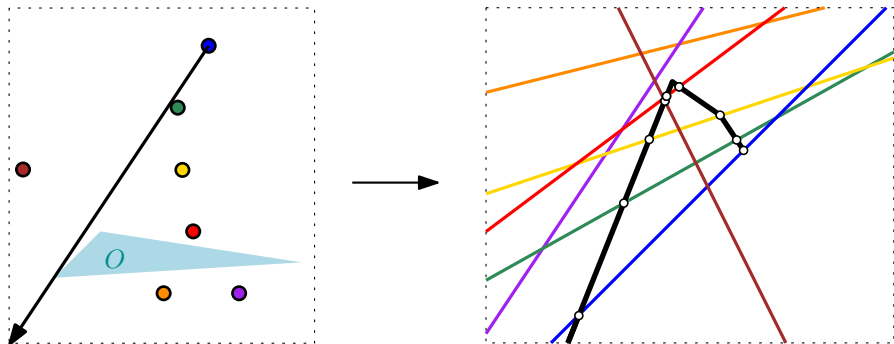
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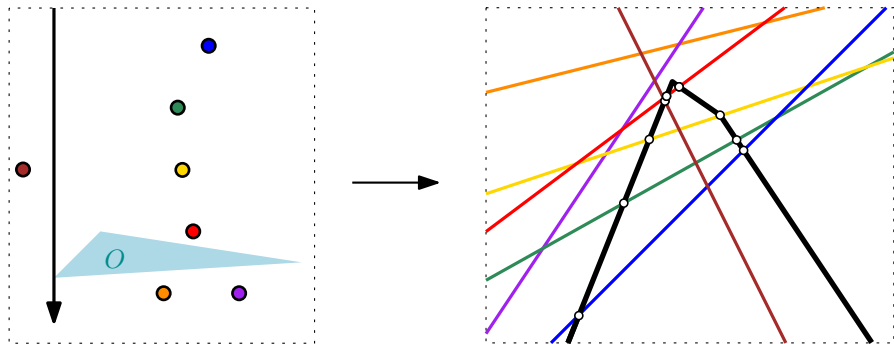
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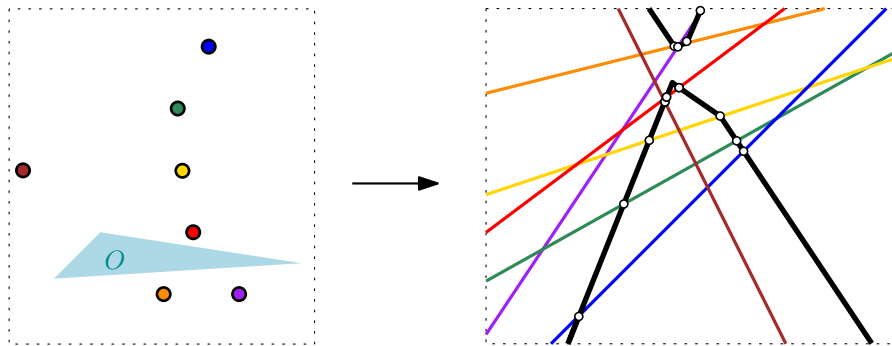
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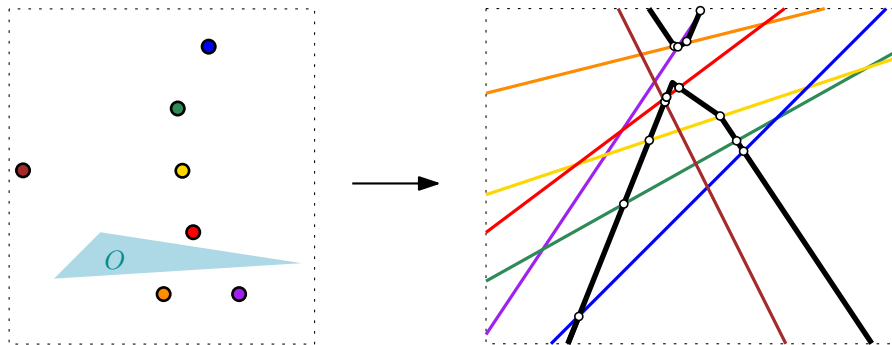
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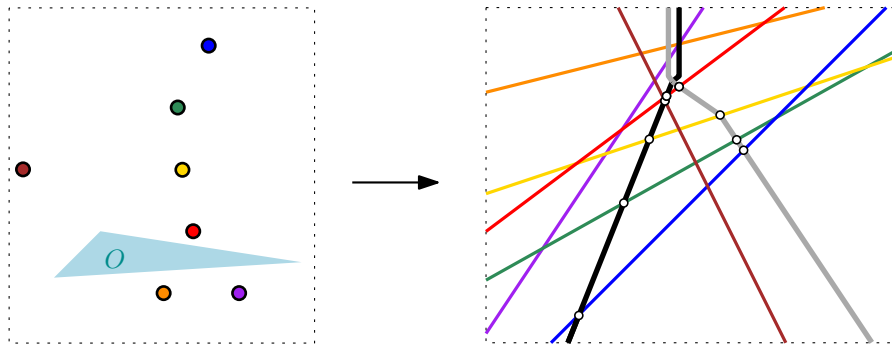
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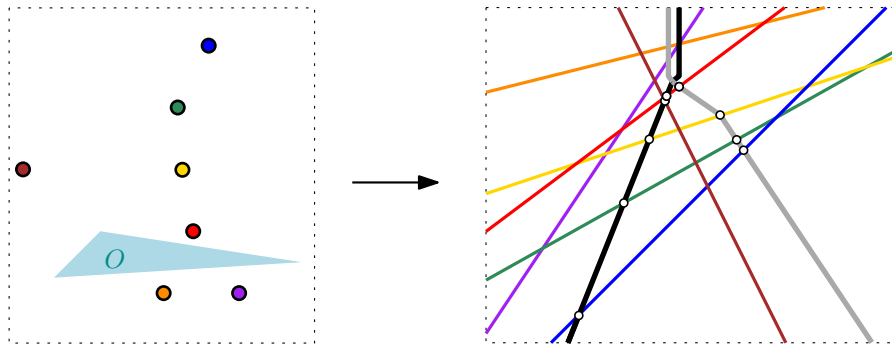
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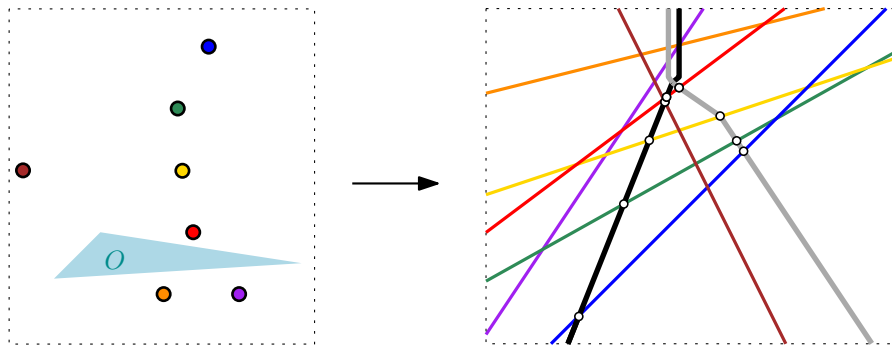
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