

Approximation Algorithms

Lecture 3:

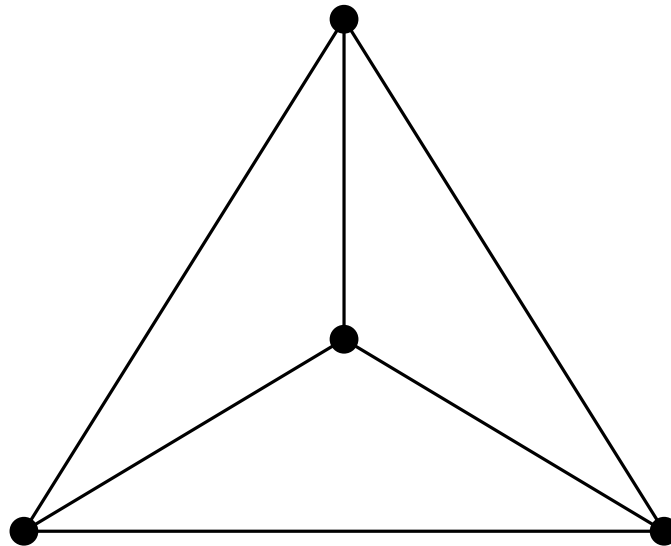
STEINERTREE and MULTIWAYCUT

Part I:

STEINERTREE

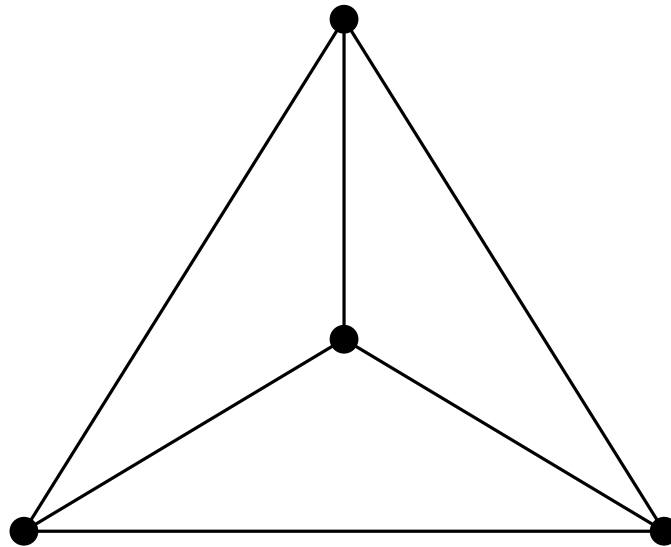
STEINERTREE

Given: A graph $G = (V, E)$



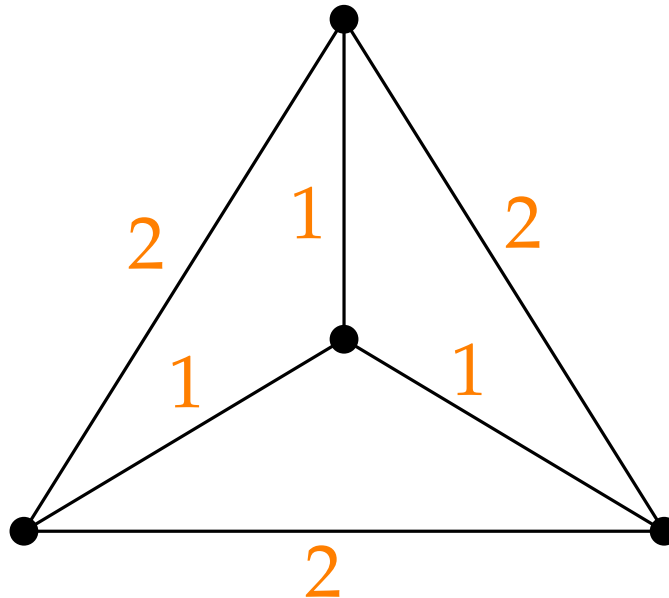
STEINERTREE

Given: A graph $G = (V, E)$ with edge weights $c: E \rightarrow \mathbb{Q}^+$



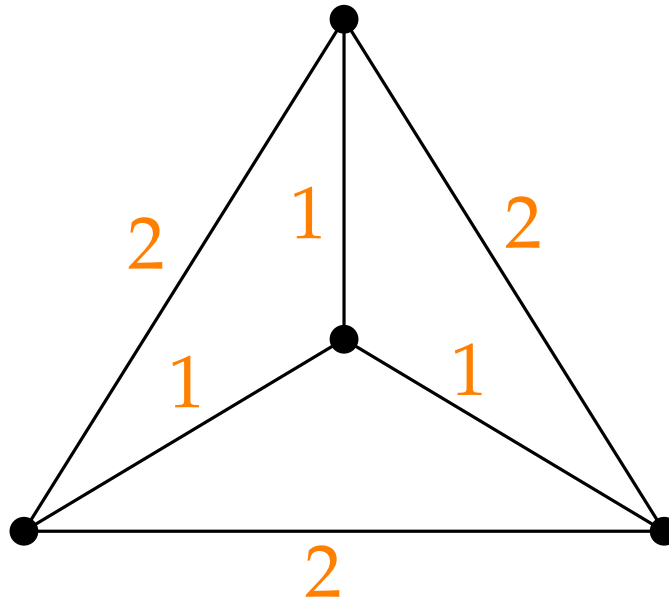
STEINERTREE

Given: A graph $G = (V, E)$ with edge weights $c: E \rightarrow \mathbb{Q}^+$



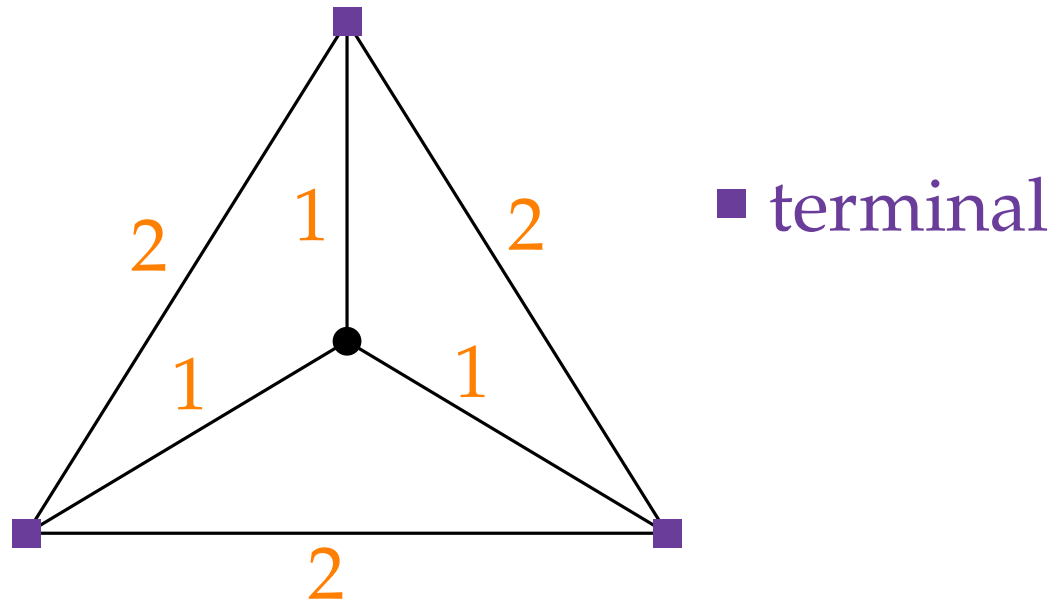
STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.



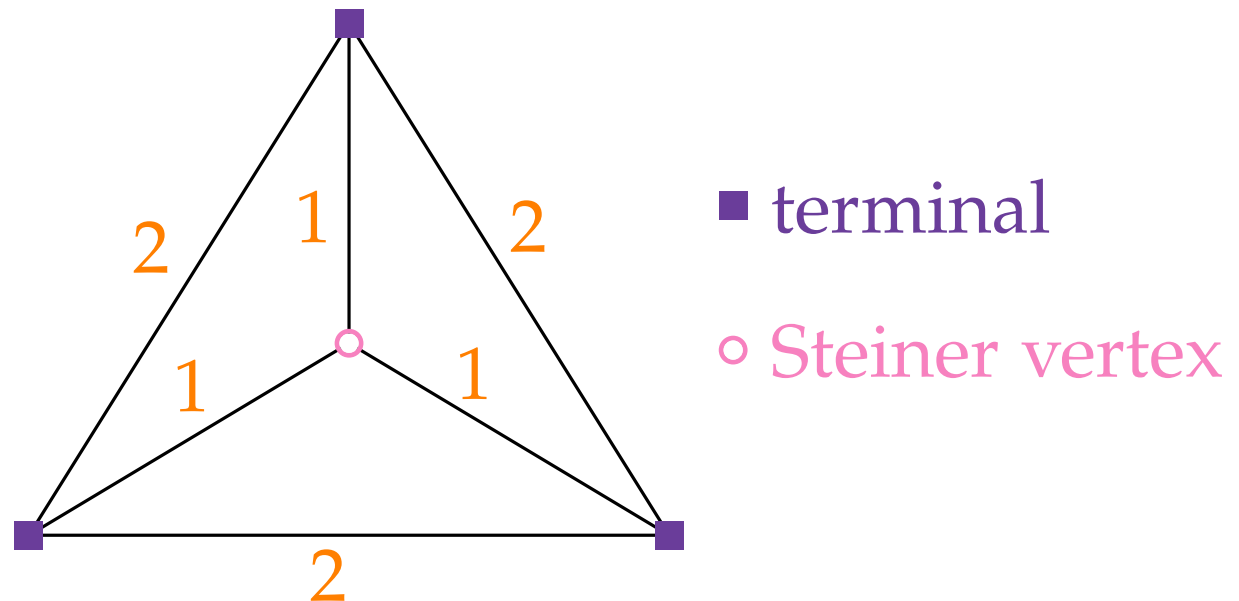
STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.



STEINERTREE

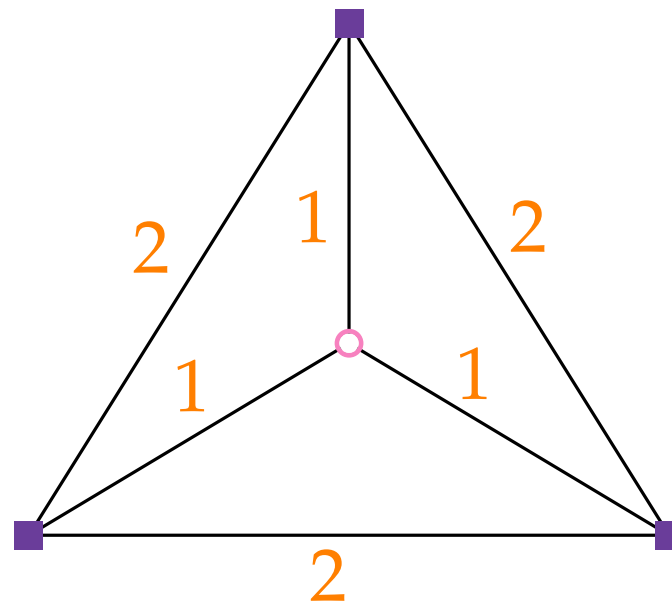
Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.



STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.

Find: A **subtree** $B = (V', E')$ of G that contains all **terminals**, i.e., $T \subseteq V'$.



■ terminal

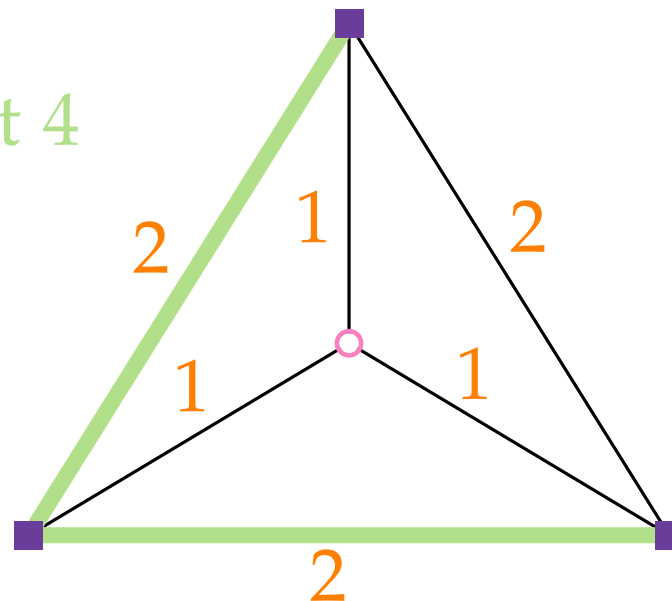
○ Steiner vertex

STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.

Find: A **subtree** $B = (V', E')$ of G that contains all **terminals**, i.e., $T \subseteq V'$

valid solution with cost 4



■ terminal

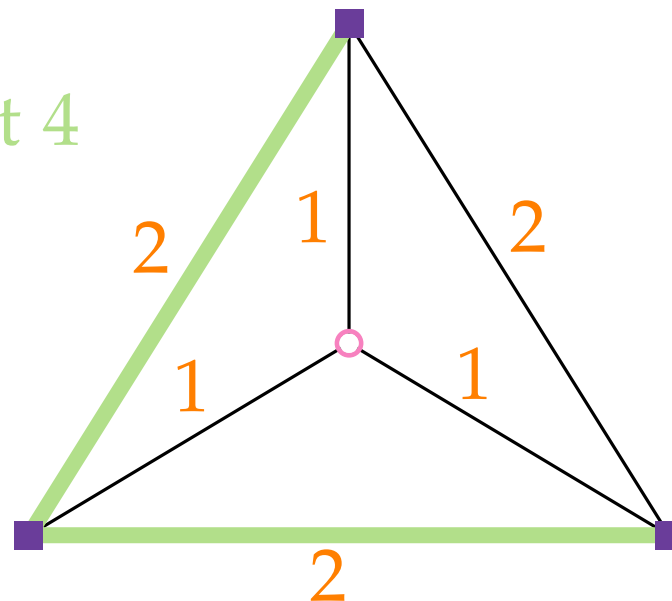
○ Steiner vertex

STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.

Find: A **subtree** $B = (V', E')$ of G that contains all **terminals**, i.e., $T \subseteq V'$, and has **minimum cost** $c(E') := \sum_{e \in E'} c(e)$ among all subtrees with this property.

valid solution with cost 4



■ terminal

○ Steiner vertex

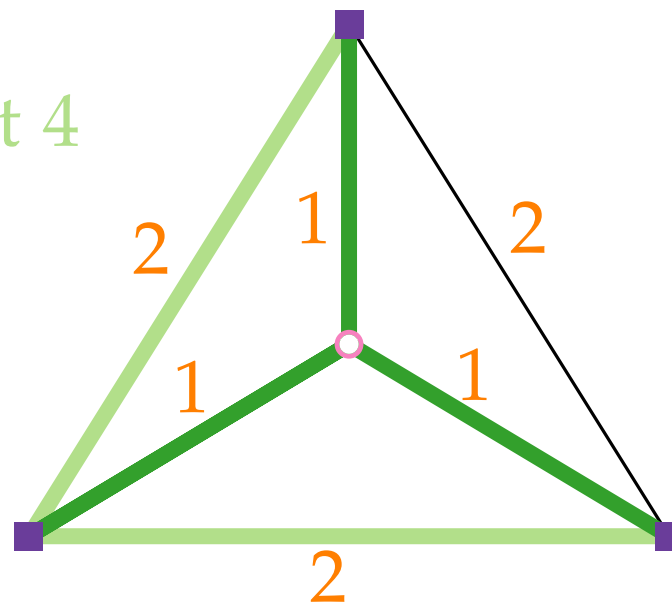
STEINERTREE

Given: A graph $G = (V, E)$ with **edge weights** $c: E \rightarrow \mathbb{Q}^+$ and a partition of V into a set T of **terminals** and a set S of **Steiner vertices**.

Find: A **subtree** $B = (V', E')$ of G that contains all **terminals**, i.e., $T \subseteq V'$, and has **minimum cost** $c(E') := \sum_{e \in E'} c(e)$ among all subtrees with this property.

valid solution with cost 4

optimum solution
with cost 3



■ terminal

○ Steiner vertex

METRICSTEINERTREE

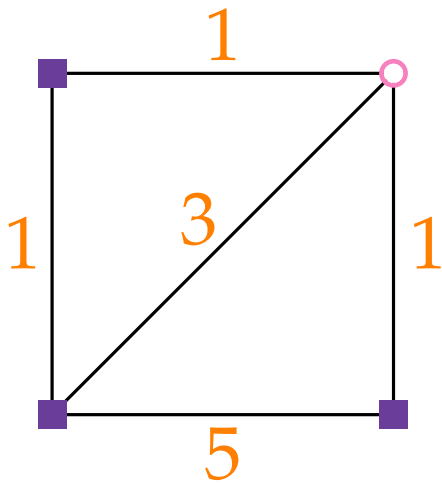
Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**

METRICSTEINERTREE

Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.

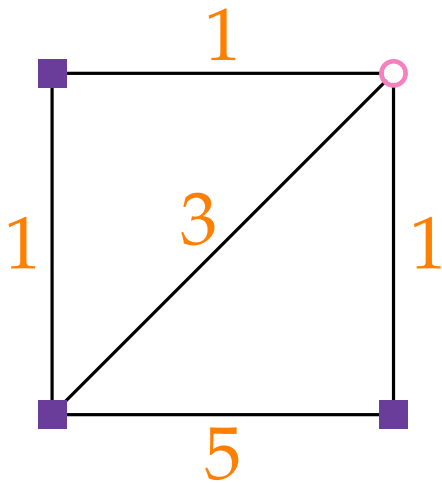
METRICSTEINERTREE

Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.



METRICSTEINERTREE

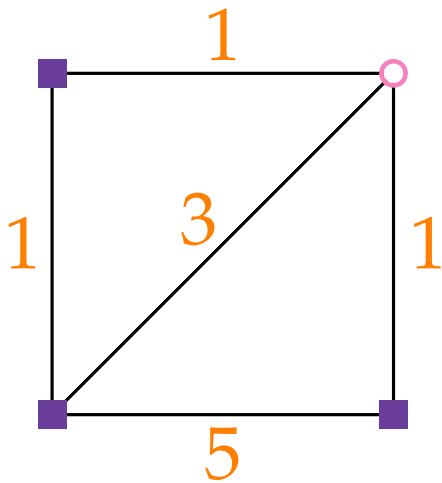
Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.



not complete

METRICSTEINERTREE

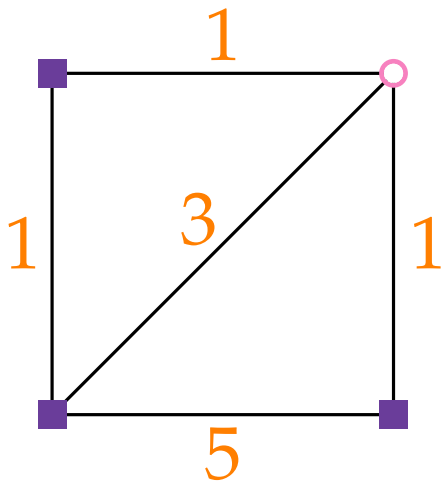
Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.



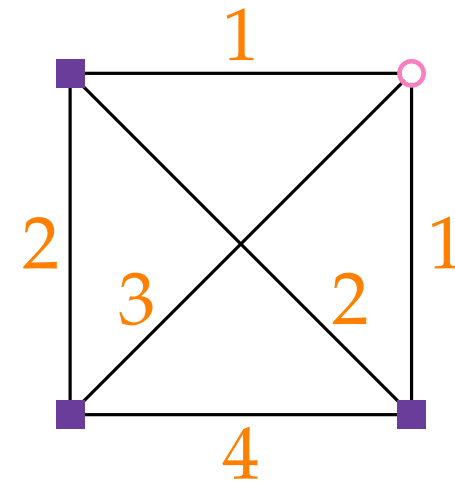
not complete
not metric

METRICSTEINERTREE

Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.

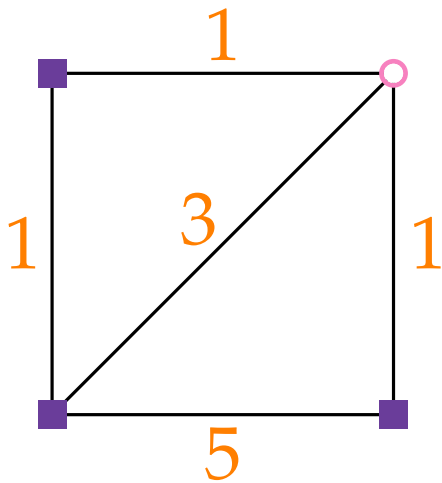


not complete
not metric

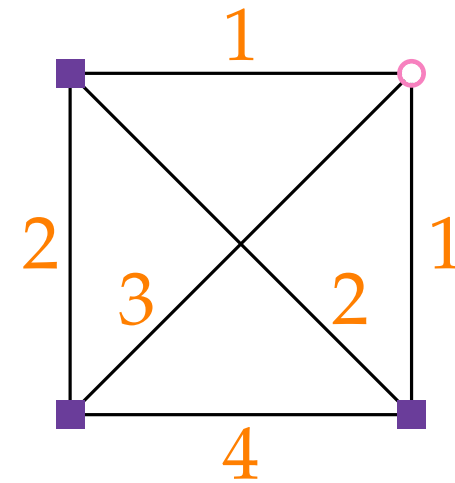


METRICSTEINERTREE

Restriction of STEINERTREE where the graph G is complete and the cost function is **metric**, i.e., for every triple u, v, w of vertices, we have $c(u, w) \leq c(u, v) + c(v, w)$.



not complete
not metric



complete
metric

Approximation Algorithms

Lecture 3:

STEINERTREE and MULTIWAYCUT

Part II:

Approximation Preserving Reduction

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems.

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems.

problems

Π_1

Π_2

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

problems

Π_1

Π_2

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.

problems

Π_1

Π_2

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

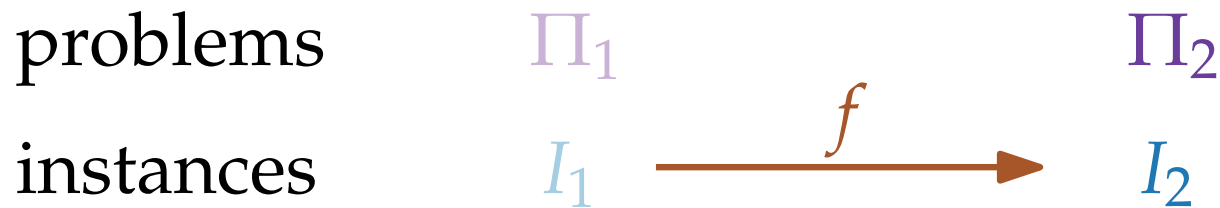
- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.

problems	Π_1	Π_2
instances	I_1	

Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

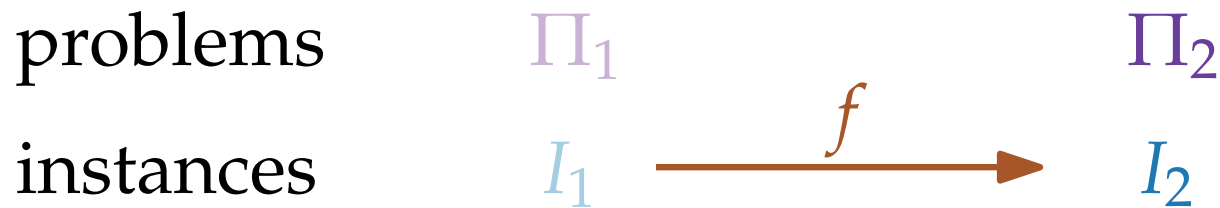
- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.



Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

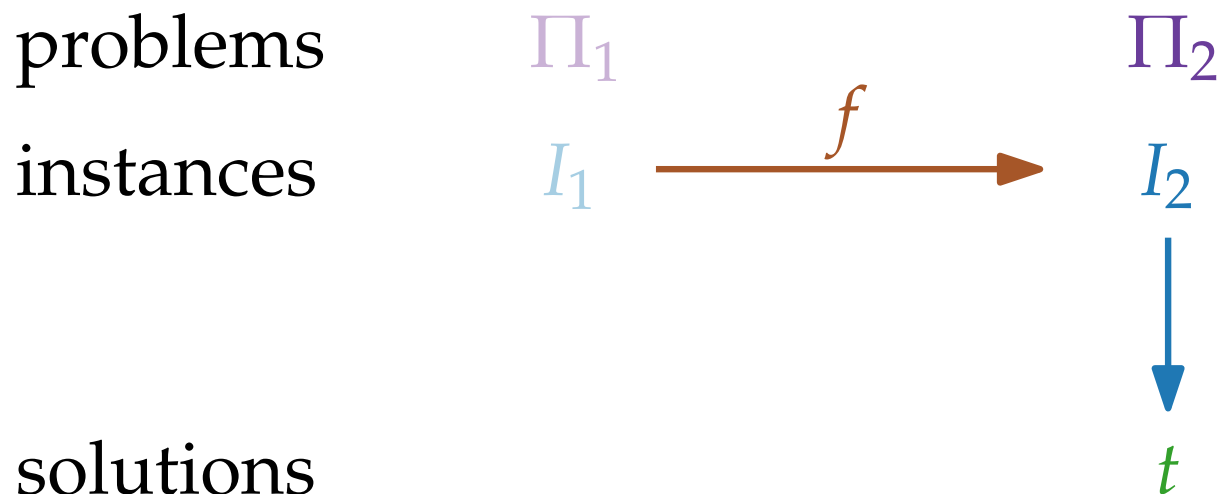
- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.
- (ii) For each feasible solution t of I_2 , $s := g(I_1, t)$ is a feasible solution of I_1 with $\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t)$.



Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

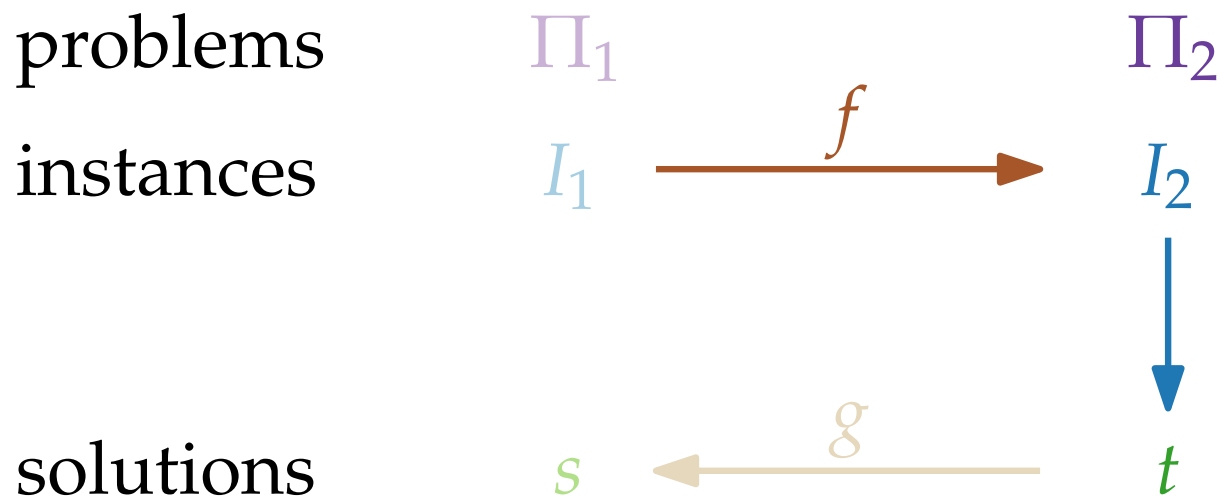
- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.
- (ii) For each feasible solution t of I_2 , $s := g(I_1, t)$ is a feasible solution of I_1 with $\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t)$.



Approximation Preserving Reduction

Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

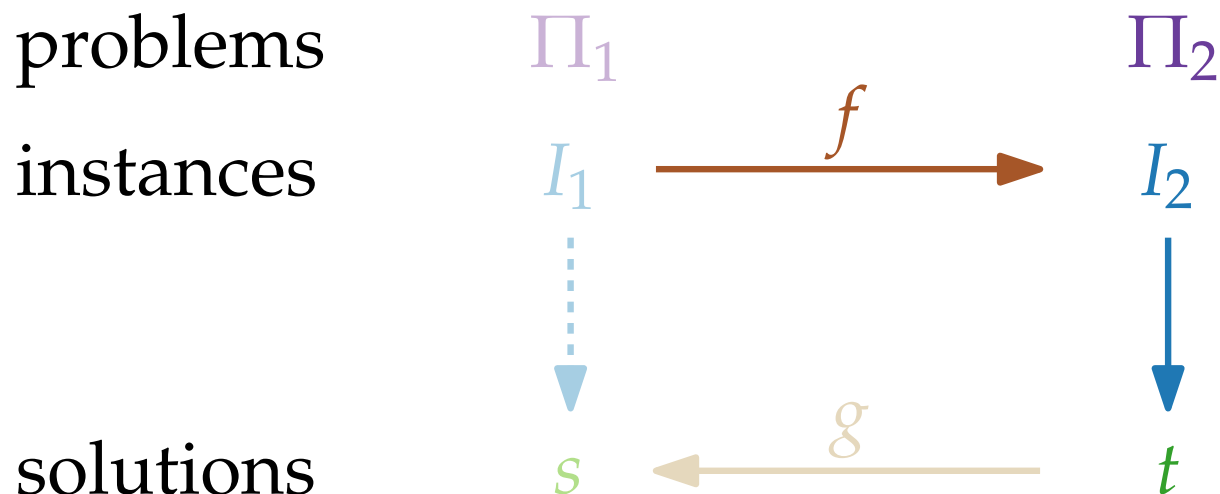
- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.
- (ii) For each feasible solution t of I_2 , $s := g(I_1, t)$ is a feasible solution of I_1 with $\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t)$.



Approximation Preserving Reduction

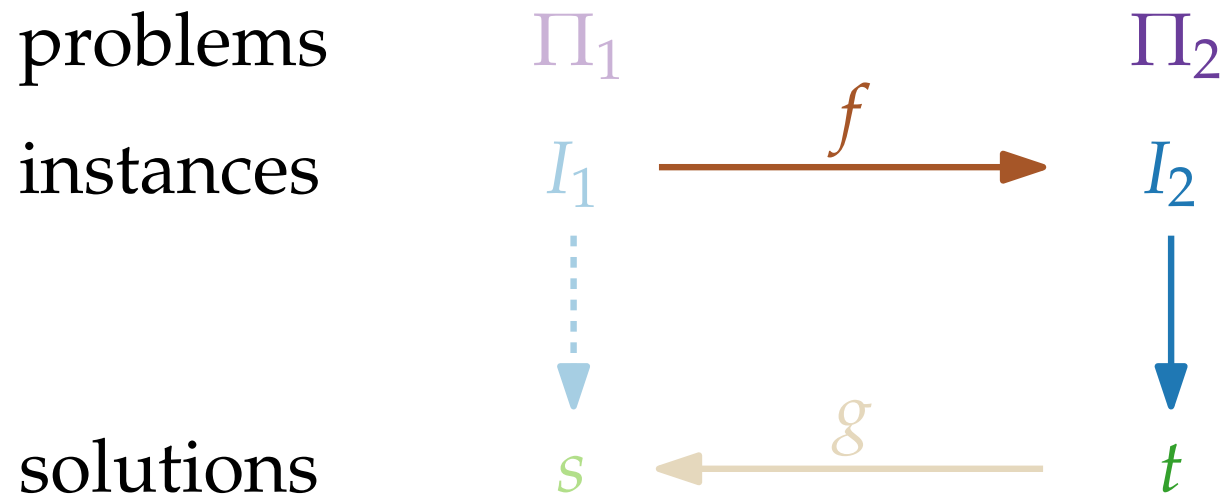
Let Π_1, Π_2 be minimization problems. An **approximation preserving reduction** from Π_1 to Π_2 is a tuple (f, g) of poly-time computable functions with the following properties.

- (i) For each instance I_1 of Π_1 , $I_2 := f(I_1)$ is an instance of Π_2 with $\text{OPT}_{\Pi_2}(I_2) \leq \text{OPT}_{\Pi_1}(I_1)$.
- (ii) For each feasible solution t of I_2 , $s := g(I_1, t)$ is a feasible solution of I_1 with $\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t)$.



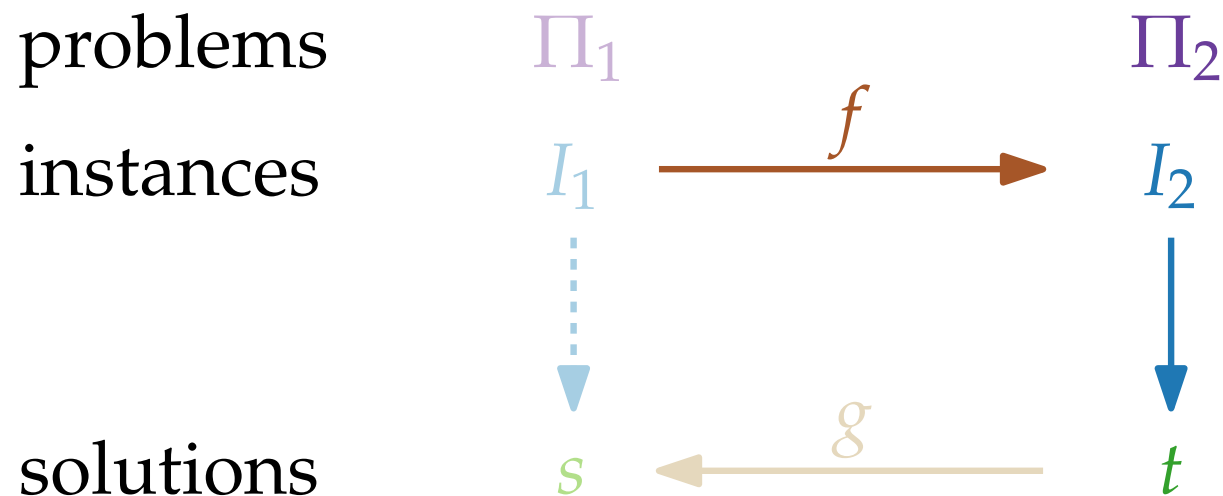
Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 .



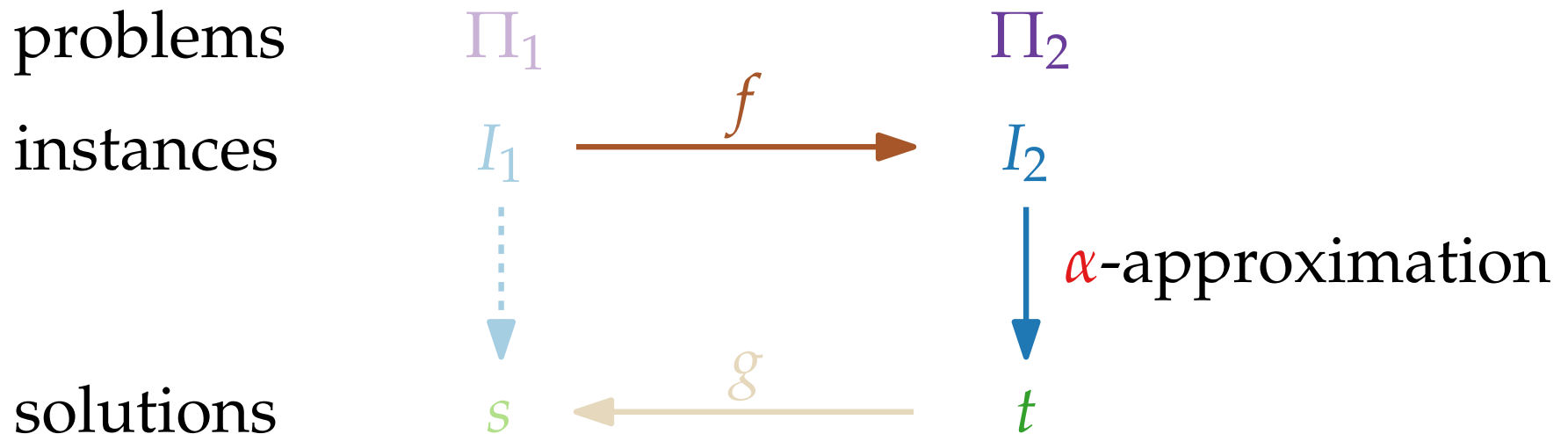
Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a factor α approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .



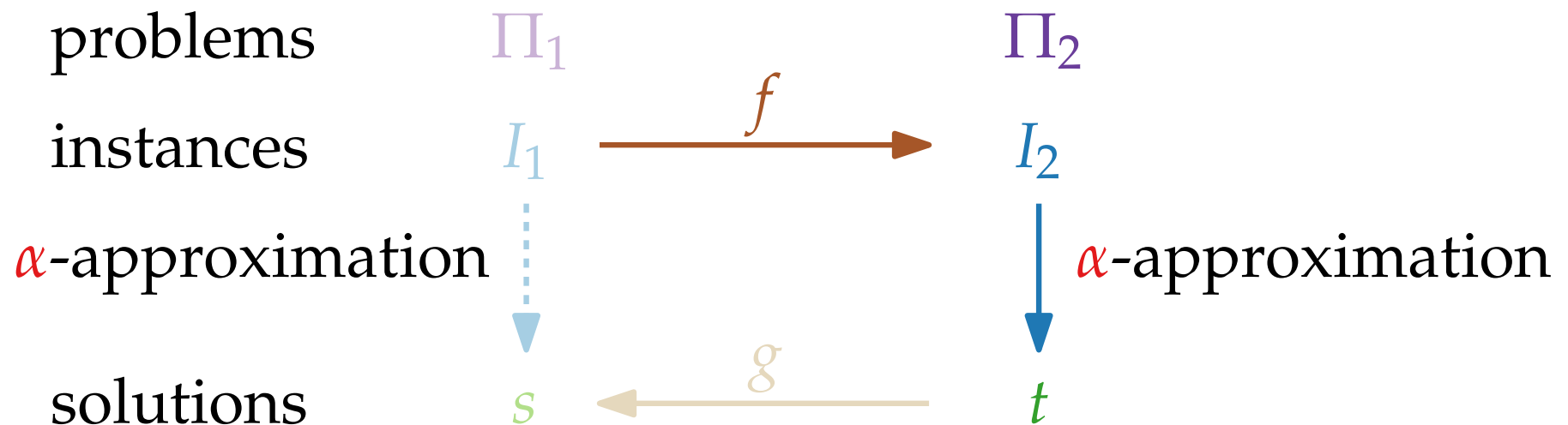
Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor α approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .



Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

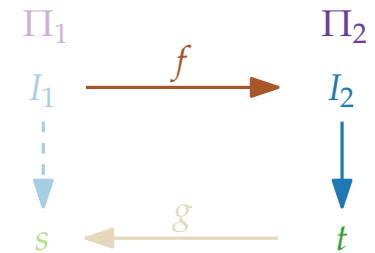


Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .



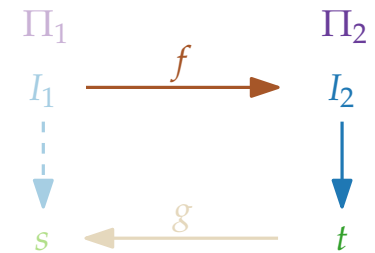
Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .



Approximation Preserving Reduction

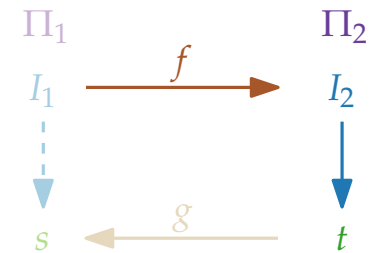
Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 :=$, $t :=$ and $s :=$.



Approximation Preserving Reduction

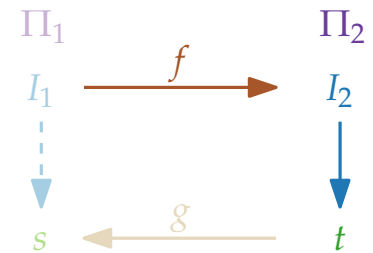
Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t :=$ and $s :=$.



Approximation Preserving Reduction

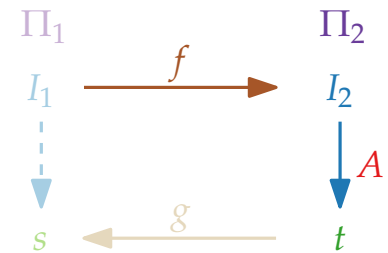
Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s :=$.



Approximation Preserving Reduction

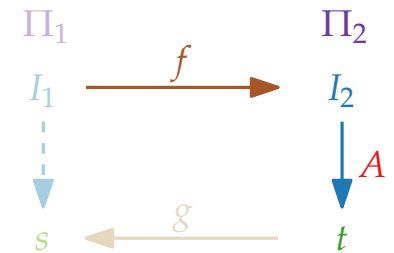
Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s := g(I_1, t)$.



Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

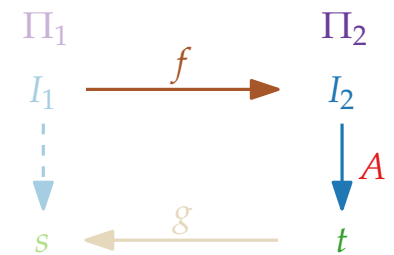
Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s := g(I_1, t)$.

Then:

$\text{obj}_{\Pi_1}(I_1, s)$



Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an approximation preserving reduction (f, g) from Π_1 to Π_2 . Then there is a factor- α -approximation algorithm of Π_1 for each factor- α -approximation algorithm of Π_2 .

Proof.

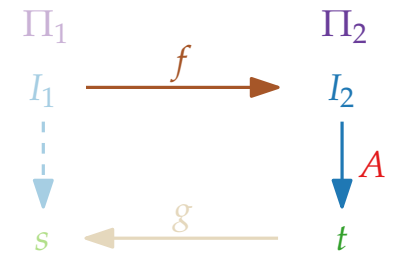
Let A be a factor- α -approx. alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s := g(I_1, t)$.

Then:

$$\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t)$$



Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a **factor- α -approximation algorithm** of Π_1 for each **factor- α -approximation algorithm** of Π_2 .

Proof.

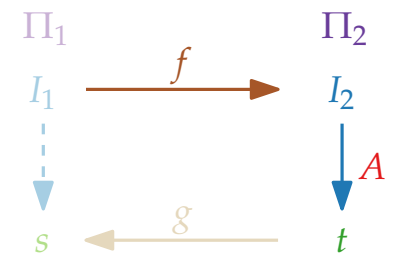
Let A be a **factor- α -approx.** alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s := g(I_1, t)$.

Then:

$$\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t) \leq \alpha \cdot \text{OPT}_{\Pi_2}(I_2)$$



Approximation Preserving Reduction

Theorem. Let Π_1, Π_2 be minimization problems where there is an **approximation preserving reduction** (f, g) from Π_1 to Π_2 . Then there is a **factor- α -approximation** algorithm of Π_1 for each **factor- α -approximation** algorithm of Π_2 .

Proof.

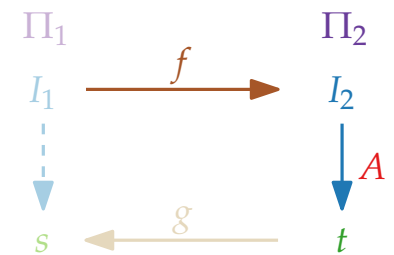
Let A be a **factor- α -approx.** alg. for Π_2 .

Let I_1 be an instance of Π_1 .

Set $I_2 := f(I_1)$, $t := A(I_2)$ and $s := g(I_1, t)$.

Then:

$$\text{obj}_{\Pi_1}(I_1, s) \leq \text{obj}_{\Pi_2}(I_2, t) \leq \alpha \cdot \text{OPT}_{\Pi_2}(I_2) \leq \alpha \cdot \text{OPT}_{\Pi_1}(I_1)$$



Approximation Algorithms

Lecture 3:

STEINERTREE and MULTIWAYCUT

Part III:

Reduction to METRICSTEINERTREE

METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping f $I_1 \xrightarrow{f} I_2$

METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

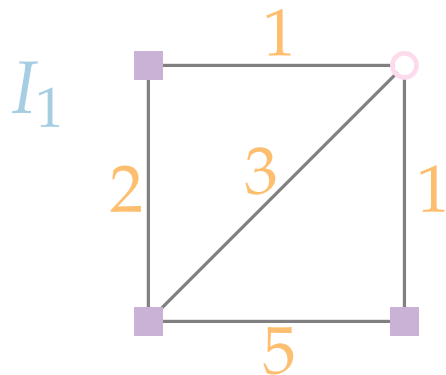
Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$



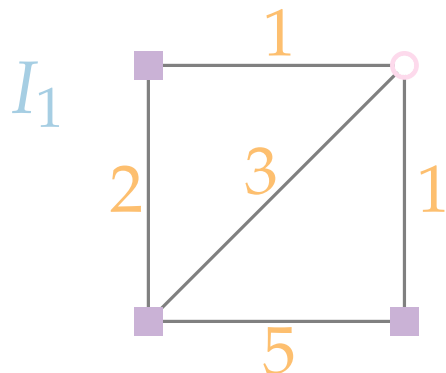
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1



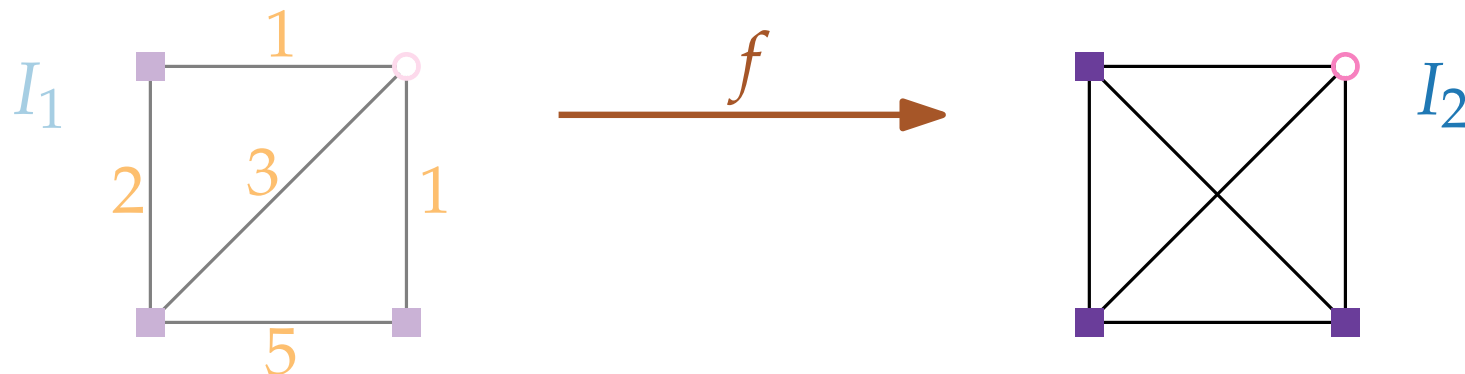
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1



METRICSTEINERTREE

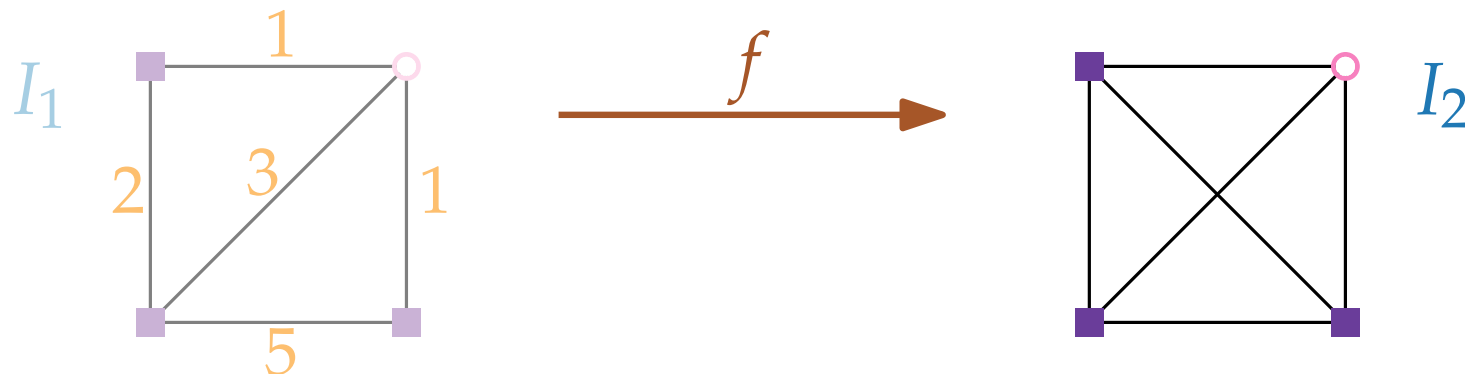
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

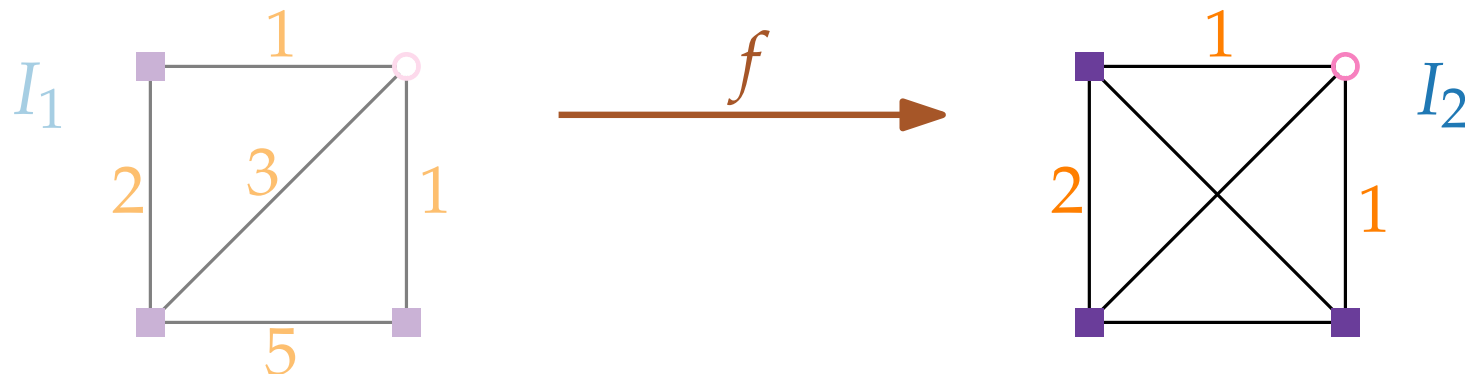
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

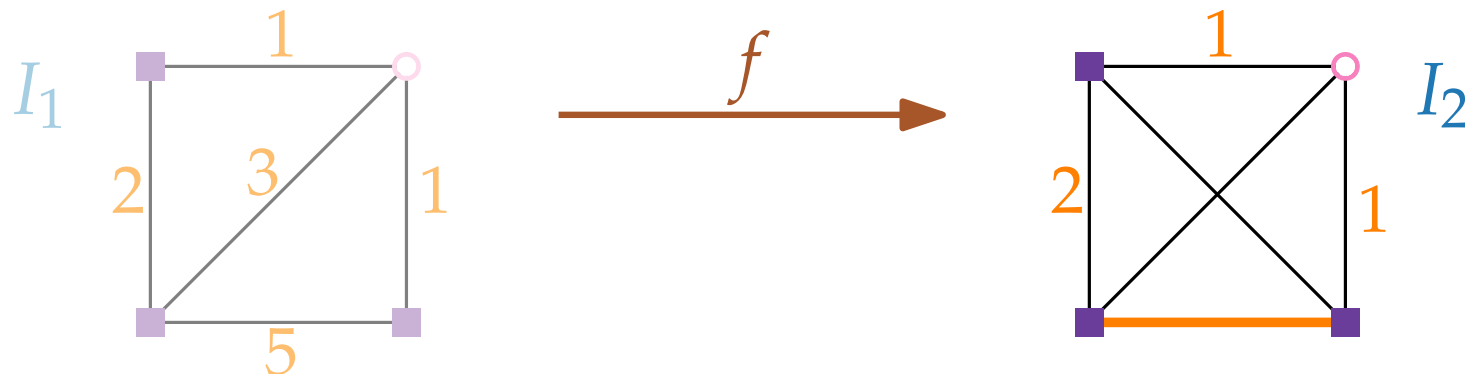
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

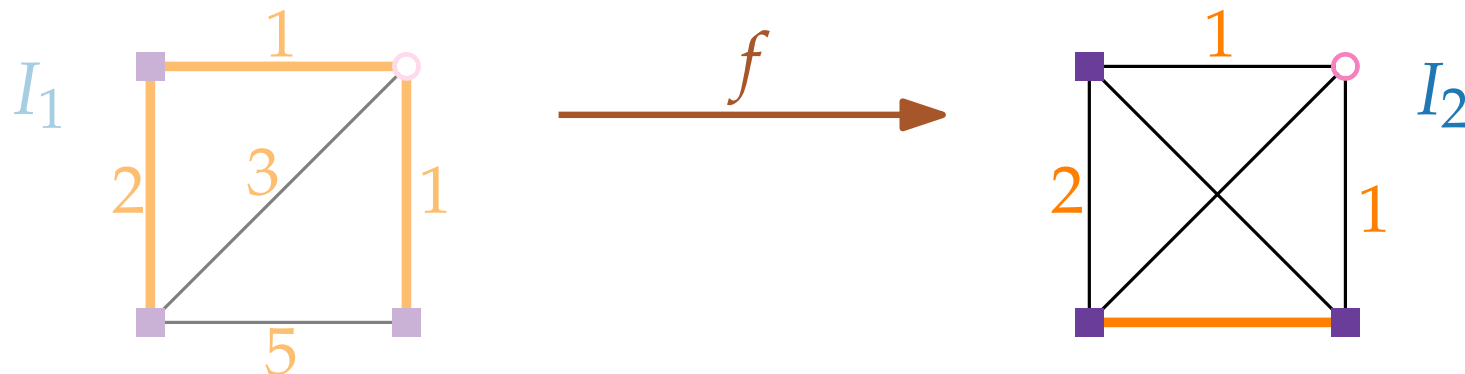
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

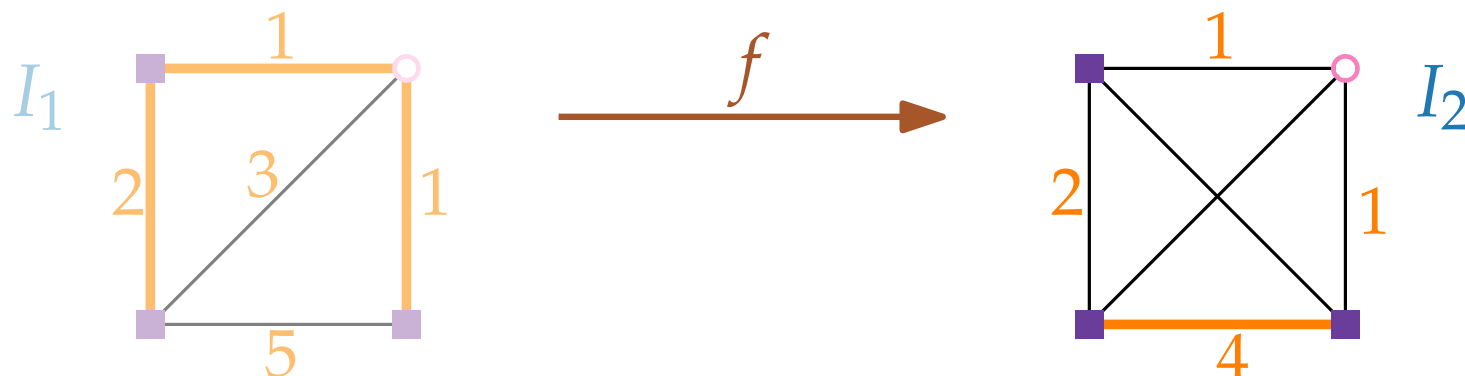
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

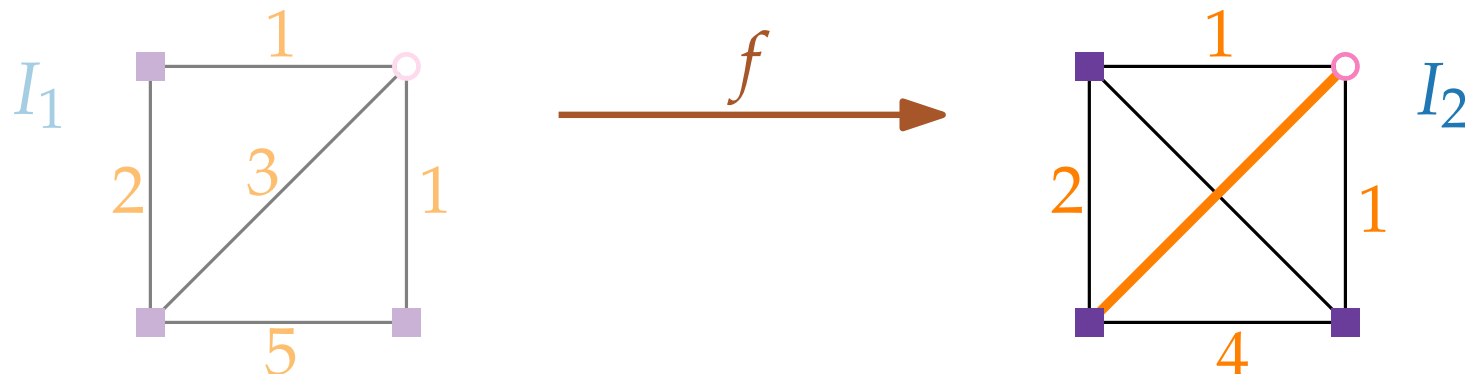
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

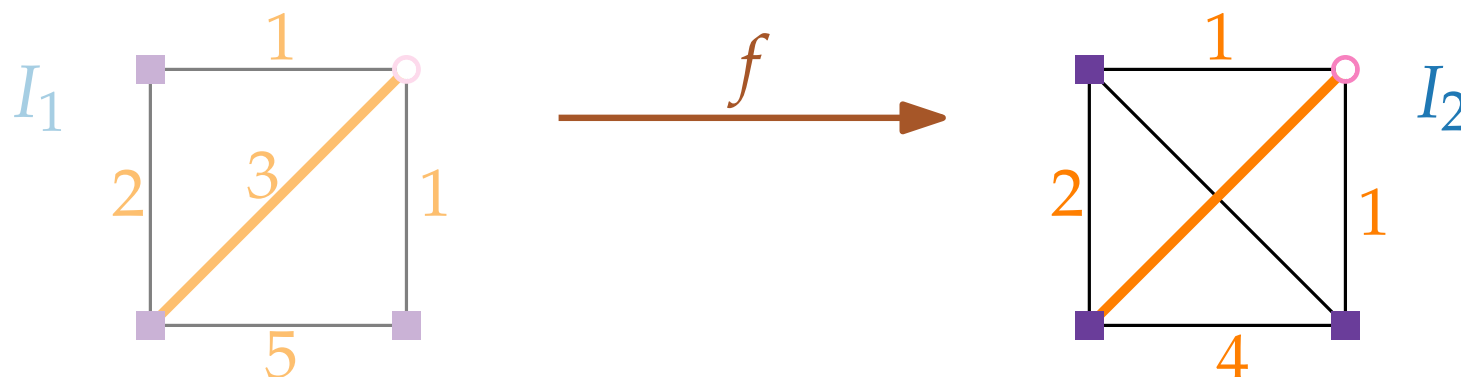
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

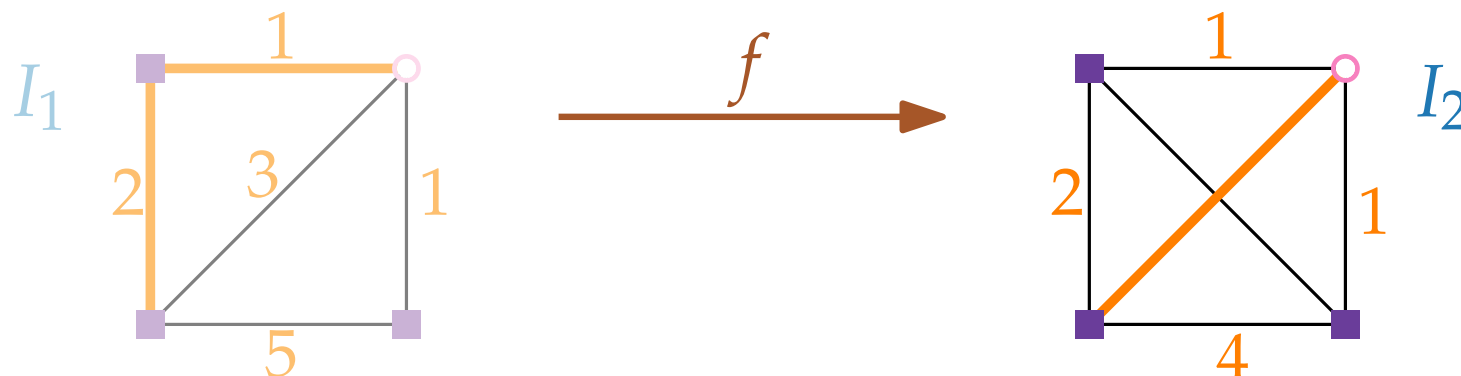
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

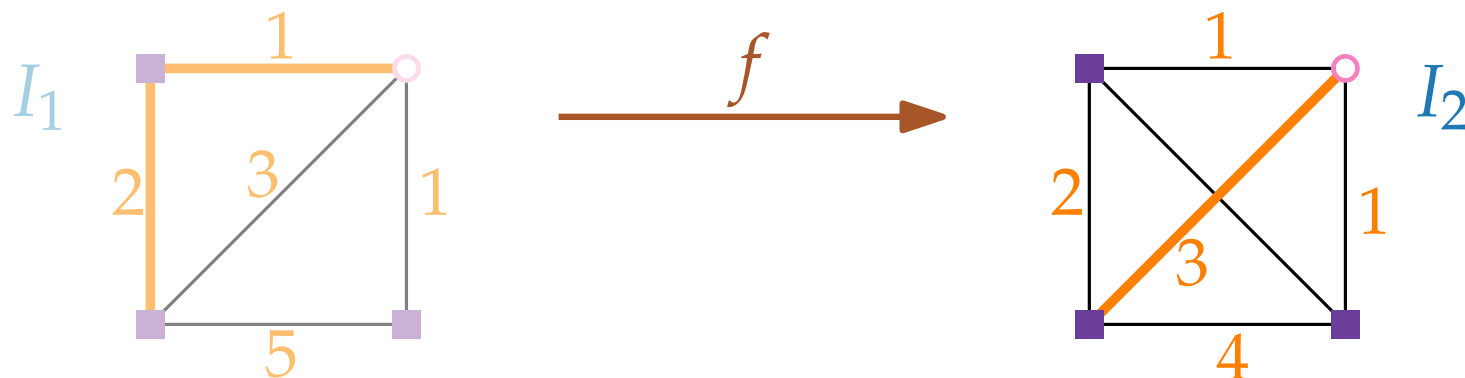
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

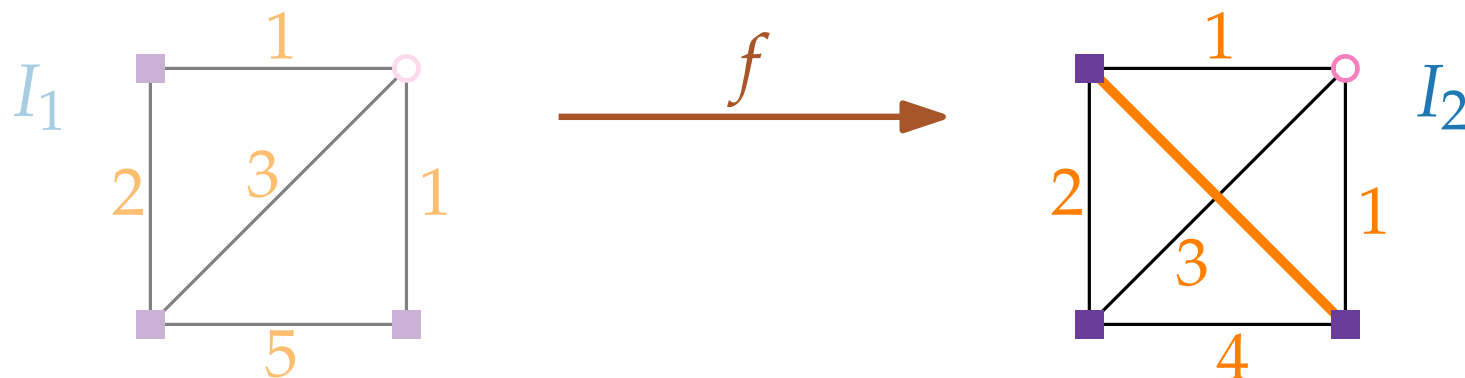
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

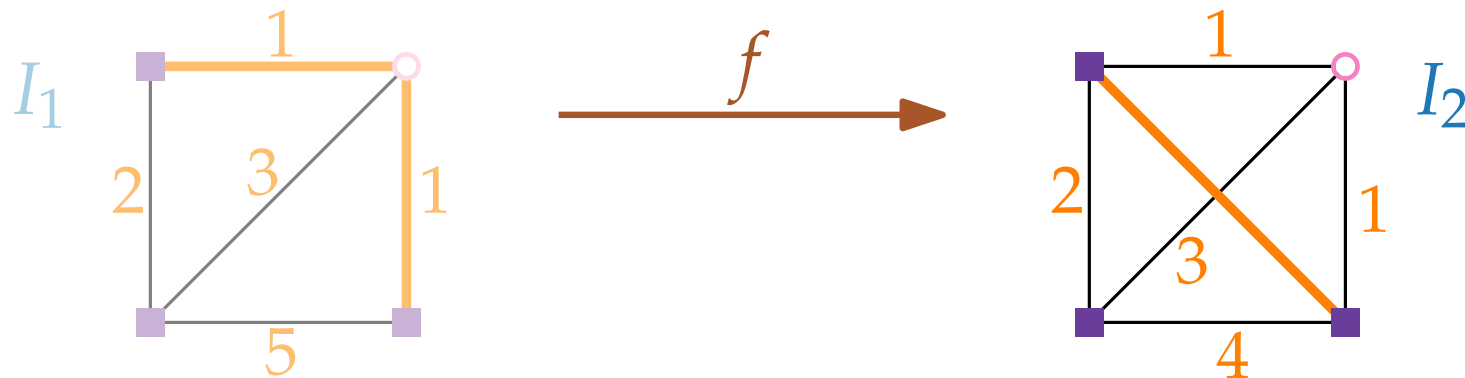
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

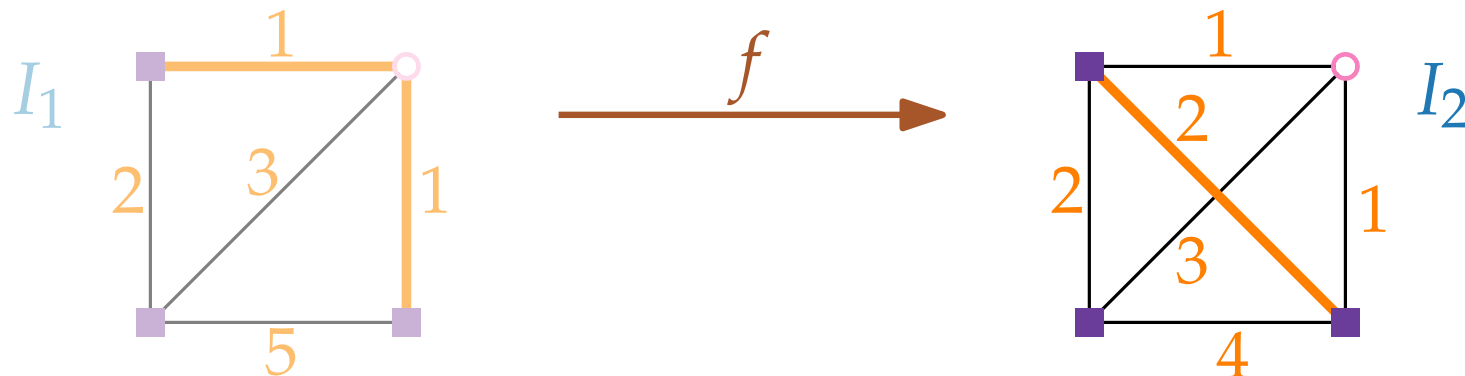
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

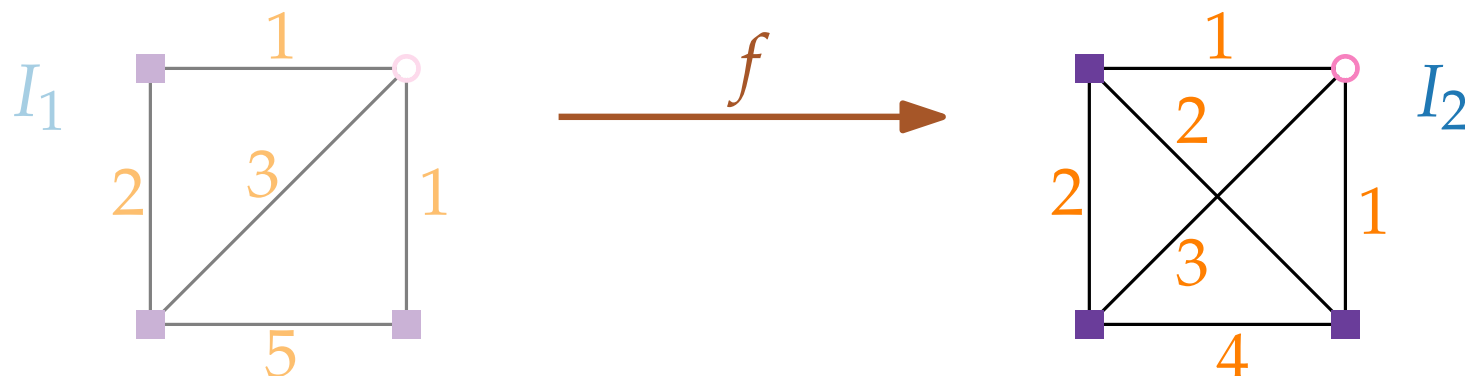
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest $u-v$ -path in G_1



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

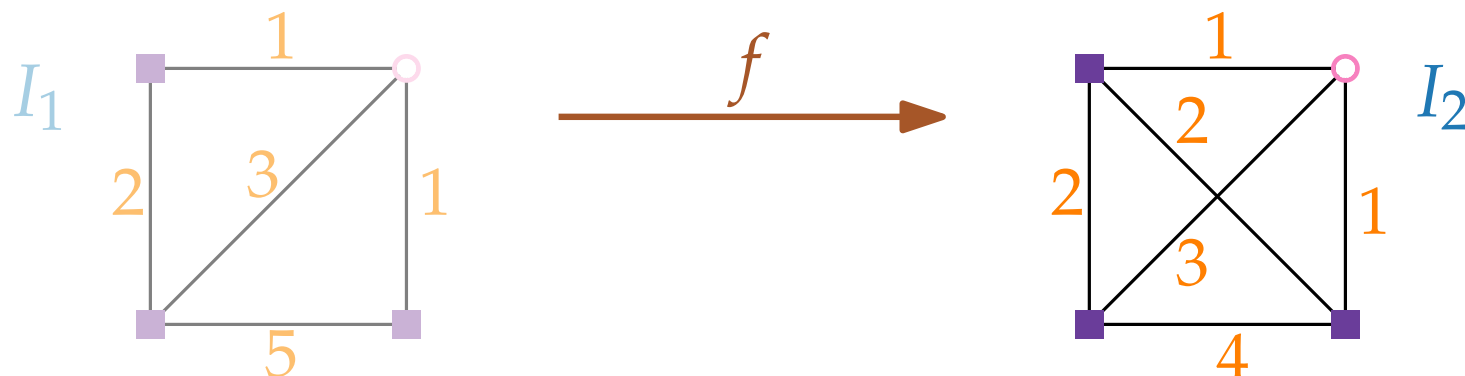
Proof. (1) Mapping $f: I_1 \longrightarrow I_2$

Instance I_1 of STEINERTREE: Graph $G_1 = (V, E_1)$, edge weights c_1 , partition $V = T \cup S$

Metric instance $I_2 := f(I_1)$: Complete graph $G_2 = (V, E_2)$, partition T, S as in I_1

$c_2(u, v) :=$ Length of shortest u - v -path in G_1

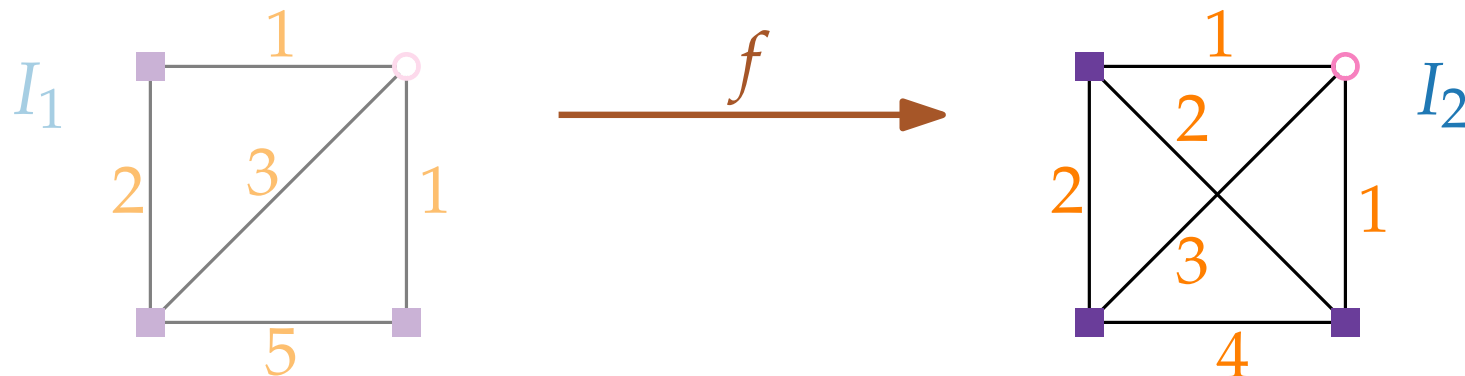
$c_2(u, v) \leq c_1(u, v)$ for all $(u, v) \in E$



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

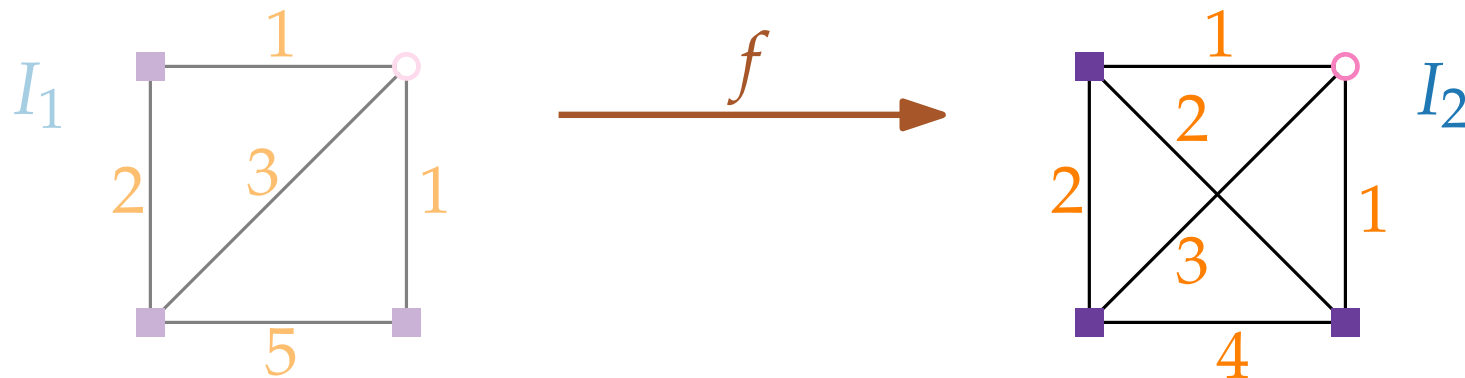


METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

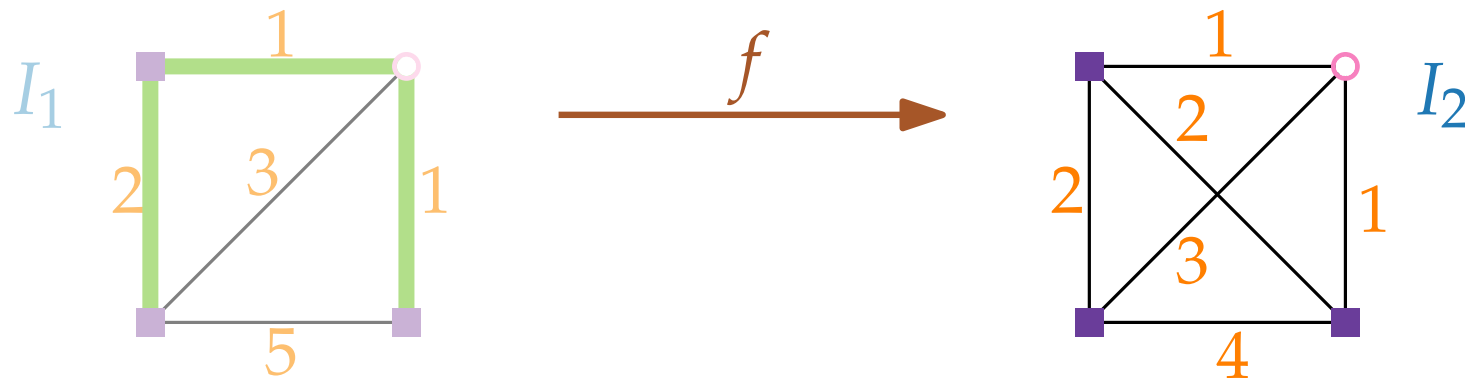


METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1



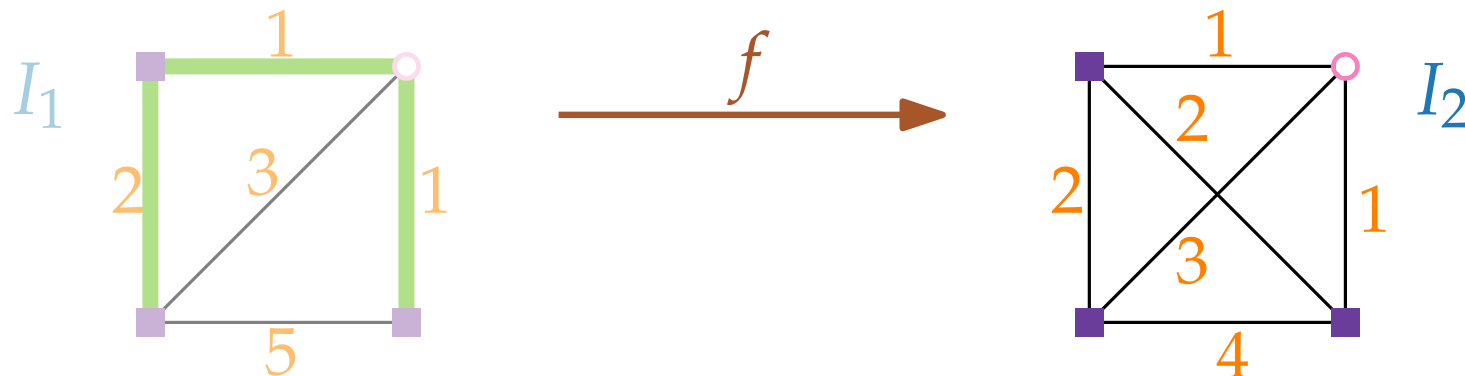
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same



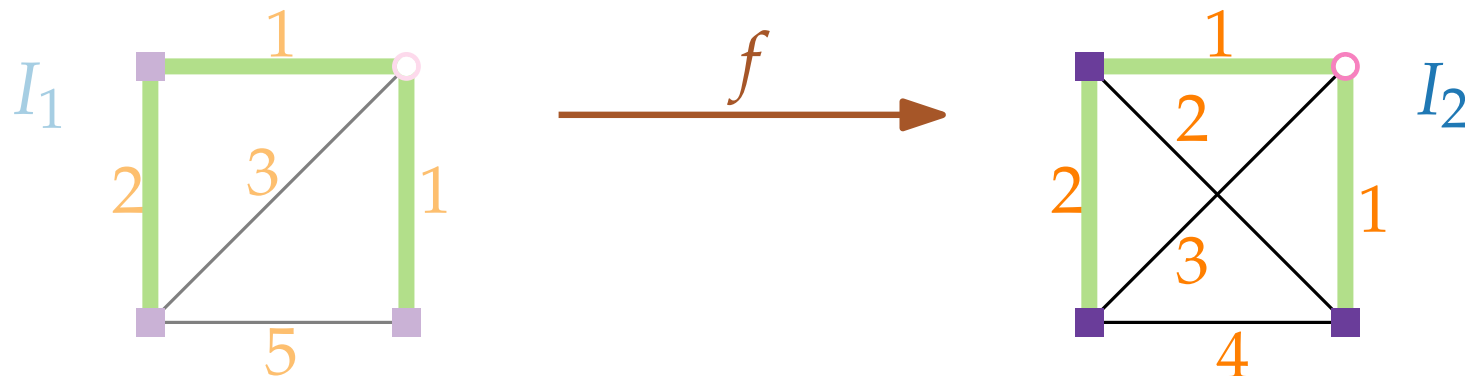
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same



METRICSTEINERTREE

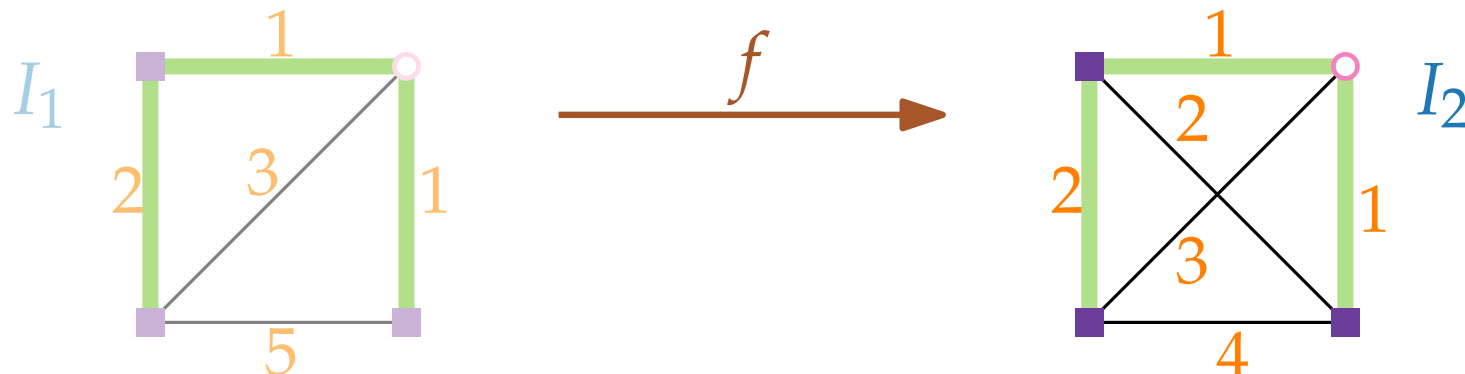
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same

$\text{OPT}(I_2)$



METRICSTEINERTREE

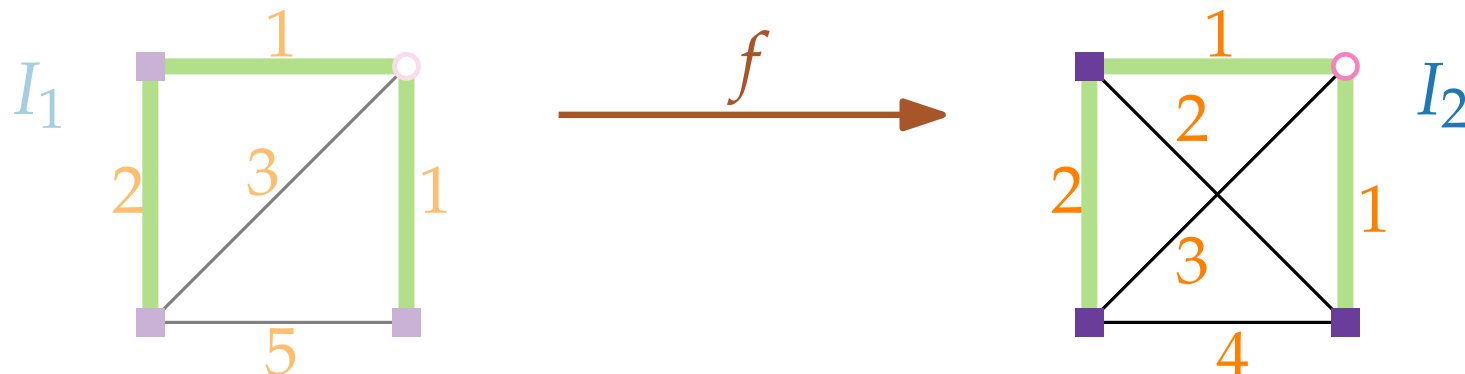
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same

$\text{OPT}(I_2) \leq c_2(B^*)$



METRICSTEINERTREE

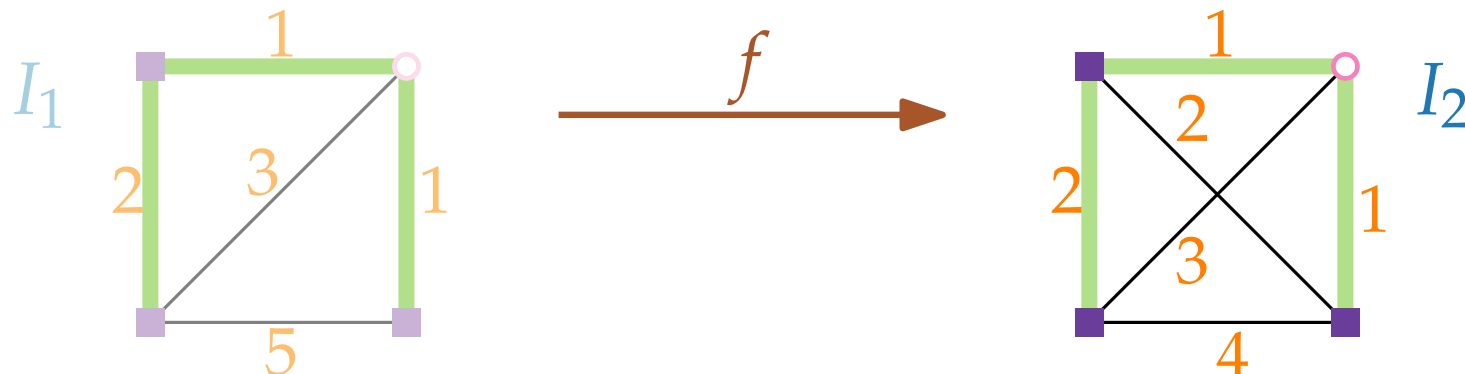
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same

$$\text{OPT}(I_2) \leq c_2(B^*) \leq c_1(B^*)$$



METRICSTEINERTREE

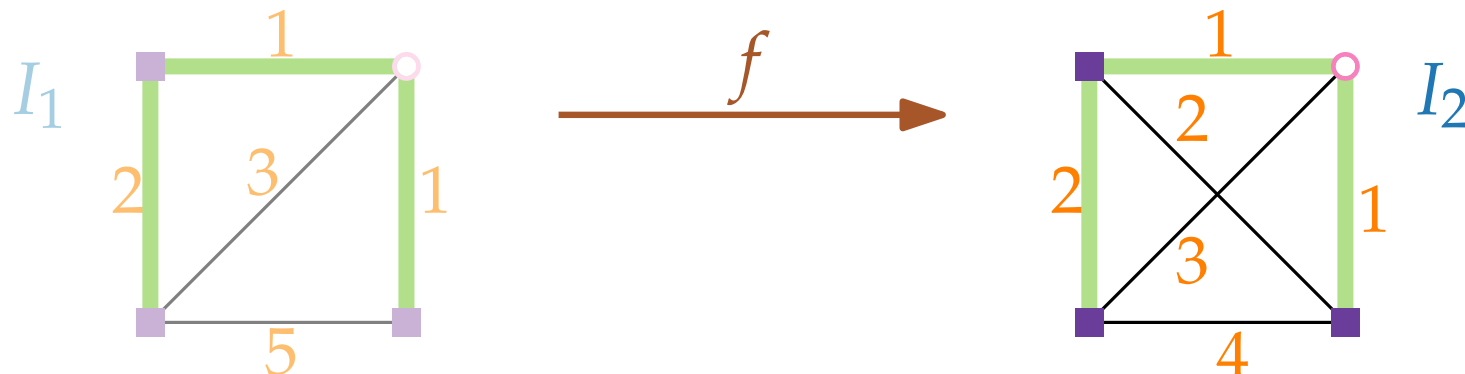
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (2) $\text{OPT}(I_2) \leq \text{OPT}(I_1)$

Let B^* be optimal Steiner tree for I_1

B^* is also a feasible solution for I_2 , since $E_1 \subseteq E_2$ and the vertex sets V, T, S are the same

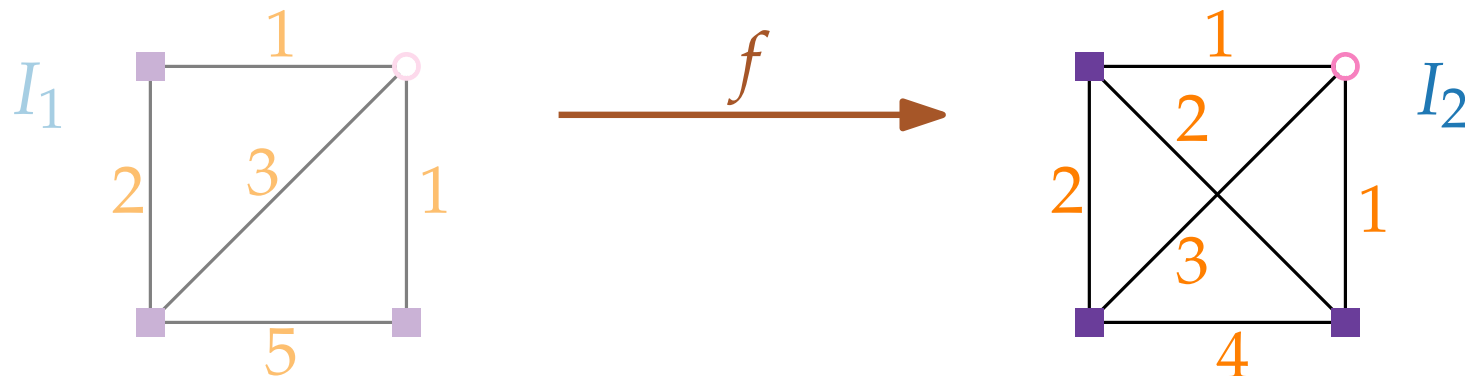
$$\text{OPT}(I_2) \leq c_2(B^*) \leq c_1(B^*) = \text{OPT}(I_1)$$



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g $s \longleftarrow g \longleftarrow t$

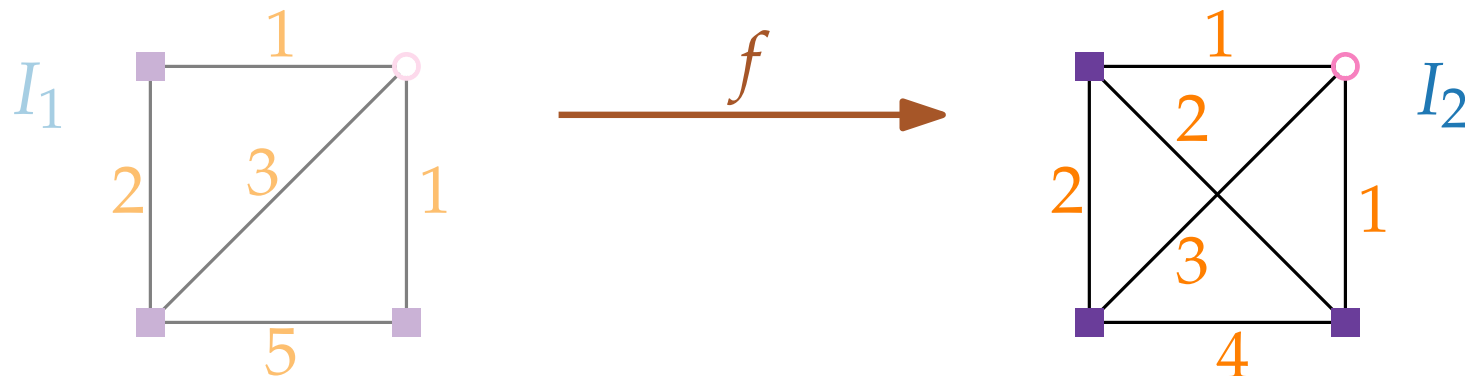


METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

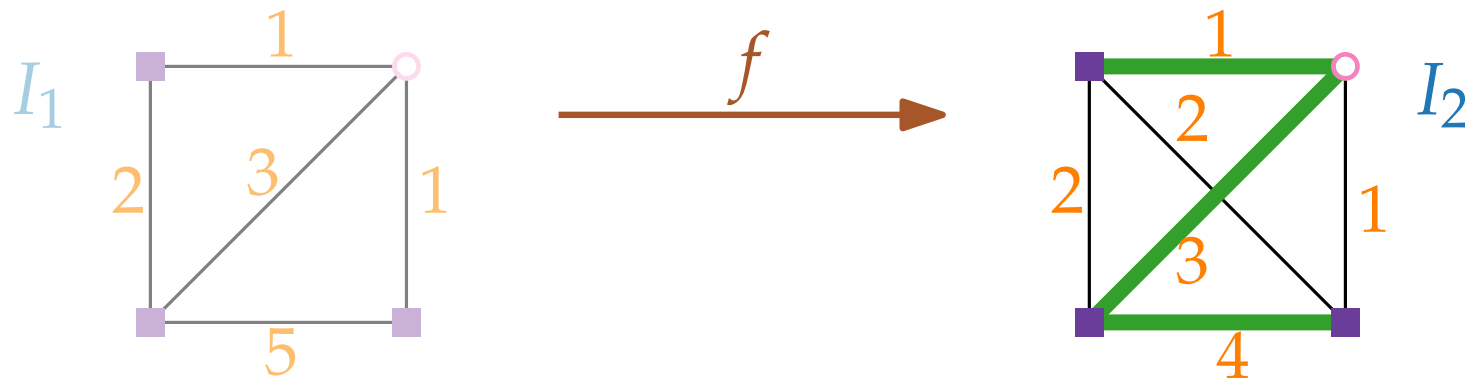


METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2



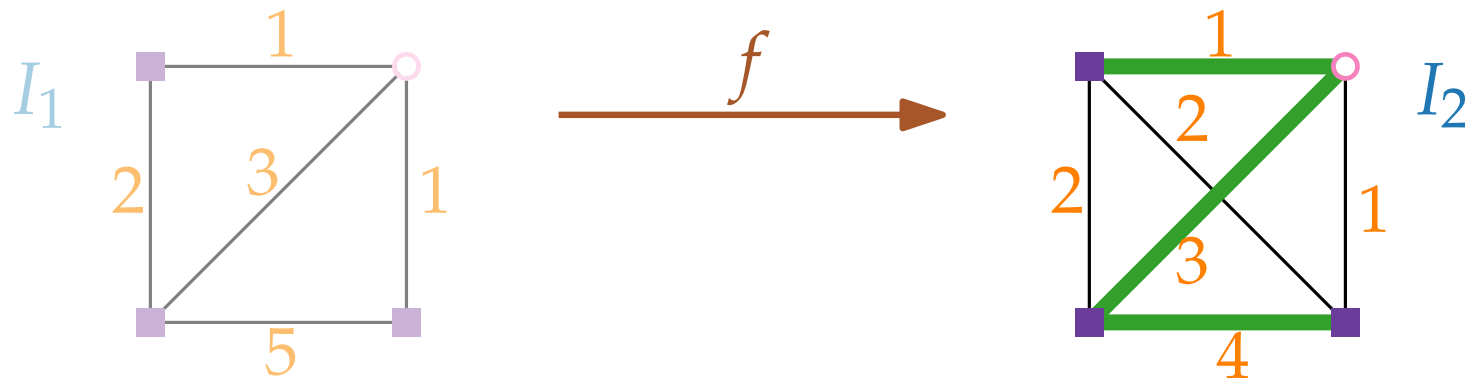
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .



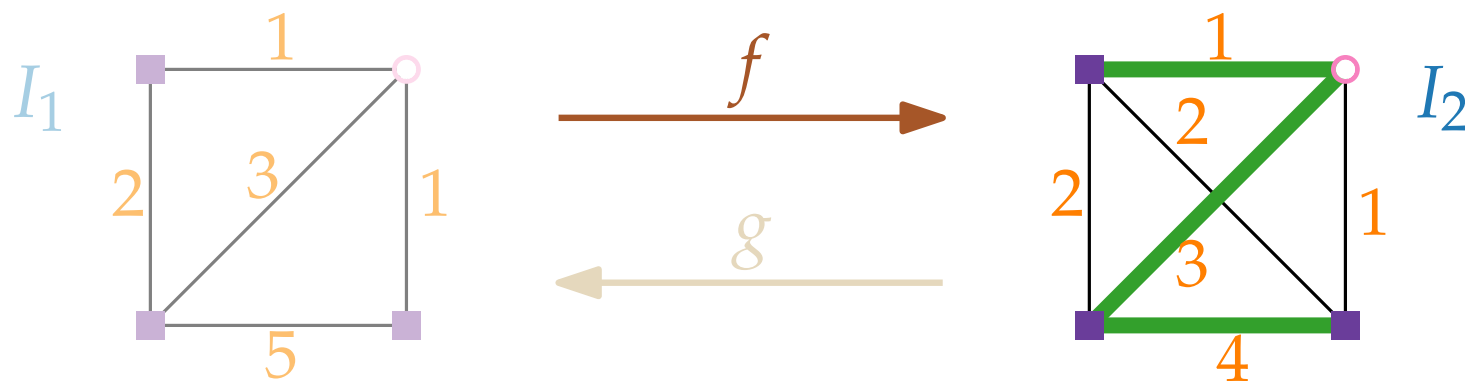
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .



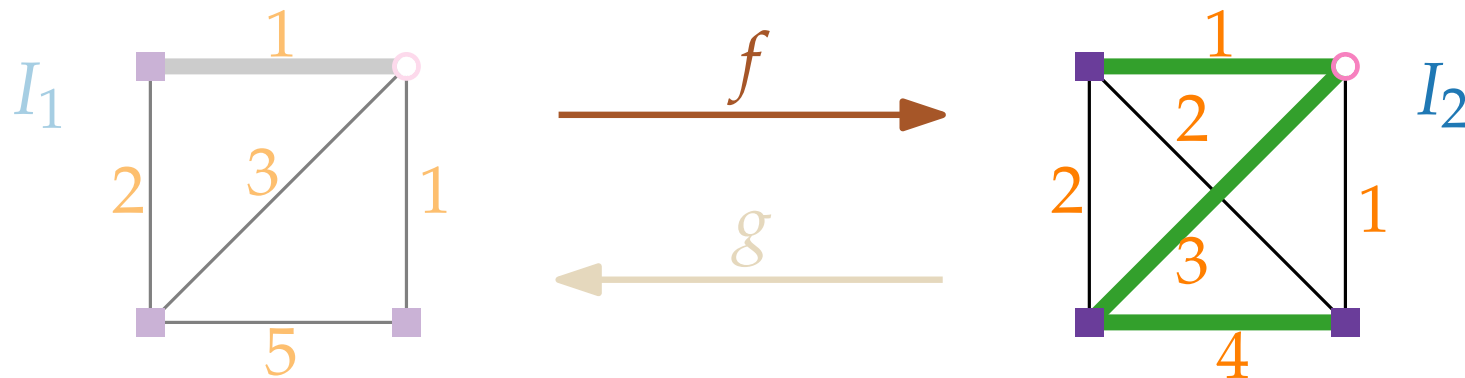
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .



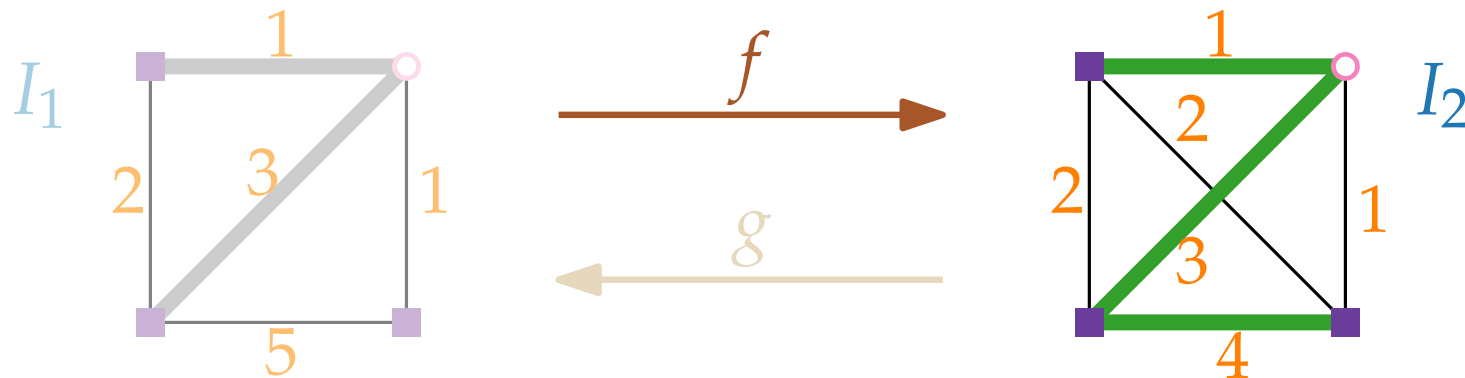
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .



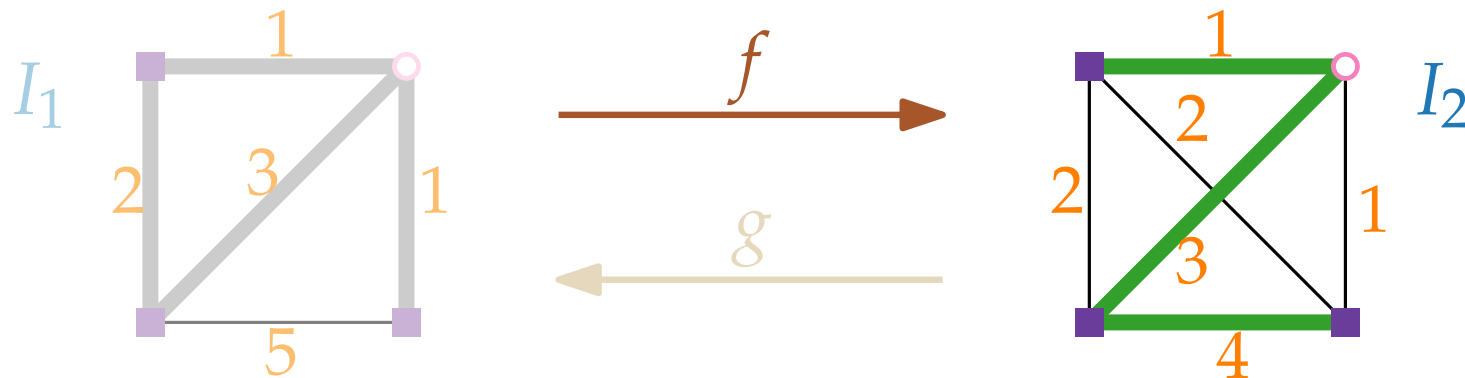
METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .



METRICSTEINERTREE

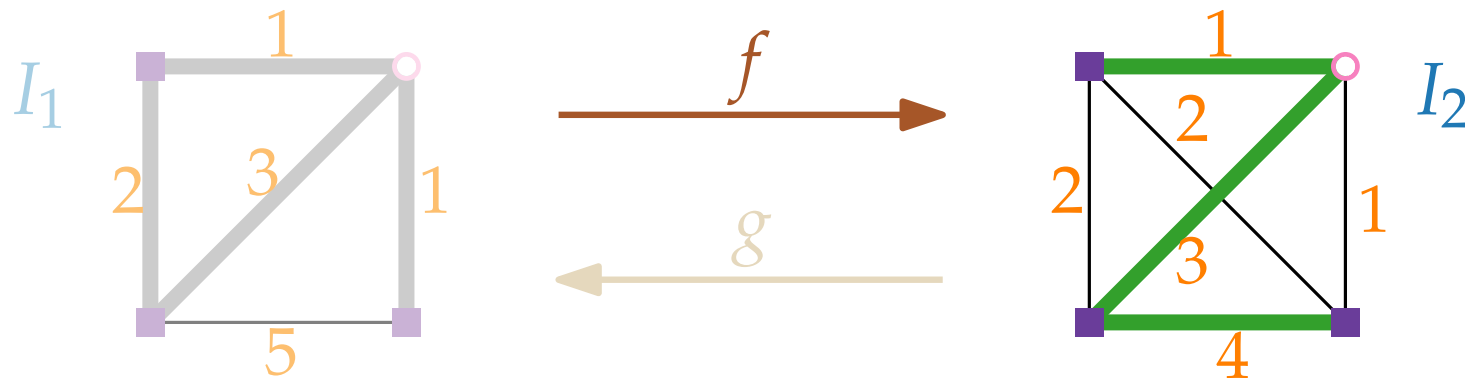
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$$c_1(G'_1) \leq c_2(B_2)$$



METRICSTEINERTREE

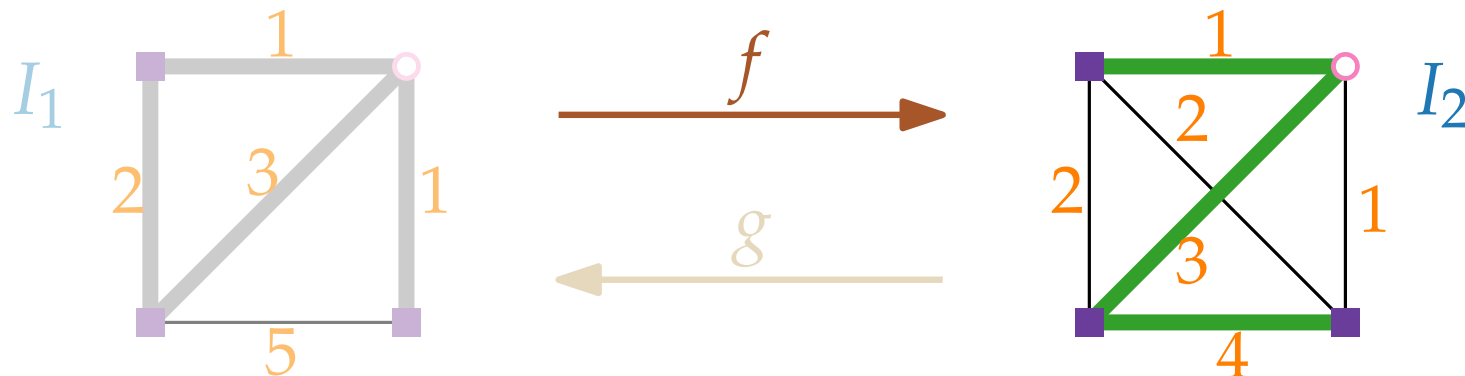
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals



METRICSTEINERTREE

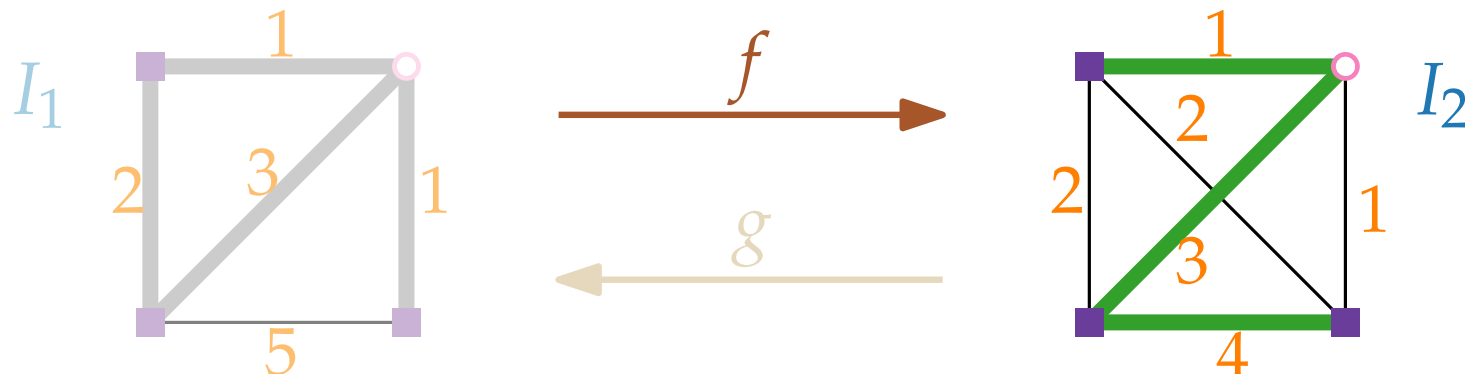
Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals; not nec. a tree



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

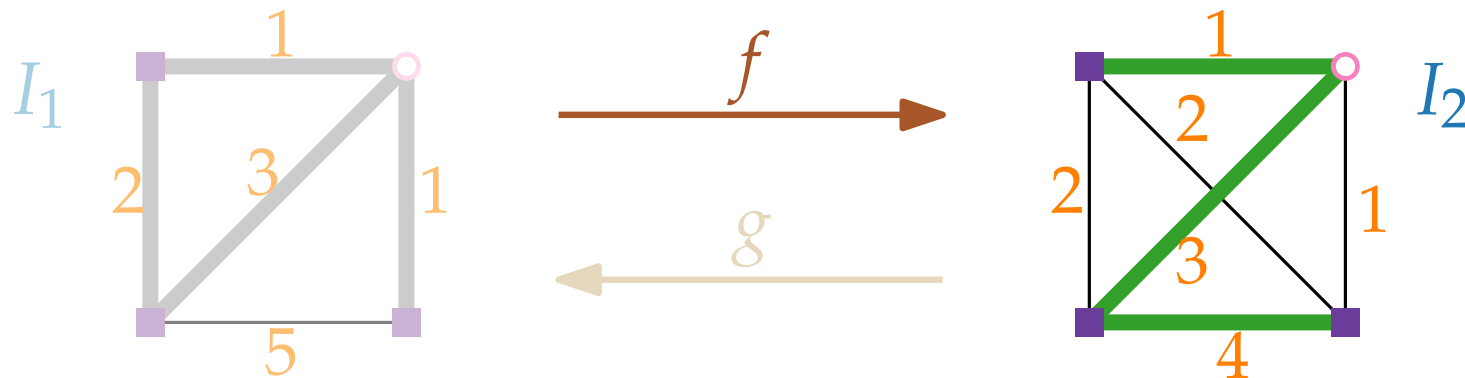
Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals; not nec. a tree

Consider spanning tree B_1 of G'_1



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

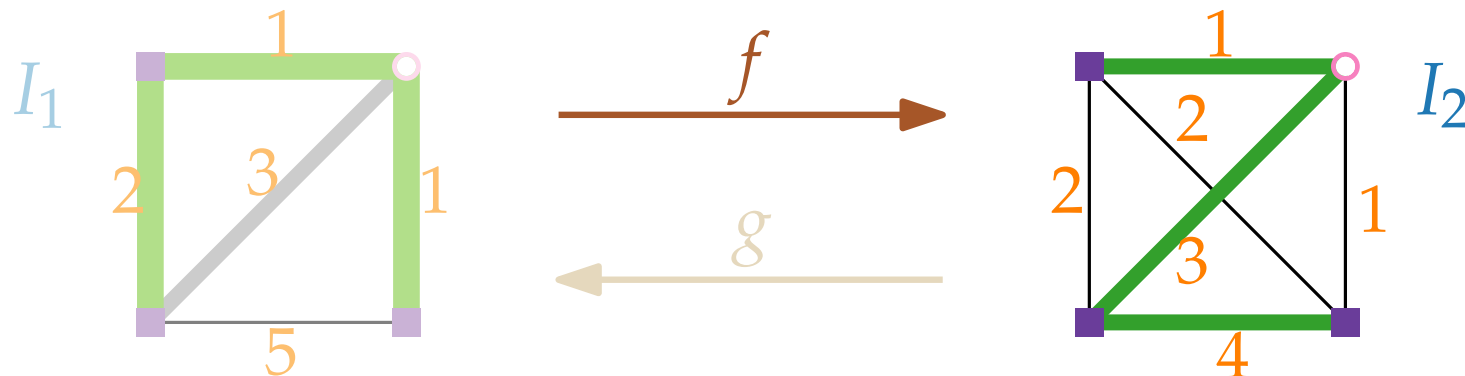
Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals; not nec. a tree

Consider spanning tree B_1 of G'_1



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

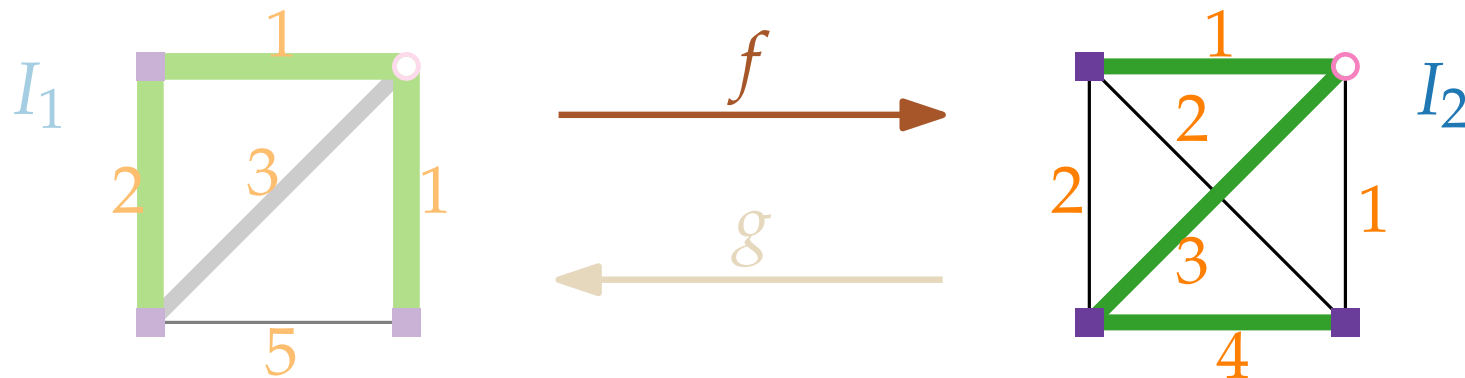
Proof. (3) Mapping g 

Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals; not nec. a tree

Consider spanning tree B_1 of $G'_1 \rightsquigarrow$ Steiner tree B_1 of G_1



METRICSTEINERTREE

Theorem. There is an approximation preserving reduction from STEINERTREE to METRICSTEINERTREE.

Proof. (3) Mapping g 

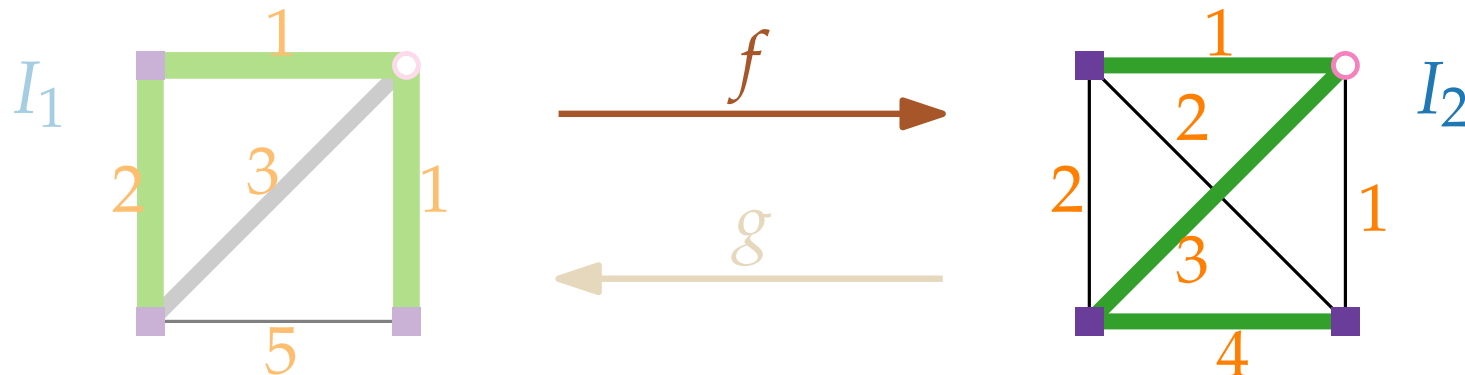
Let B_2 be Steiner tree of G_2

Construct $G'_1 \subseteq G_1$ from B_2 by replacing each edge (u, v) of B_2 by a shortest $u-v$ -path in G_1 .

$c_1(G'_1) \leq c_2(B_2)$; G'_1 connects all terminals; not nec. a tree

Consider spanning tree B_1 of $G'_1 \rightsquigarrow$ Steiner tree B_1 of G_1

$c_1(B_1) \leq c_1(G'_1) \leq c_2(B_2)$



Approximation Algorithms

Lecture 3:

STEINERTREE and MULTIWAYCUT

Part IV:

2-Approximation for STEINERTREE

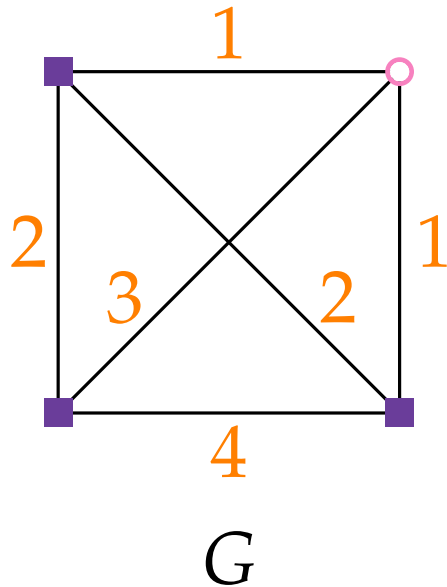
2-Approximation for STEINERTREE

2-Approximation for STEINERTREE

Theorem. For an instance of METRICSTEINERTREE, let B be a minimum spanning tree (MST) of the subgraph $G[T]$ induced by the terminal set T . Then $c(B) \leq 2 \cdot \text{OPT}$.

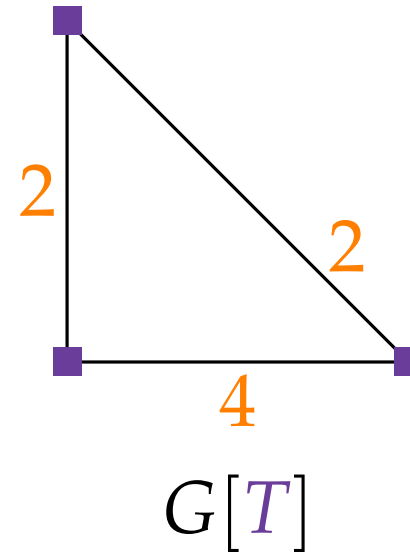
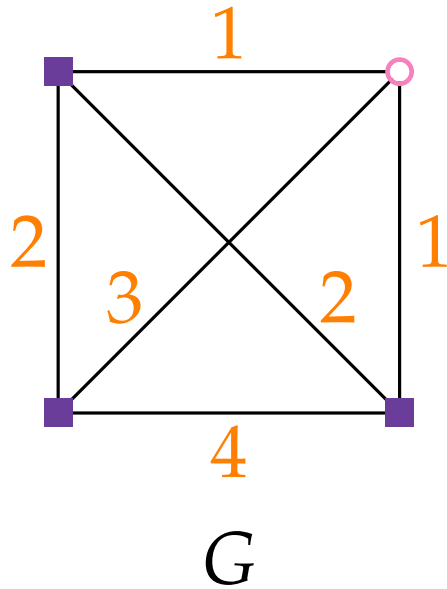
2-Approximation for STEINERTREE

Theorem. For an instance of METRICSTEINERTREE, let B be a minimum spanning tree (MST) of the subgraph $G[T]$ induced by the terminal set T . Then $c(B) \leq 2 \cdot \text{OPT}$.



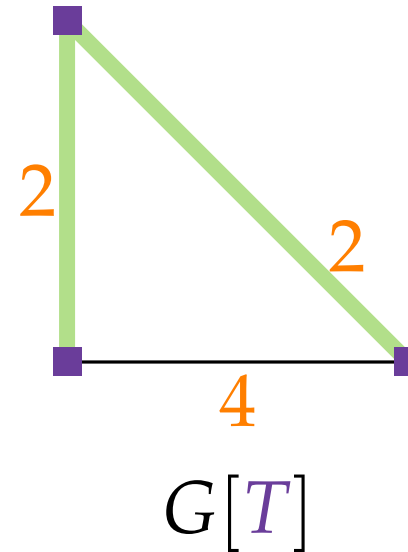
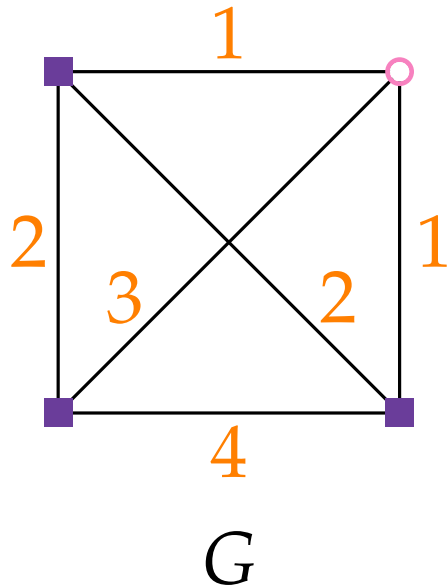
2-Approximation for STEINERTREE

Theorem. For an instance of METRICSTEINERTREE, let B be a minimum spanning tree (MST) of the subgraph $G[T]$ induced by the terminal set T . Then $c(B) \leq 2 \cdot \text{OPT}$.



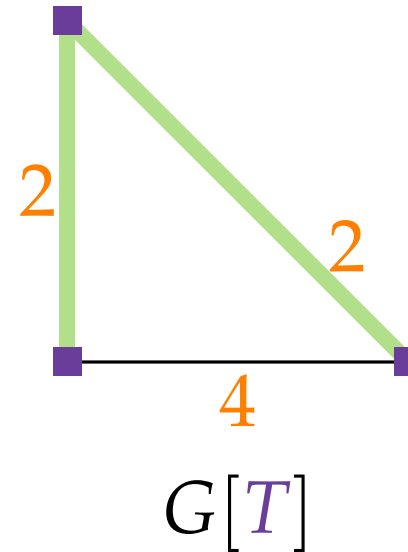
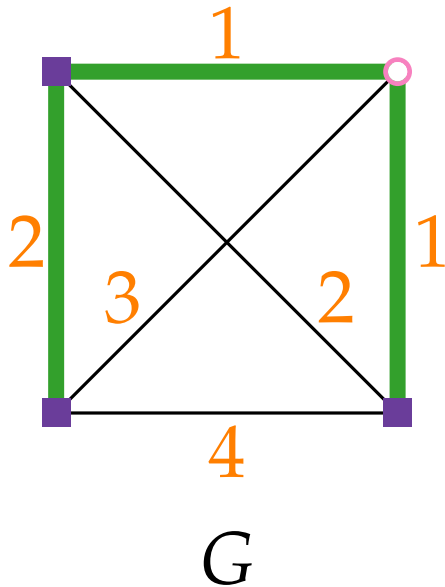
2-Approximation for STEINERTREE

Theorem. For an instance of METRICSTEINERTREE, let B be a minimum spanning tree (MST) of the subgraph $G[T]$ induced by the terminal set T . Then $c(B) \leq 2 \cdot \text{OPT}$.



2-Approximation for STEINERTREE

Theorem. For an instance of METRICSTEINERTREE, let B be a minimum spanning tree (MST) of the subgraph $G[T]$ induced by the terminal set T . Then $c(B) \leq 2 \cdot \text{OPT}$.

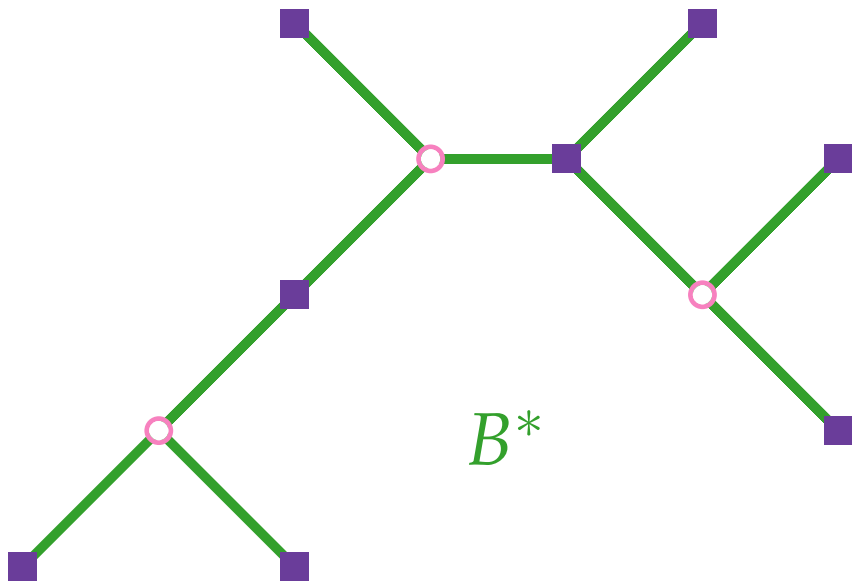


Proof of Approximation Factor

Consider optimal Steiner tree B^*

Proof of Approximation Factor

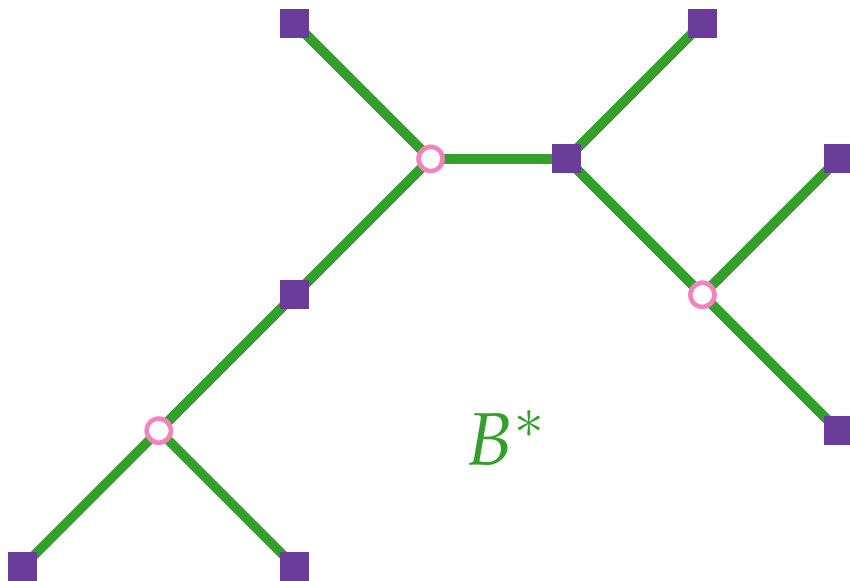
Consider optimal Steiner tree B^*



Proof of Approximation Factor

Consider optimal Steiner tree B^*

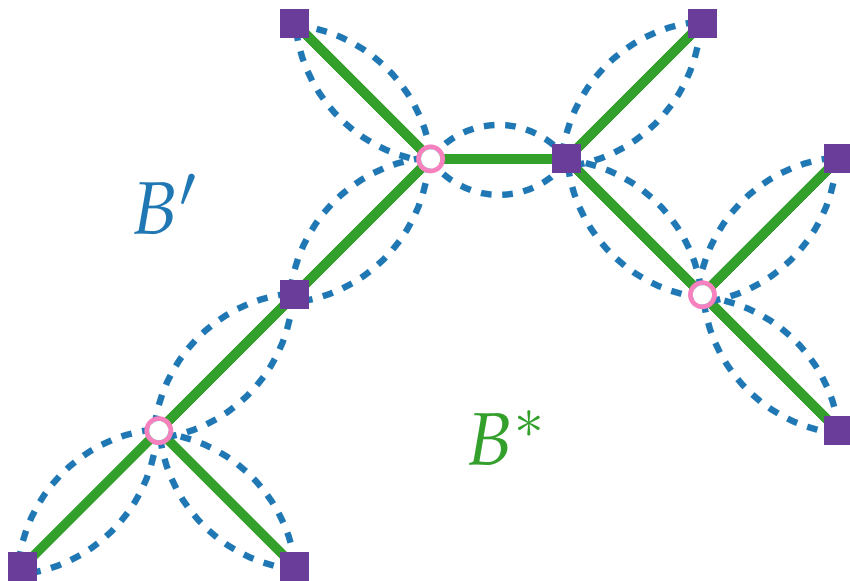
Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$



Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost
 $c(B') = 2 \cdot \text{OPT}$

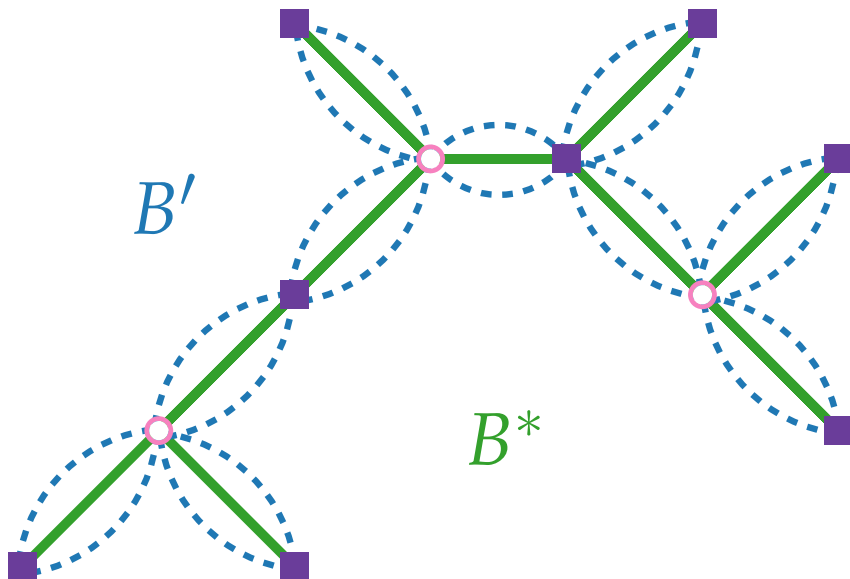


Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

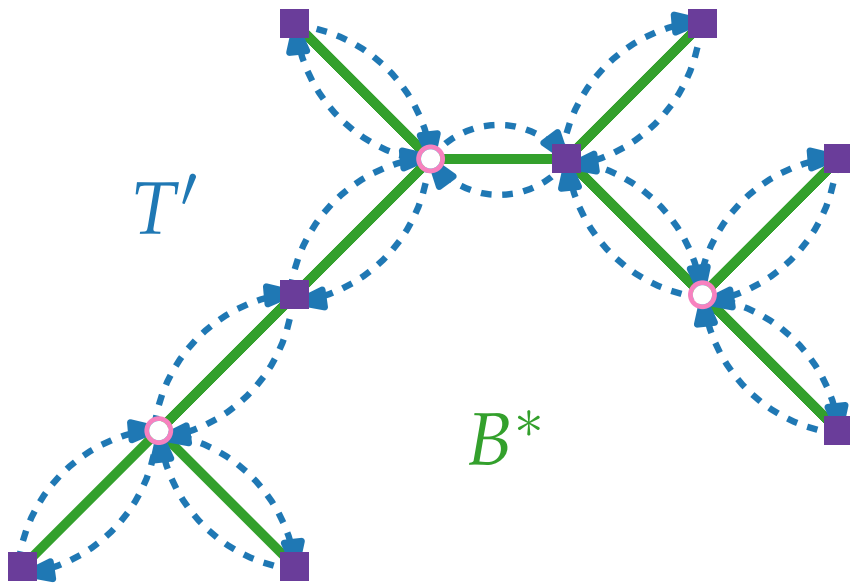


Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$



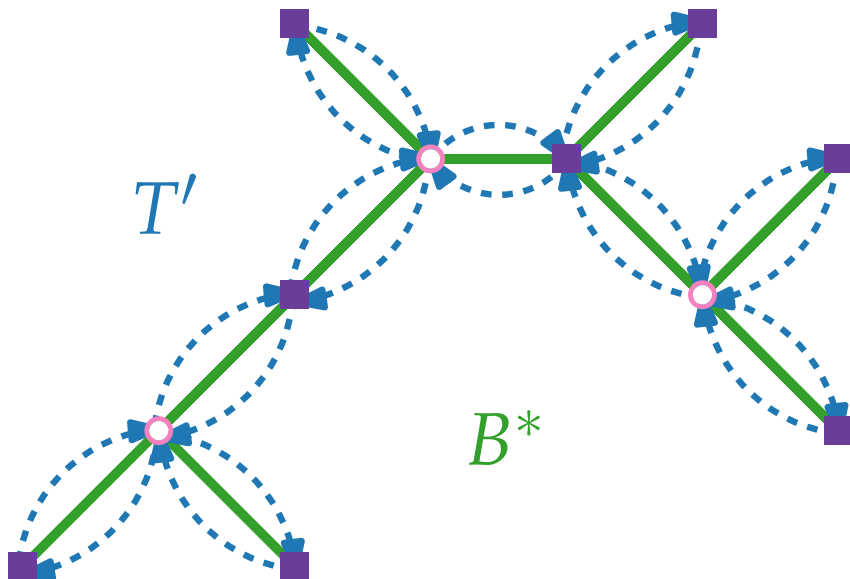
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



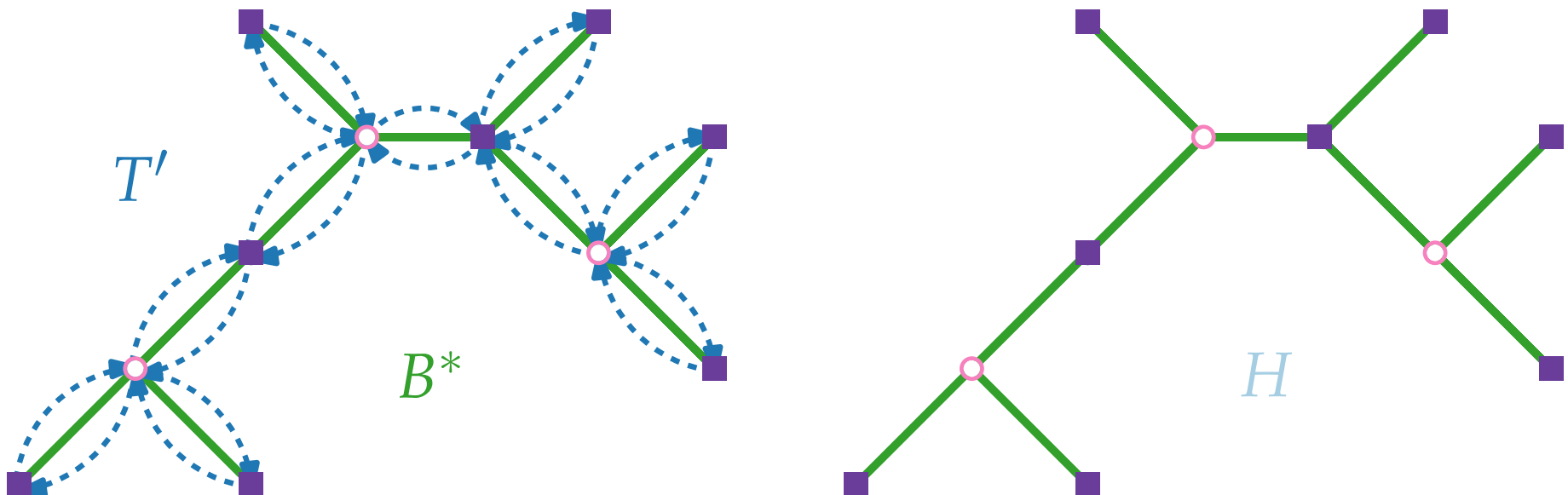
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



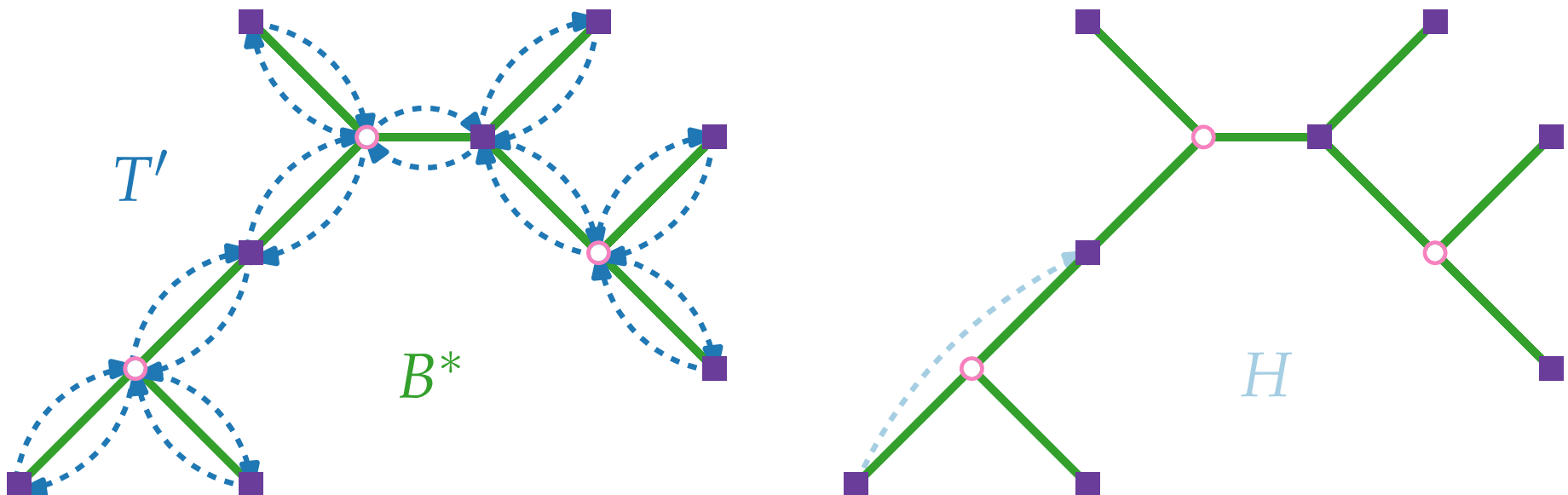
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



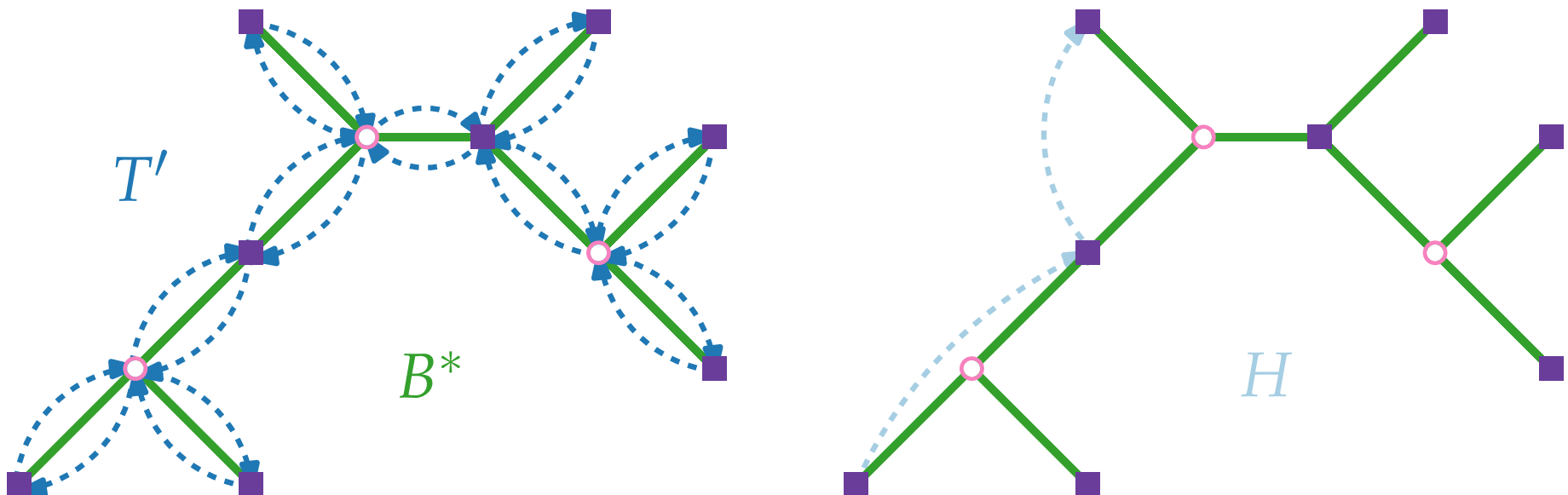
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



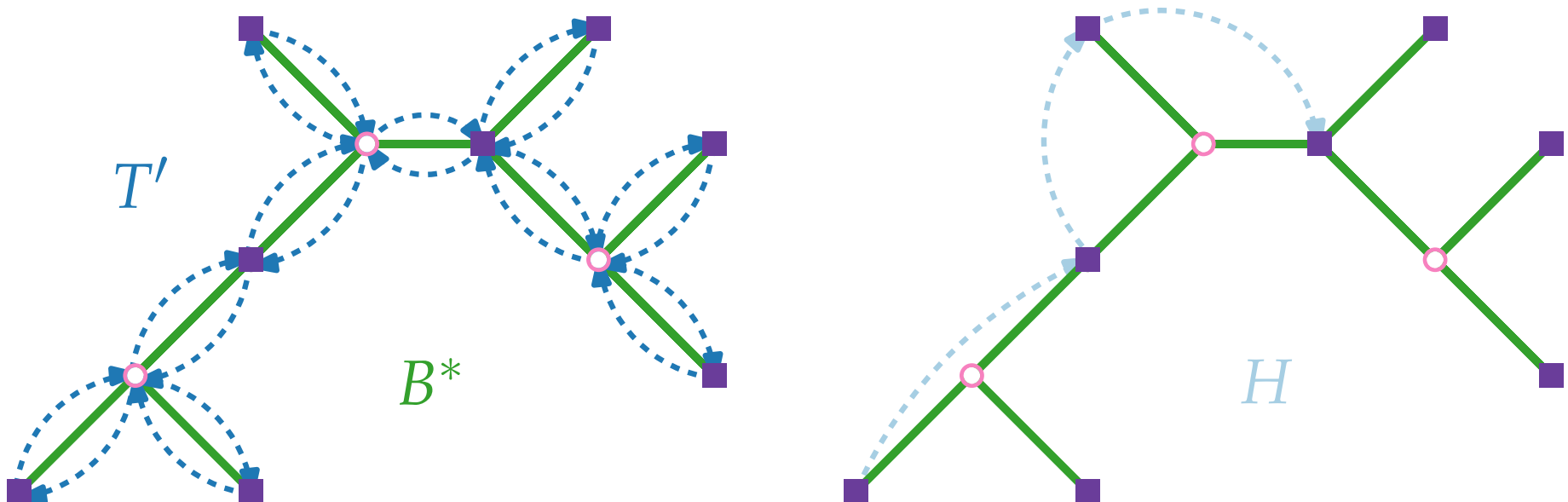
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



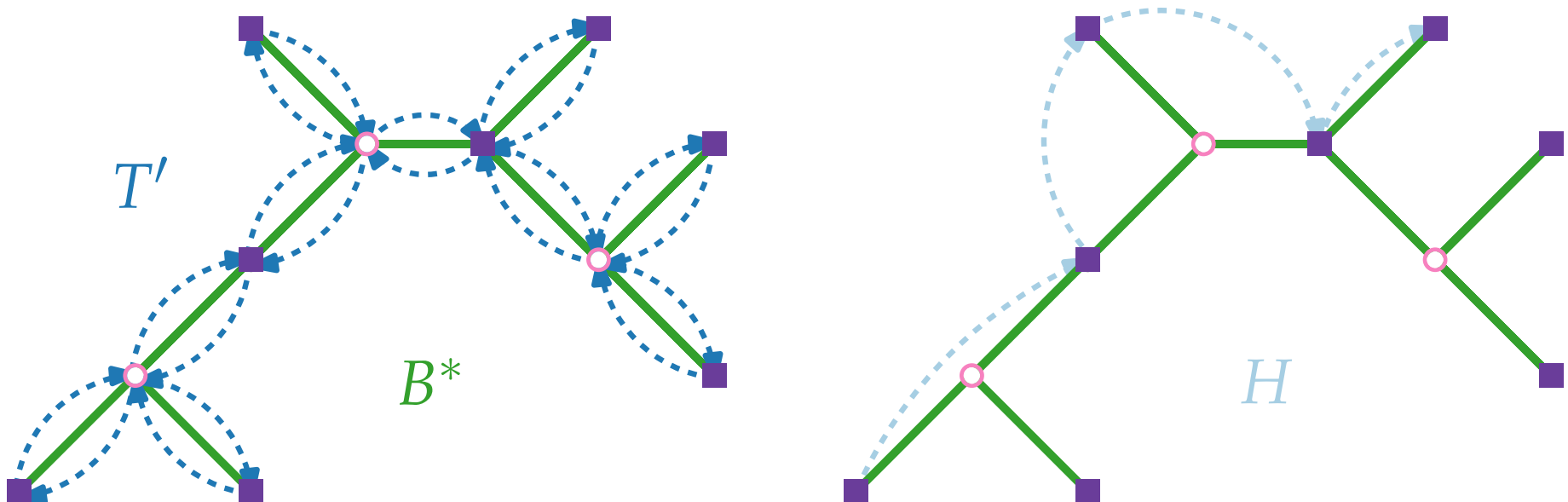
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



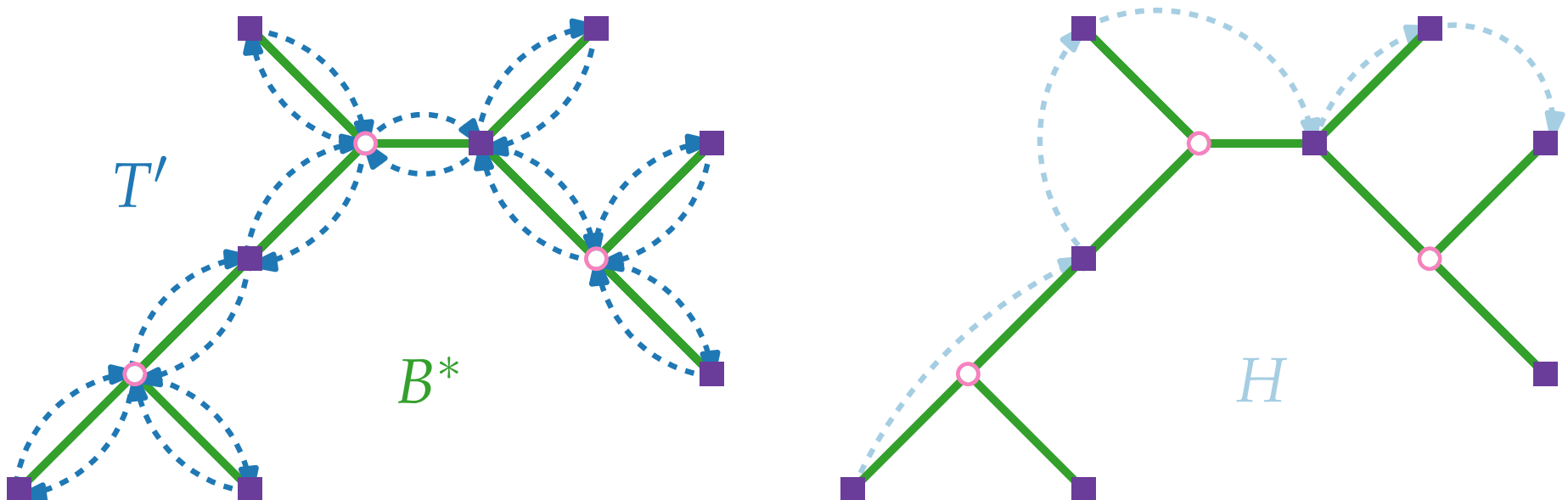
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



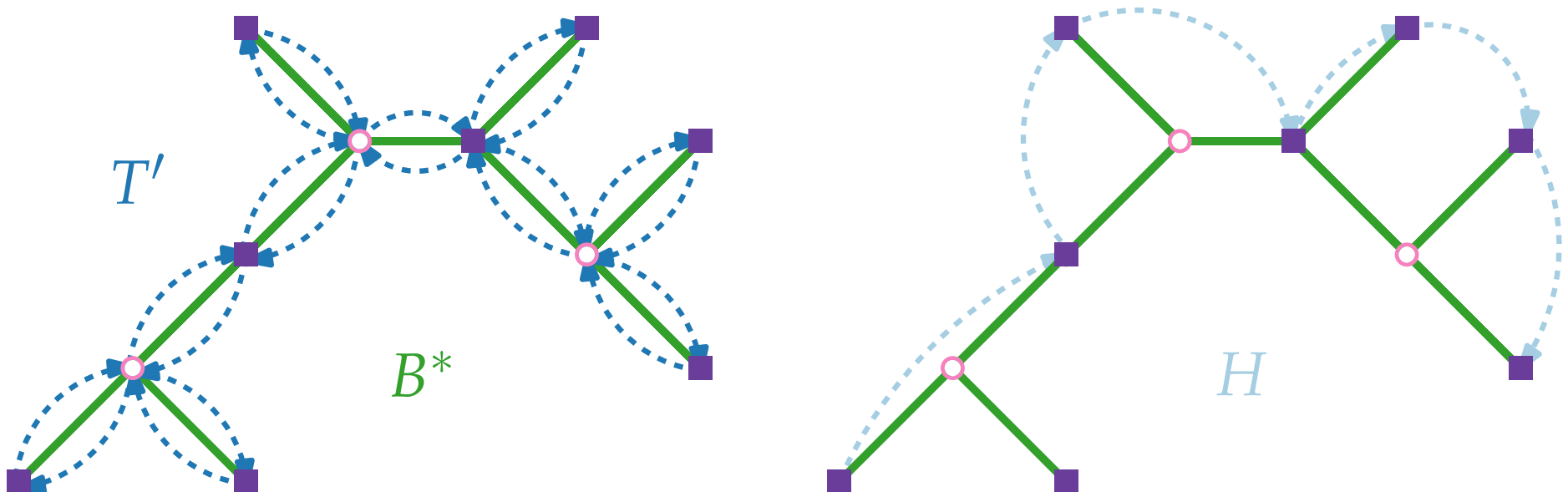
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



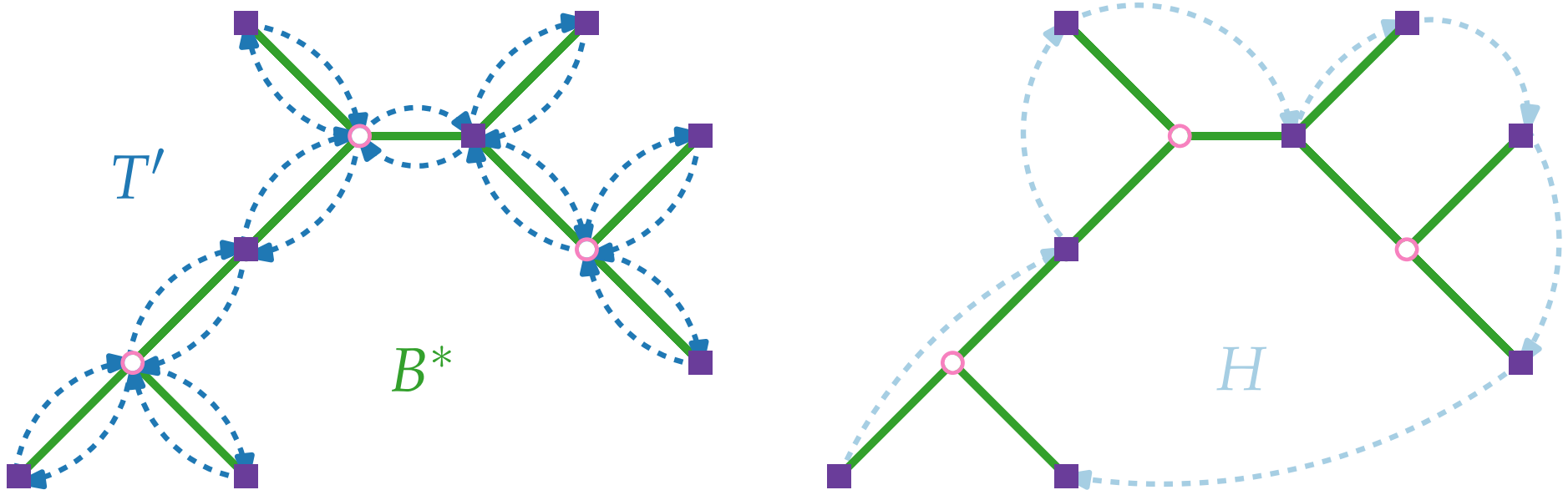
Proof of Approximation Factor

Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals



Proof of Approximation Factor

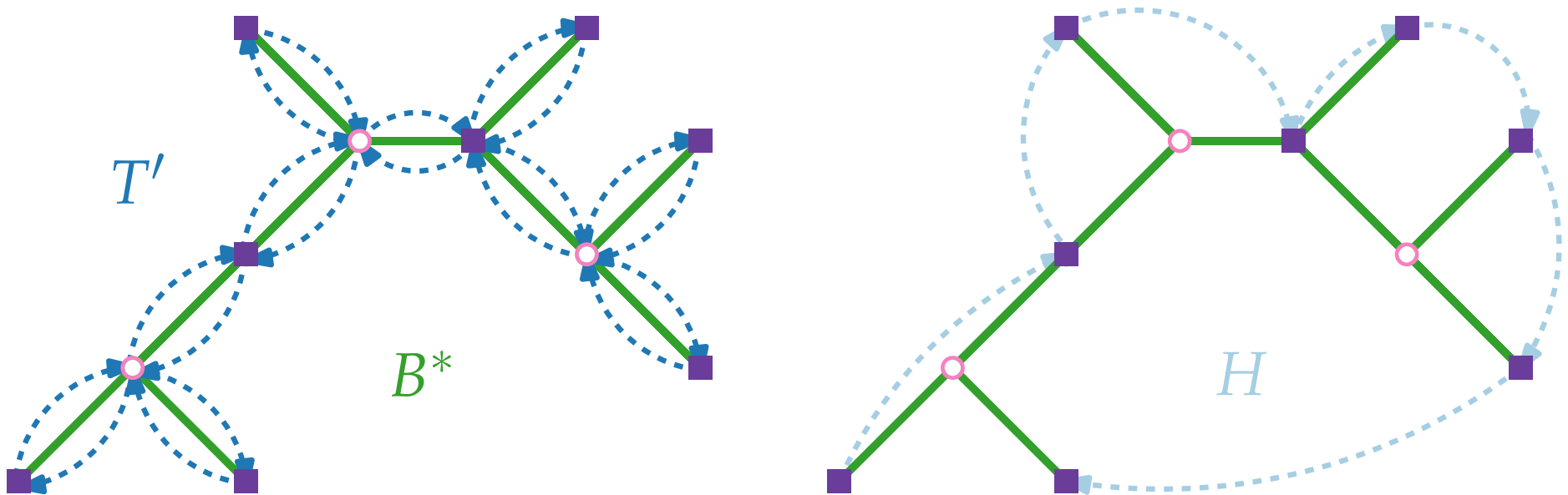
Consider optimal Steiner tree B^*

Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals

$\rightsquigarrow c(H) \leq c(T') = 2 \cdot \text{OPT}$, since G is metric



Proof of Approximation Factor

Consider optimal Steiner tree B^*

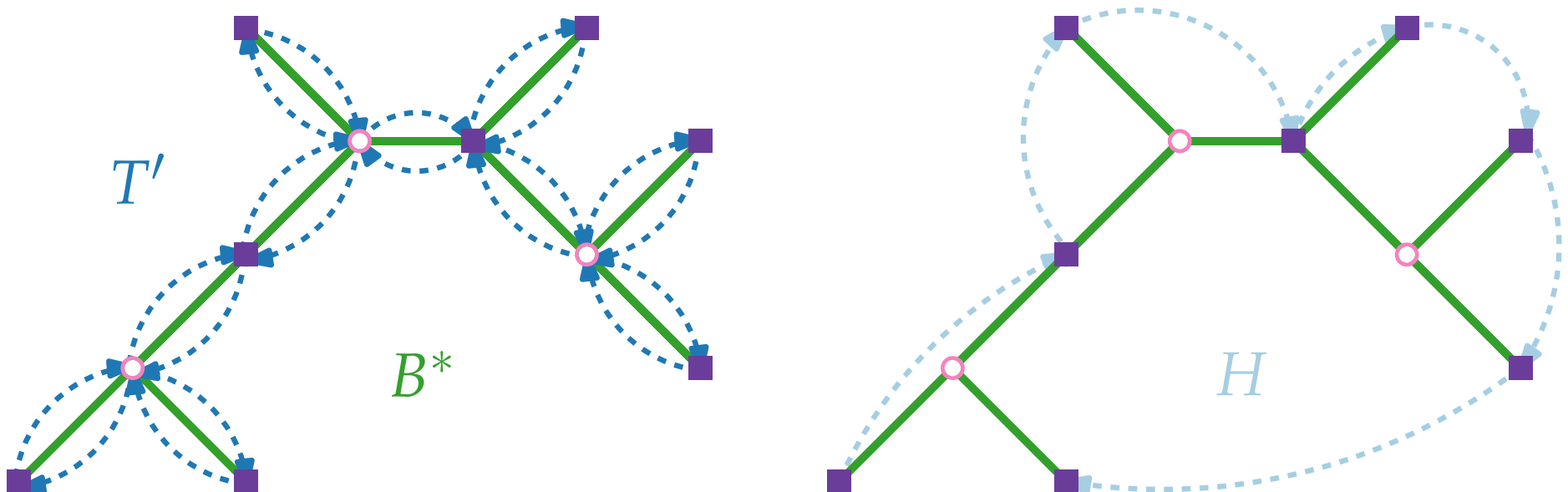
Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals

$\rightsquigarrow c(H) \leq c(T') = 2 \cdot \text{OPT}$, since G is metric

MST B of $G[T]$ has $c(B) \leq c(H) \leq 2 \cdot \text{OPT}$,



Proof of Approximation Factor

Consider optimal Steiner tree B^*

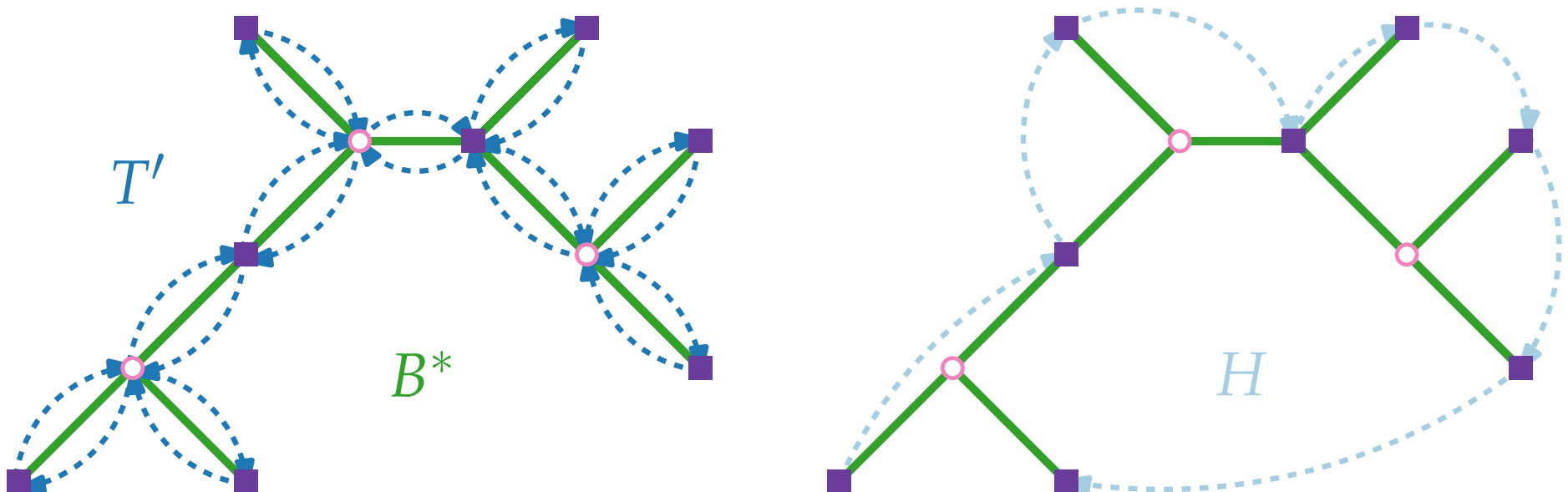
Duplicate all edges in B^* \rightsquigarrow Eulerian (multi-)graph B' with cost $c(B') = 2 \cdot \text{OPT}$

Find an Eulerian tour T' in B' $\rightsquigarrow c(T') = c(B') = 2 \cdot \text{OPT}$

Find a Hamiltonian path H in $G[T]$ by “short-cutting” Steiner vertices and previously visited terminals

$\rightsquigarrow c(H) \leq c(T') = 2 \cdot \text{OPT}$, since G is metric

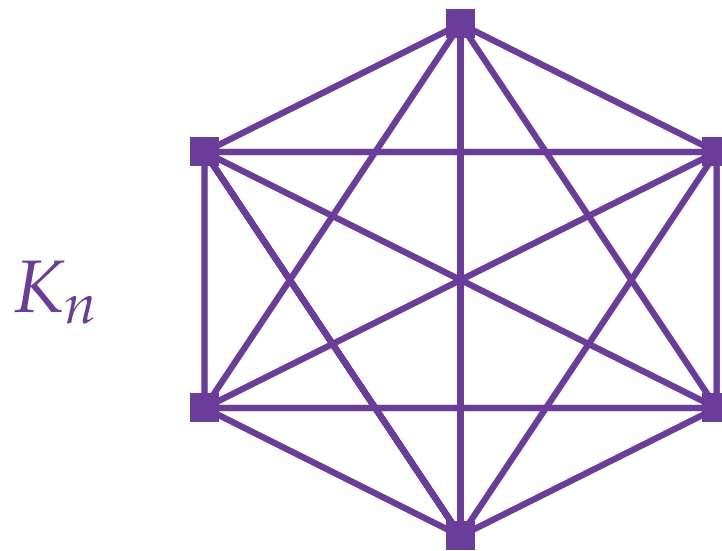
MST B of $G[T]$ has $c(B) \leq c(H) \leq 2 \cdot \text{OPT}$, since H is a spanning tree of $G[T]$



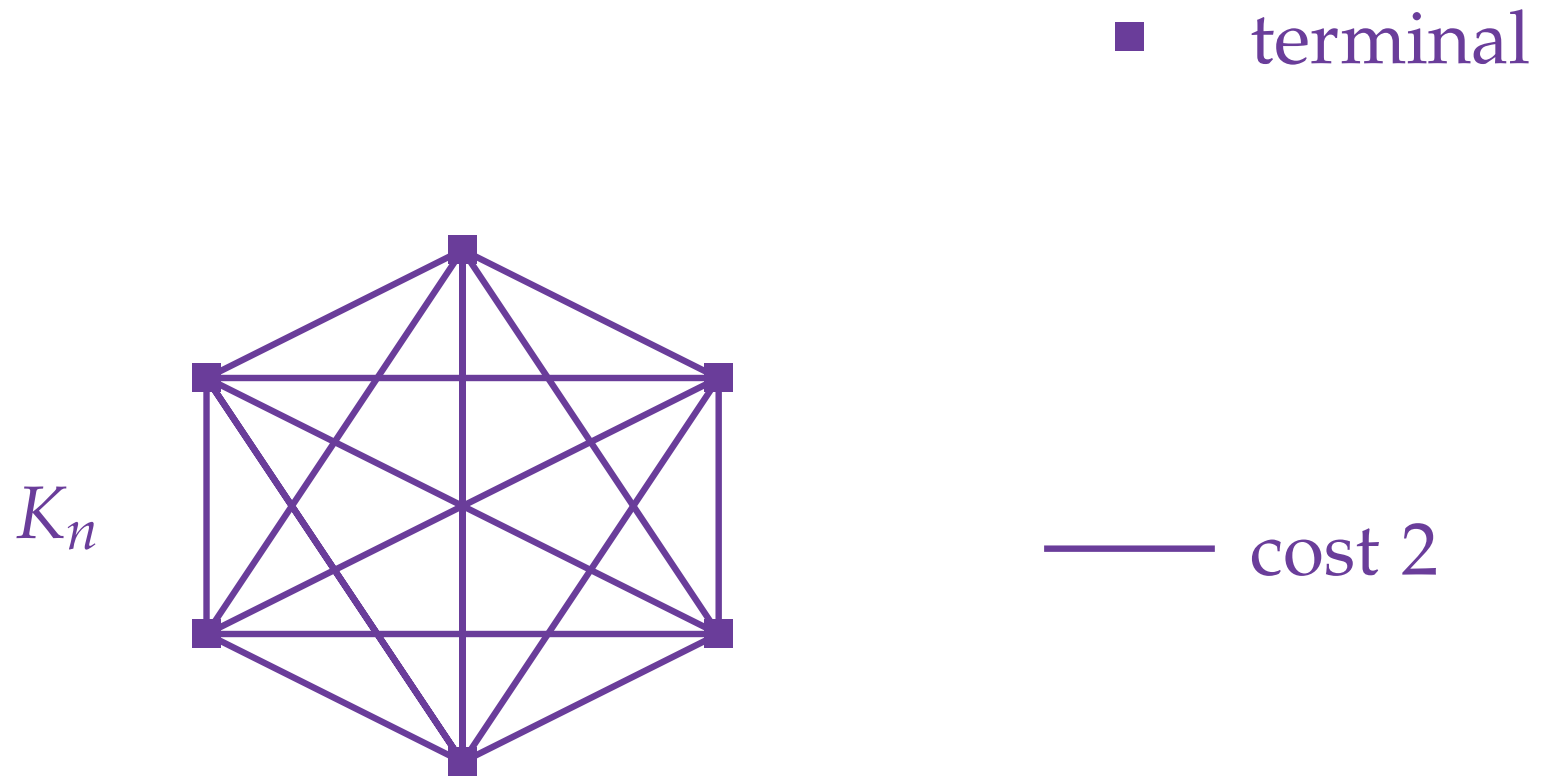
Analysis Sharp?

Analysis Sharp?

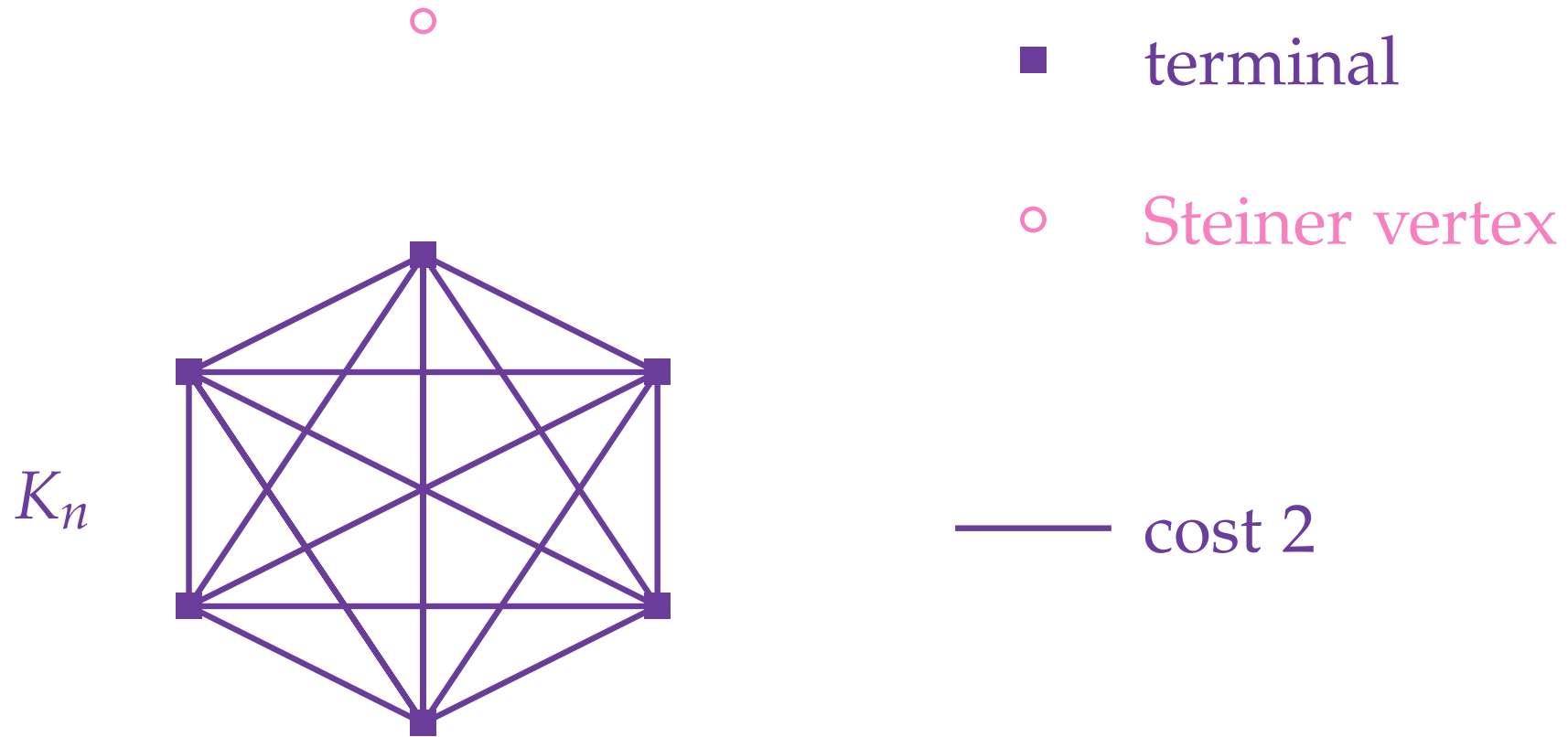
- terminal



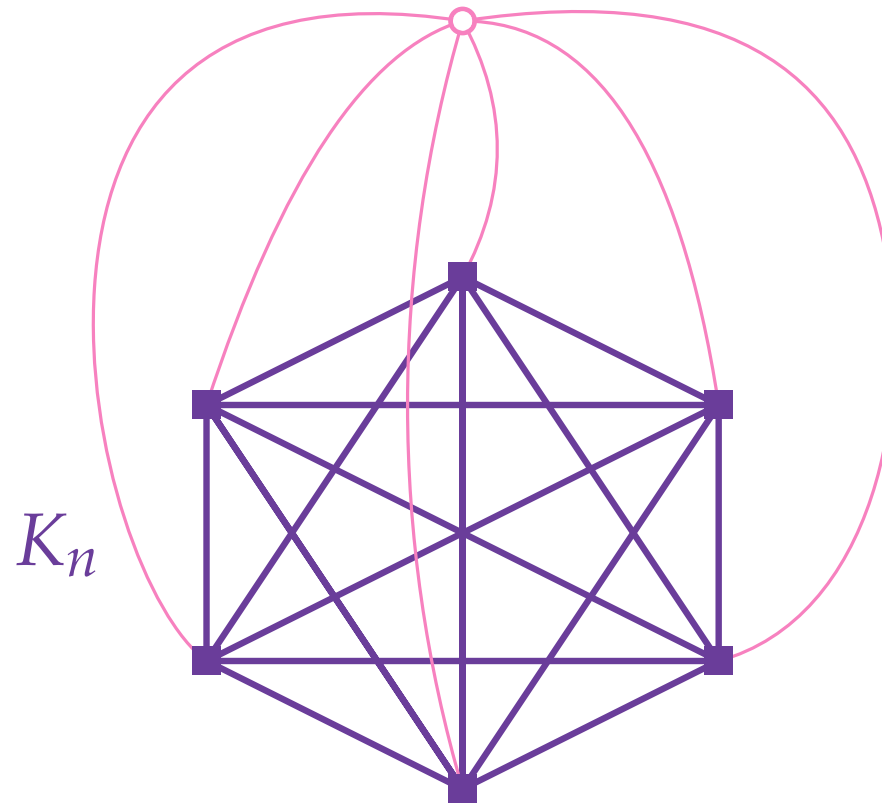
Analysis Sharp?



Analysis Sharp?



Analysis Sharp?

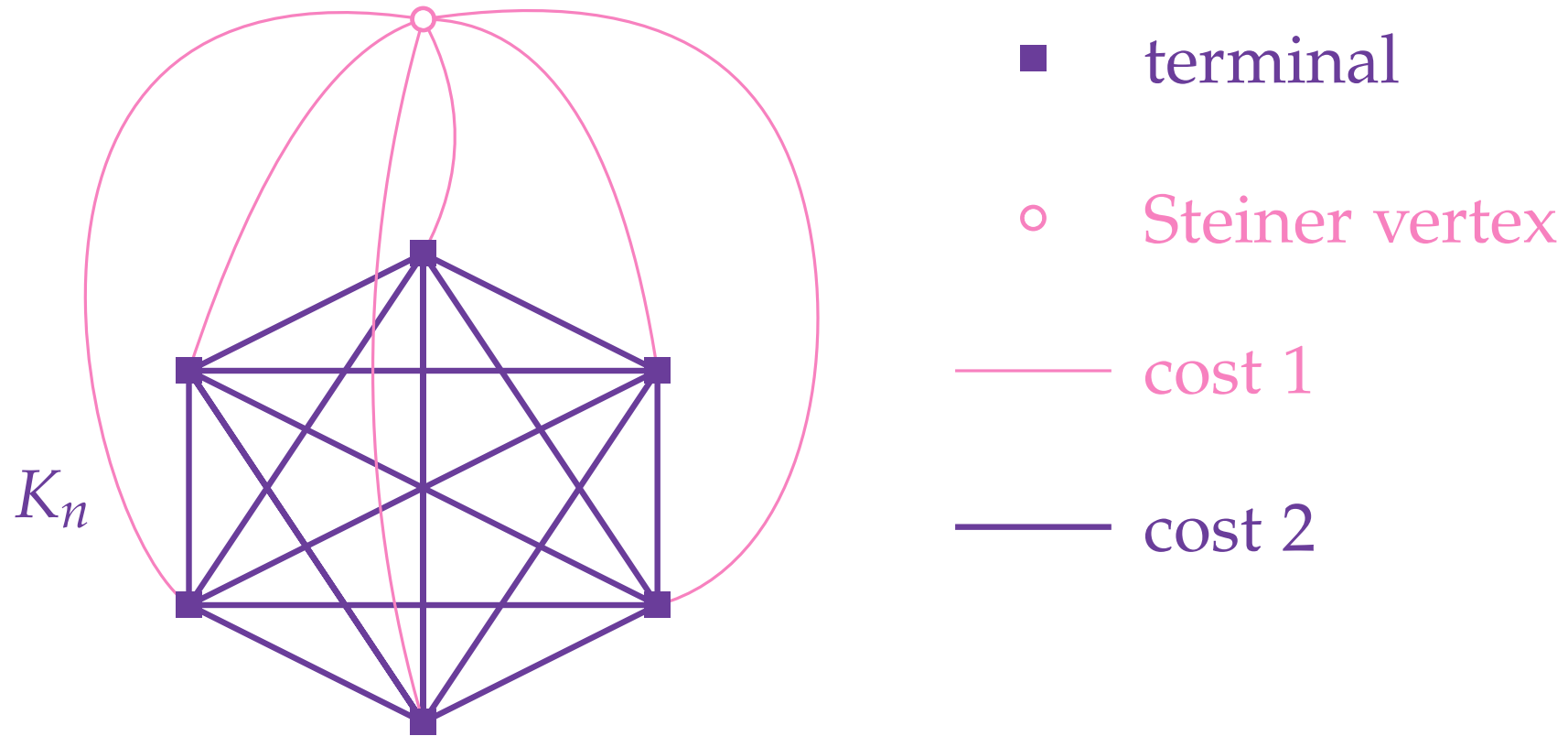


■ terminal

○ Steiner vertex

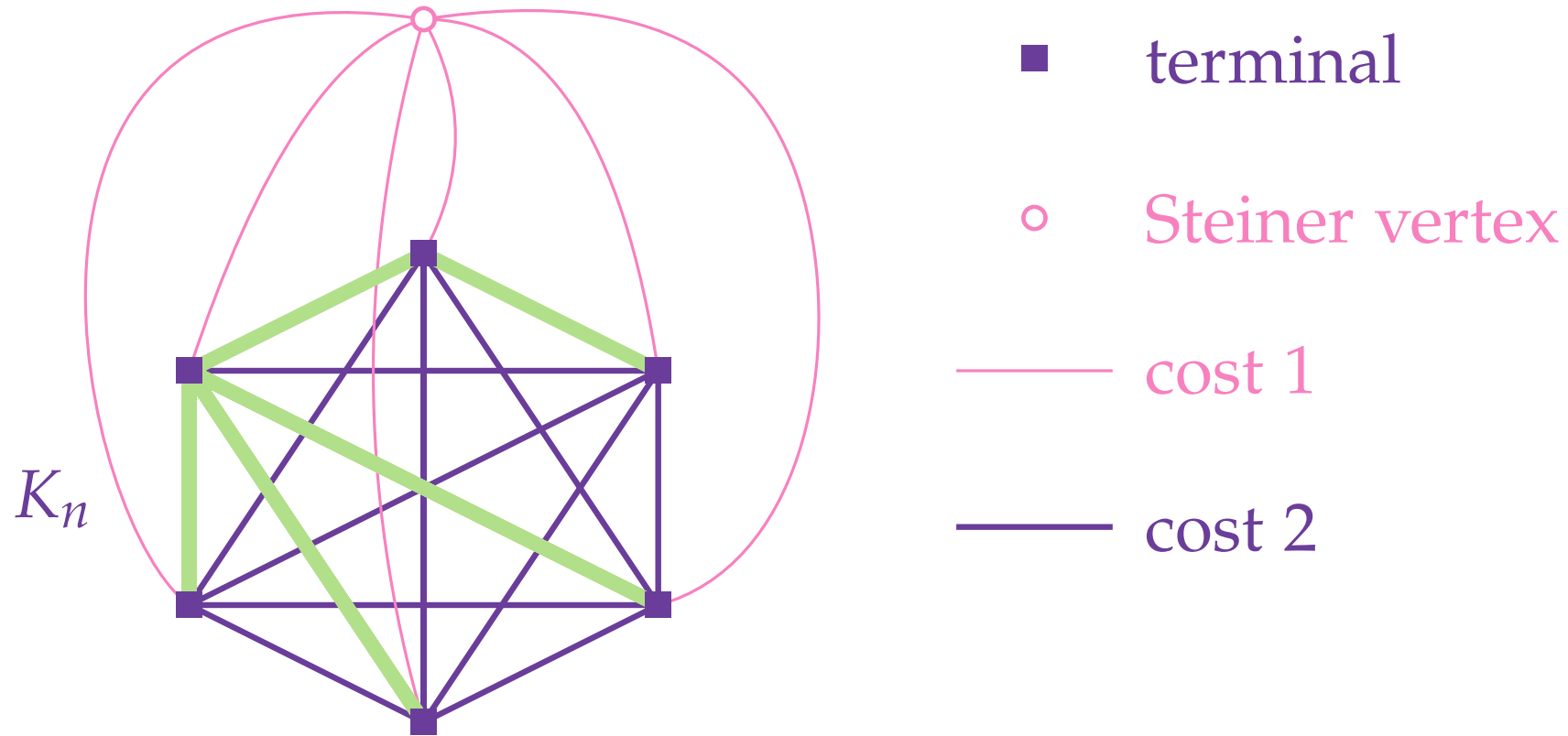
— cost 2

Analysis Sharp?



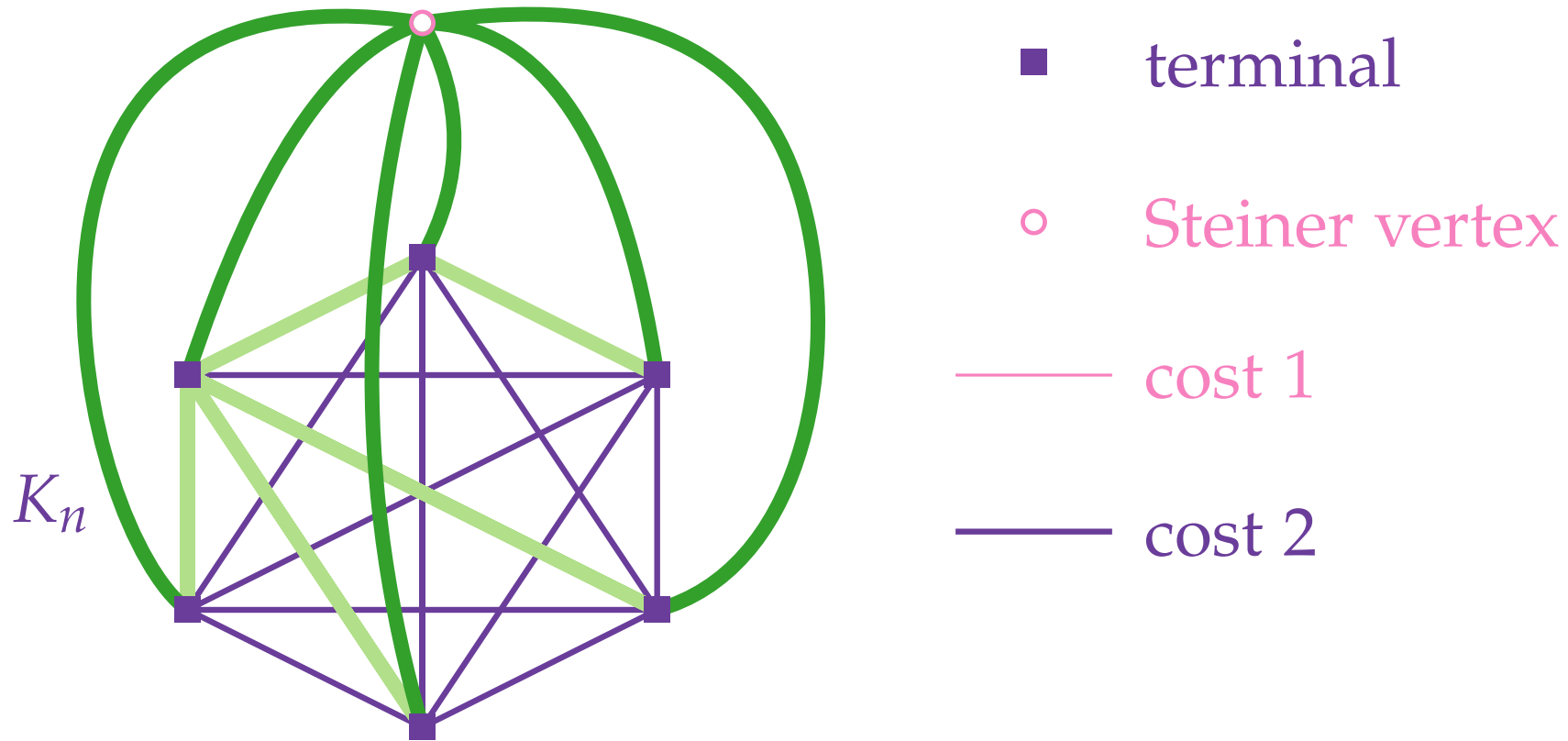
Analysis Sharp?

MST of $G[T]$ with cost $2(n - 1)$



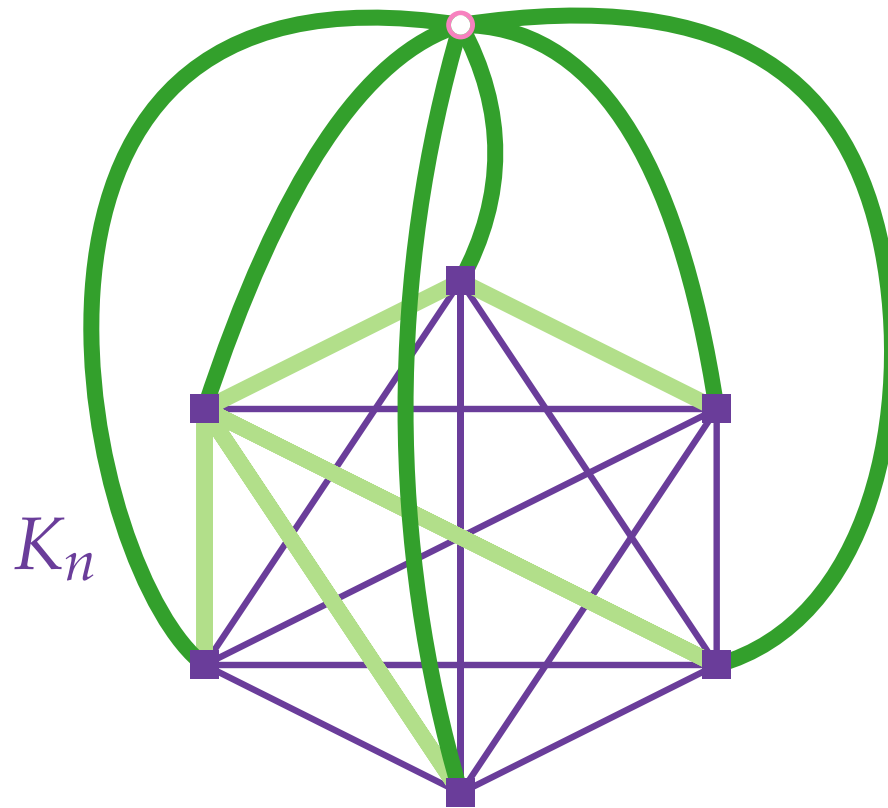
Analysis Sharp?

MST of $G[T]$ with cost $2(n - 1)$
 Optimal solution with cost n



Analysis Sharp?

MST of $G[T]$ with cost $2(n - 1)$
 Optimal solution with cost n



$$\frac{2(n - 1)}{n} \rightarrow 2$$

■ terminal

○ Steiner vertex

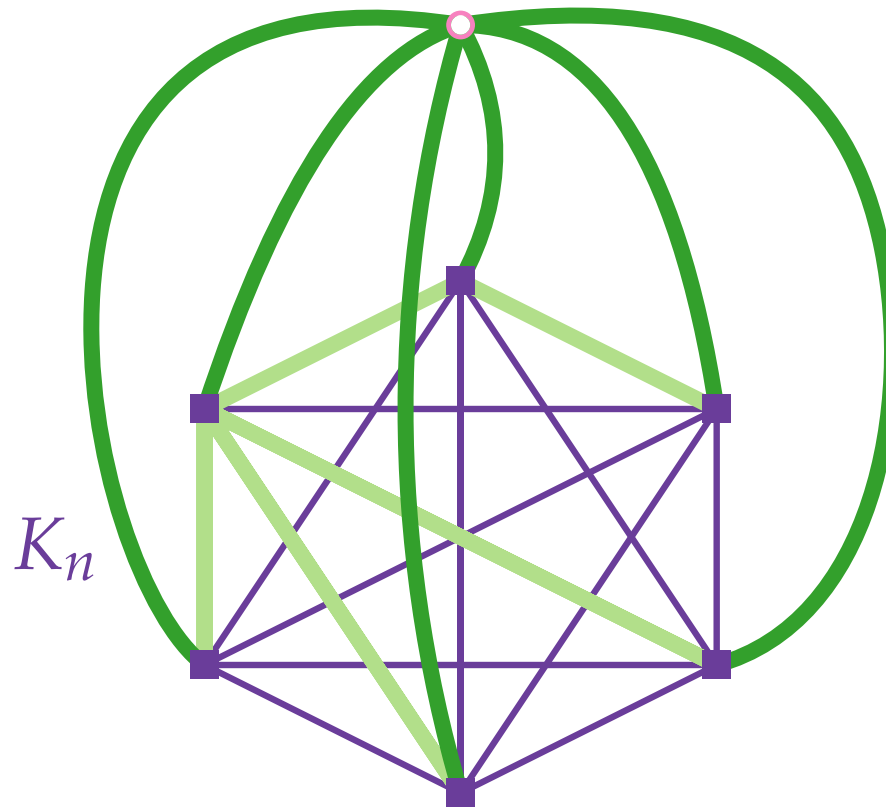
— cost 1

— cost 2

Analysis Sharp?

MST of $G[T]$ with cost $2(n-1)$
 Optimal solution with cost n

$$\frac{2(n-1)}{n} \rightarrow 2$$



■ terminal

○ Steiner vertex

— cost 1

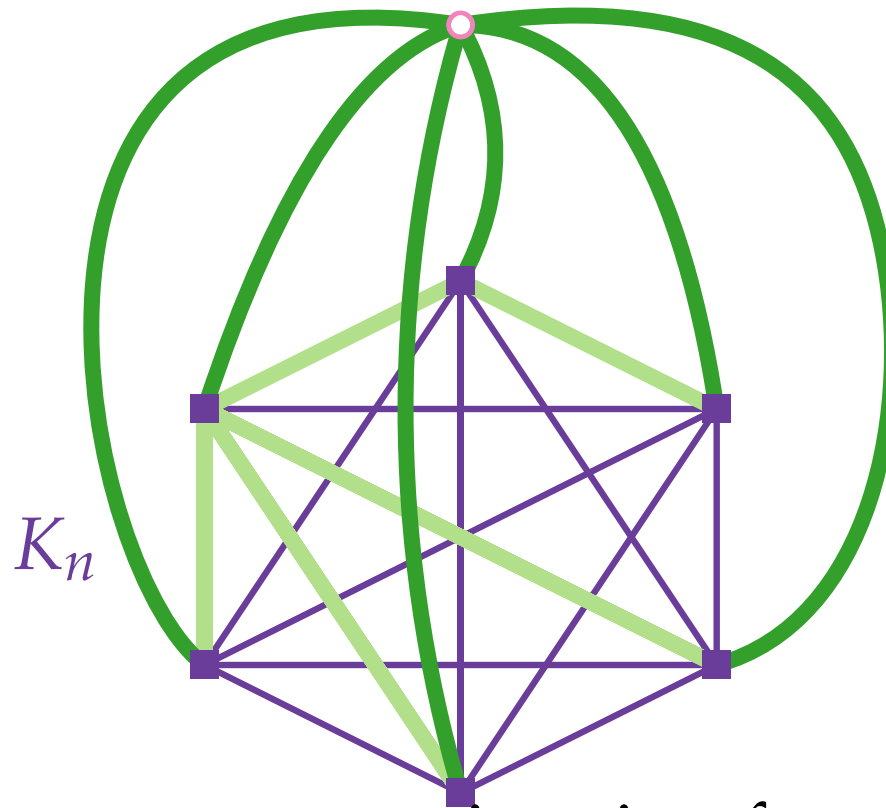
— cost 2

better?

Analysis Sharp?

MST of $G[T]$ with cost $2(n - 1)$
 Optimal solution with cost n

$$\frac{2(n - 1)}{n} \rightarrow 2$$



- terminal
- Steiner vertex
- cost 1
- cost 2

better?

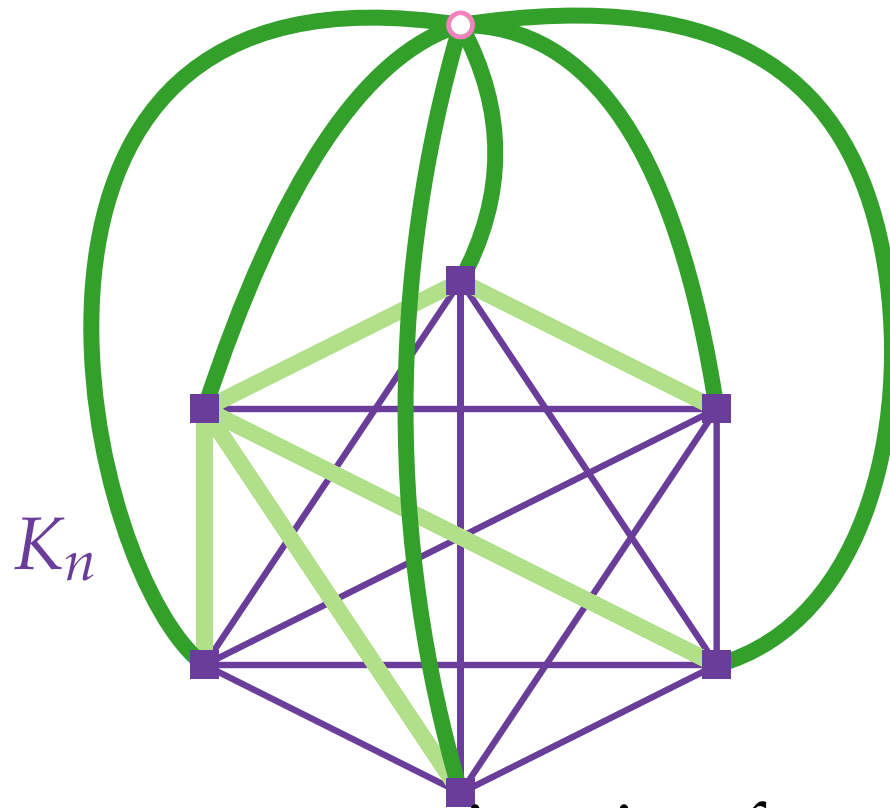
The best-known approximation factor for
 STEINERTREE is $\ln(4) + \epsilon \approx 1.39$

[Byrka, Grandoni,
 Rothvoß & Sanita '10]

Analysis Sharp?

MST of $G[T]$ with cost $2(n-1)$
 Optimal solution with cost n

$$\frac{2(n-1)}{n} \rightarrow 2$$



■ terminal

○ Steiner vertex

— cost 1

— cost 2

better?

The best-known approximation factor for
 STEINERTREE is $\ln(4) + \varepsilon \approx 1.39$

[Byrka, Grandoni,
 Rothvoß & Sanita '10]

STEINERTREE cannot be approximated within factor

$\frac{96}{95} \approx 1.0105$ (unless $P=NP$)

[Chlebik & Chlebikova '08]

Approximation Algorithms

Lecture 3:

STEINERTREE and MULTIWAYCUT

Part V:

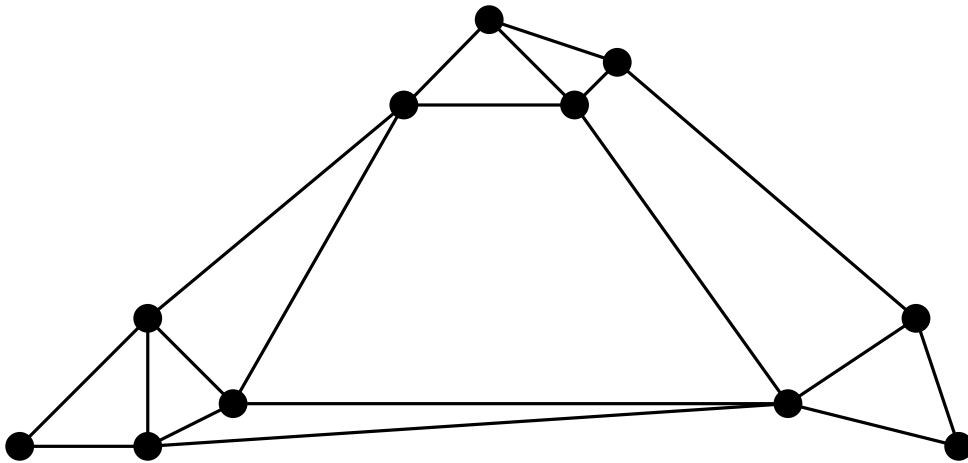
MULTIWAYCUT

MULTIWAYCUT

Given: A connected graph $G = (V, E)$

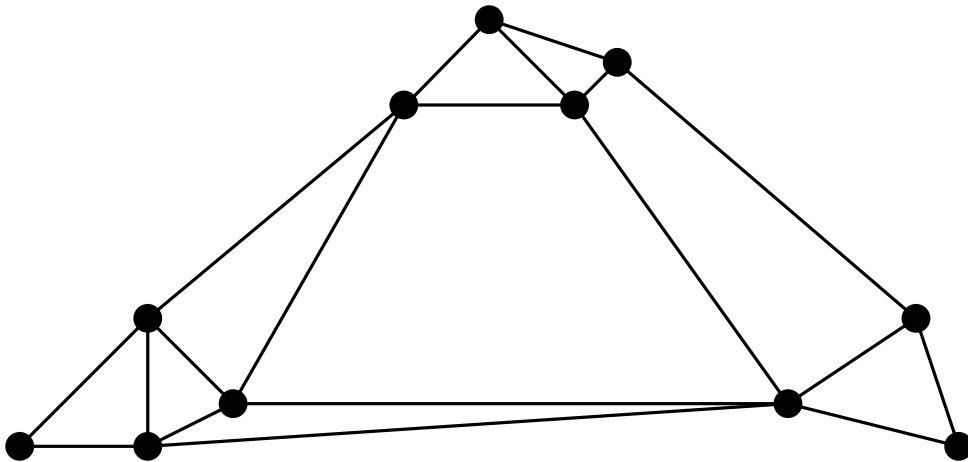
MULTIWAYCUT

Given: A connected graph $G = (V, E)$



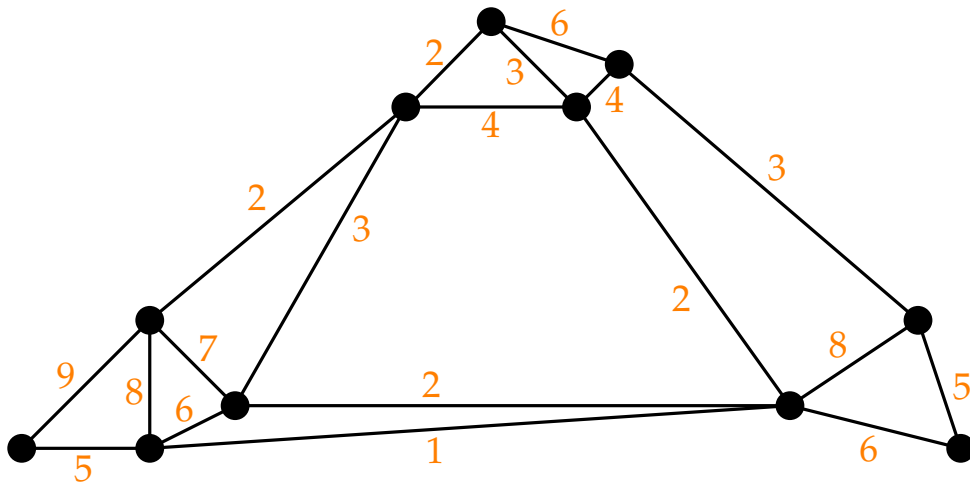
MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs**
 $c: E \rightarrow \mathbb{Q}^+$



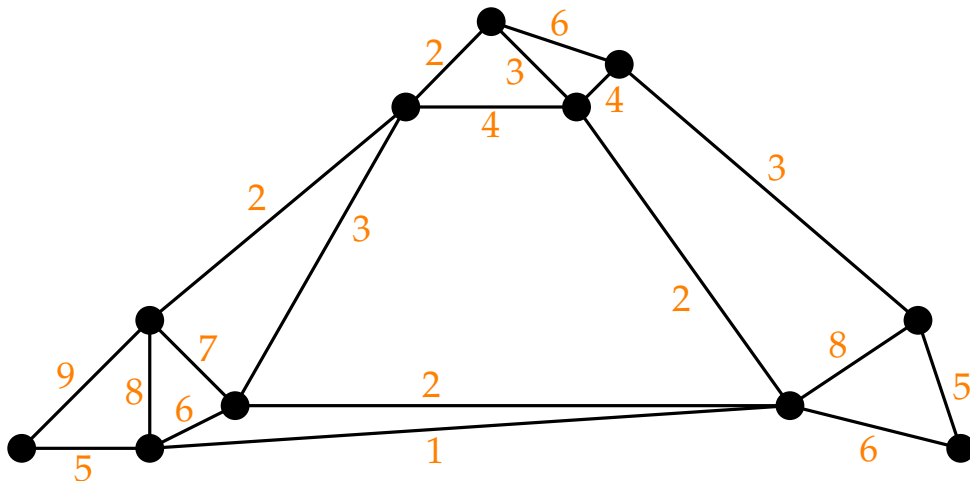
MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs**
 $c: E \rightarrow \mathbb{Q}^+$



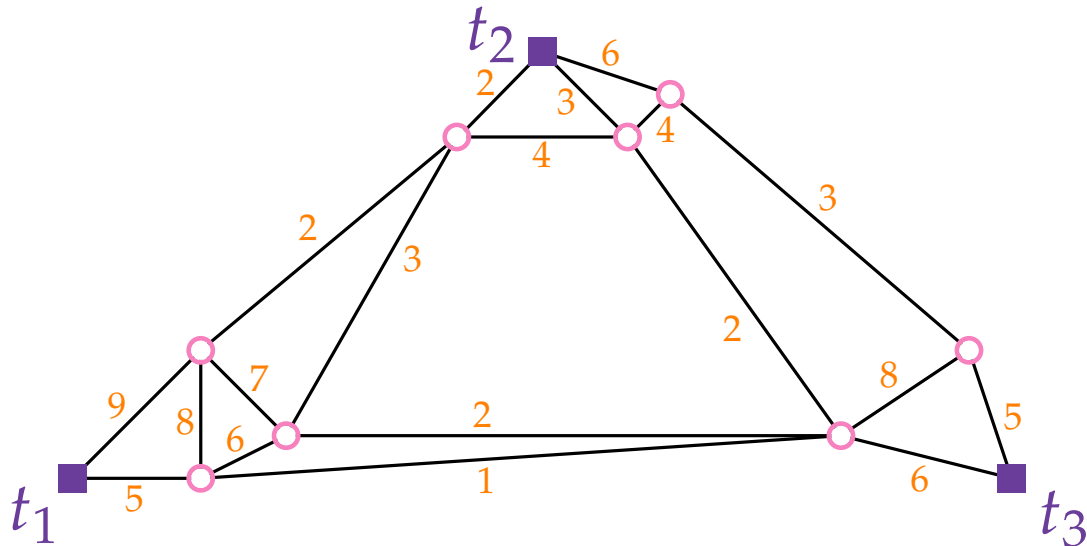
MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.



MULTIWAYCUT

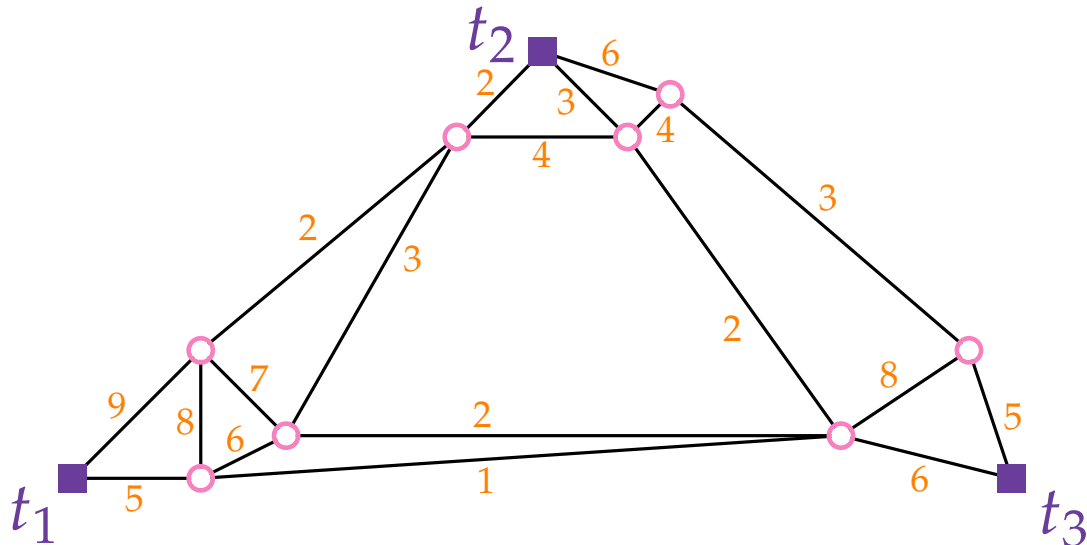
Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.



MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

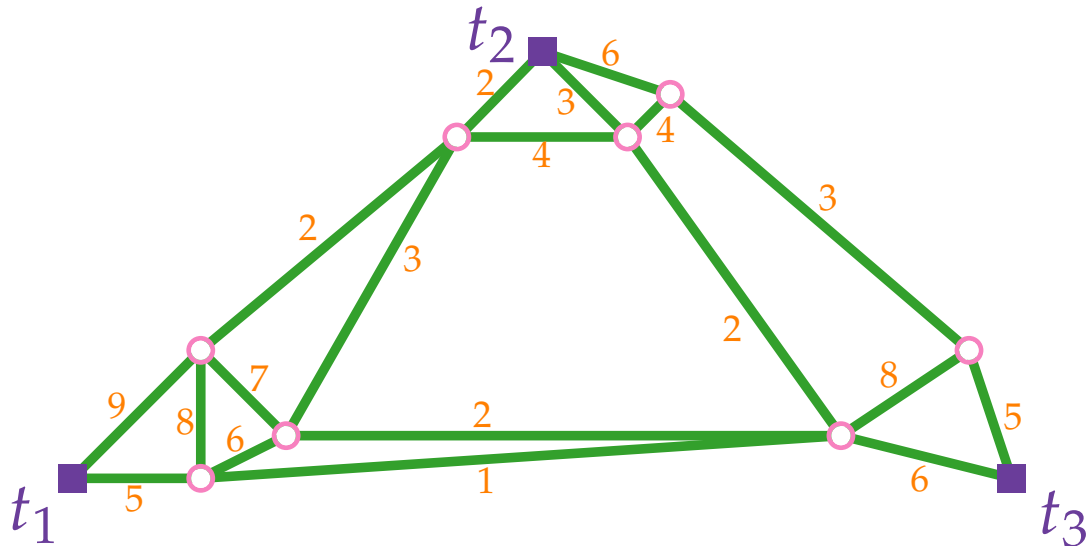
A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.



MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

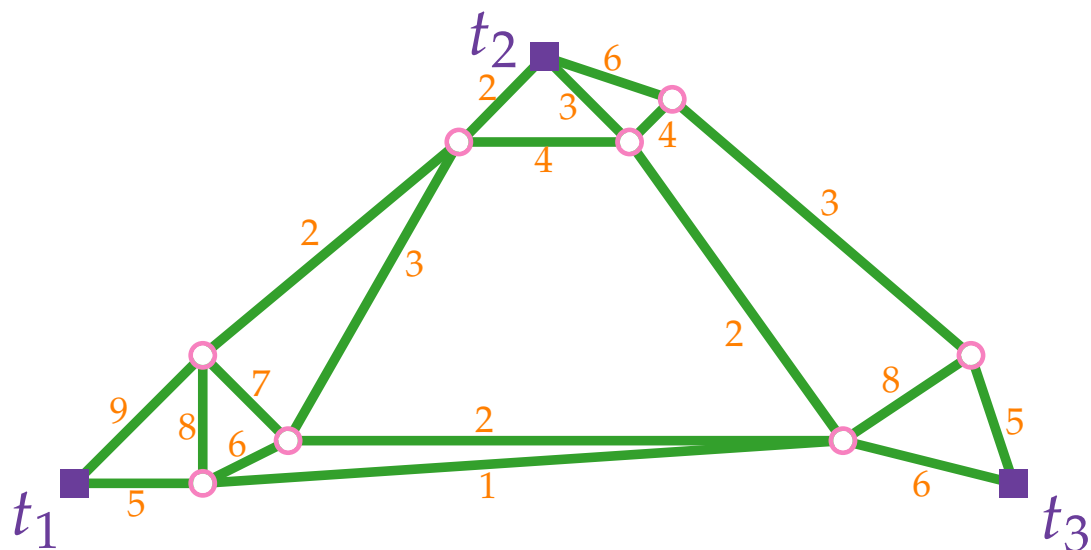


MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

Find: A **minimum cost multiway cut** of T .

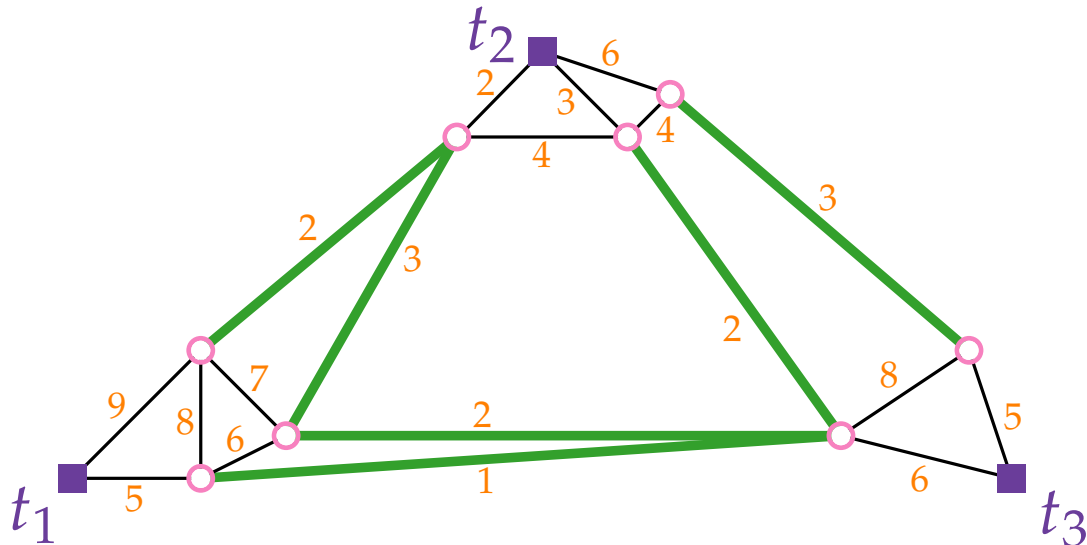


MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

Find: A **minimum cost multiway cut** of T .

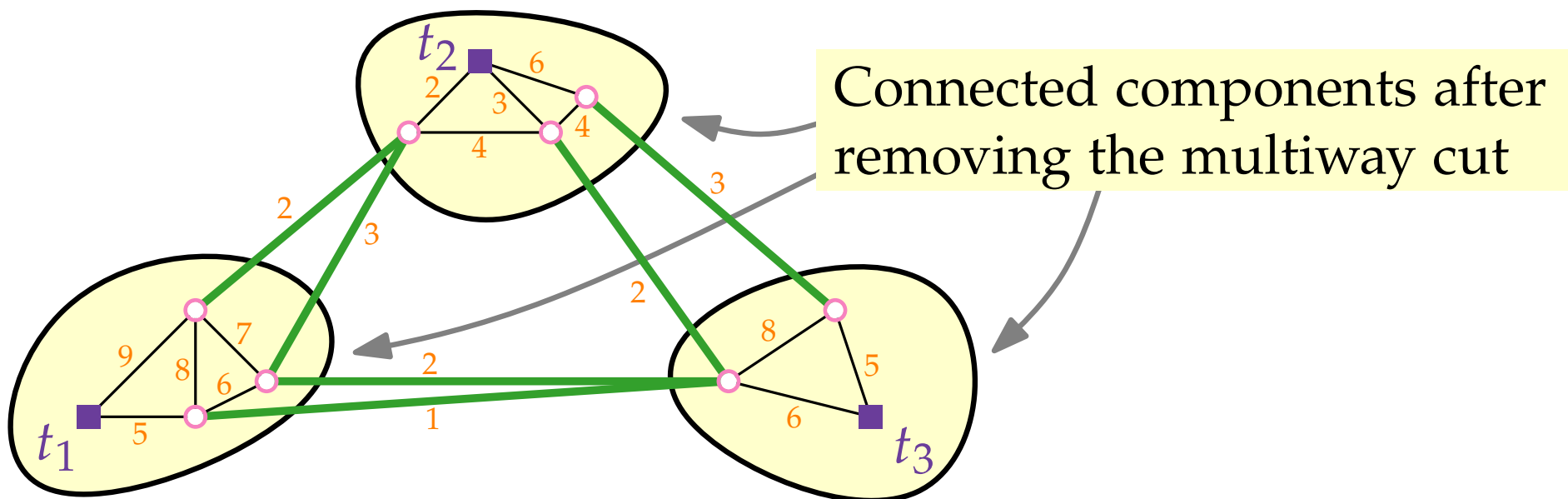


MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

Find: A **minimum cost multiway cut** of T .

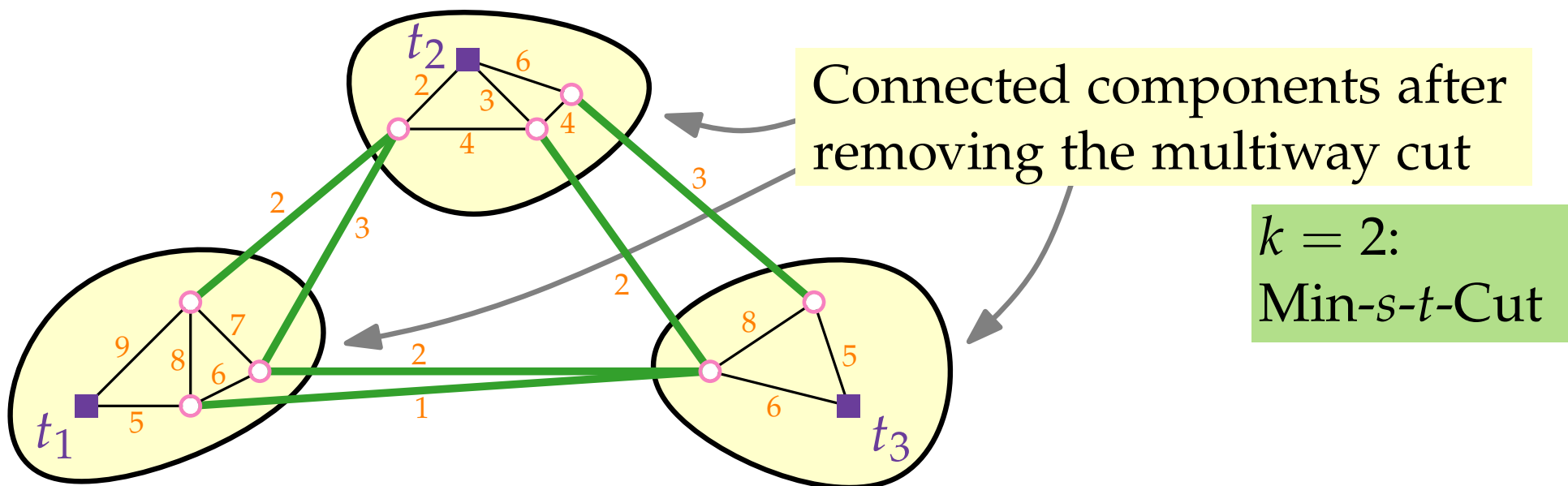


MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

Find: A **minimum cost multiway cut** of T .

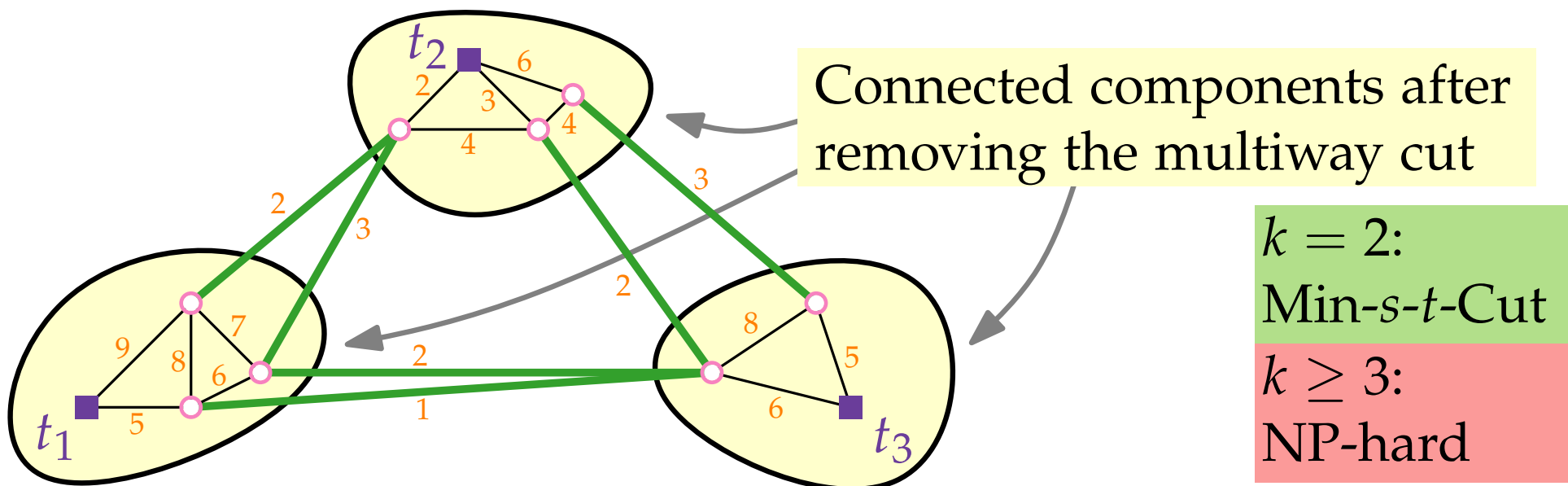


MULTIWAYCUT

Given: A connected graph $G = (V, E)$ with **edge costs** $c: E \rightarrow \mathbb{Q}^+$ and a set $T = \{t_1, \dots, t_k\} \subseteq V$ of **terminals**.

A **multiway cut** of T is a subset E' of edges such that no two terminals in the graph $(V, E - E')$ are connected.

Find: A **minimum cost multiway cut** of T .

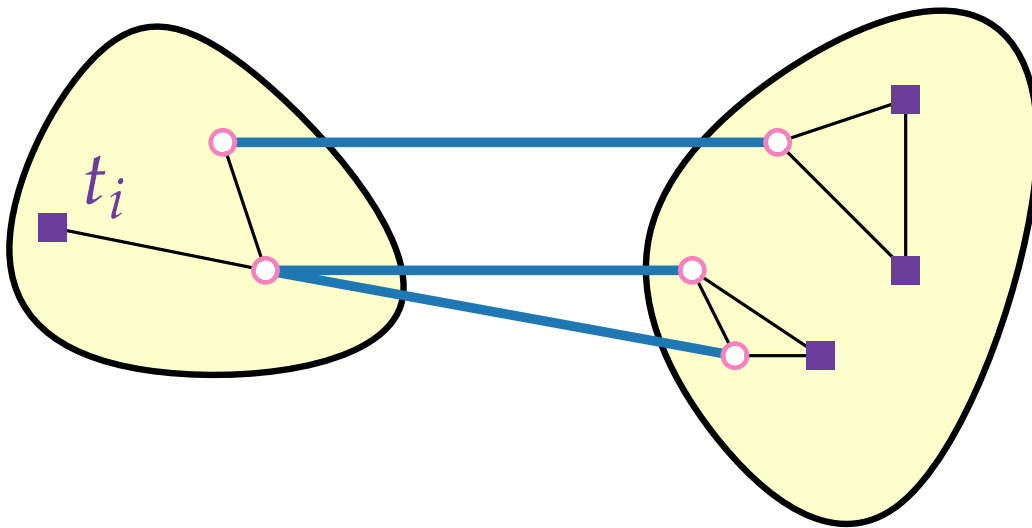


Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Isolating Cuts

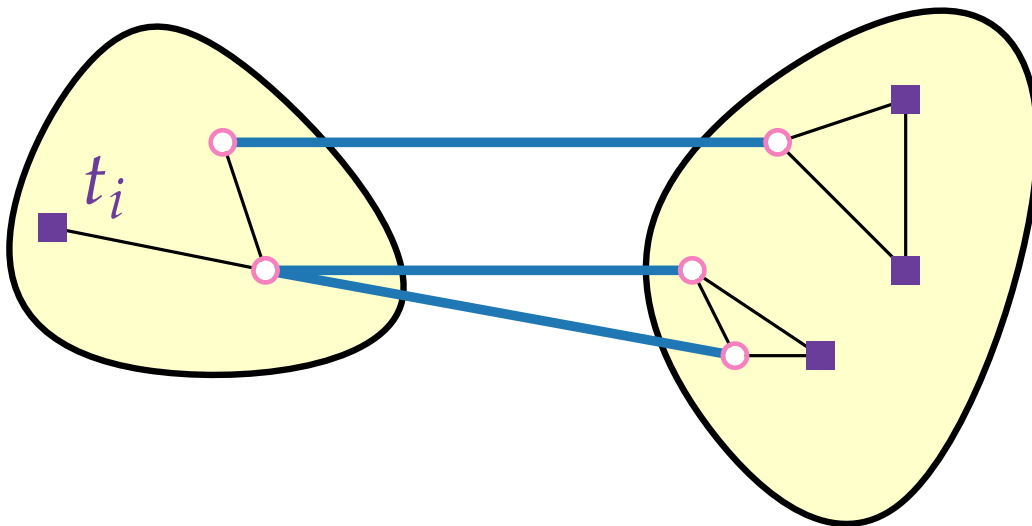
An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.



Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

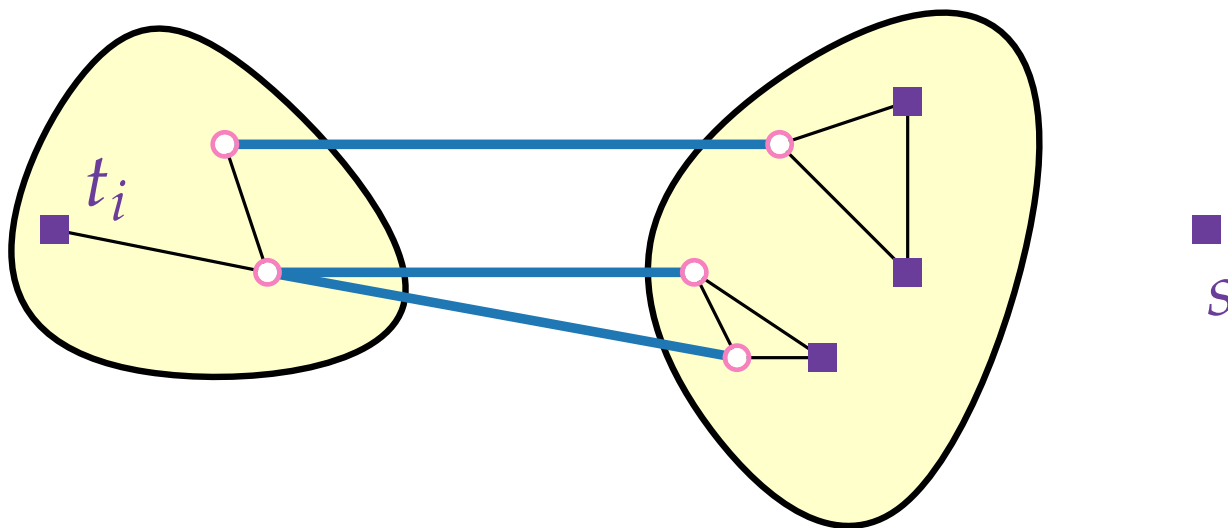
Minimum cost **isolating cut** can be computed efficiently!



Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Minimum cost **isolating cut** can be computed efficiently!

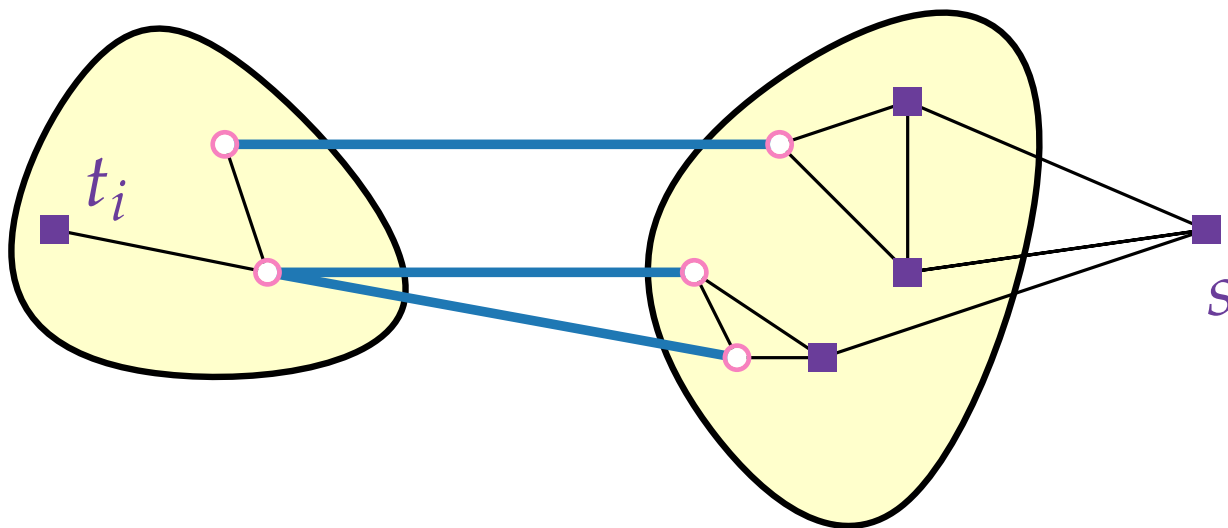


Add dummy terminal s

Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Minimum cost **isolating cut** can be computed efficiently!

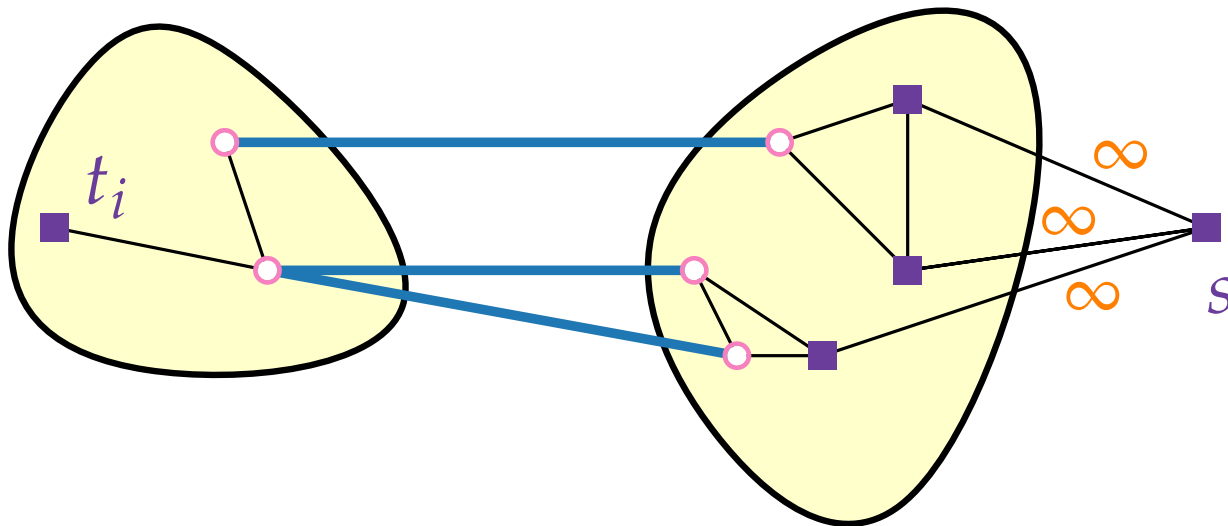


Add dummy terminal s

Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Minimum cost **isolating cut** can be computed efficiently!

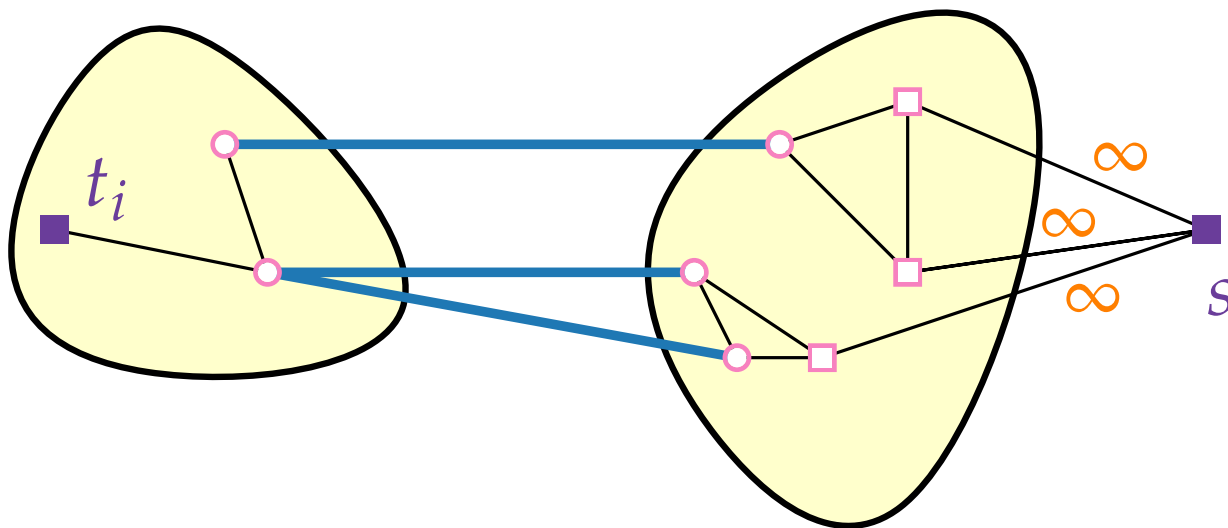


Add dummy terminal s

Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Minimum cost **isolating cut** can be computed efficiently!

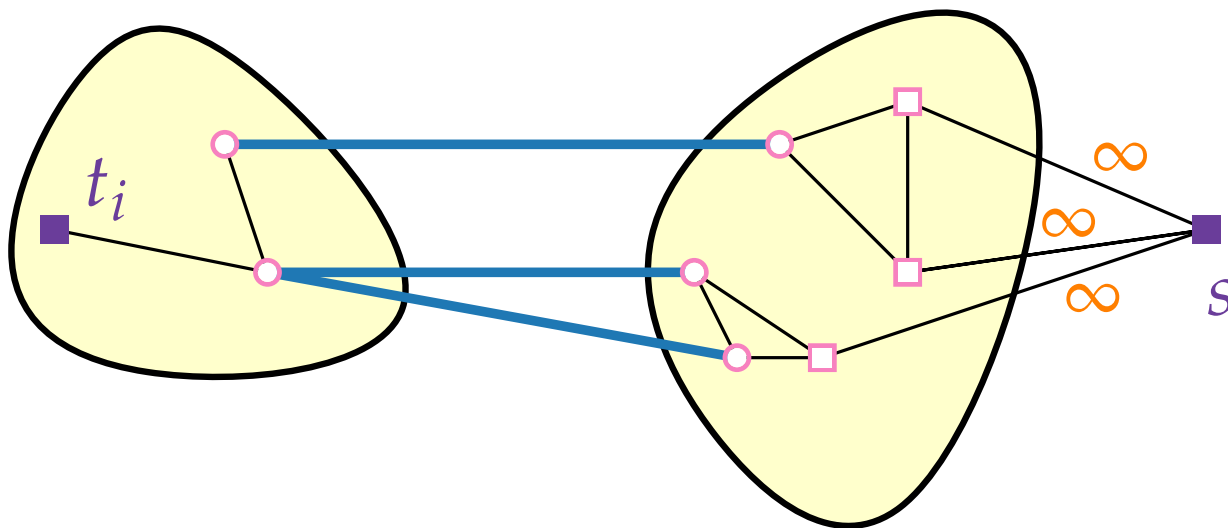


Add dummy terminal s

Isolating Cuts

An **isolating cut** for a terminal t_i is a set of edges separating t_i from all other terminals.

Minimum cost **isolating cut** can be computed efficiently!



Add dummy terminal s and find minimum cost $s-t_i$ -cut.

Approximation Algorithms

Lecture 3:

STEINERTREE and MULTIWAYCUT

Part VI:

Algorithm for MULTIWAYCUT

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$$\Rightarrow c(\mathcal{C}) \quad ? \quad \sum_{i=1}^k c(C_i)$$

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$$\Rightarrow c(\mathcal{C}) \leq \sum_{i=1}^k c(C_i)$$

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$$\Rightarrow c(\mathcal{C}) \leq \frac{k-1}{k} \sum_{i=1}^k c(C_i)$$

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$\Rightarrow c(\mathcal{C}) \leq \frac{k-1}{k} \sum_{i=1}^k c(C_i)$ by pigeonhole principle:

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$\Rightarrow c(\mathcal{C}) \leq \frac{k-1}{k} \sum_{i=1}^k c(C_i)$ by pigeonhole principle:

for the most expensive cut of C_1, \dots, C_k , say C_1 , we have

$$c(C_1) \geq$$

Algorithm MULTIWAYCUT

For $i = 1, \dots, k$:

Compute a minimum cost isolating cut C_i for t_i .

Return the union of \mathcal{C} of the $k - 1$ cheapest such isolating cuts.

In other words:

Ignore the most expensive of the isolating cuts C_1, \dots, C_k .

$\Rightarrow c(\mathcal{C}) \leq \frac{k-1}{k} \sum_{i=1}^k c(C_i)$ by pigeonhole principle:

for the most expensive cut of C_1, \dots, C_k , say C_1 , we have

$$c(C_1) \geq \frac{1}{k} \sum_{i=1}^k c(C_i).$$

Approximation Factor

Theorem. This algorithm is a factor-()-
approximation algorithm for `MULTIWAYCUT`.

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Approximation Factor

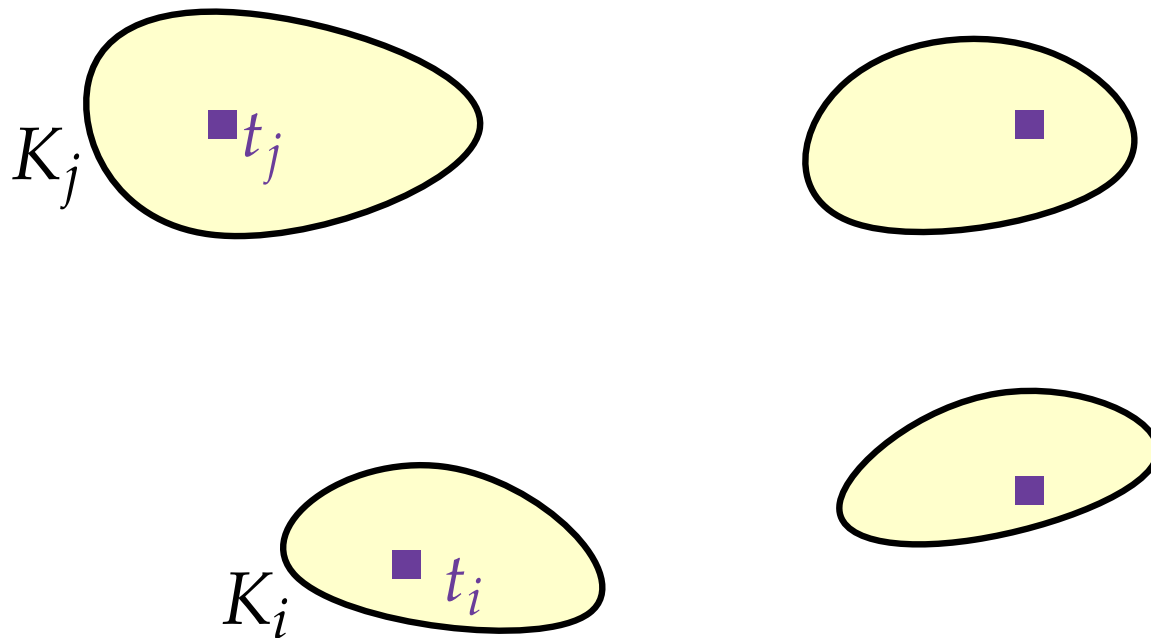
Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

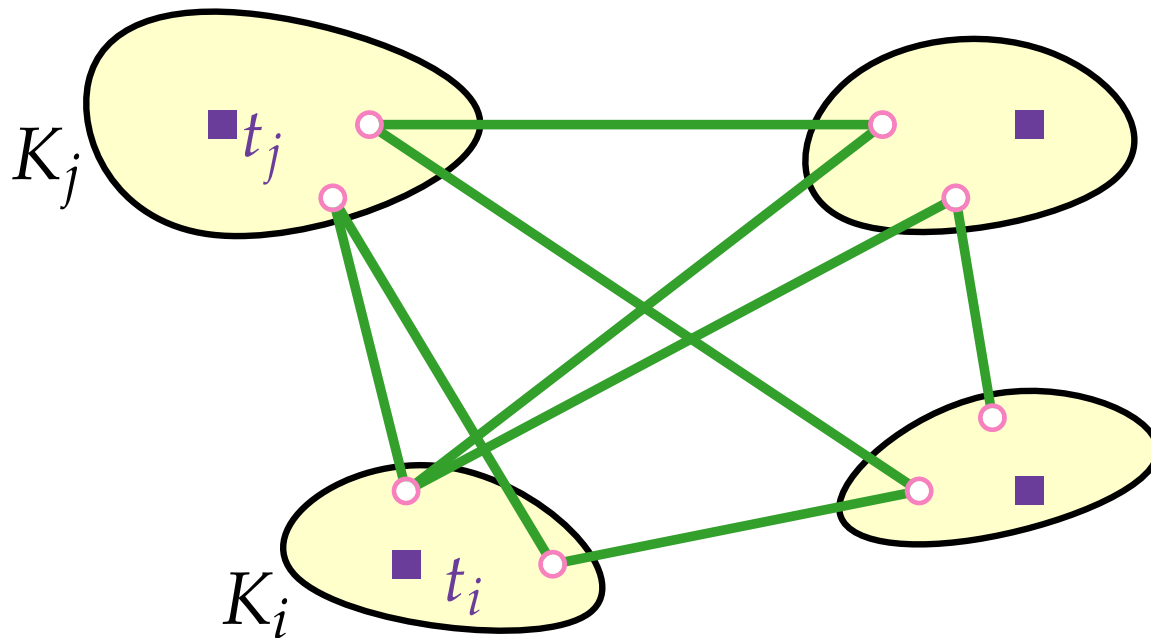
Proof. Consider optimal multiway cut A :



Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

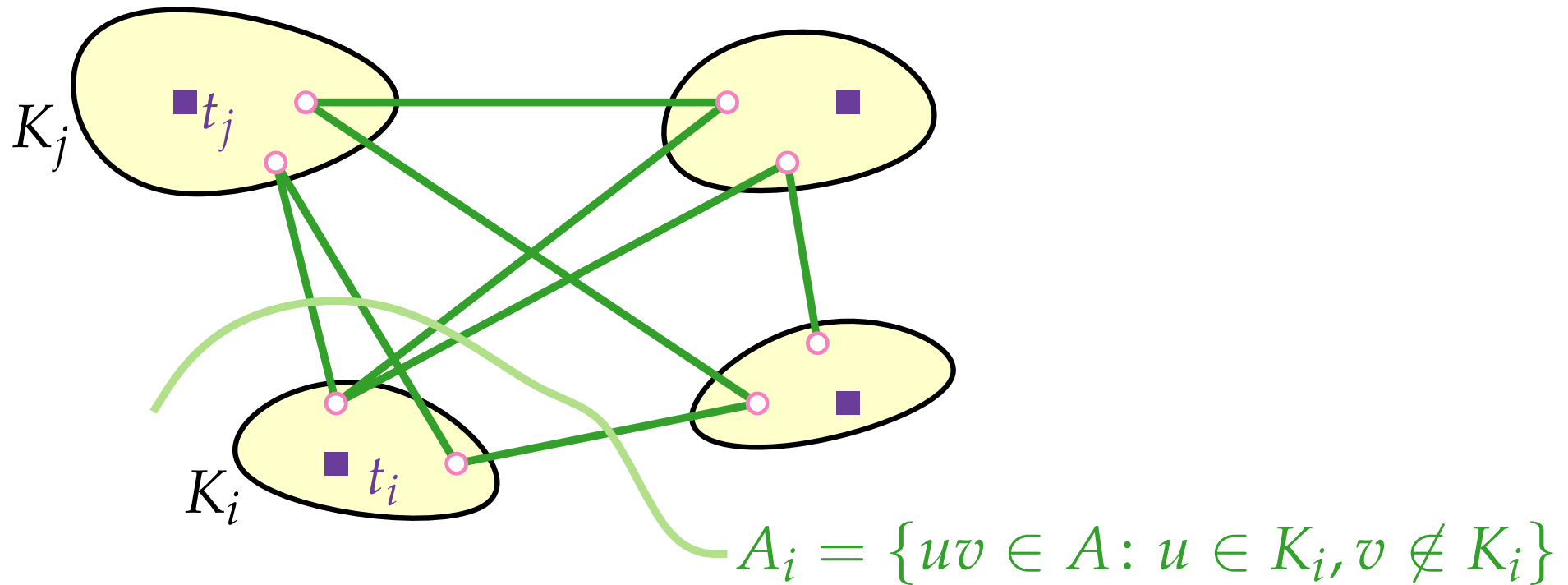
Proof. Consider optimal multiway cut A :



Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

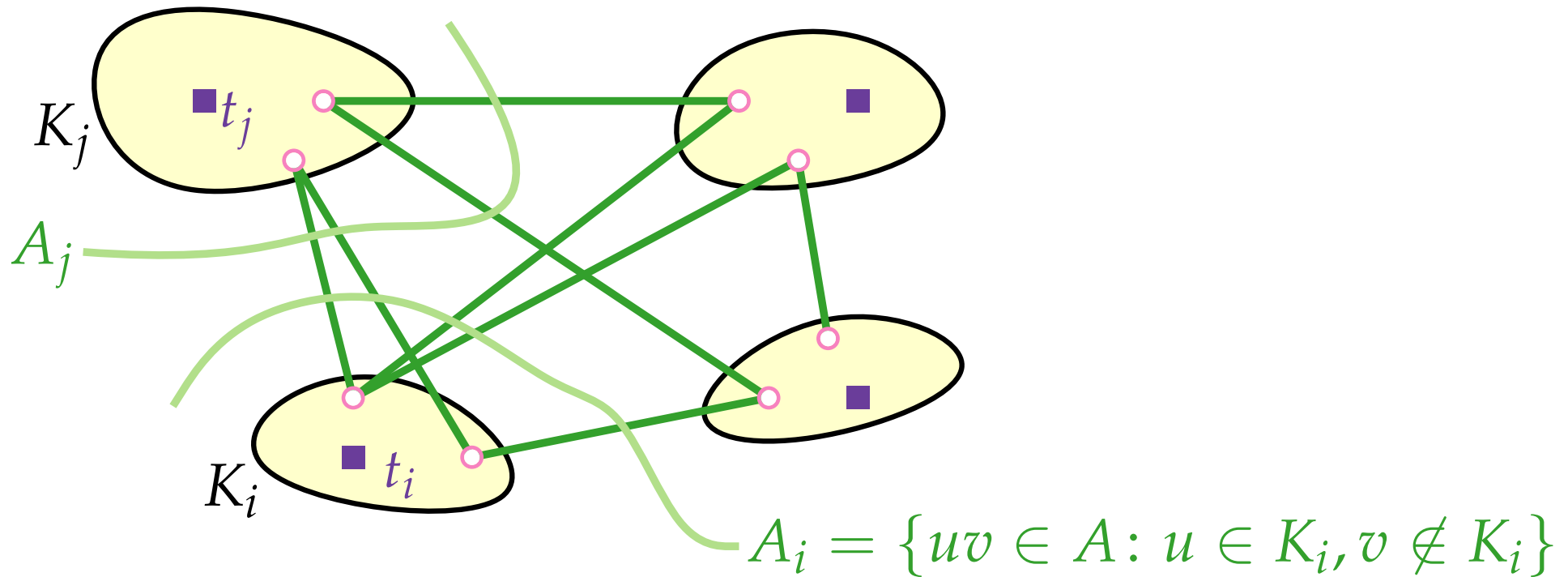
Proof. Consider optimal multiway cut A :



Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

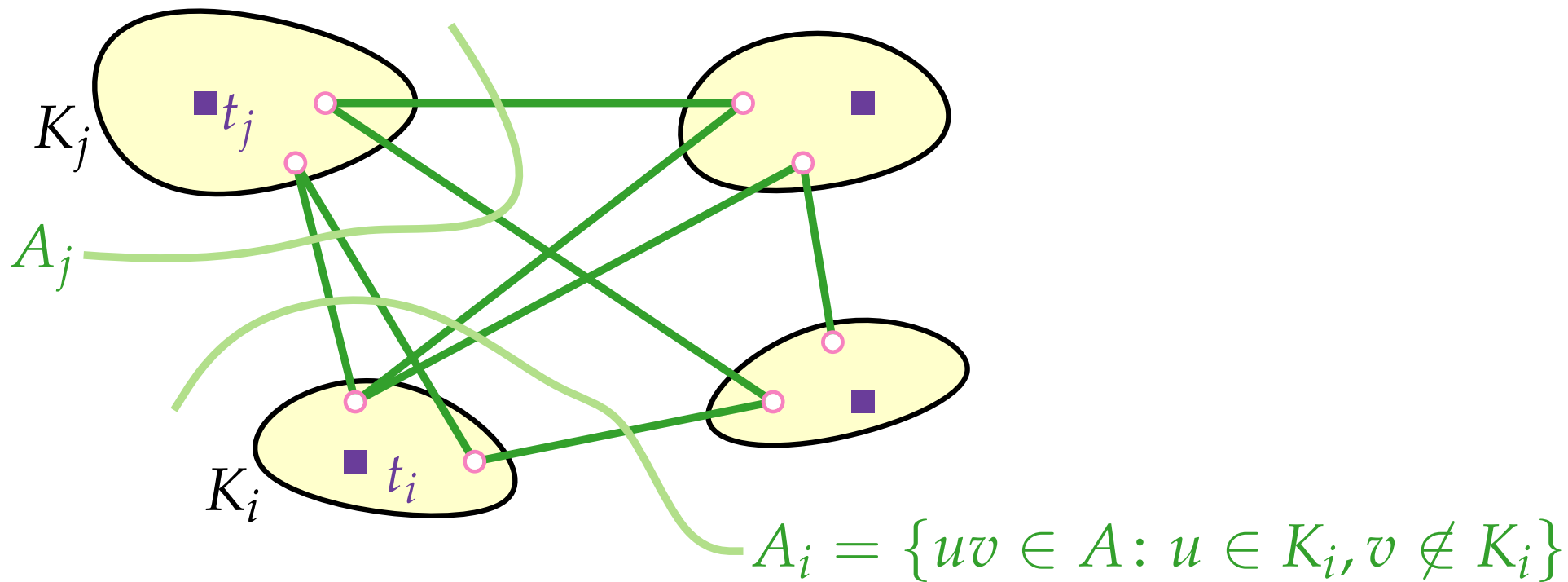
Proof. Consider optimal multiway cut A :



Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

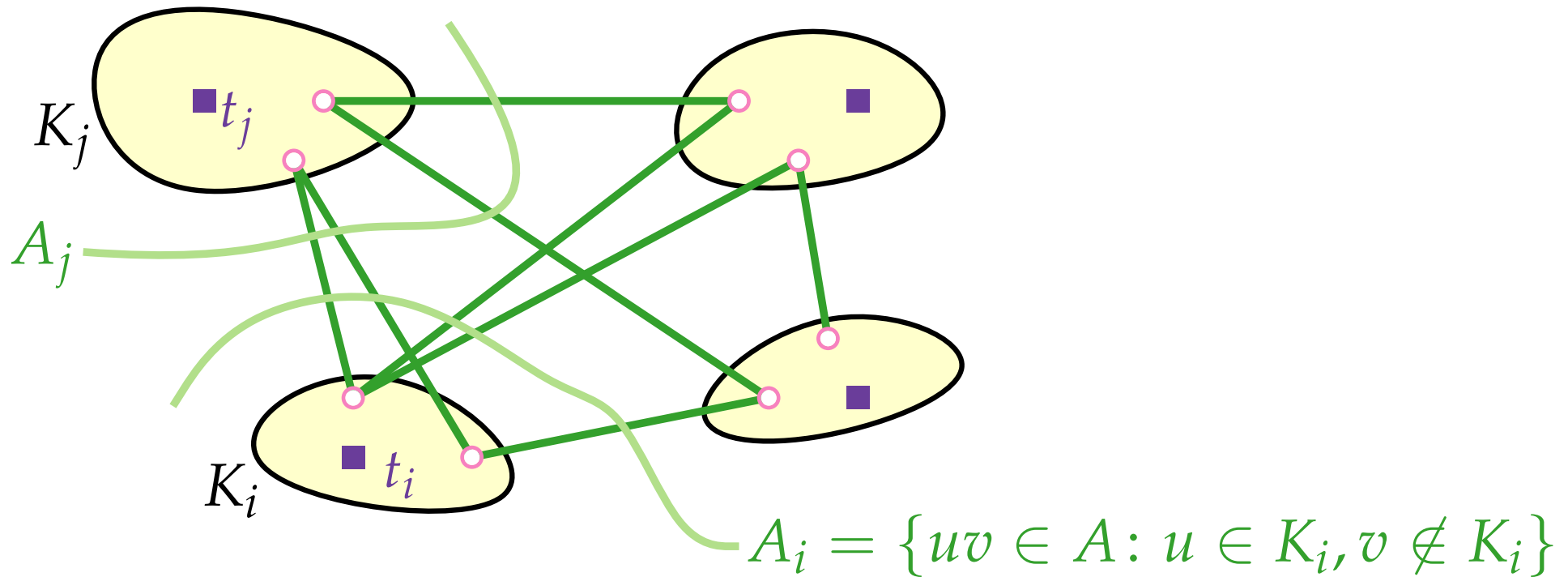


Observation. $A =$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

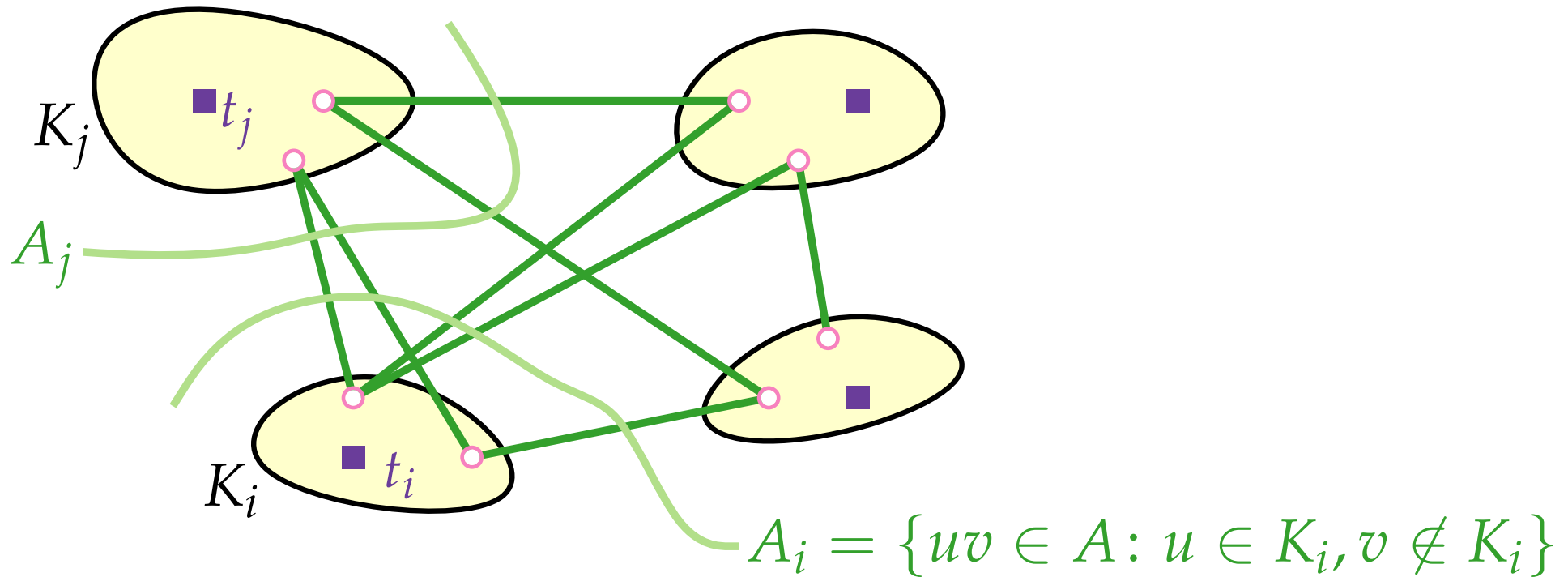


Observation. $A = \bigcup_{i=1}^k A_i$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

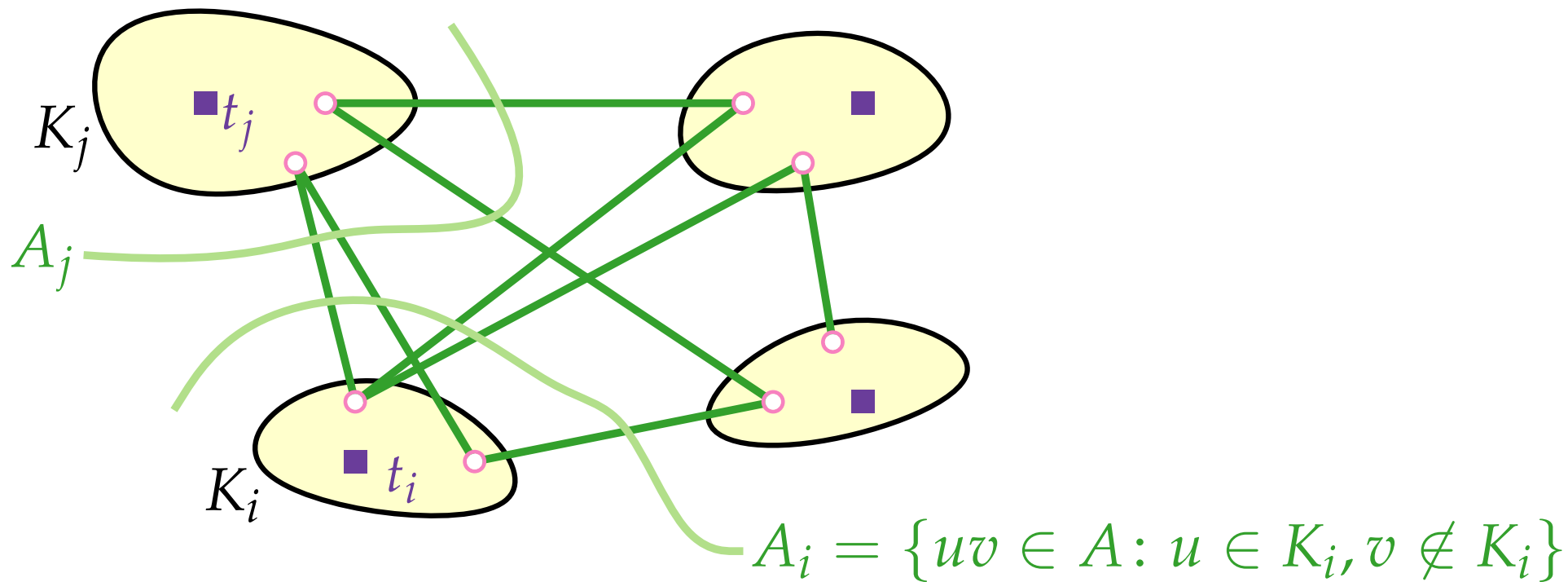


Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) =$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

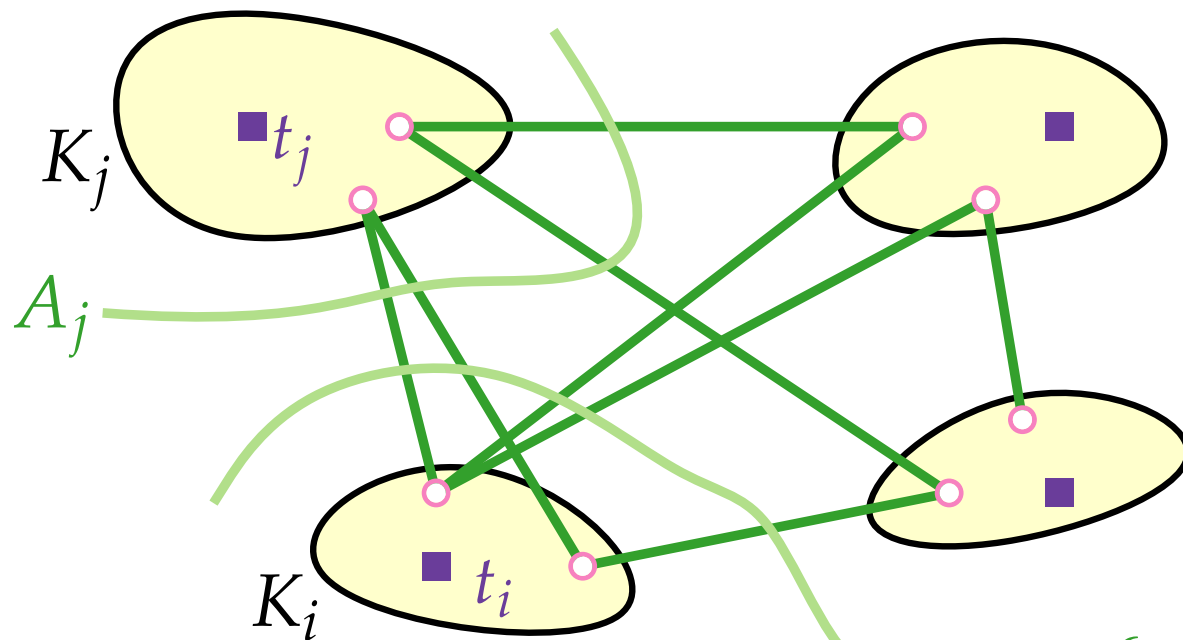


Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) = \frac{1}{2} \sum_{i=1}^k c(A_i)$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :

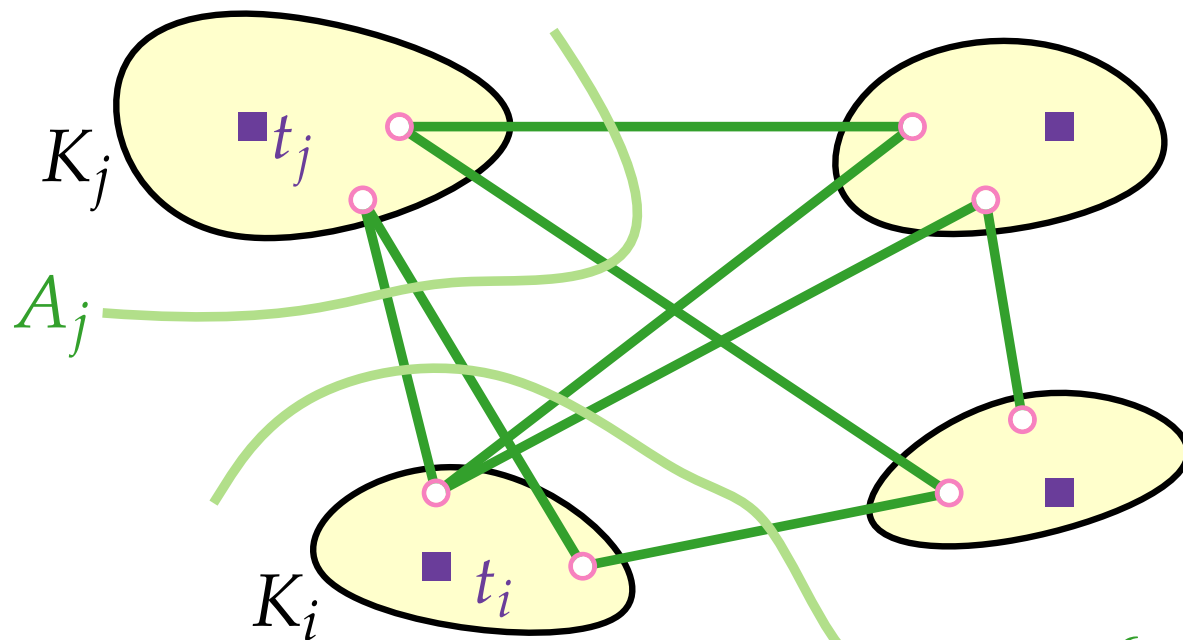


Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) = \frac{1}{2} \sum_{i=1}^k c(A_i)$
 $\Rightarrow \text{OPT} = c(A) \geq$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :



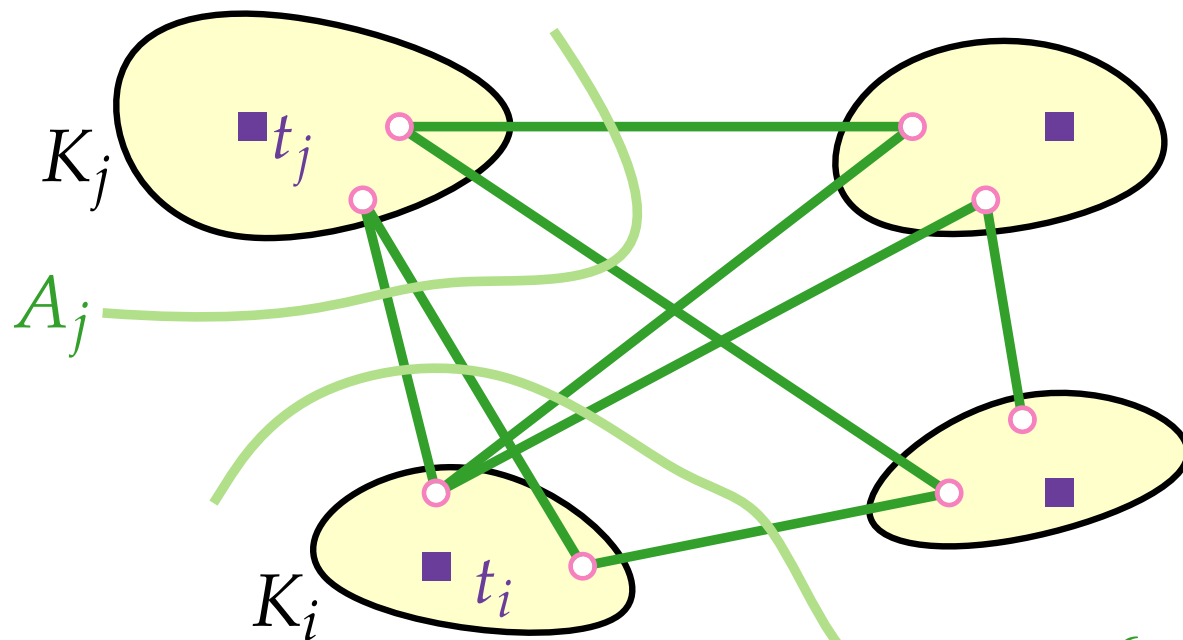
$$A_i = \{uv \in A : u \in K_i, v \notin K_i\}$$

Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) = \frac{1}{2} \sum_{i=1}^k c(A_i)$
 $\Rightarrow \text{OPT} = c(A) \geq \frac{1}{2} \sum_{i=1}^k c(C_i) \geq$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :



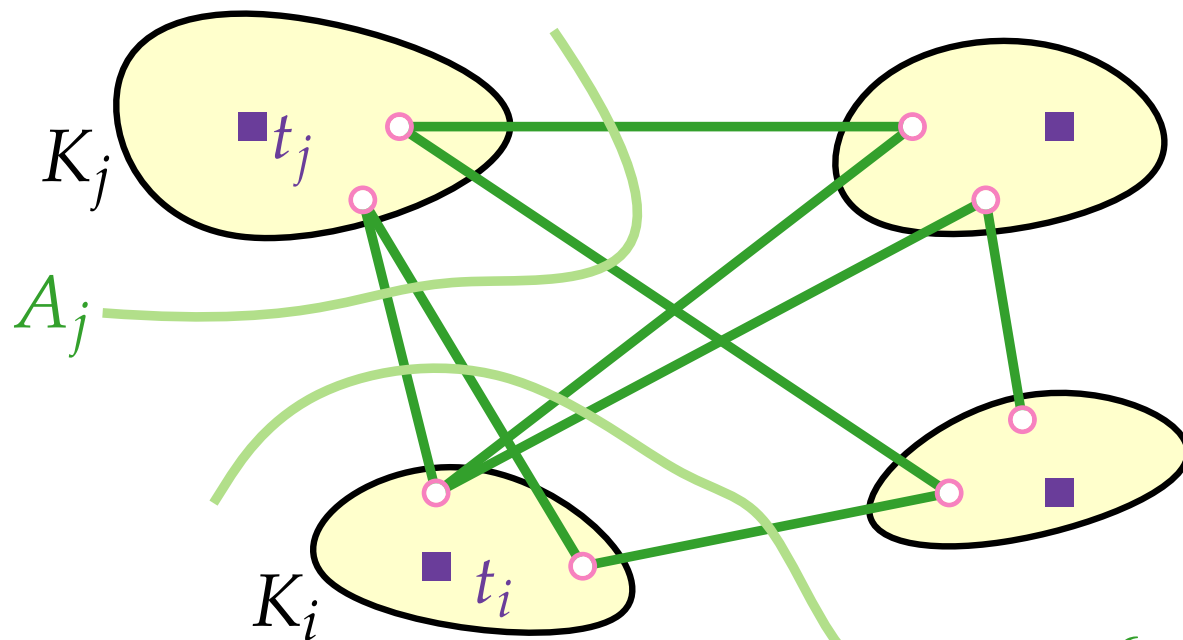
$$A_i = \{uv \in A : u \in K_i, v \notin K_i\}$$

Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) = \frac{1}{2} \sum_{i=1}^k c(A_i)$
 $\Rightarrow \text{OPT} = c(A) \geq \frac{1}{2} \sum_{i=1}^k c(C_i) \geq \frac{1}{2} \cdot \frac{k}{k-1} c(C).$

Approximation Factor

Theorem. This algorithm is a factor- $(2 - 2/k)$ -approximation algorithm for MULTIWAYCUT.

Proof. Consider optimal multiway cut A :



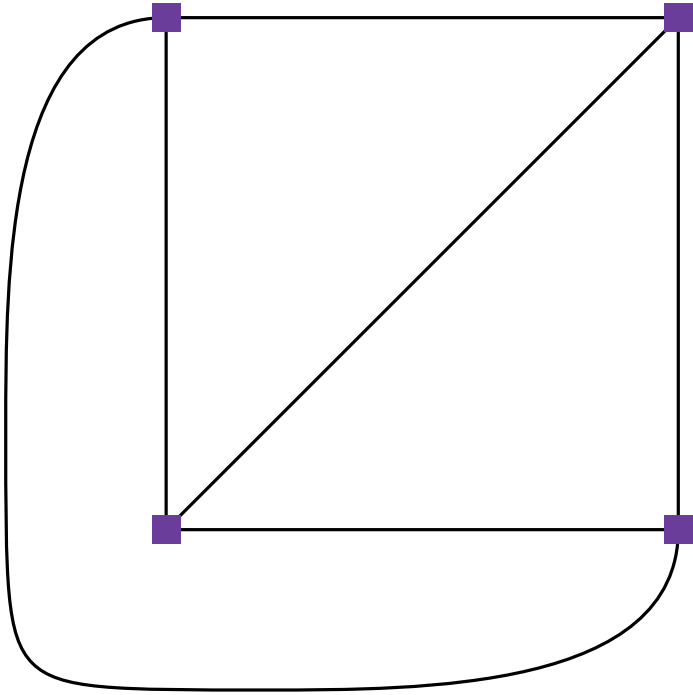
$$A_i = \{uv \in A : u \in K_i, v \notin K_i\}$$

Observation. $A = \bigcup_{i=1}^k A_i$ and $c(A) = \frac{1}{2} \sum_{i=1}^k c(A_i)$ ALG
 $\Rightarrow \text{OPT} = c(A) \geq \frac{1}{2} \sum_{i=1}^k c(C_i) \geq \frac{1}{2} \cdot \frac{k}{k-1} c(C)$.

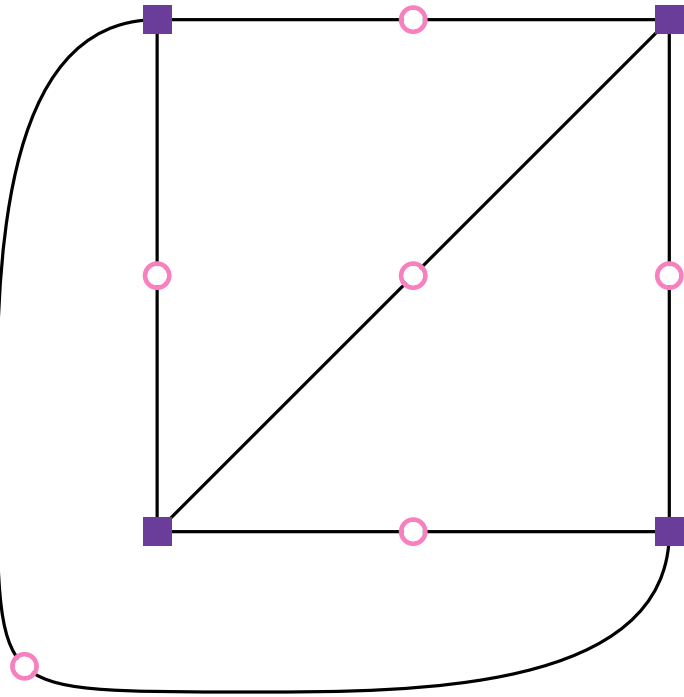
Analysis Sharp?

K_k

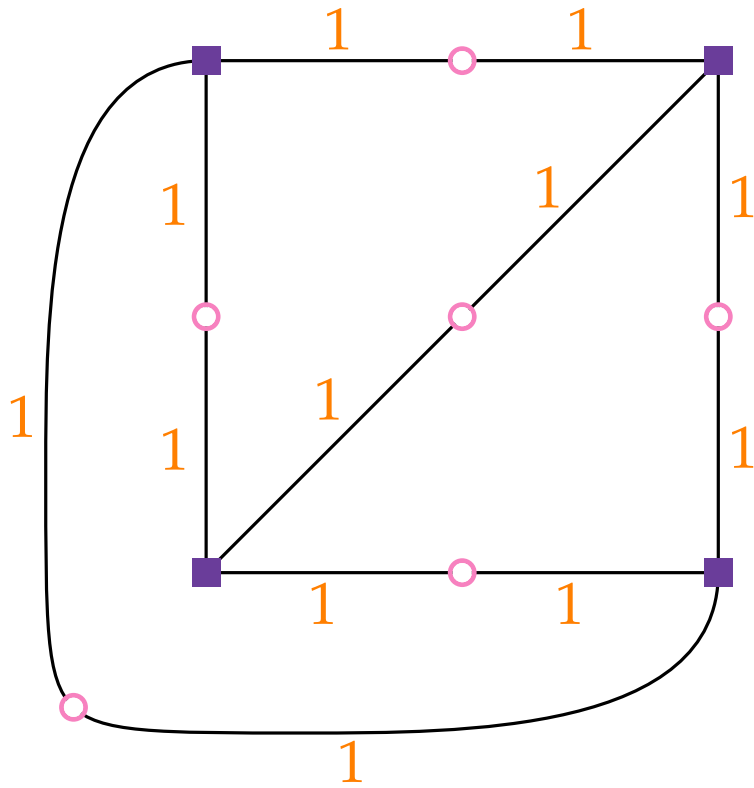
Analysis Sharp?

 K_k 

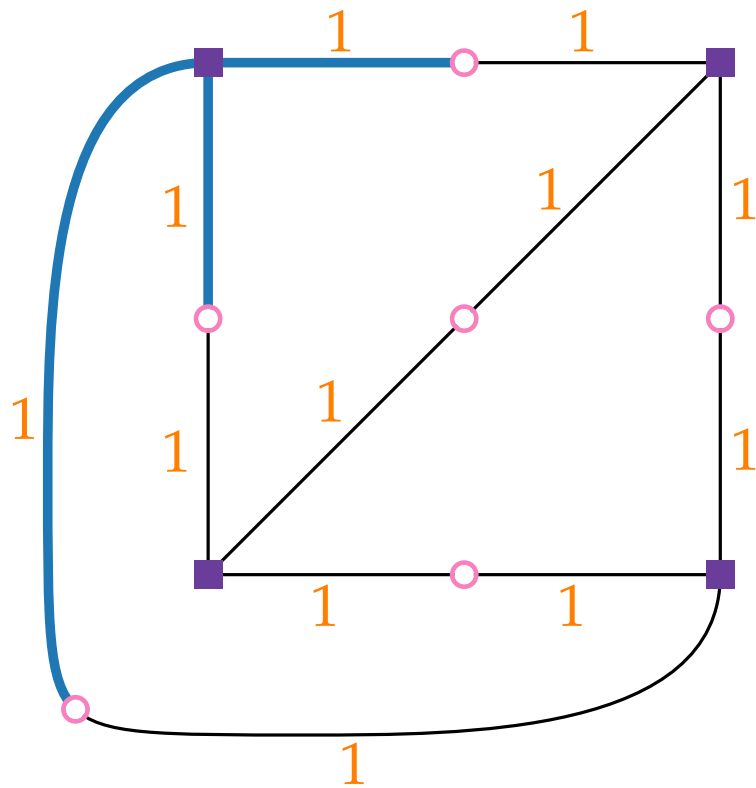
Analysis Sharp?

 K_k 

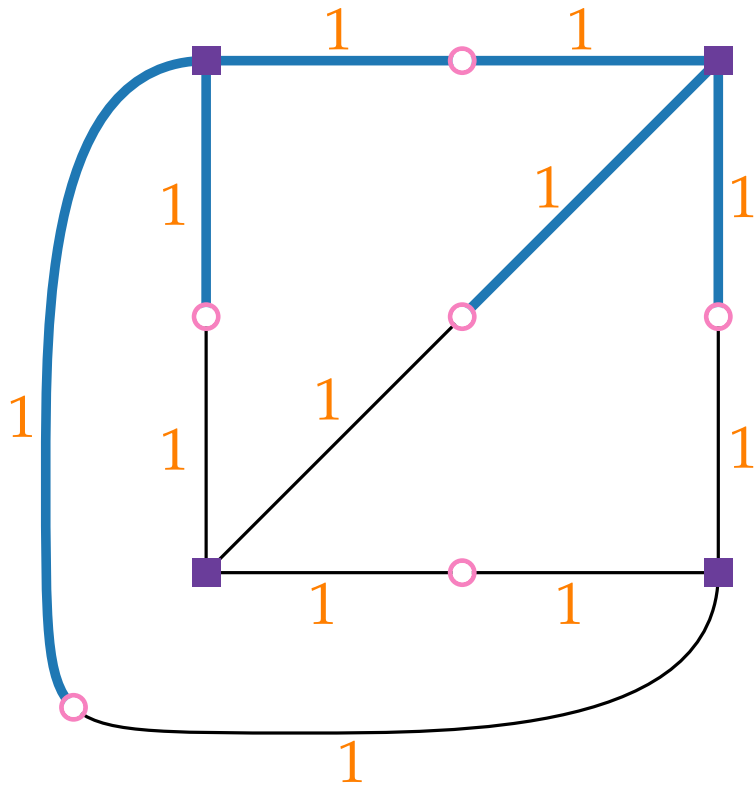
Analysis Sharp?

 K_k 

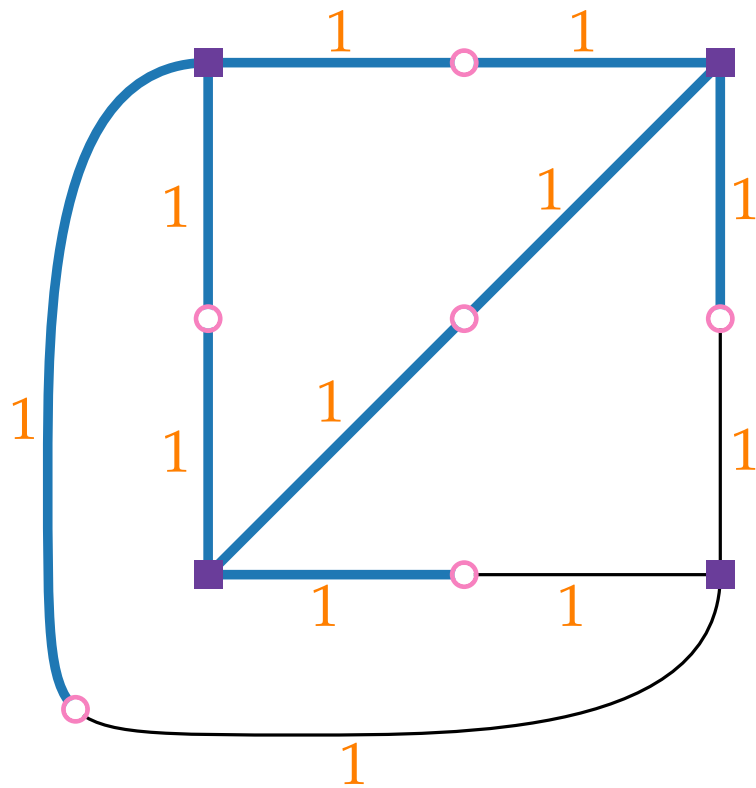
Analysis Sharp?

 K_k


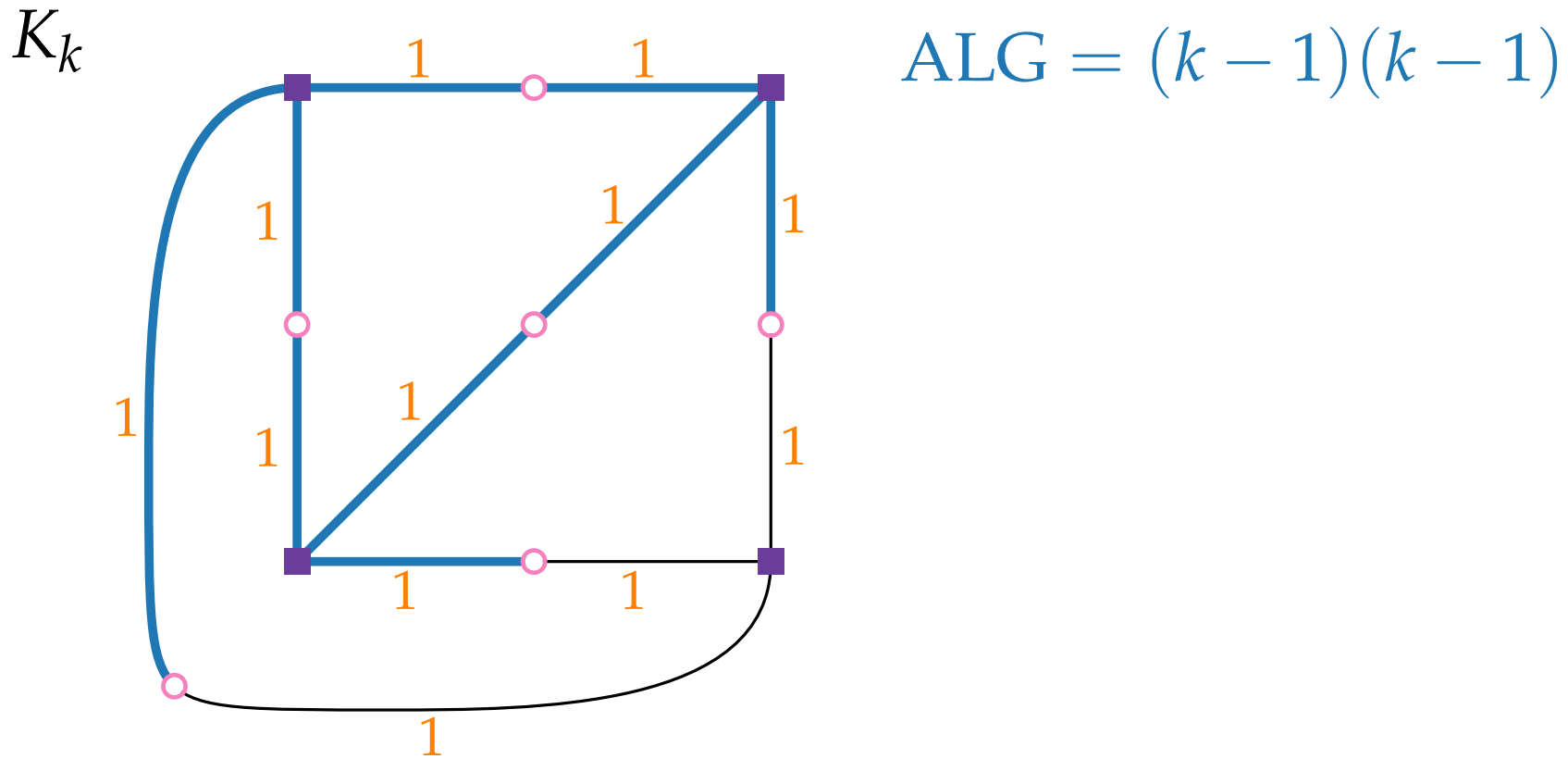
Analysis Sharp?

 K_k


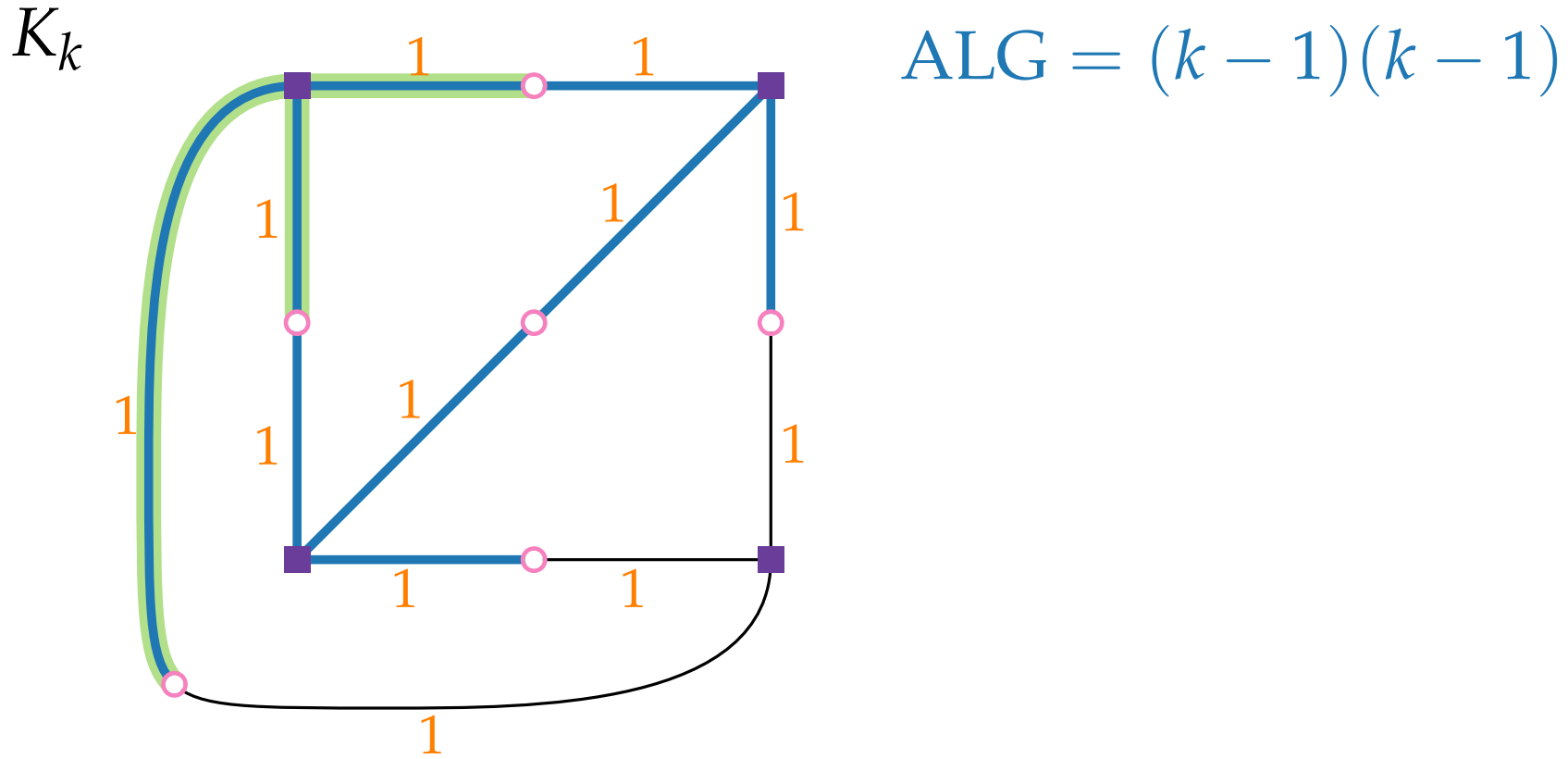
Analysis Sharp?

 K_k 

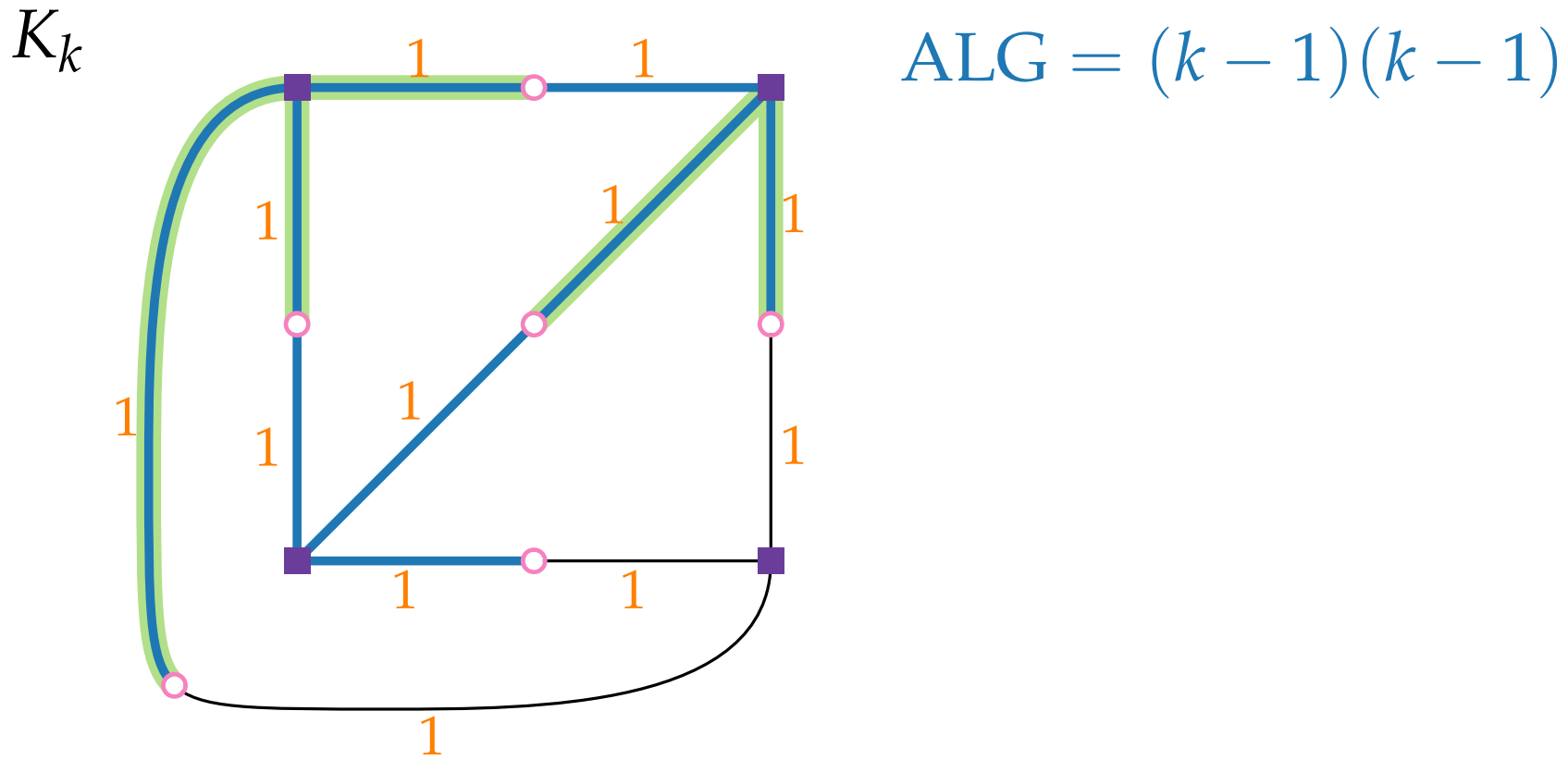
Analysis Sharp?



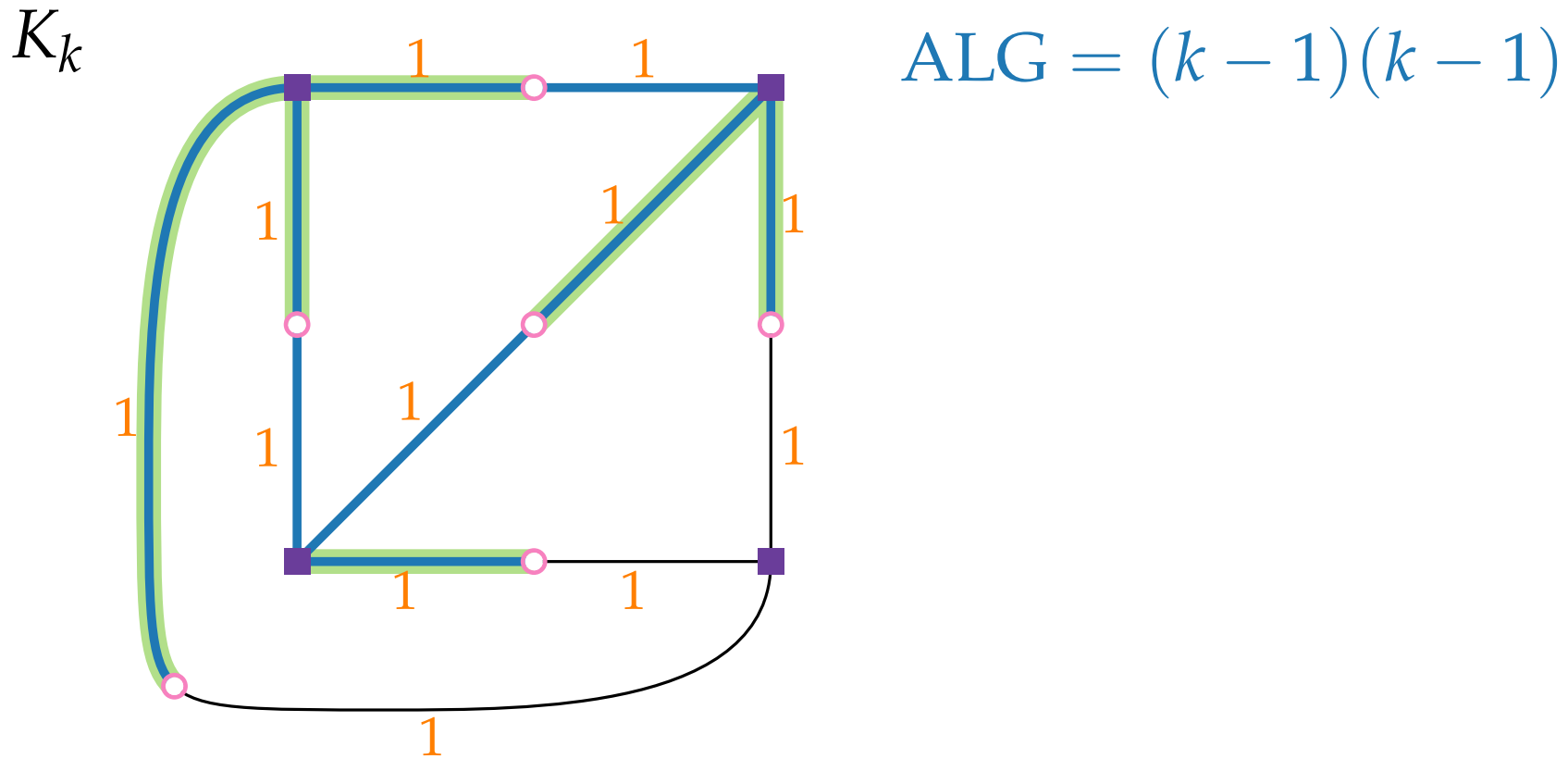
Analysis Sharp?



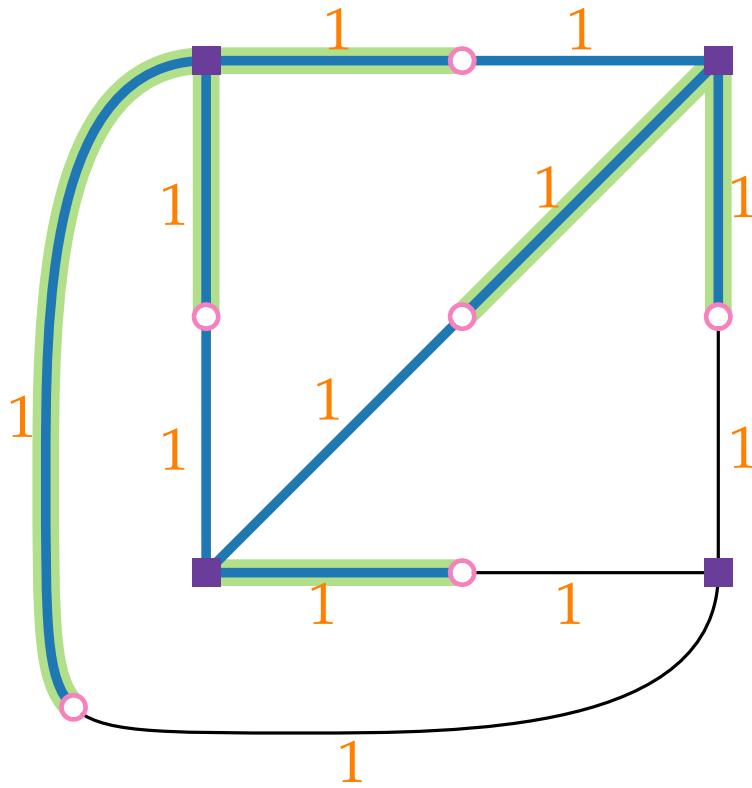
Analysis Sharp?



Analysis Sharp?



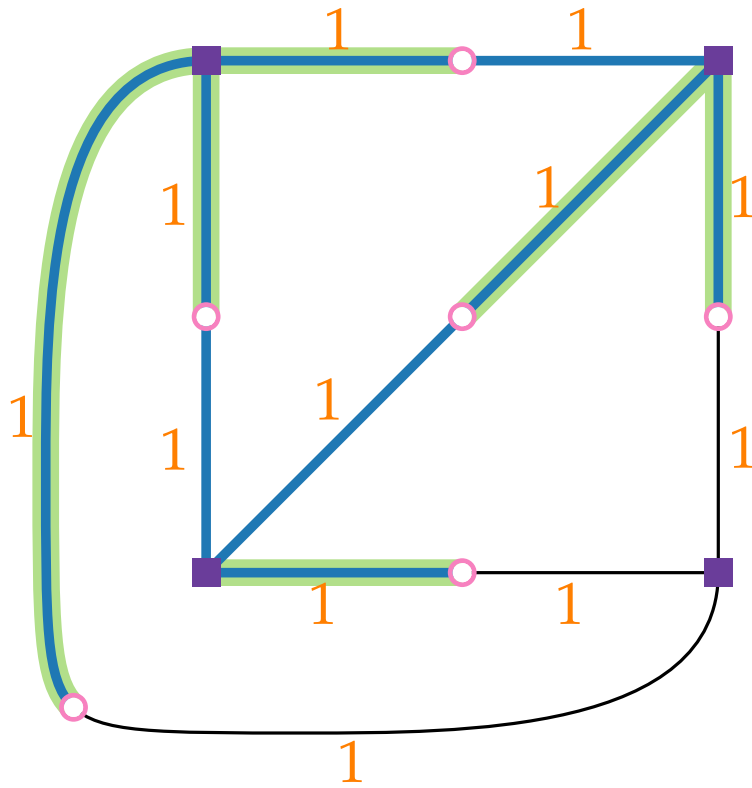
Analysis Sharp?

 K_k


$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i =$$

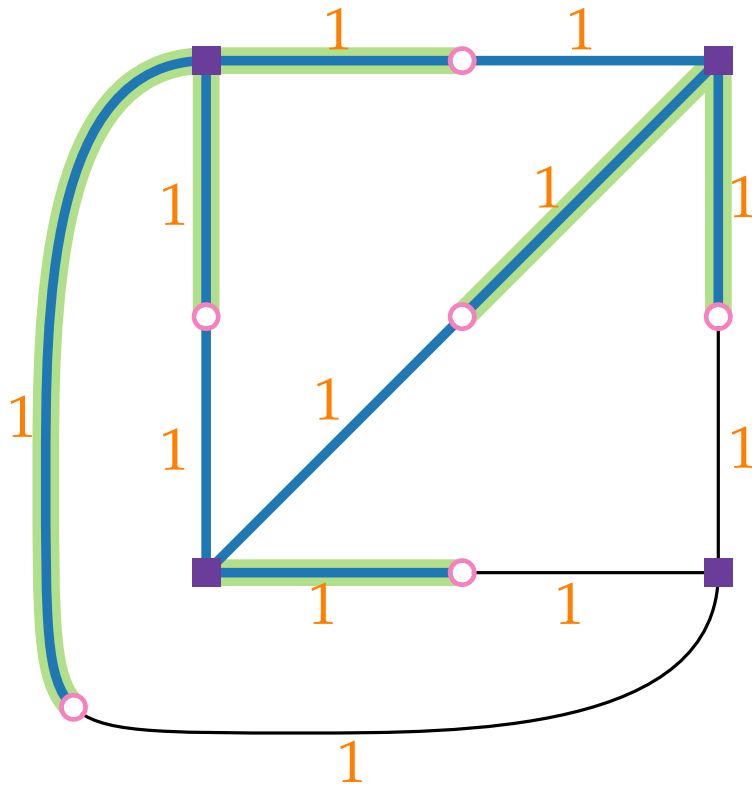
Analysis Sharp?

 K_k


$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

Analysis Sharp?

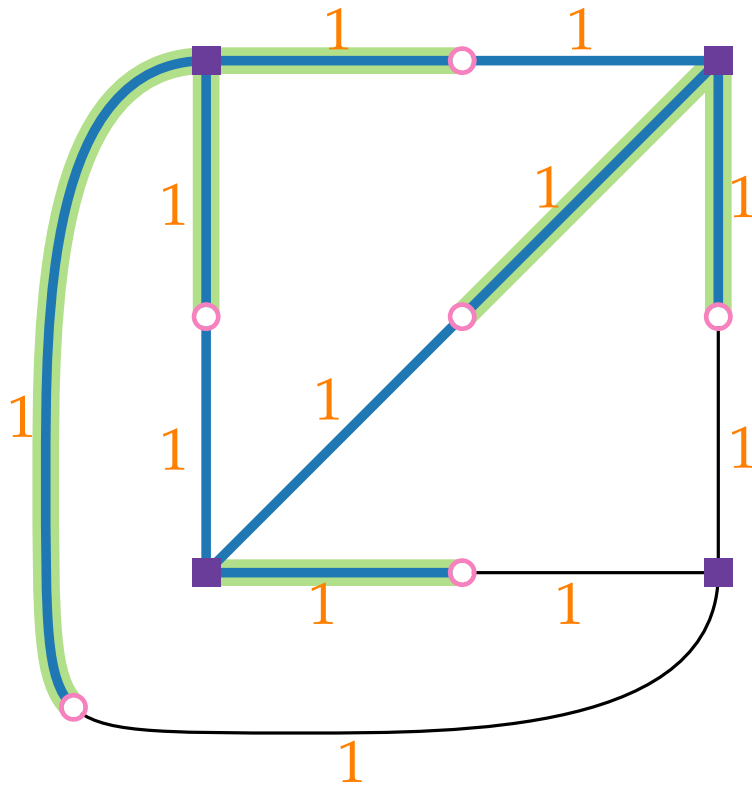
 K_k


$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

$$\text{ALG} / \text{OPT} =$$

Analysis Sharp?

 K_k


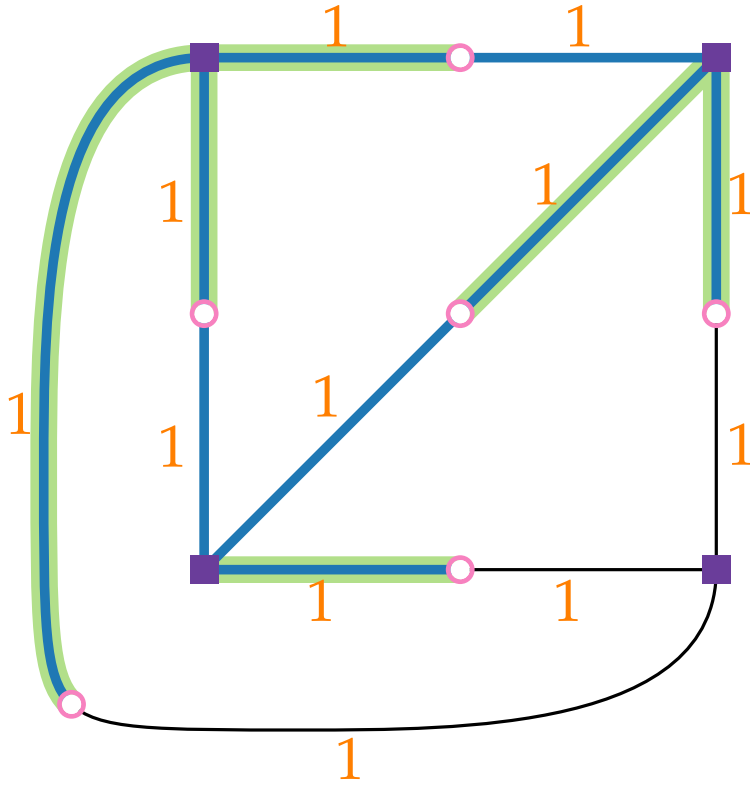
$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

$$\text{ALG} / \text{OPT} = \frac{2k-2}{k} =$$

Analysis Sharp?

K_k

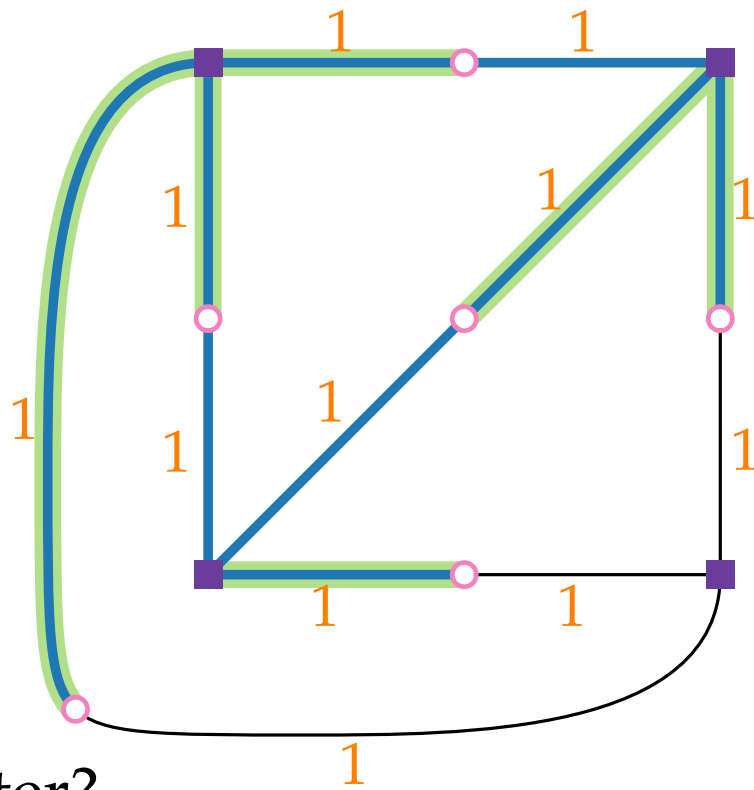


$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

$$\text{ALG}/\text{OPT} = \frac{2k-2}{k} = 2 - \frac{2}{k}$$

Analysis Sharp?

 K_k


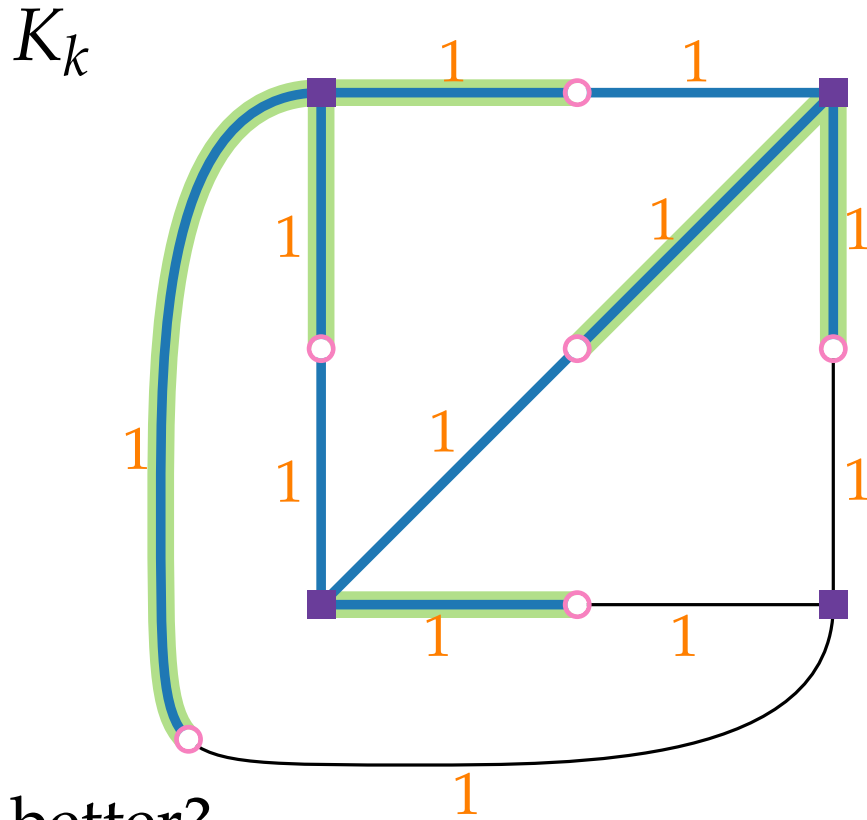
better?

$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

$$\text{ALG/OPT} = \frac{2k-2}{k} = 2 - \frac{2}{k}$$

Analysis Sharp?



$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

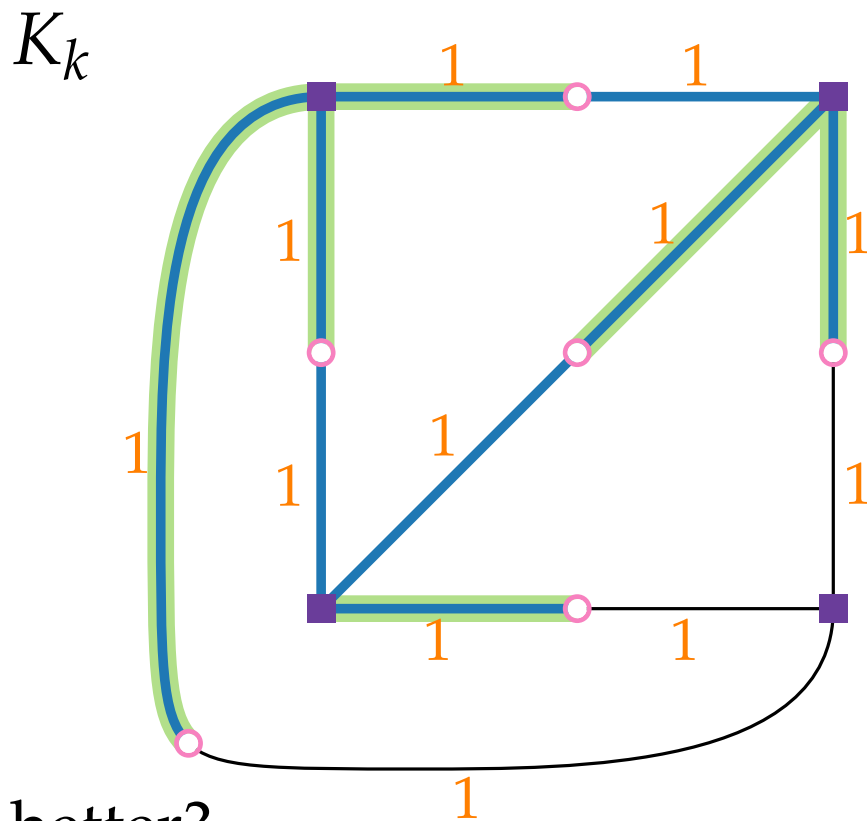
$$\text{ALG}/\text{OPT} = \frac{2k-2}{k} = 2 - \frac{2}{k}$$

better?

The best known approximation factor for
MULTIWAYCUT is $1.2965 - \frac{1}{k}$.

[Sharma & Vondrák '14]

Analysis Sharp?



$$\text{ALG} = (k - 1)(k - 1)$$

$$\text{OPT} = \sum_{i=1}^{k-1} i = \frac{k \cdot (k-1)}{2}$$

$$\text{ALG}/\text{OPT} = \frac{2k-2}{k} = 2 - \frac{2}{k}$$

better?

The best known approximation factor for

MULTIWAYCUT is $1.2965 - \frac{1}{k}$.

[Sharma & Vondrák '14]

MULTIWAYCUT cannot be approximated within factor

$1.20016 - O(1/k)$ (unless $P=NP$).

[Bérczi, Chandrasekaran, Király & Madan '18]