

# Outside-Obstacle Representations with All Vertices on the Outer Face

**Oksana Firman**

Philipp Kindermann

Jonathan Klawitter

Boris Klemz

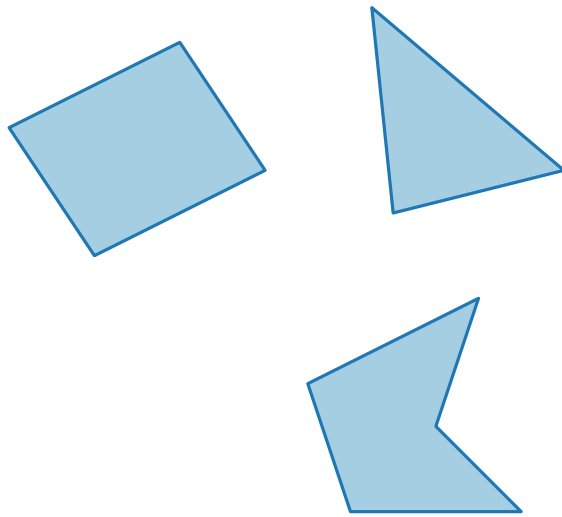
Felix Klesen

Alexander Wolff



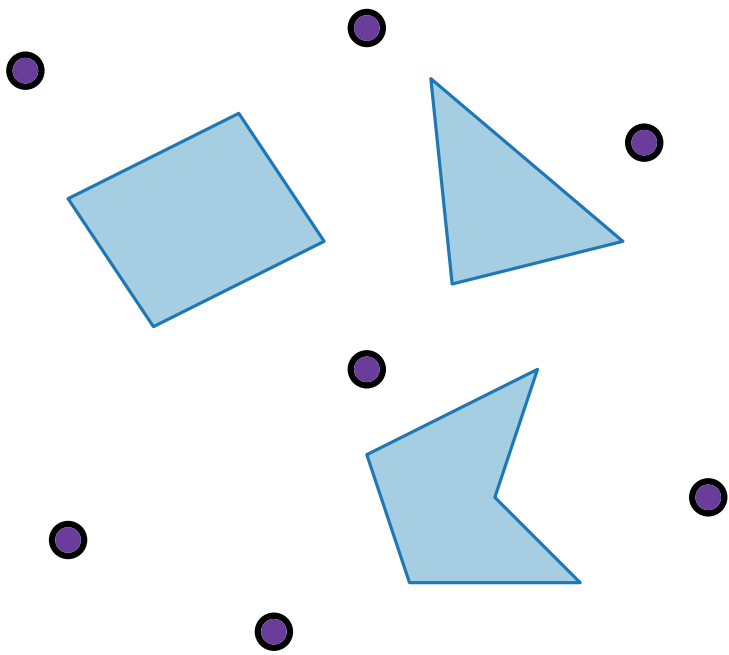
# Visibility Graph

**Given:** ■ a set of polygons  $\mathcal{C}$  (*obstacles*)



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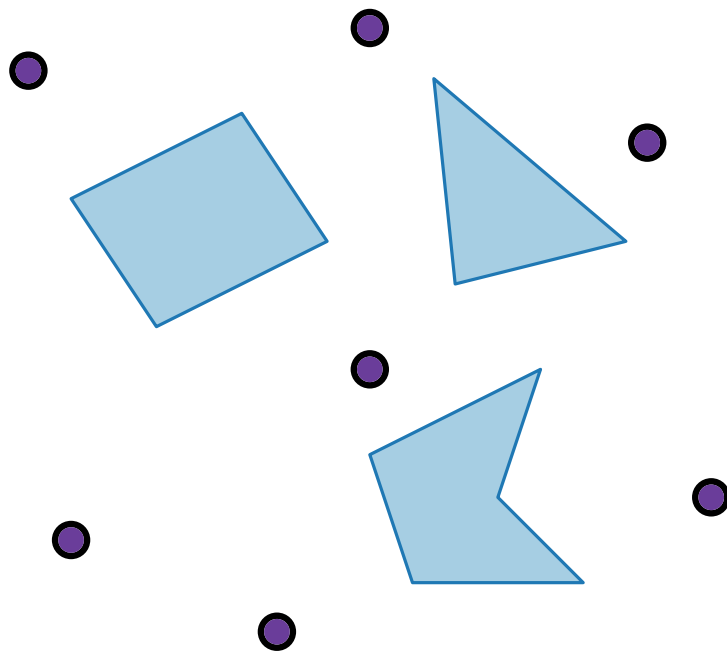


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induces ...

visibility graph  $G_{\mathcal{C}}(P)$

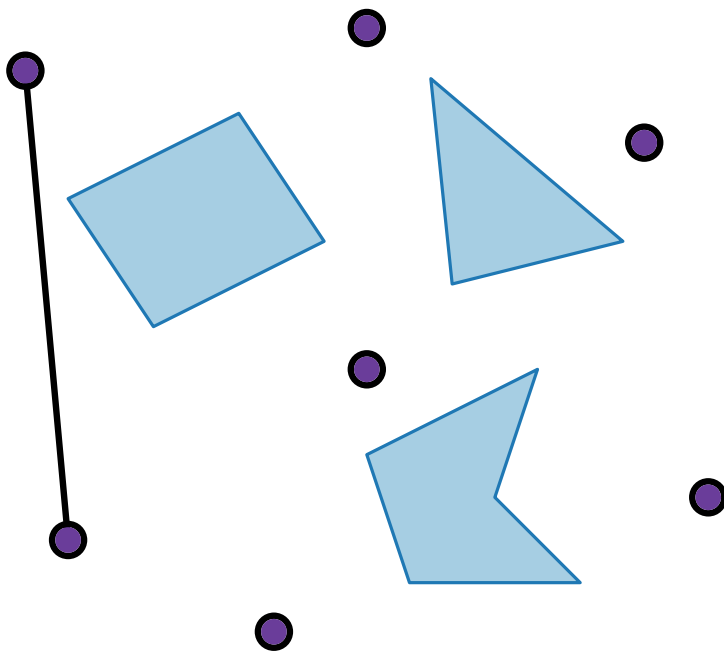


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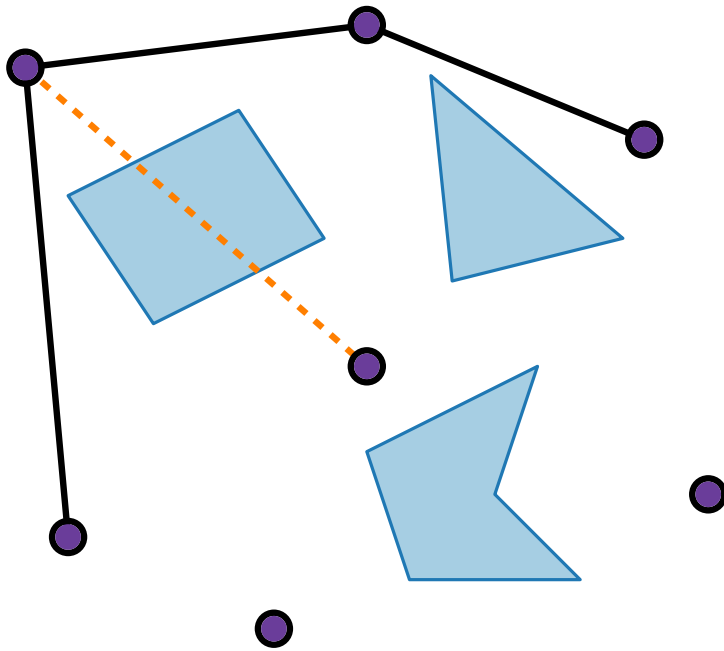


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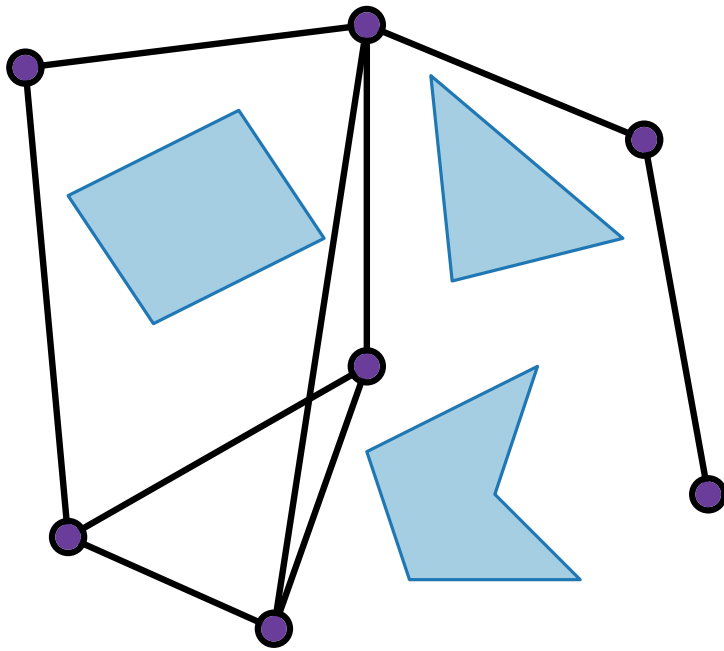


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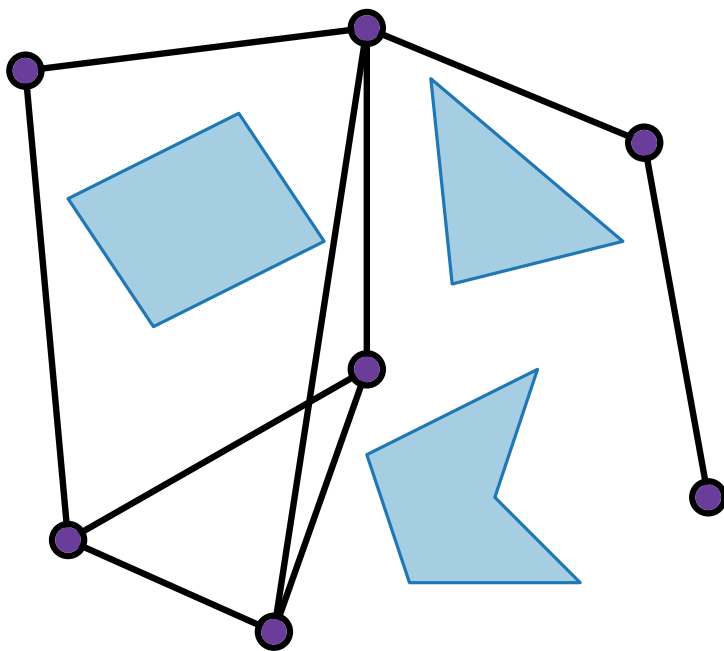


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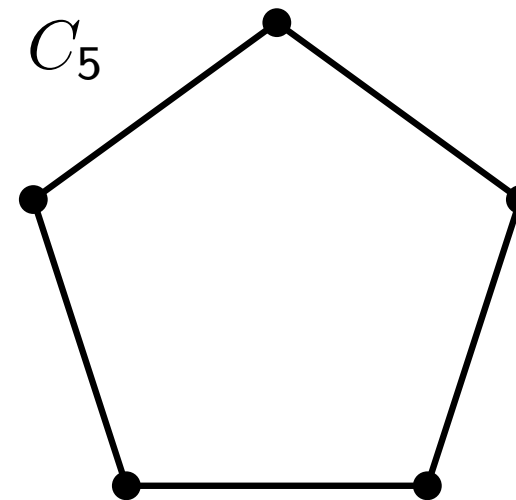
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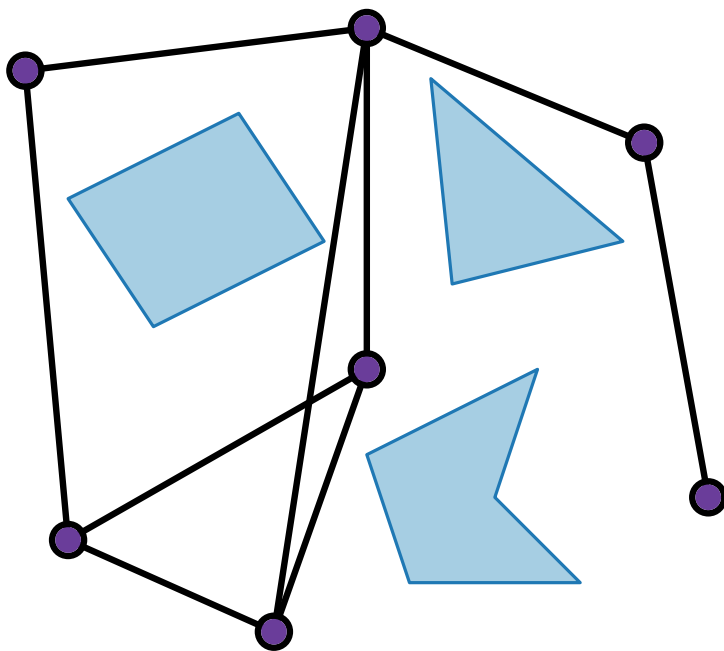


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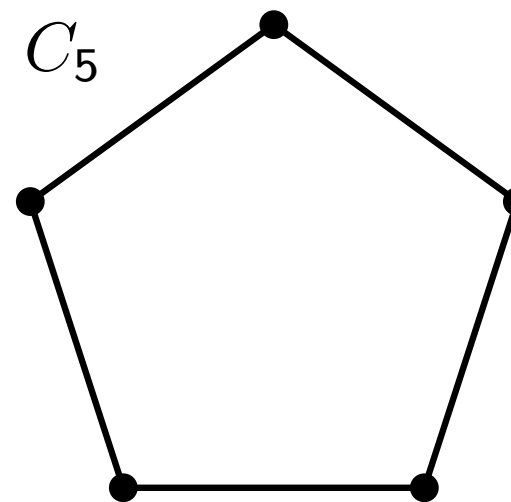
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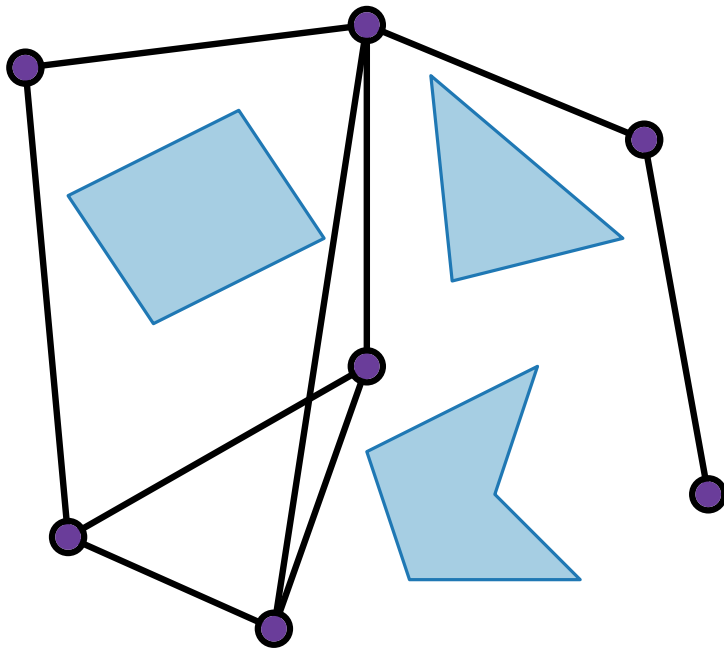


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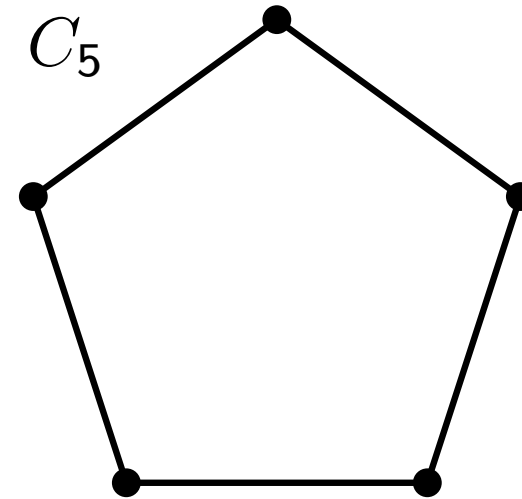
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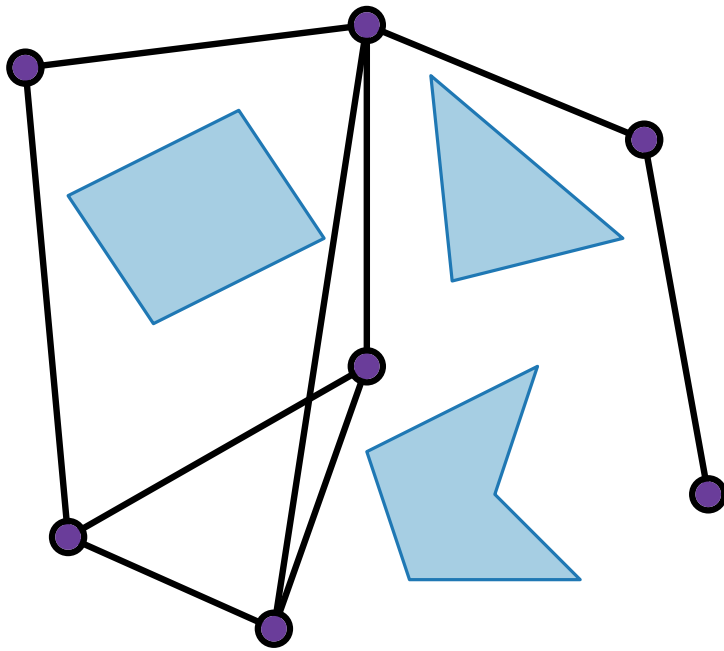


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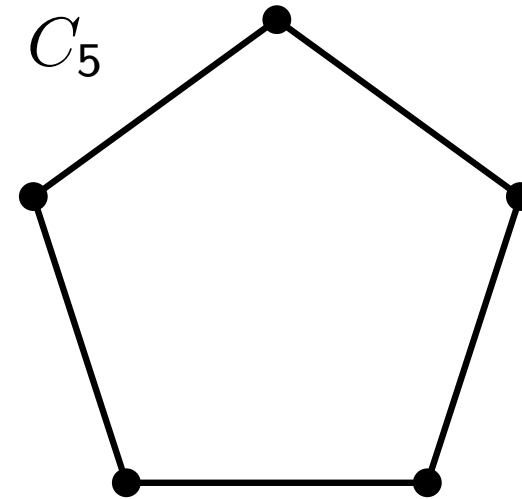
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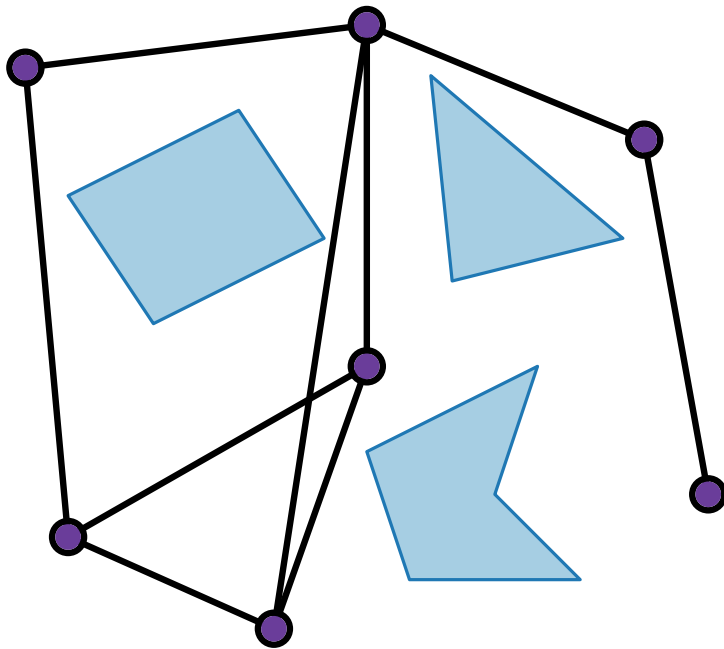


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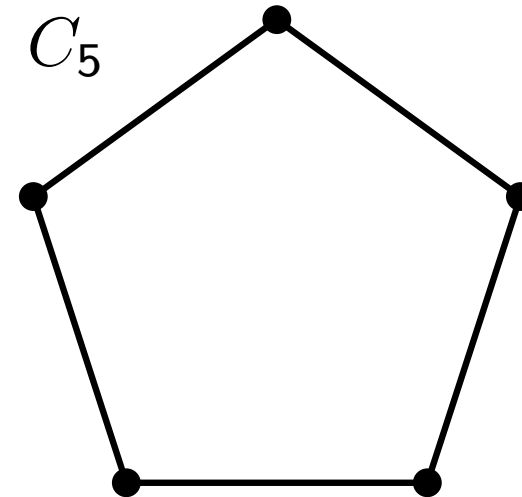
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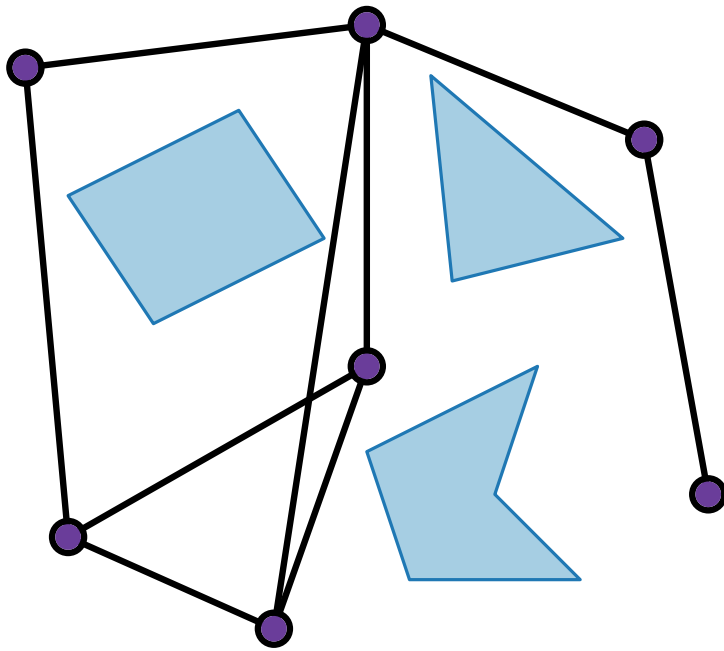


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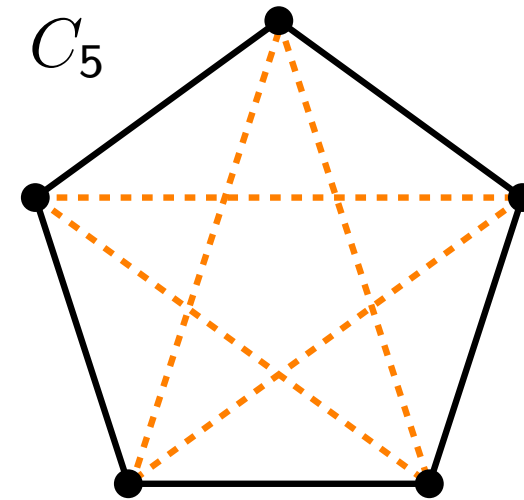


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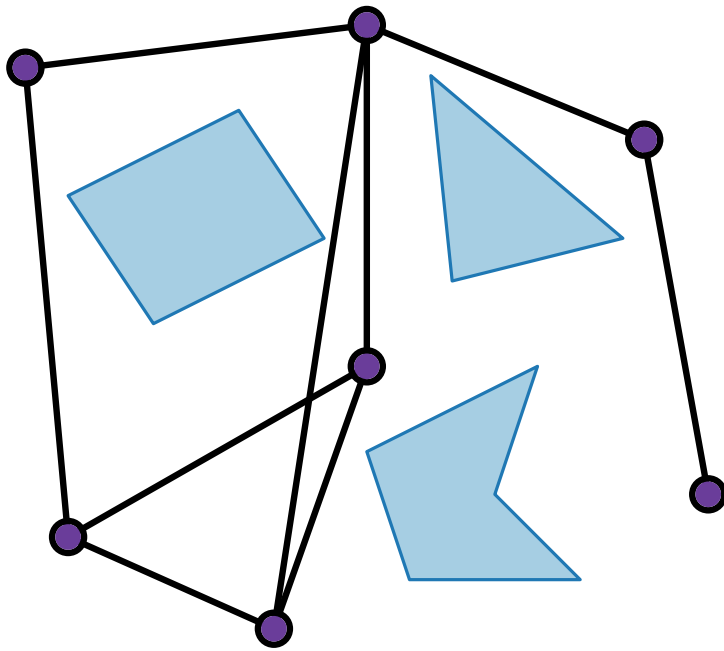


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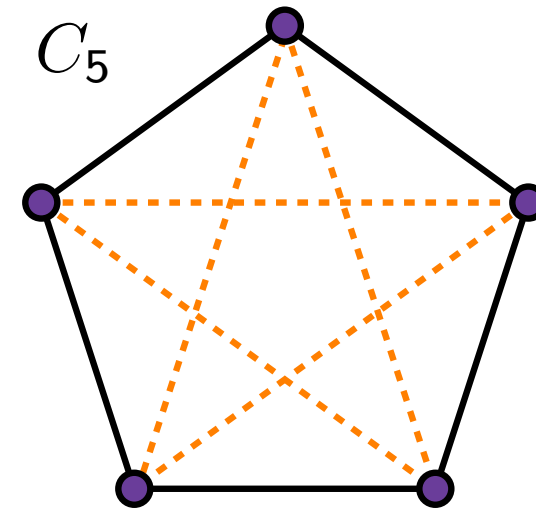


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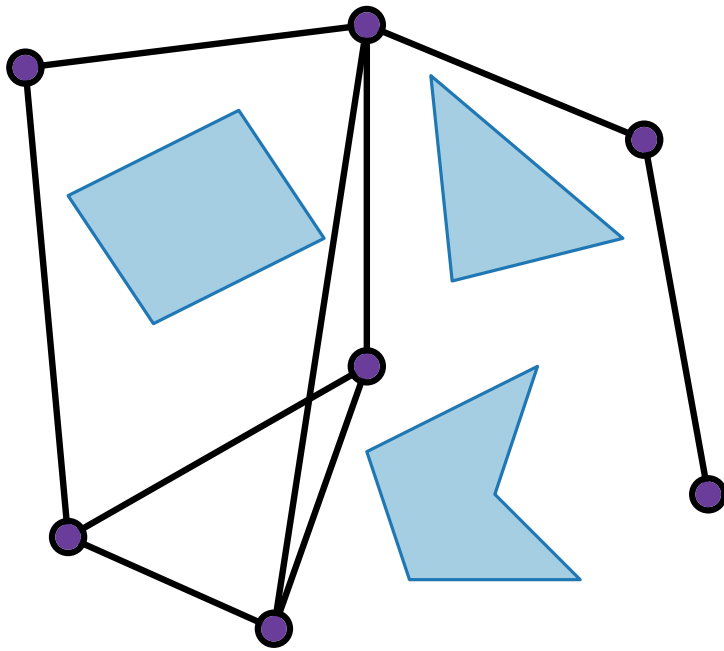


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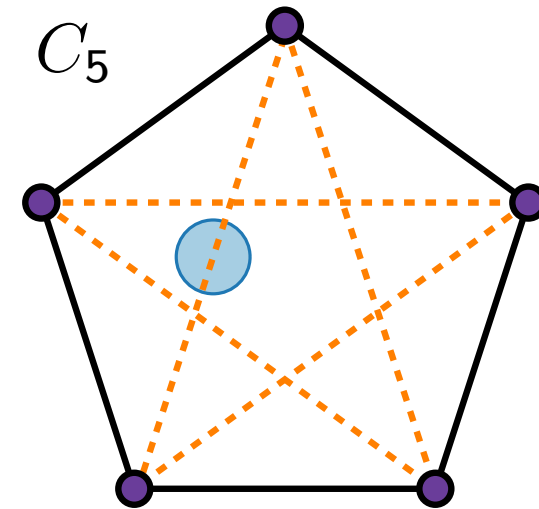


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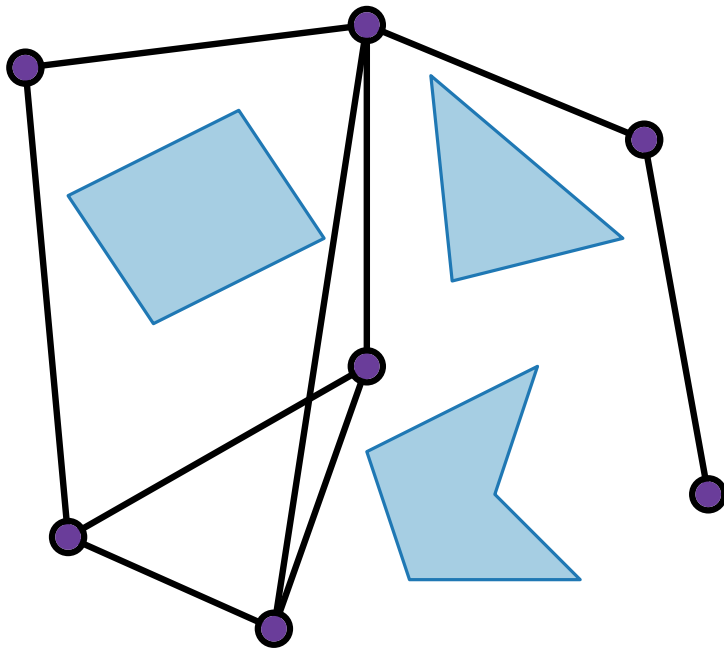


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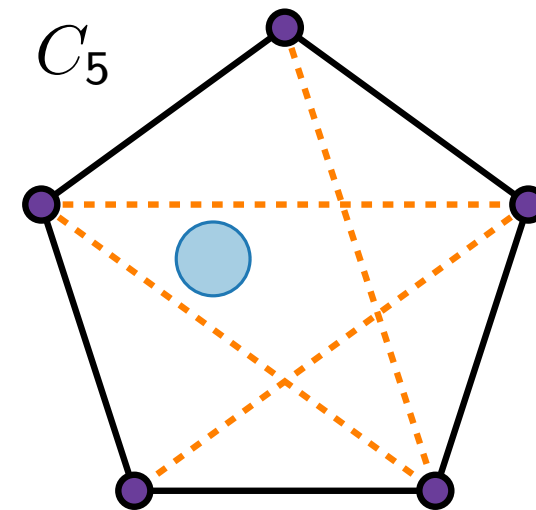
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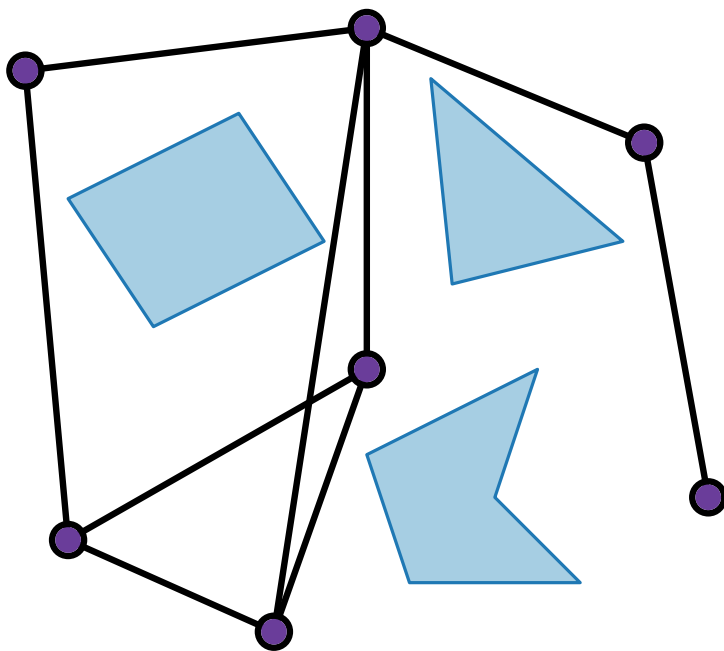


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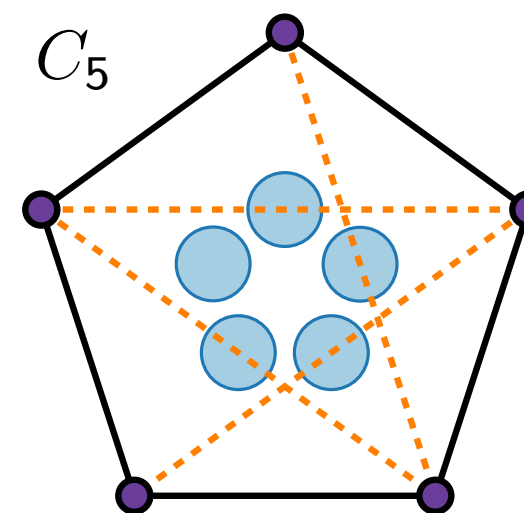
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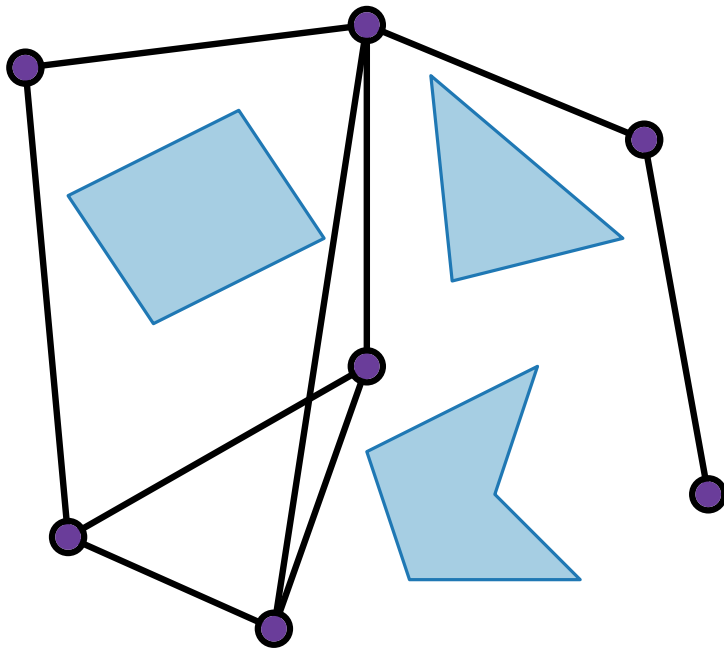


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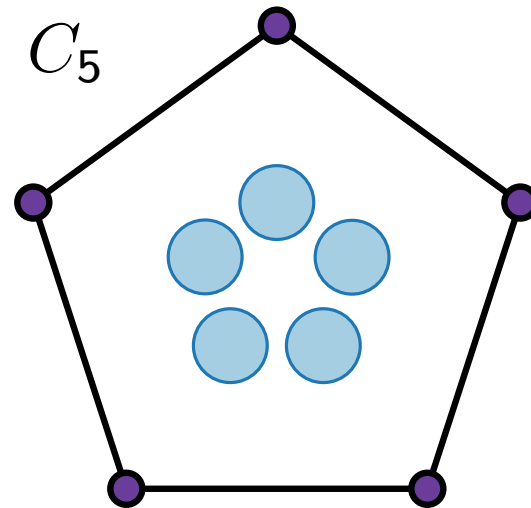
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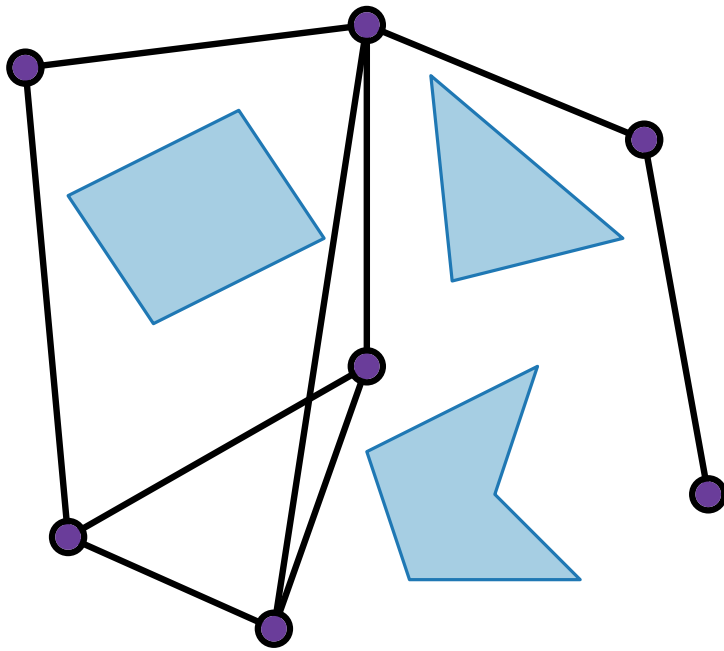


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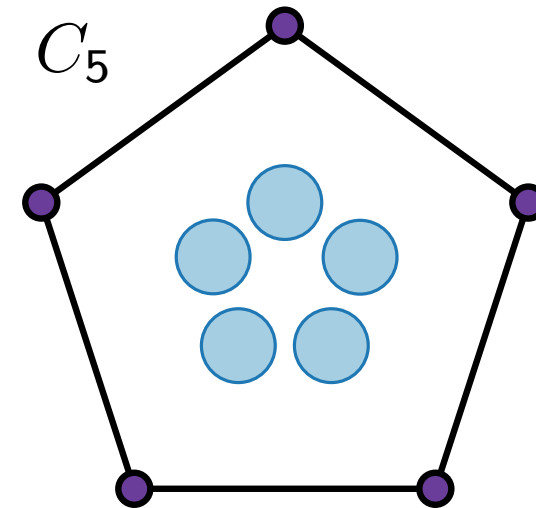
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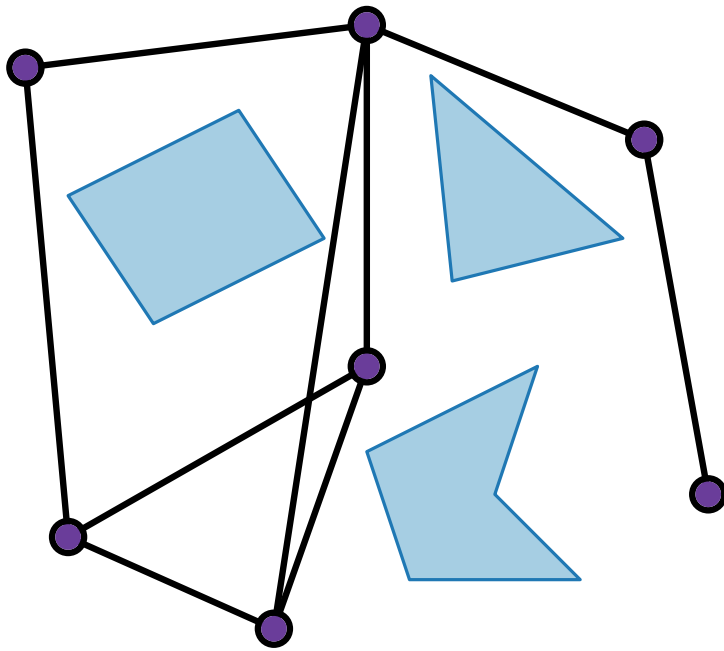


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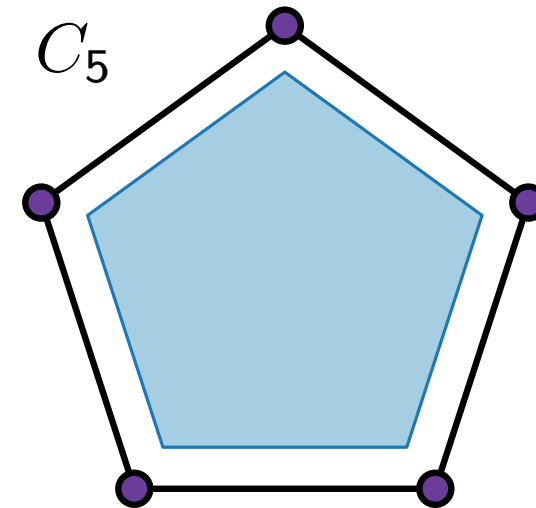
$\Rightarrow$  minimization  
problem

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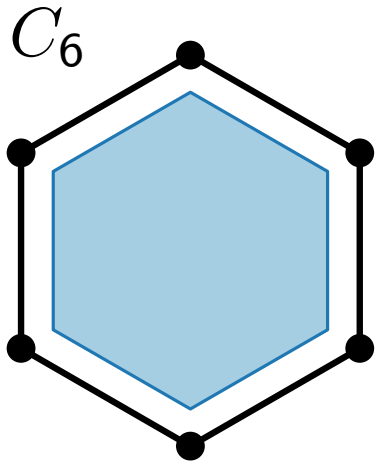
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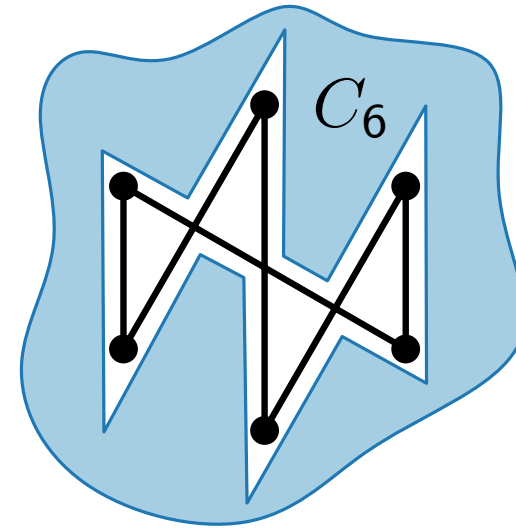
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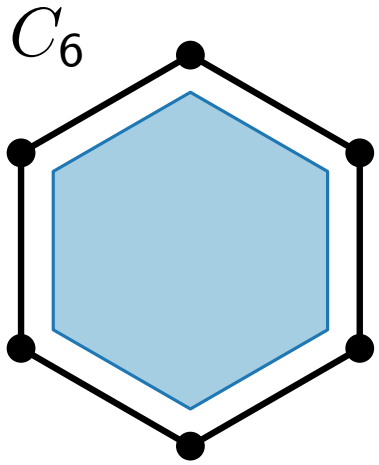


inside obstacle

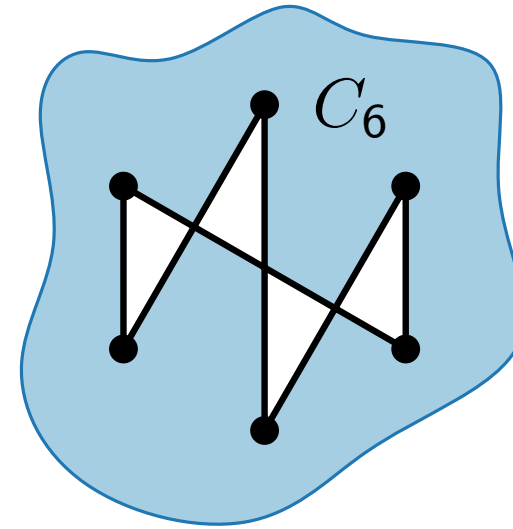


outside obstacle

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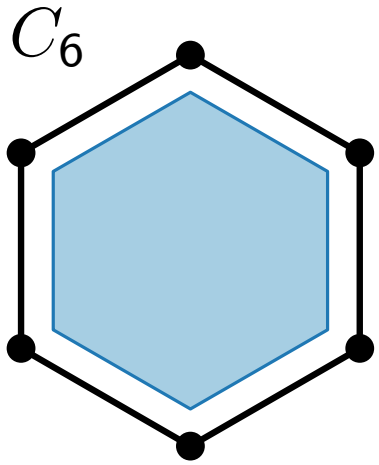


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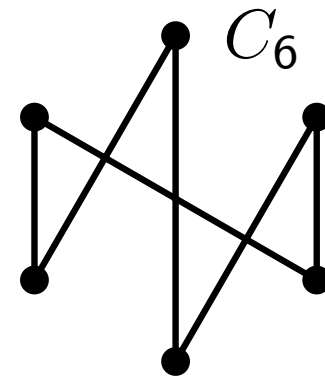


outside obstacle

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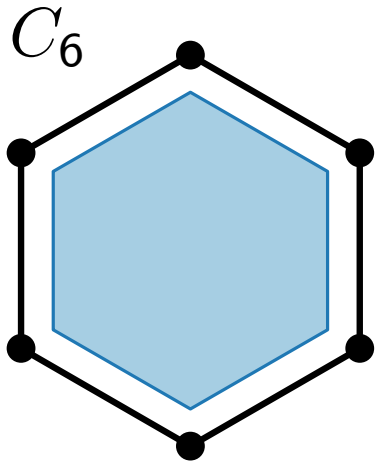
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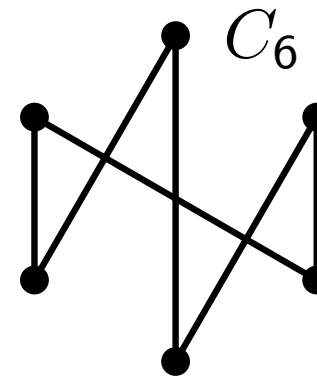
# Previous Work



inside obstacle

- single convex obstacle

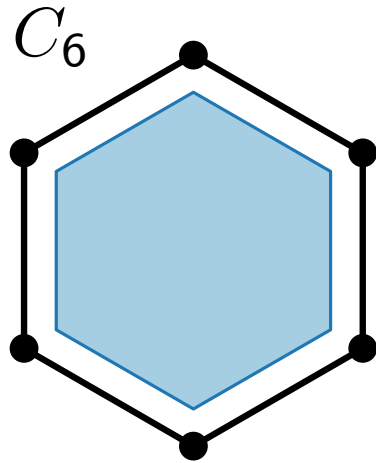
[Alpert et al.,  
DCG 2010]



outside obstacle

- every outerplanar graph

# Previous Work

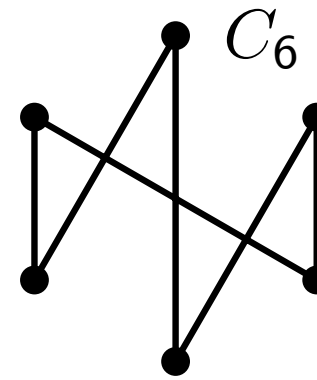


inside obstacle

- single convex obstacle
- necessary conditions to have a single obstacle
- planar graphs (icosahedron needs 2 obstacles)

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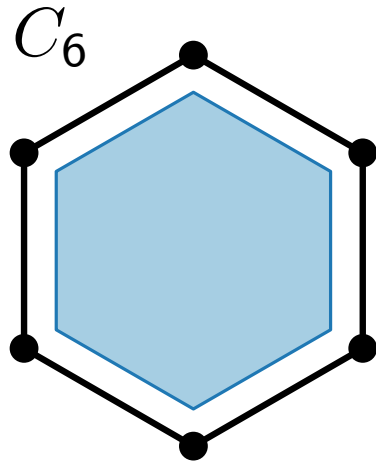
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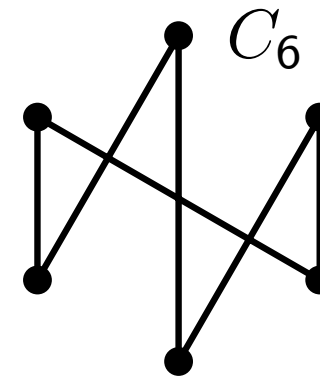
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[Chaplick et al.,  
*GD* 2016]

- incomparable (with a single obstacle)

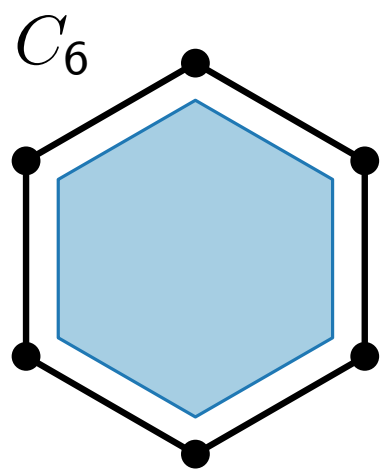


outside obstacle

- every outerplanar graph

- every graph with  $\leq 7$  vertices

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inside obstacle

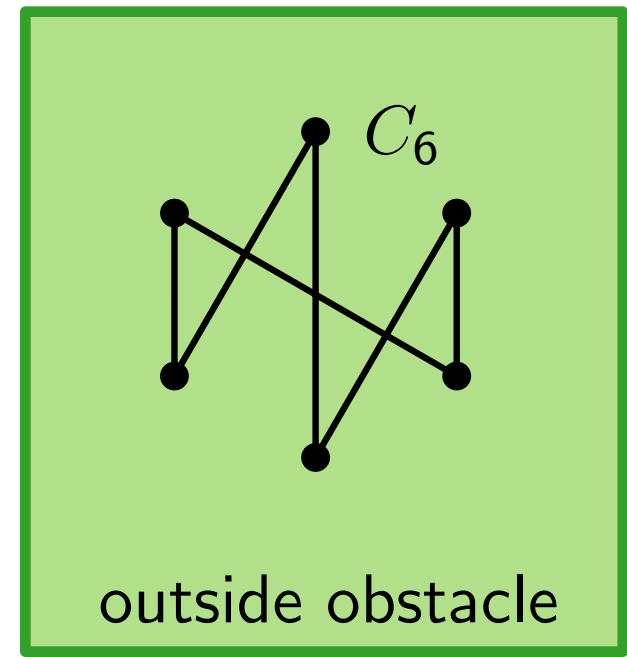
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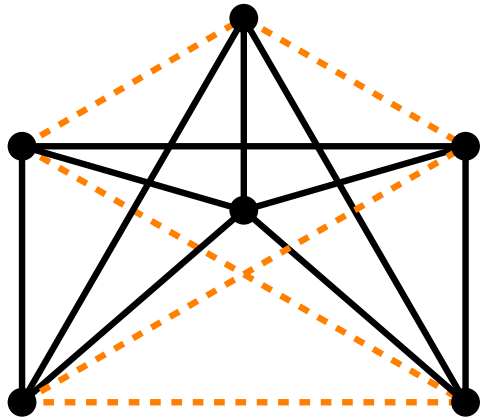


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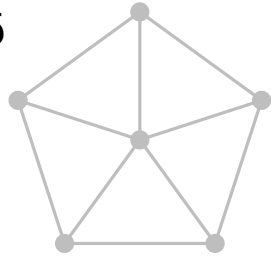
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# Types of Outside-Obstacle Representation

General



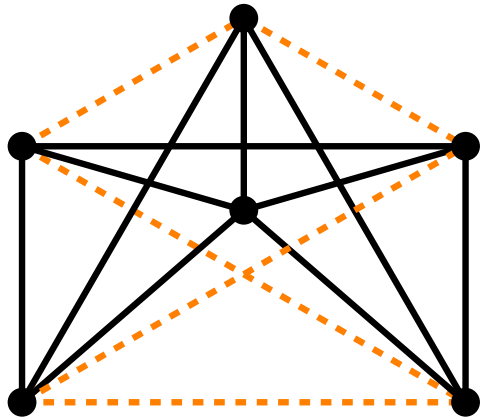
$W_6$



all vertices on  
the outer face

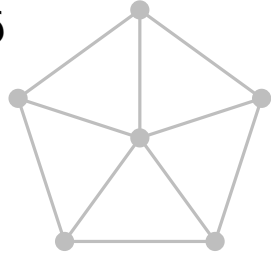
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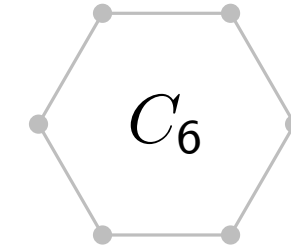
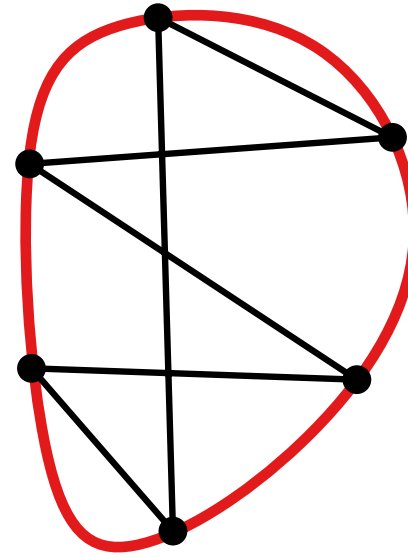


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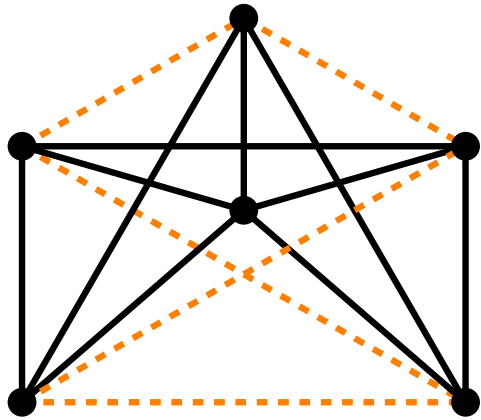


Convex



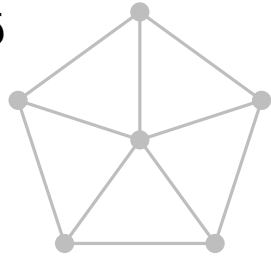
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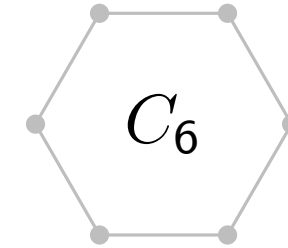
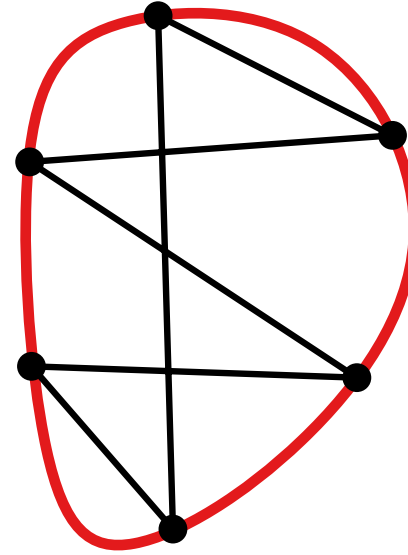


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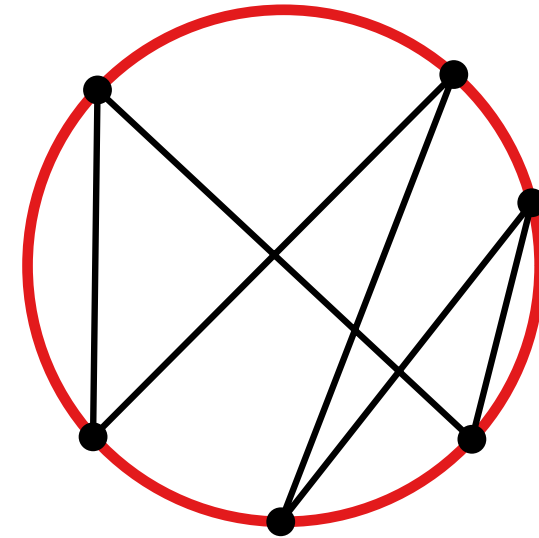
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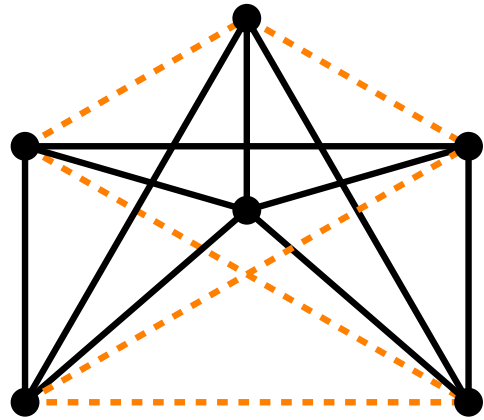


Circular



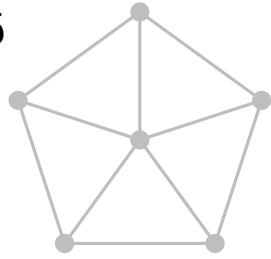
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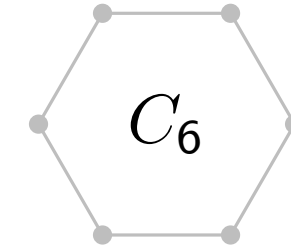
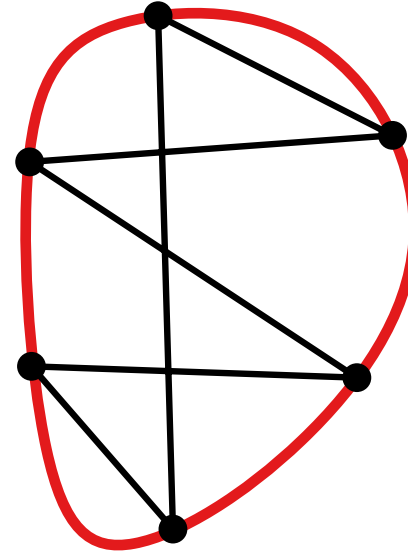


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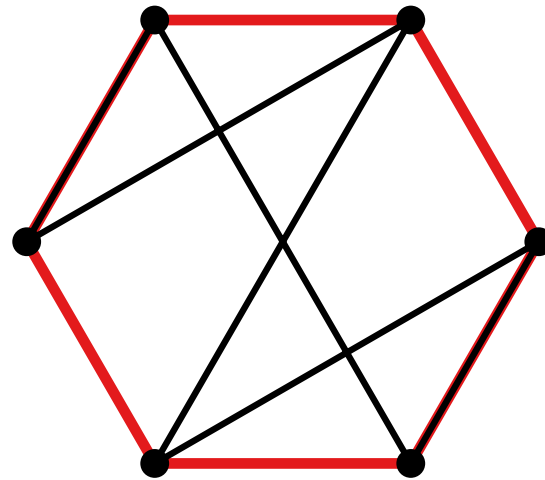


Convex

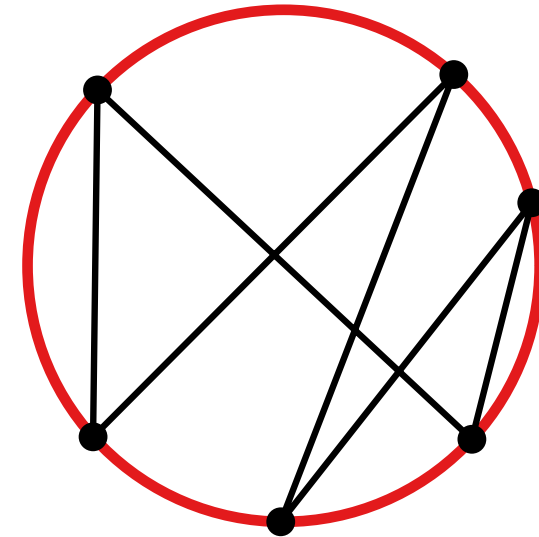


$C_6$

Regular



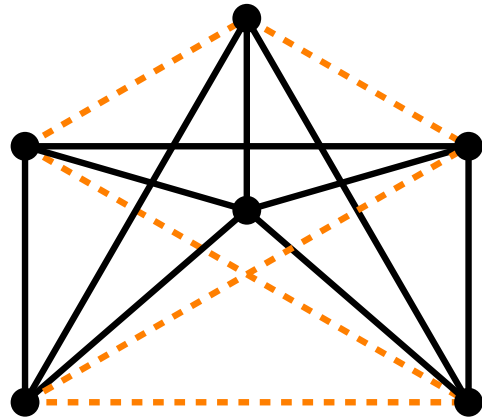
Circular





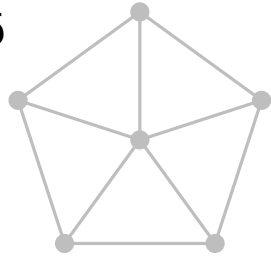
# Types of Outside-Obstacle Representation

General

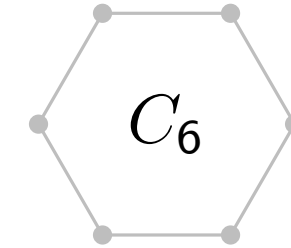
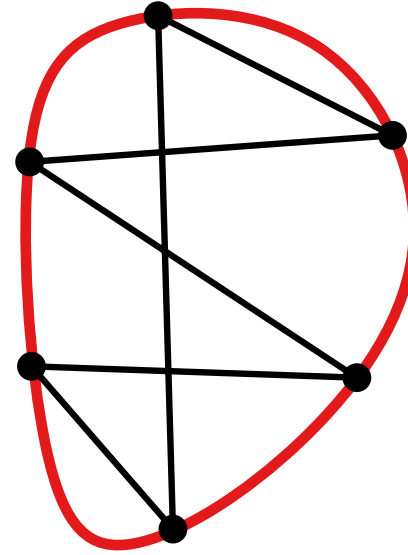


all vertices on  
the outer face

$W_6$



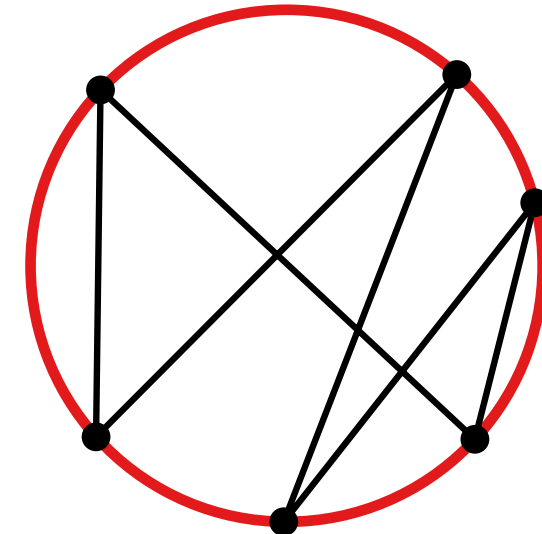
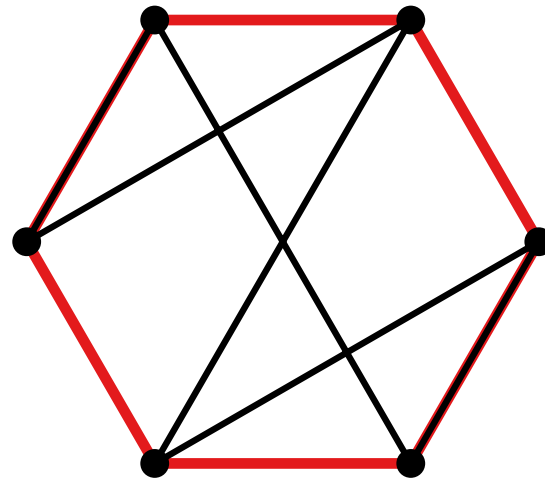
Convex



Circular

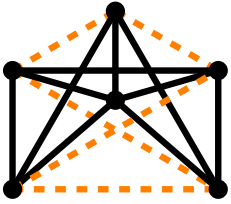


Regular



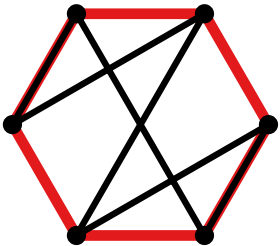
# Our Contribution

## General

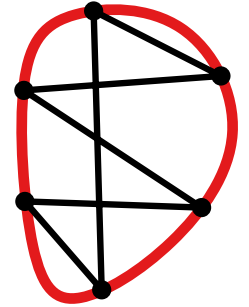


all vertices on  
the outer face

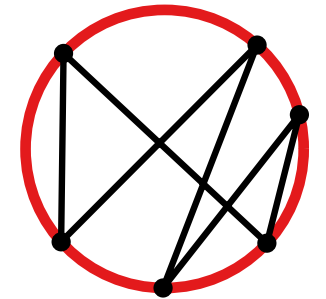
## Regular



## Convex

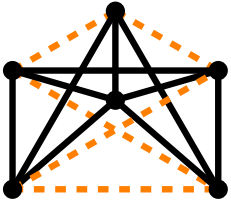


## Circular



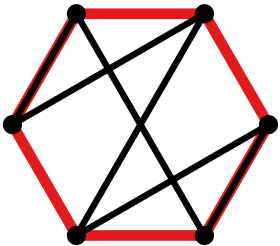
# Our Contribution

## General



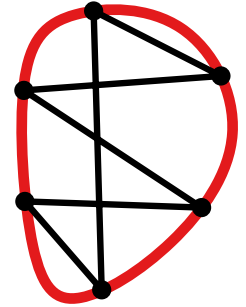
all vertices on  
the outer face

## Regular

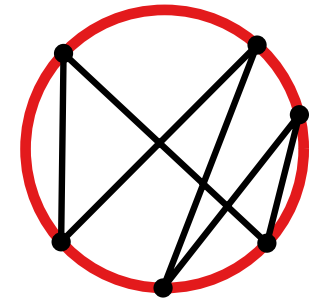


■ cactus

## Convex

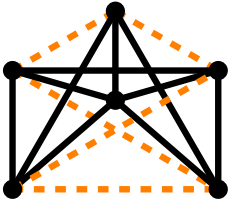


## Circular



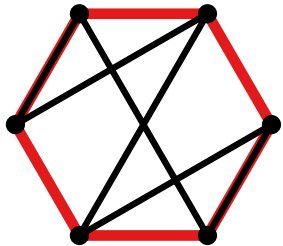
# Our Contribution

## General



all vertices on  
the outer face

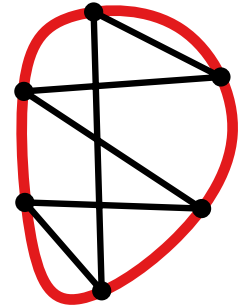
## Regular



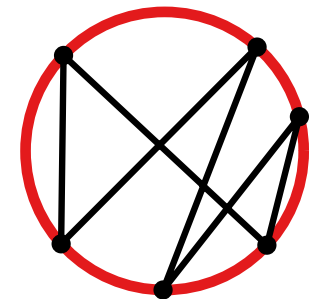
■ cactus

■ grid

## Convex

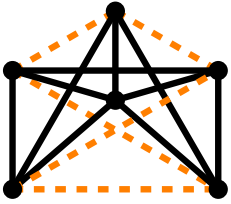


## Circular



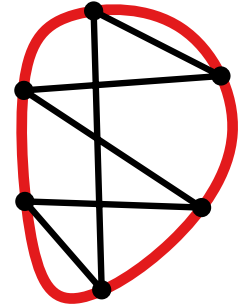
# Our Contribution

## General

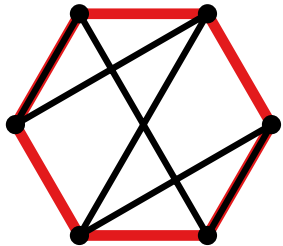


all vertices on  
the outer face

## Convex

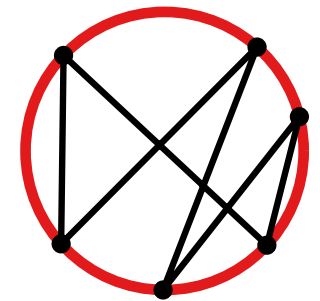


## Regular



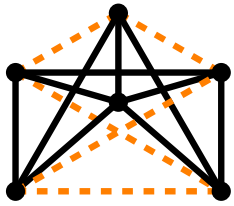
- cactus
- grid
- outerpath

## Circular



# Our Contribution

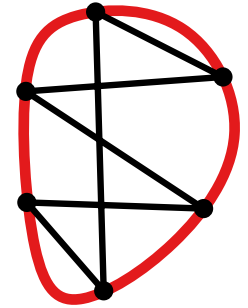
## General



all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]

## Convex

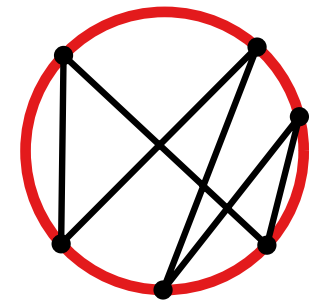


## Regular



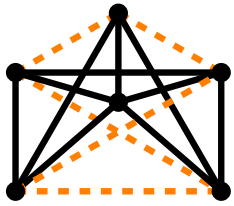
- cactus
- grid
- outerpath

## Circular



# Our Contribution

## General



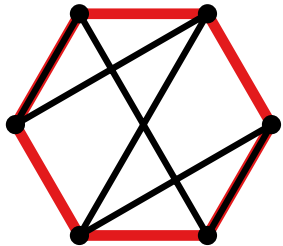
all vertices on  
the outer face

■ outerplanar graph

[Alpert et al.,  
*DCG 2010*]

■ 2-tree

## Regular

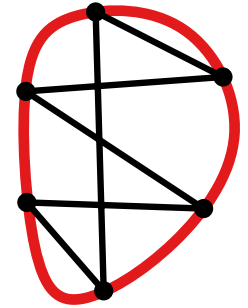


■ cactus

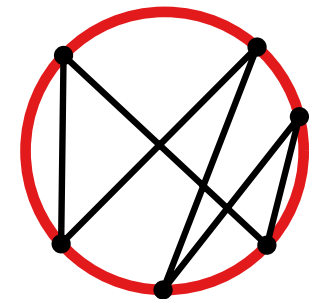
■ grid

■ outerpath

## Convex

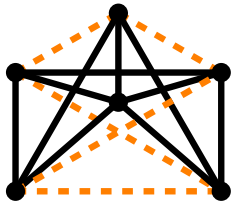


## Circular



# Our Contribution

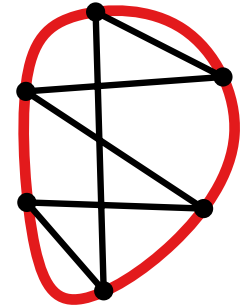
## General



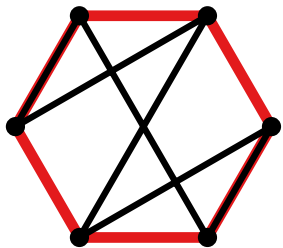
all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs?)

## Convex

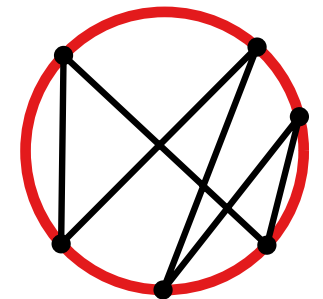


## Regular



- cactus (subgraphs?)
- grid (subgraphs?)
- outerpath (subgraphs?)

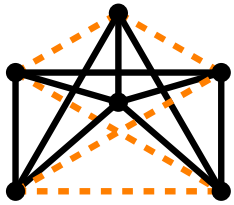
## Circular





# Our Contribution

## General

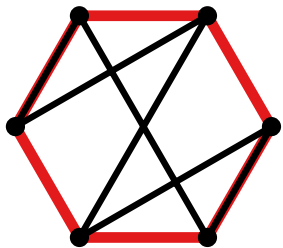


all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs?)

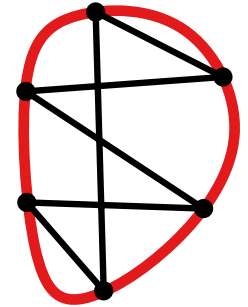
**Def.** An outside-obstacle representation of a graph is *reducible* if all its edges are incident to the outer face.

## Regular

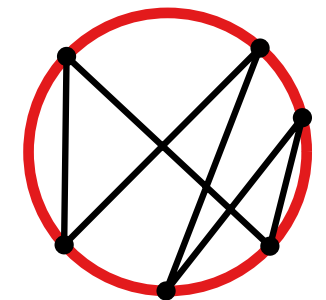


- cactus (subgraphs?)
- grid (subgraphs?)
- outerpath (subgraphs?)

## Convex

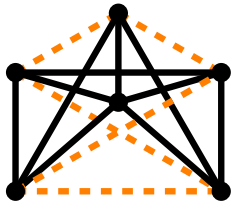


## Circular



# Our Contribution

## General

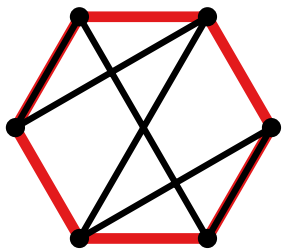


all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs ✓)

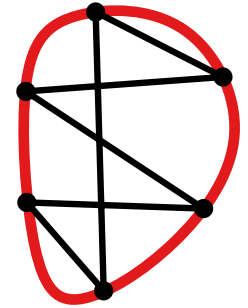
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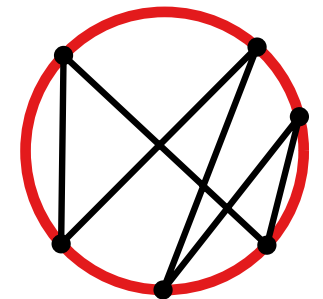


- cactus (subgraphs ✓)
- grid (subgraphs ✓)
- outerpath (subgraphs ✓)

## Convex

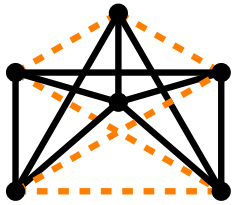


## Circular



# Our Contribution

## General

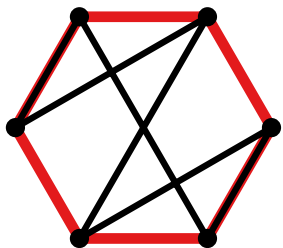


all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
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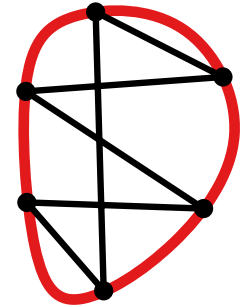
## Regular



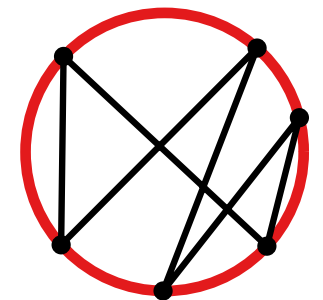
- cactus (subgraphs ✓)
- grid (subgraphs ✓)
- outerpath (subgraphs ✓)

- consecutive-neighbors property *sufficient*

## Convex

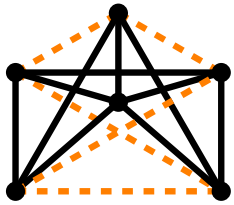


## Circular



# Our Contribution

## General

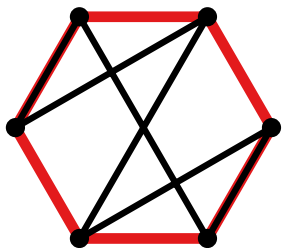


all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs ✓)

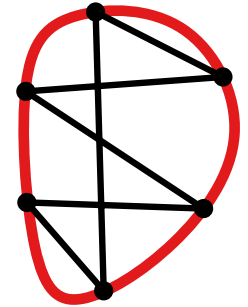
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## Regular



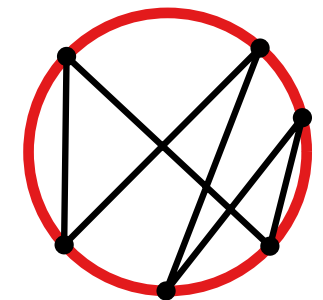
- cactus (subgraphs ✓)
- grid (subgraphs ✓)
- outerpath (subgraphs ✓)

## Convex



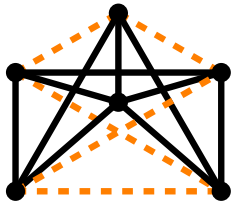
- consecutive-neighbors property *sufficient*
- gap condition *necessary*

## Circular



# Our Contribution

## General

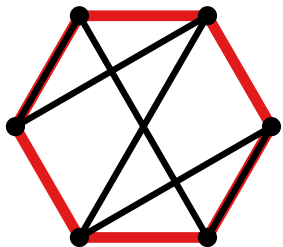


all vertices on  
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- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs ✓)

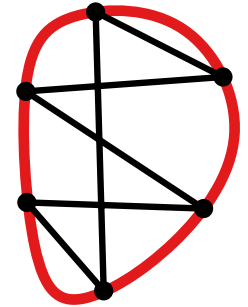
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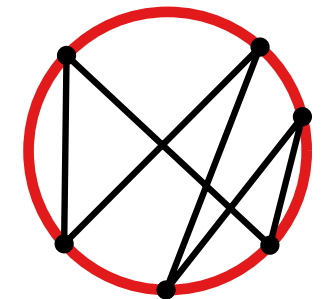
- cactus (subgraphs ✓)
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## Convex



- consecutive-neighbors property *sufficient*
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## Circular

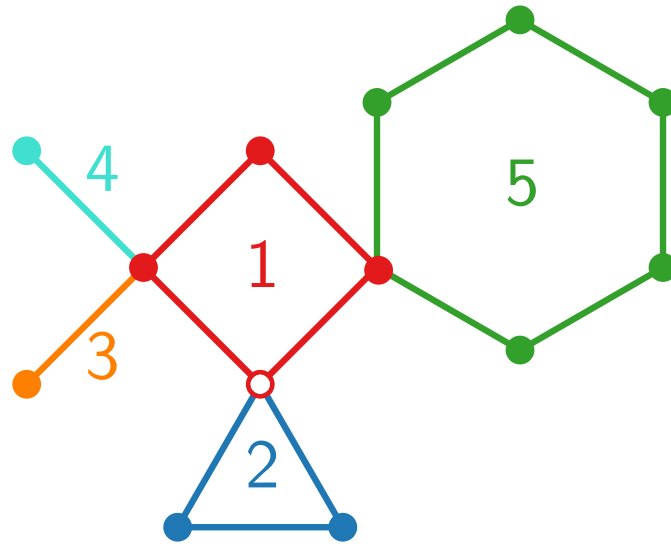


# Regular Outside-Obstacle Representation

## Theorem.

Every **cactus** admits a reducible regular outside-obstacle representation.

A *cactus* is a connected graph where every edge is contained in at most *one* simple cycle.

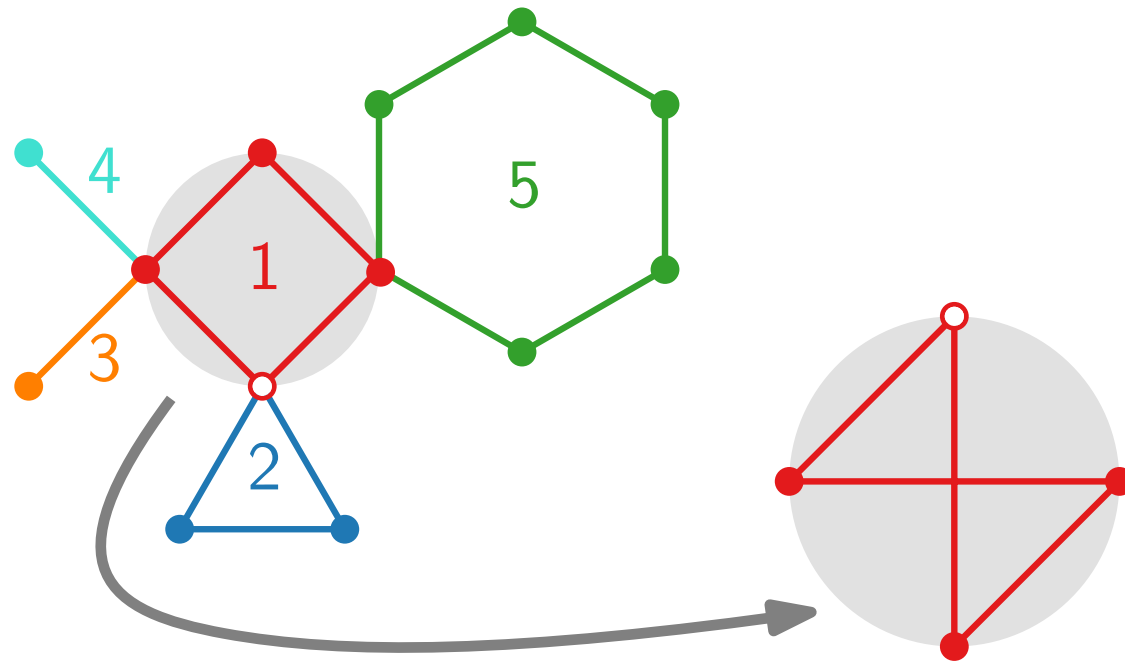


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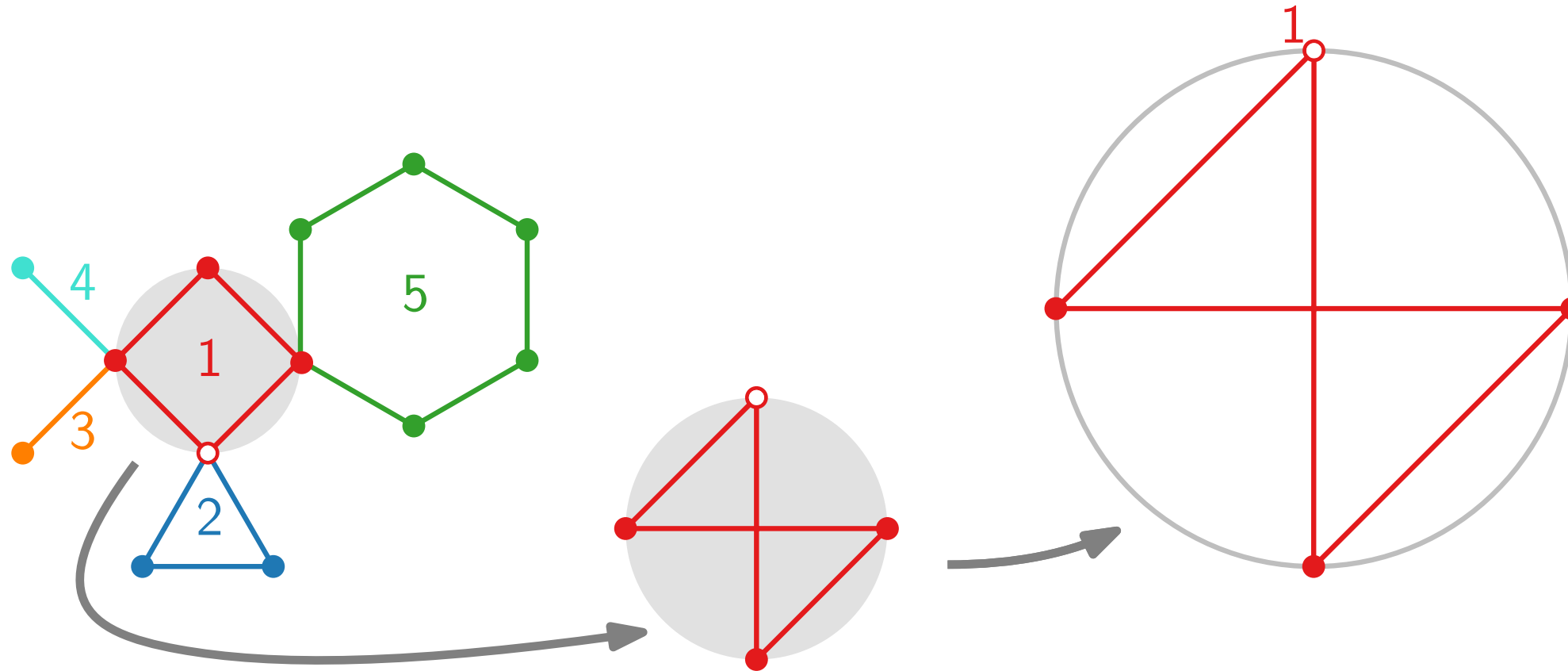


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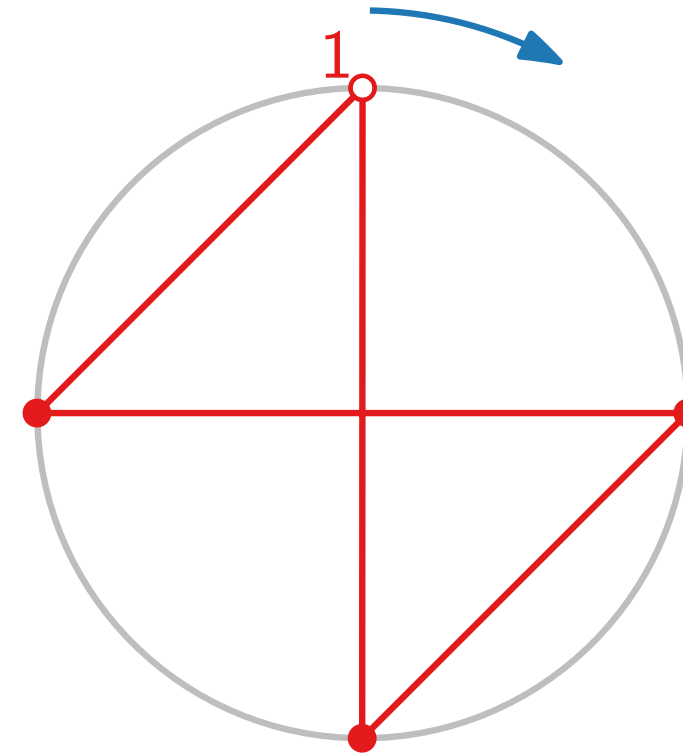
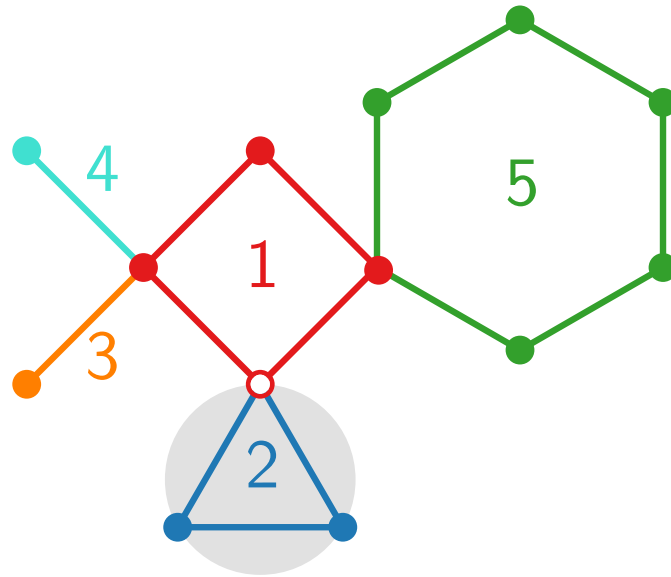


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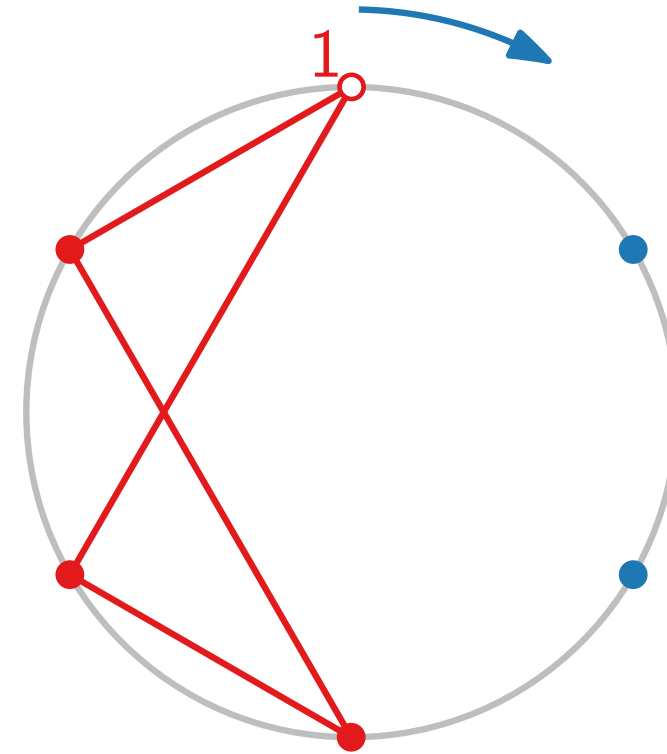
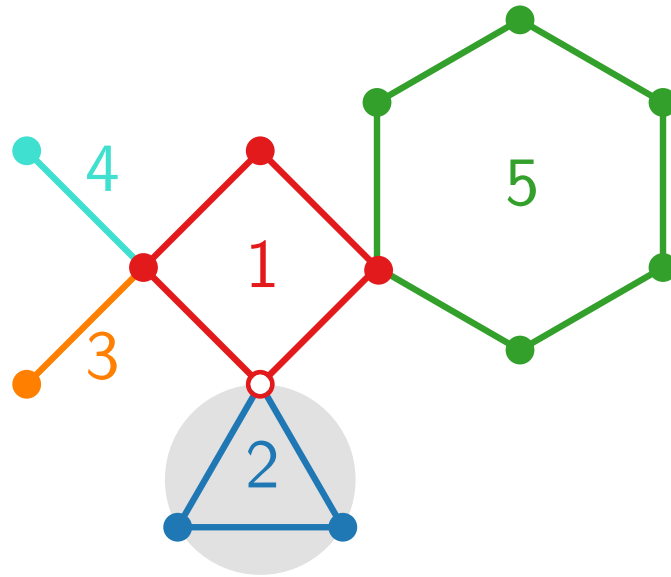


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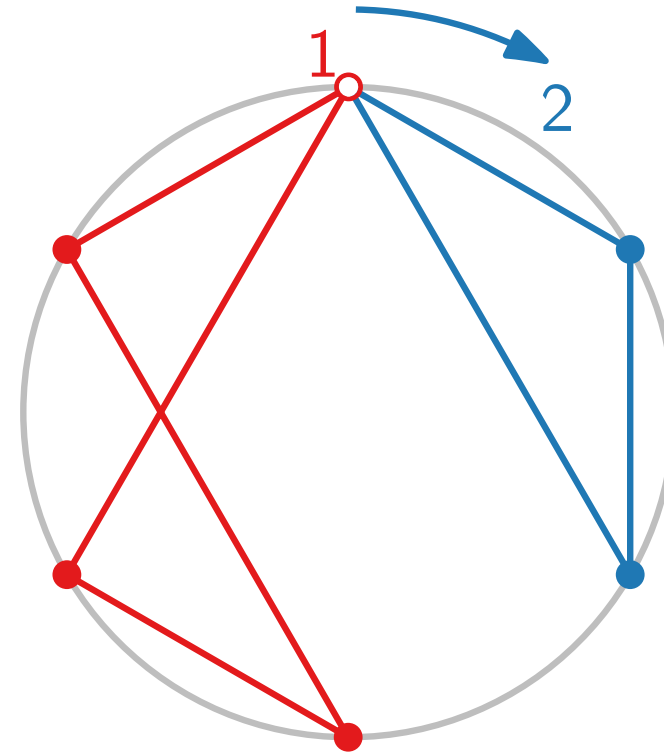
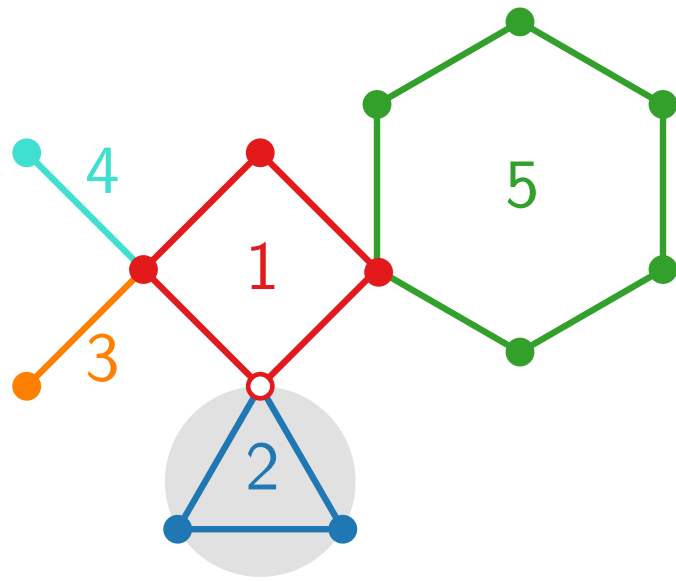


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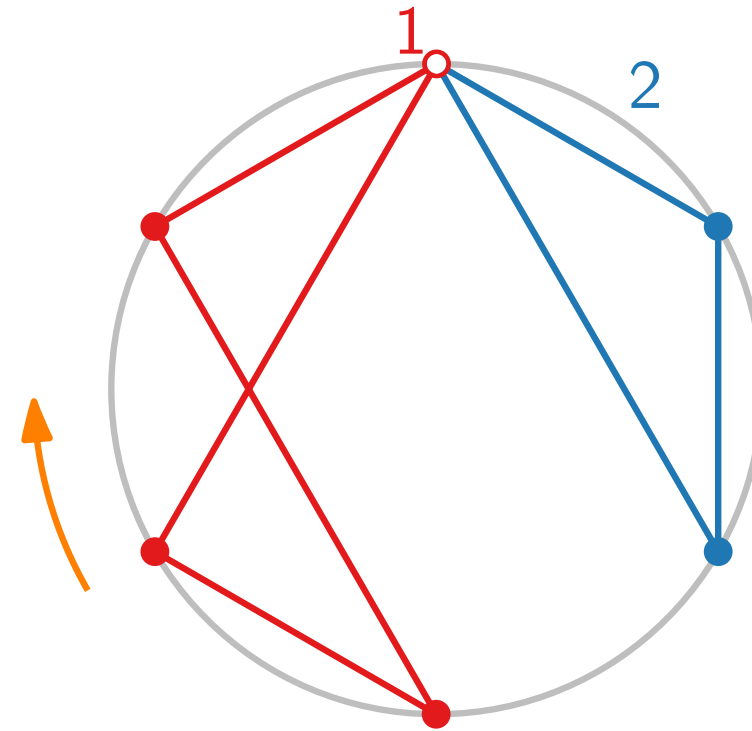
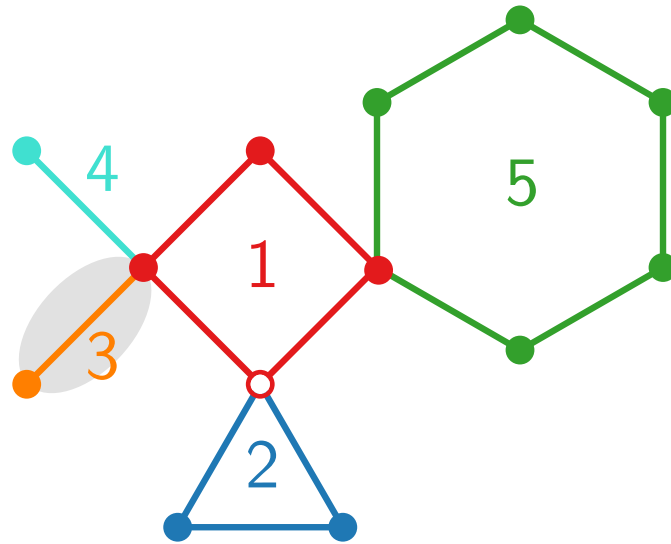


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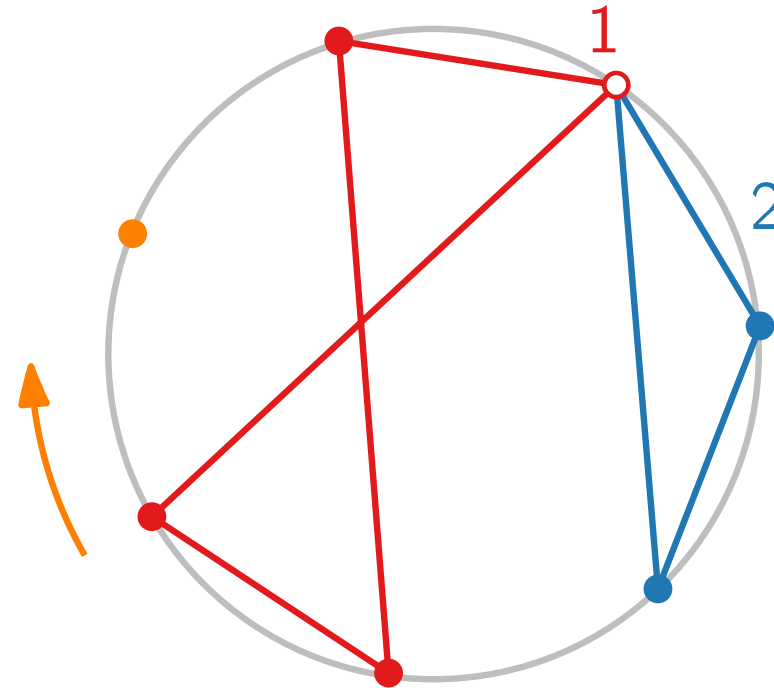
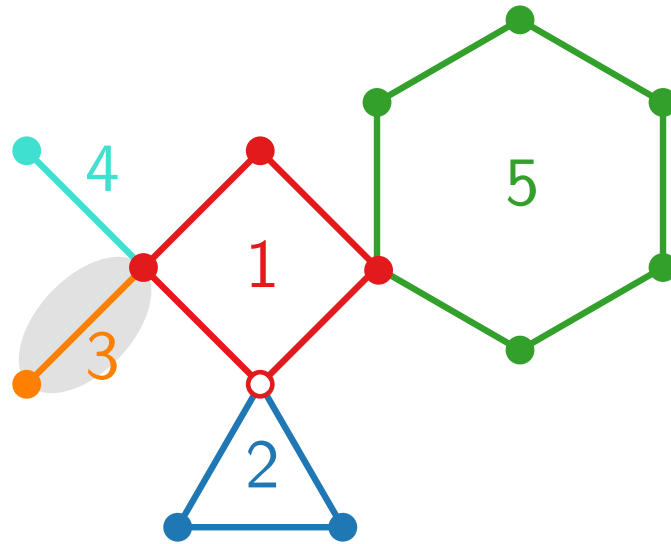


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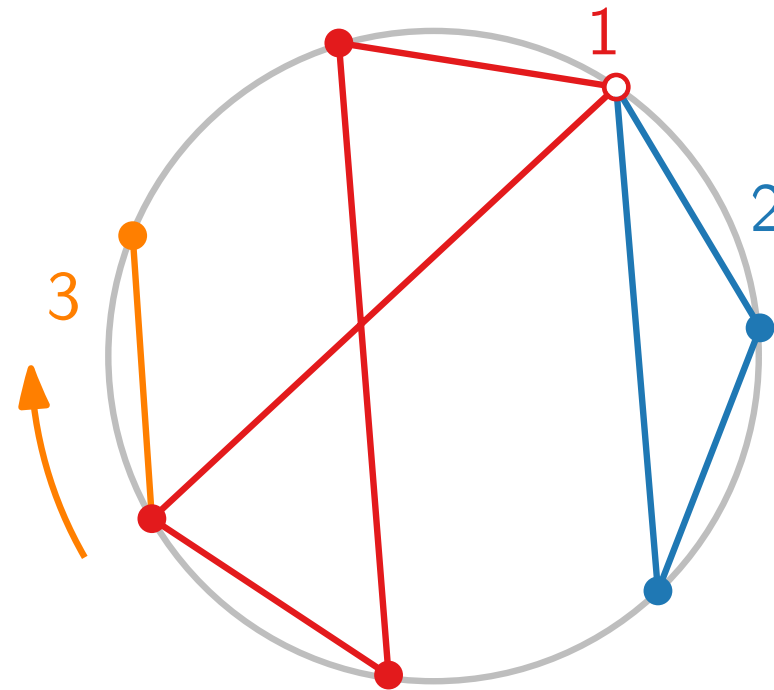
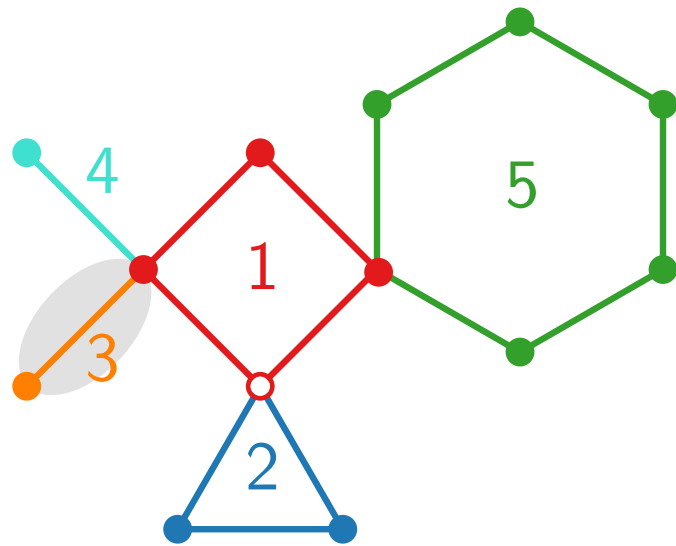


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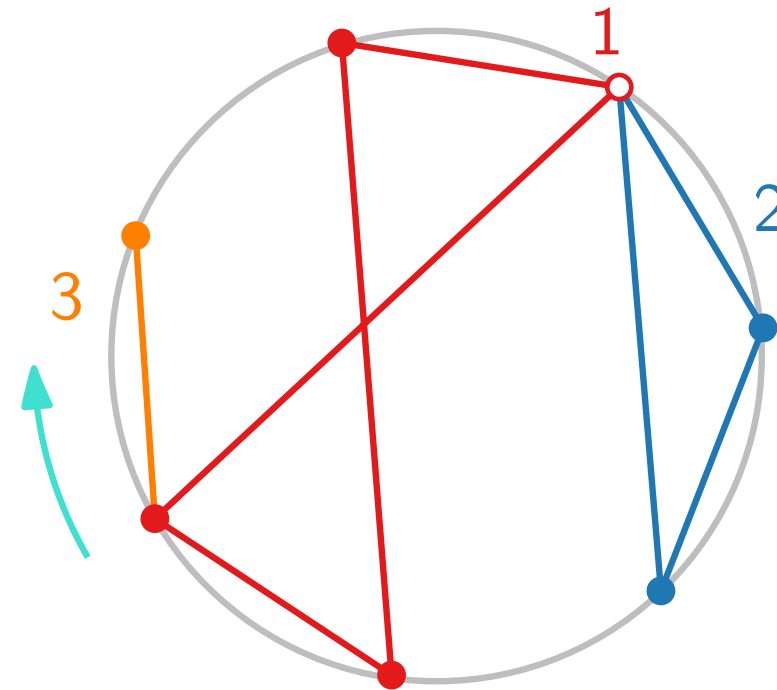
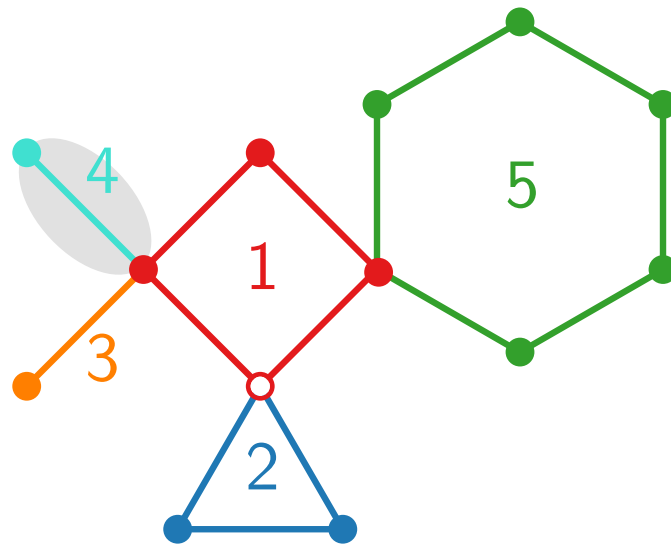


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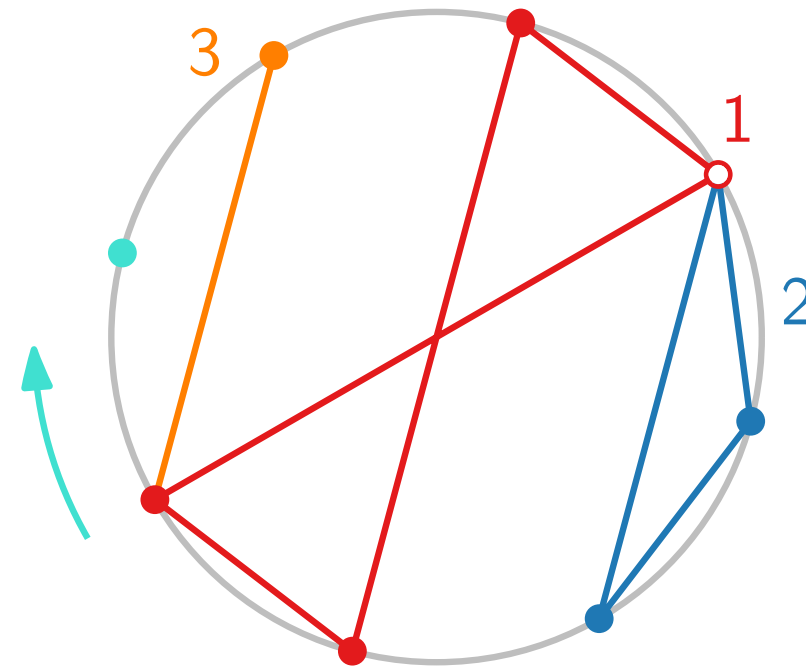
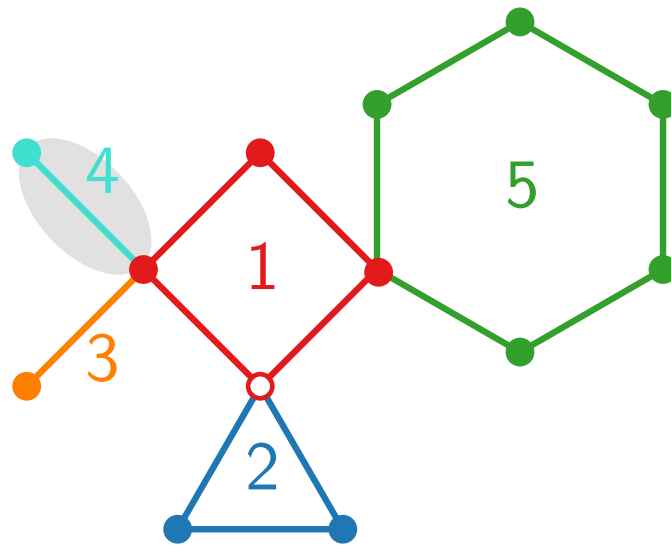


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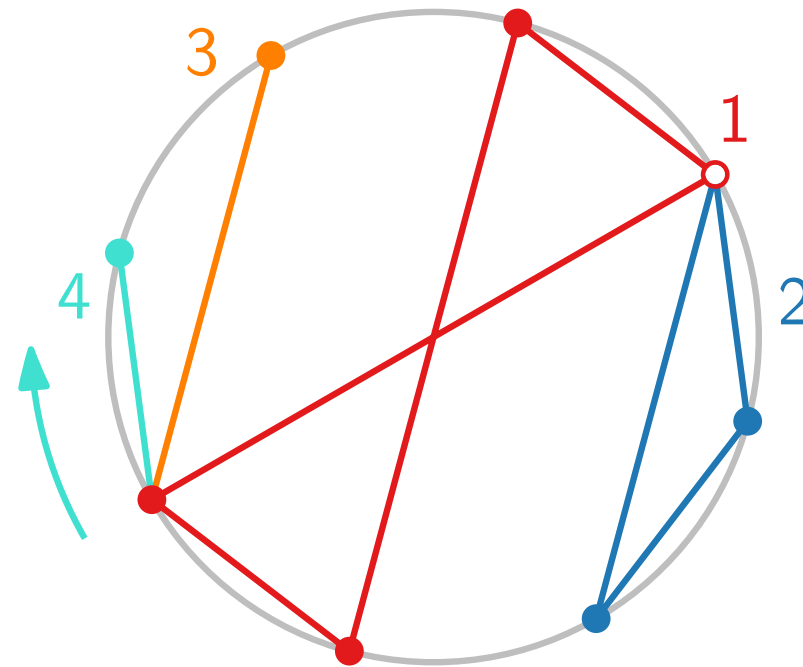
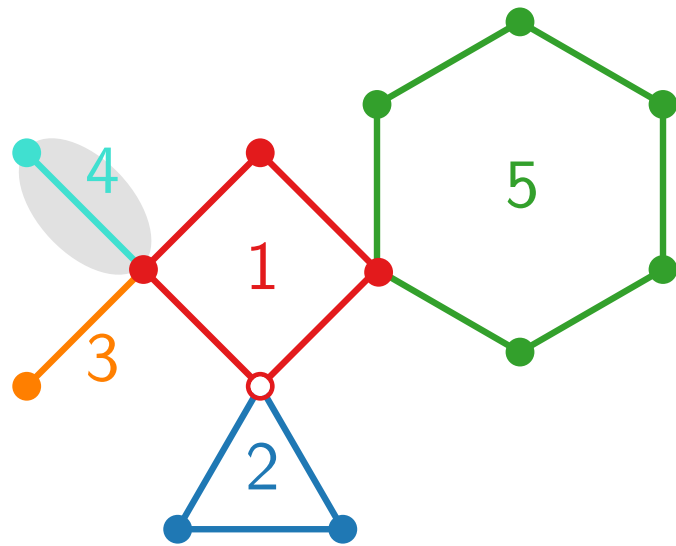


# Regular Outside-Obstacle Representation

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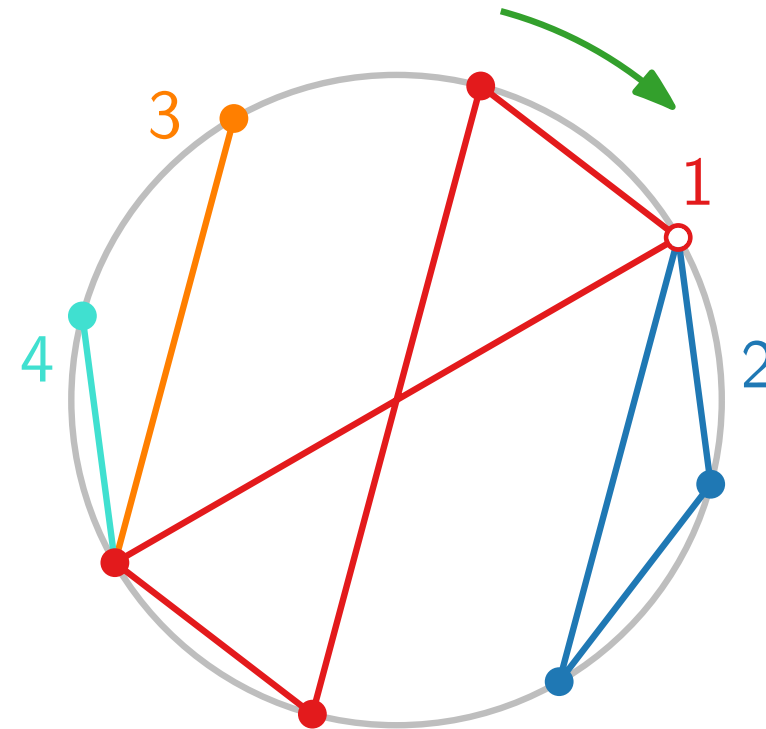
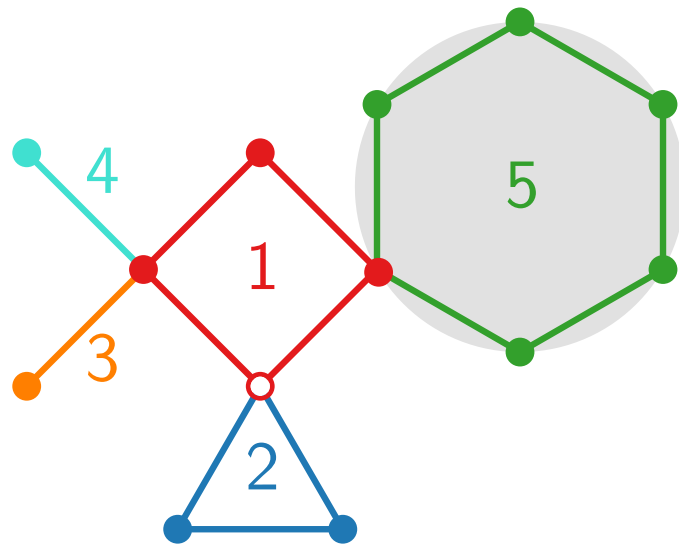


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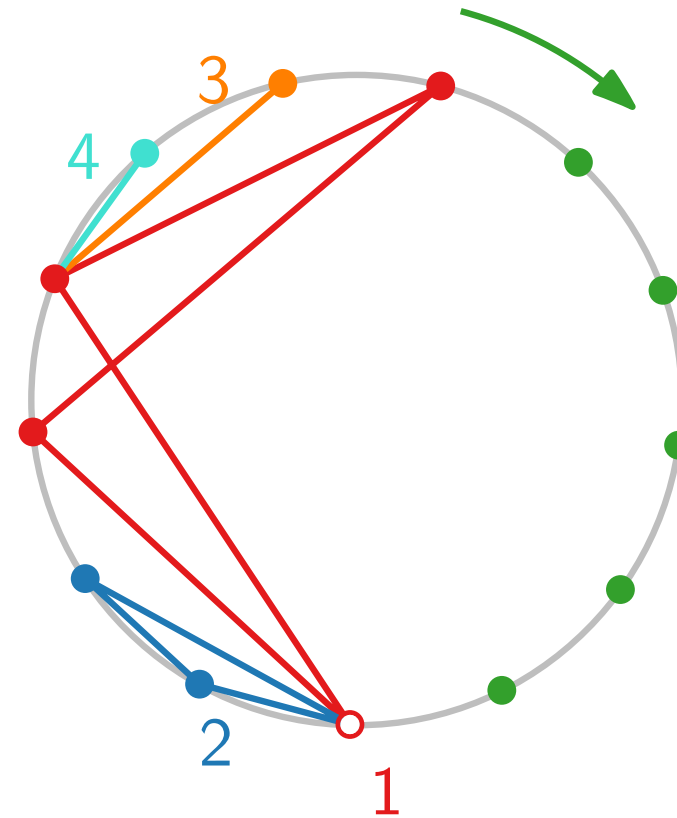
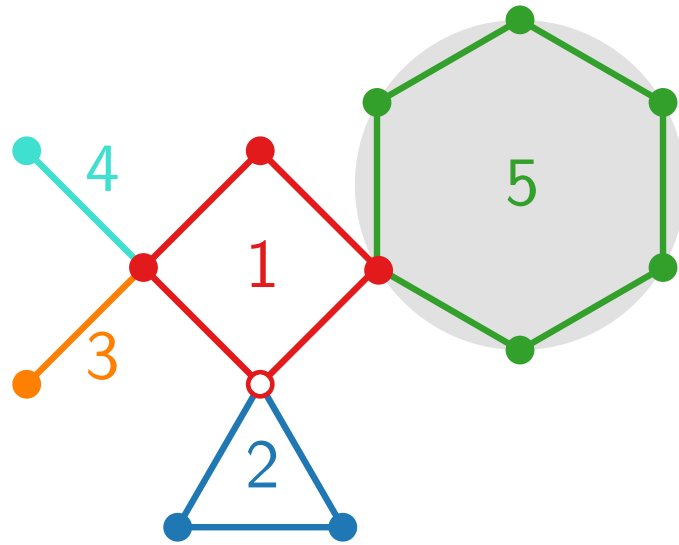


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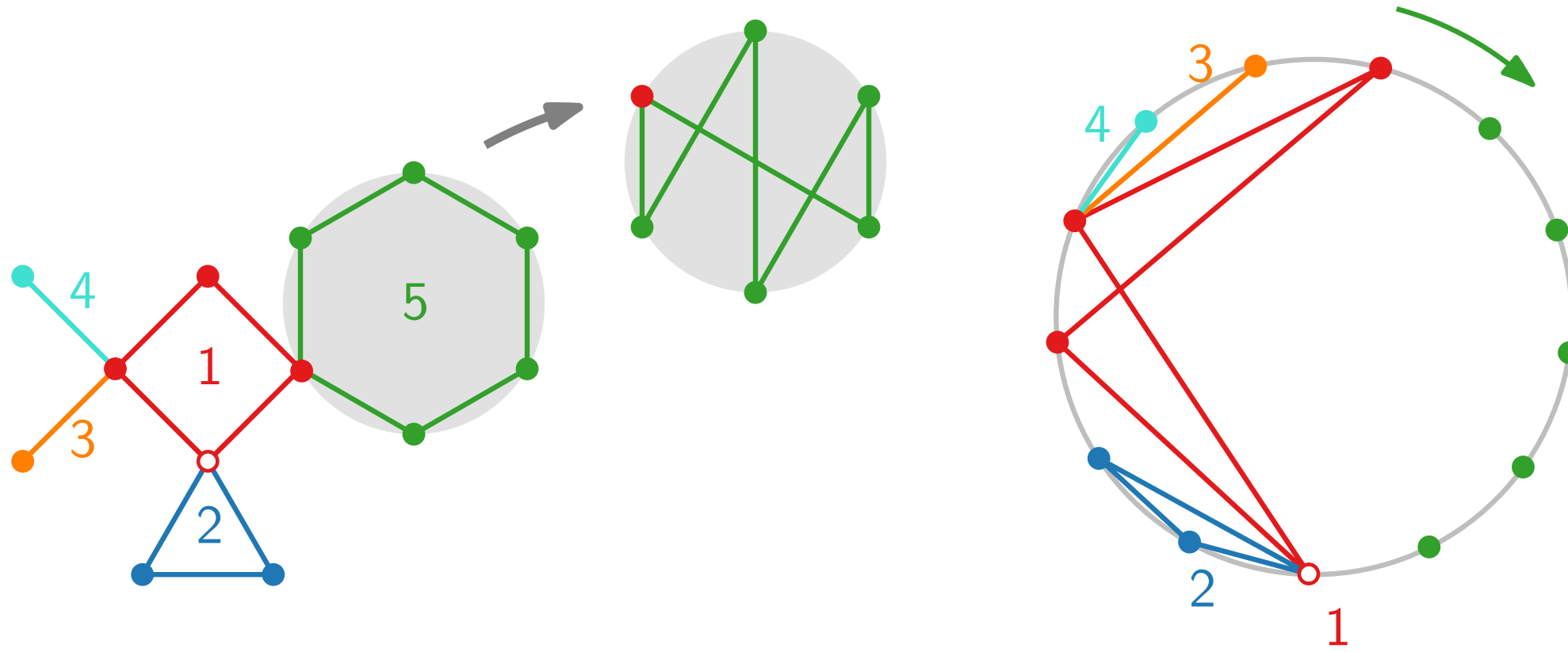


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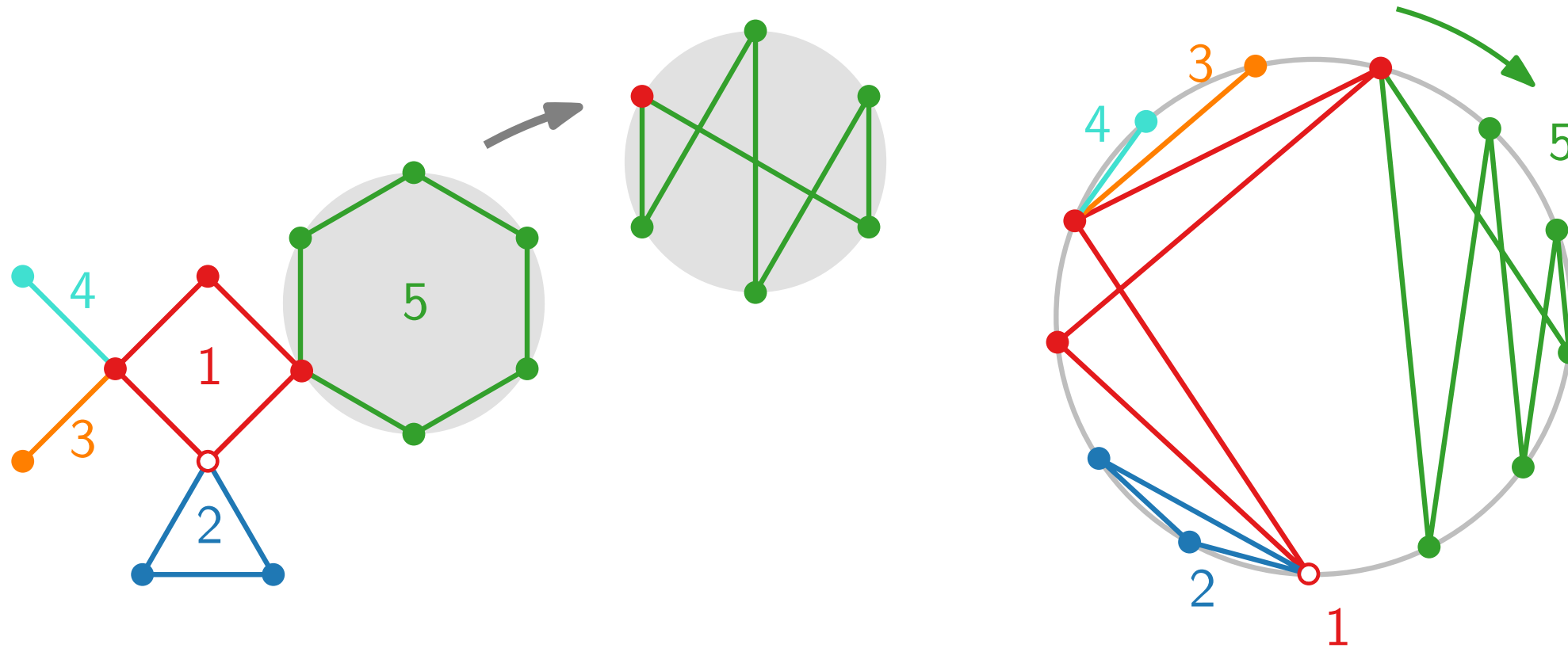


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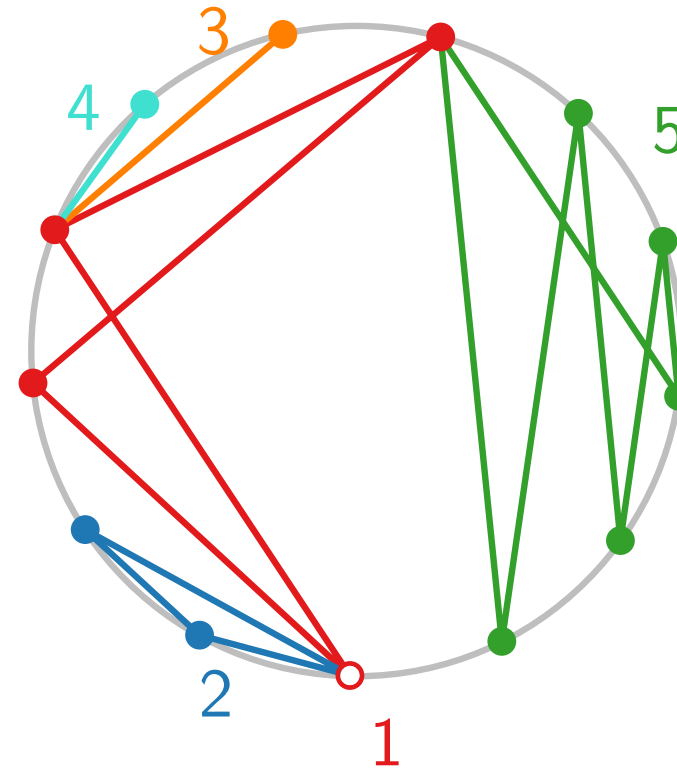
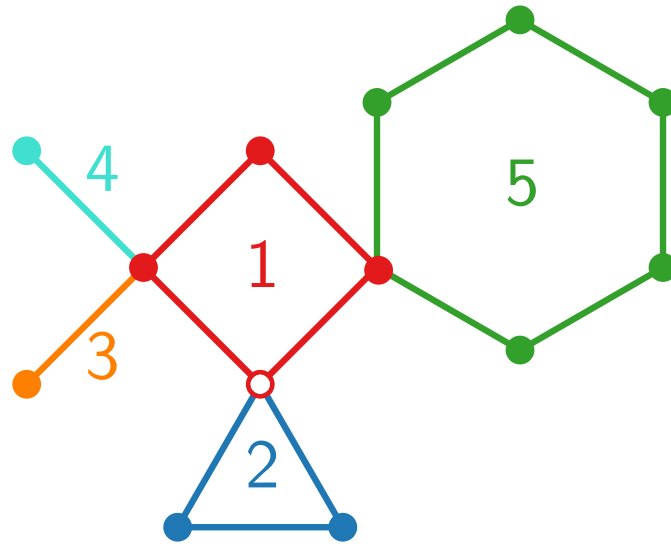


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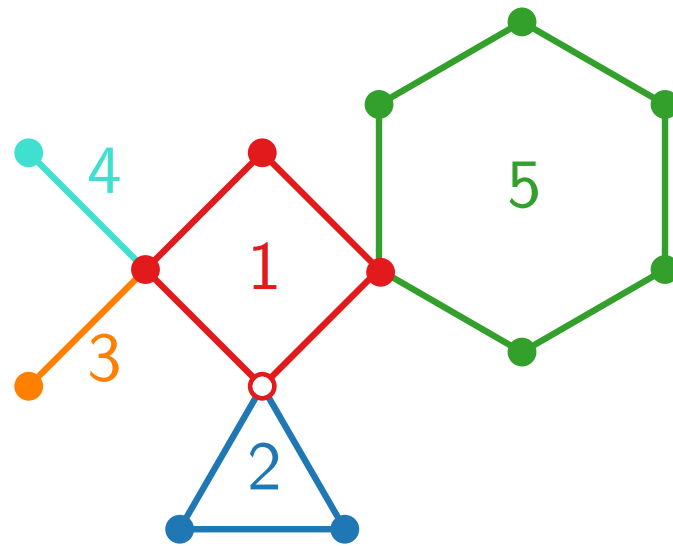


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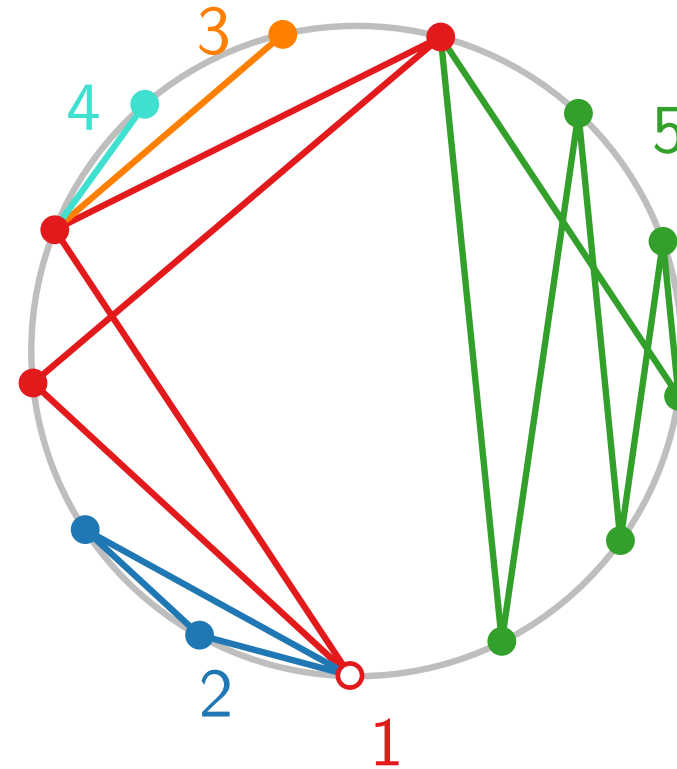
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correctness?

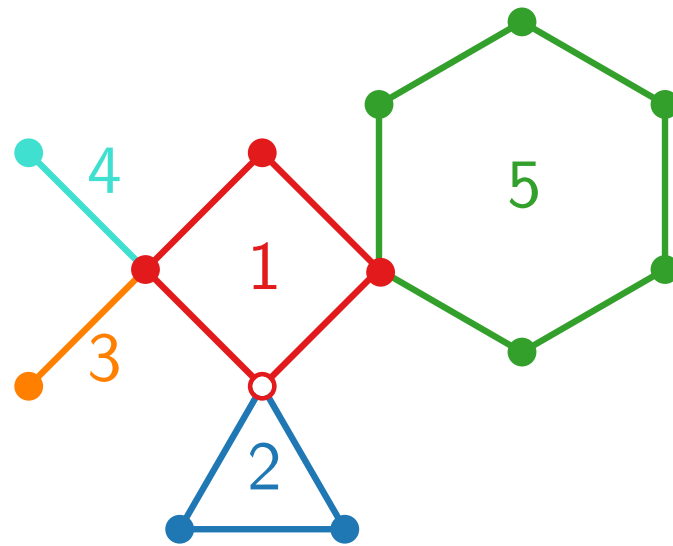


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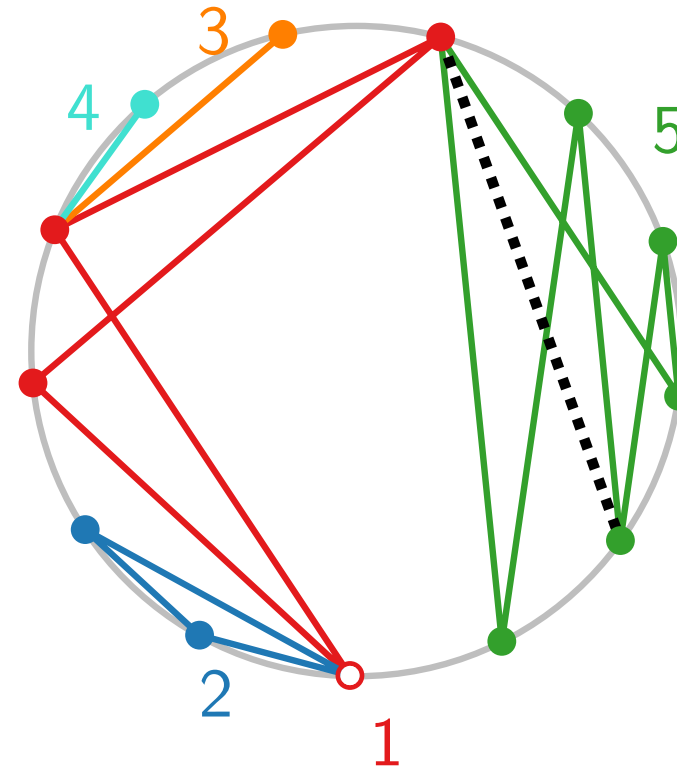
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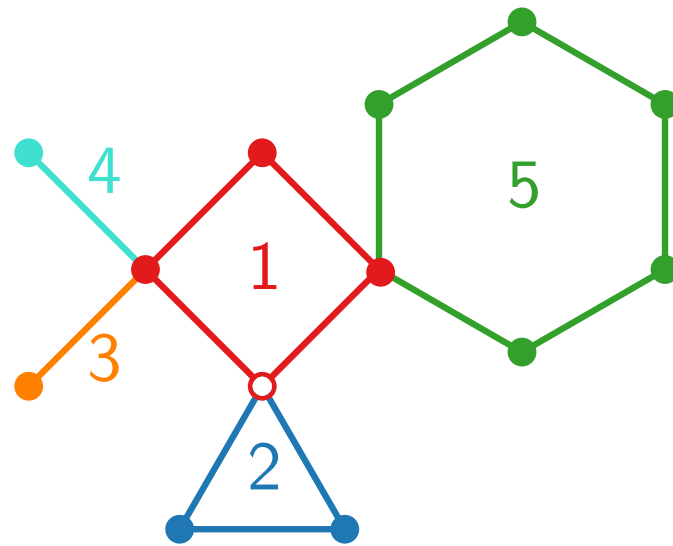


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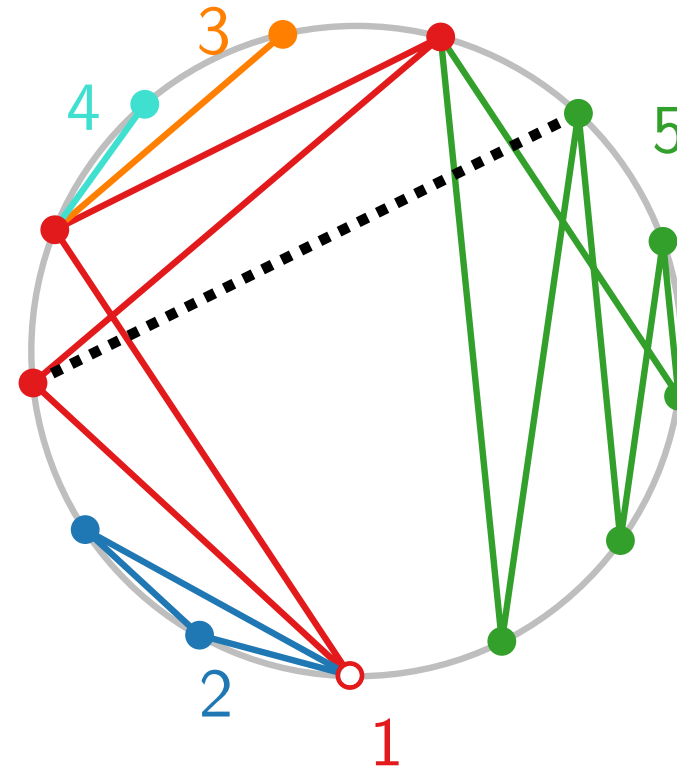
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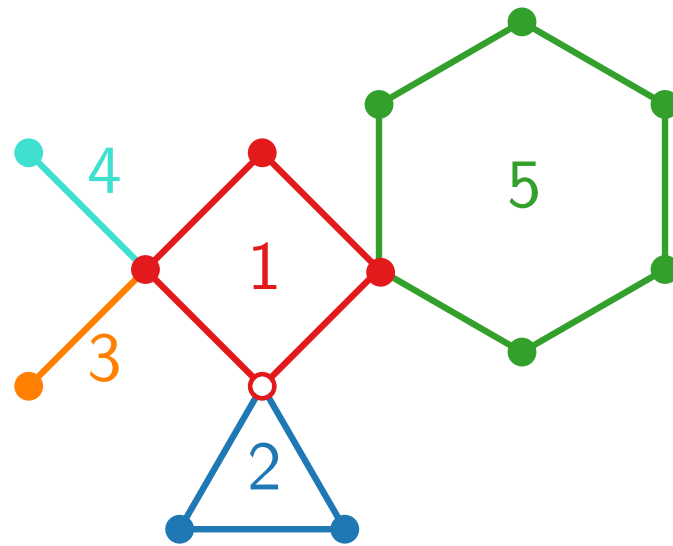


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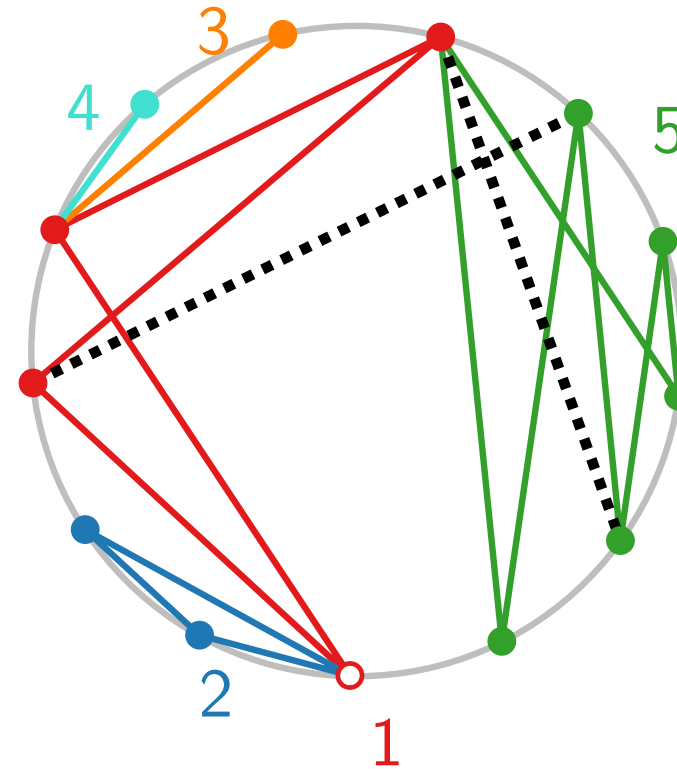
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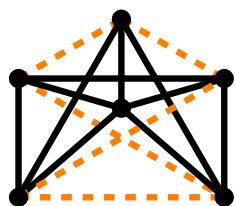


correctness ✓



# Our Contribution

## General

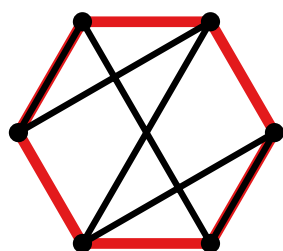


all vertices on  
the outer face

- outerplanar graph [Alpert et al., DCG 2010]
- 2-tree (subgraphs ✓)

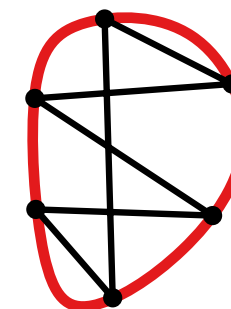
**Def.** An outside-obstacle representation of a graph is *reducible* if all its edges are incident to the outer face.

## Regular



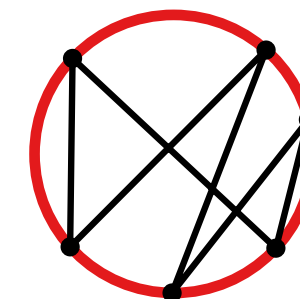
- cactus (subgraphs ✓)
- grid (subgraphs ✓)
- outerpath (subgraphs ✓)

## Convex



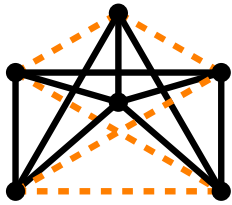
- consecutive-neighbors property *sufficient*
- gap condition *necessary*

## Circular



# Our Contribution

## General



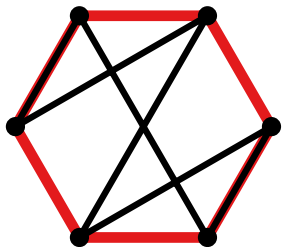
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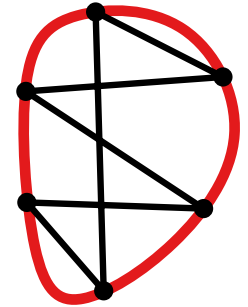


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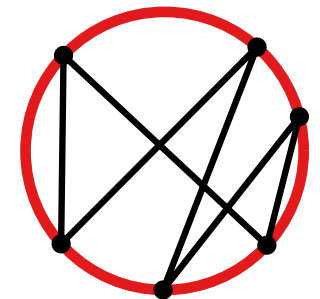
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# (General) Outside-Obstacle Representation

## Theorem.

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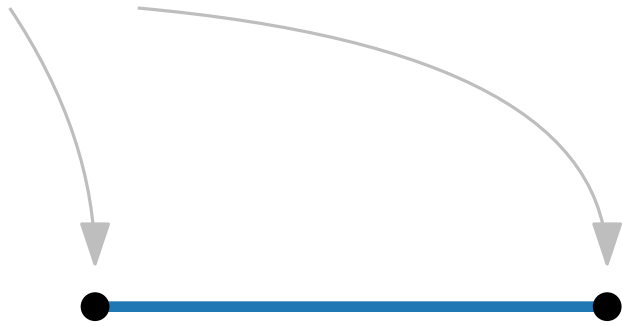
*base edge*

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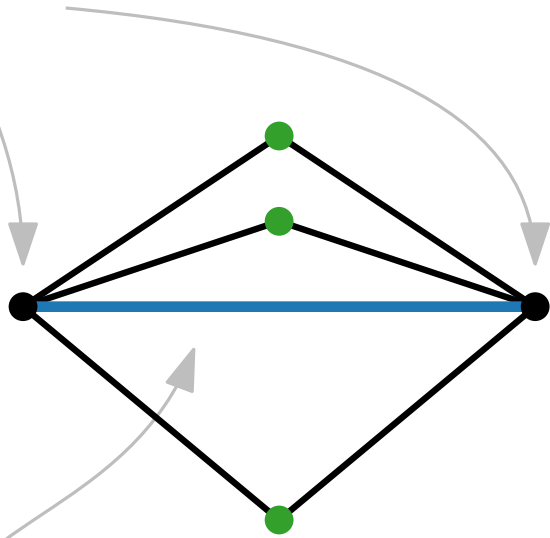
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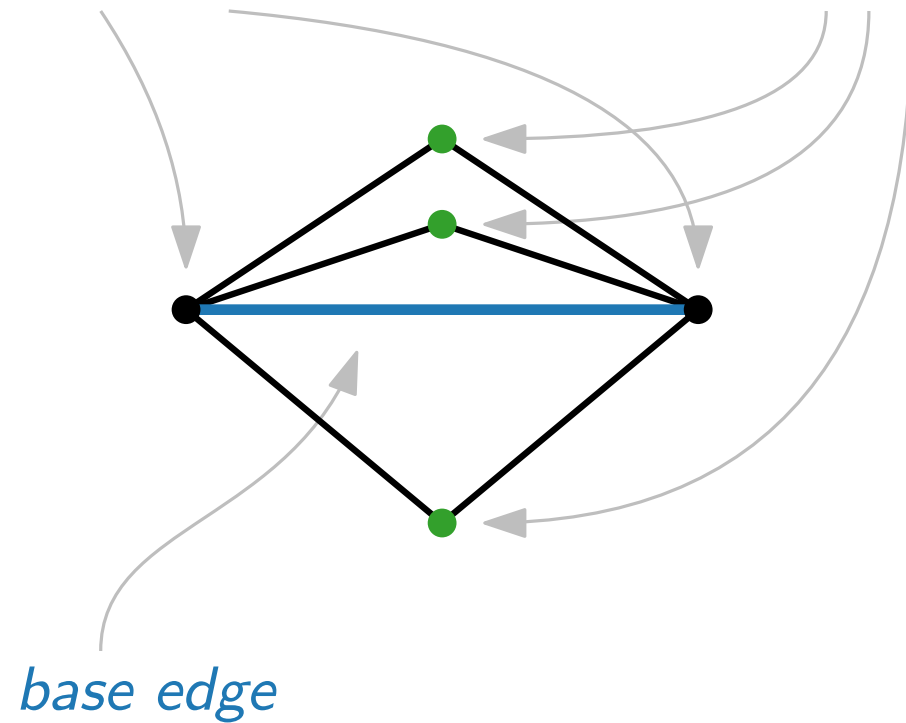
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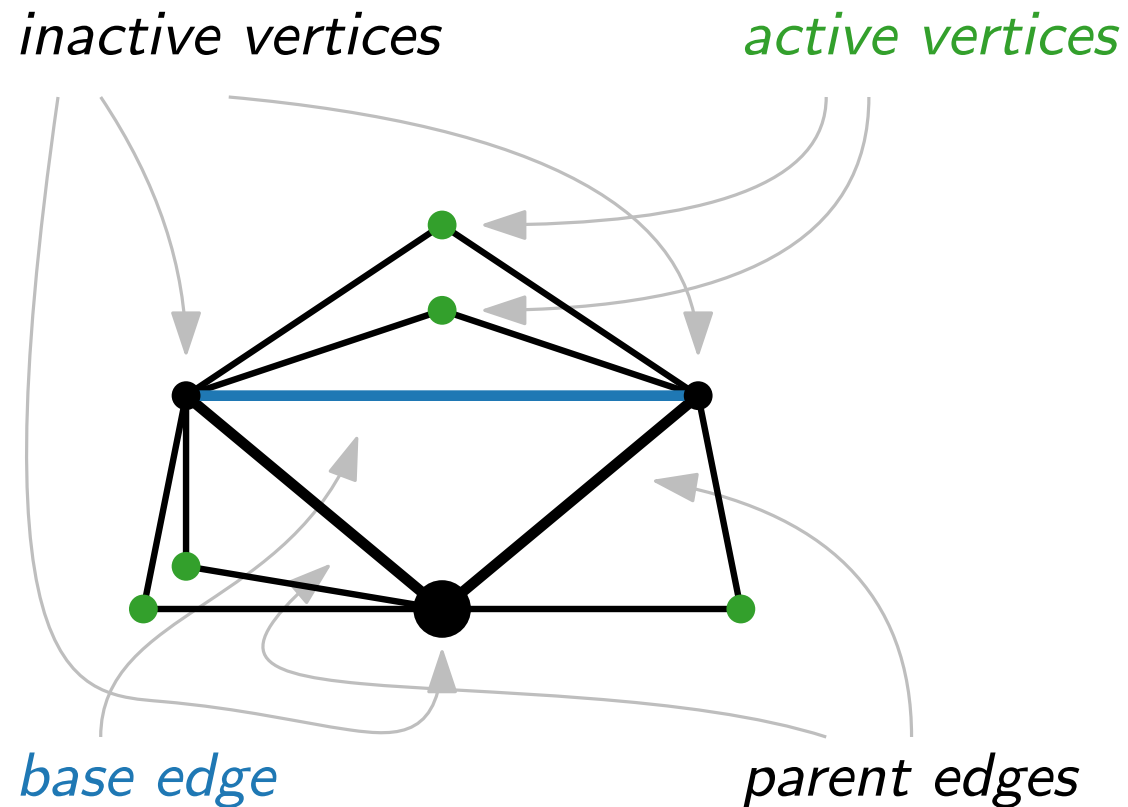




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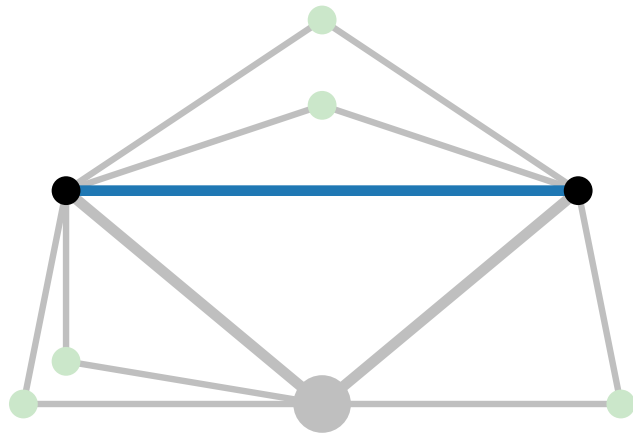
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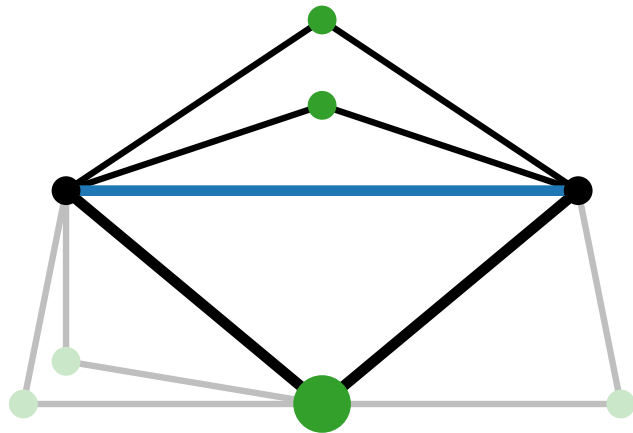
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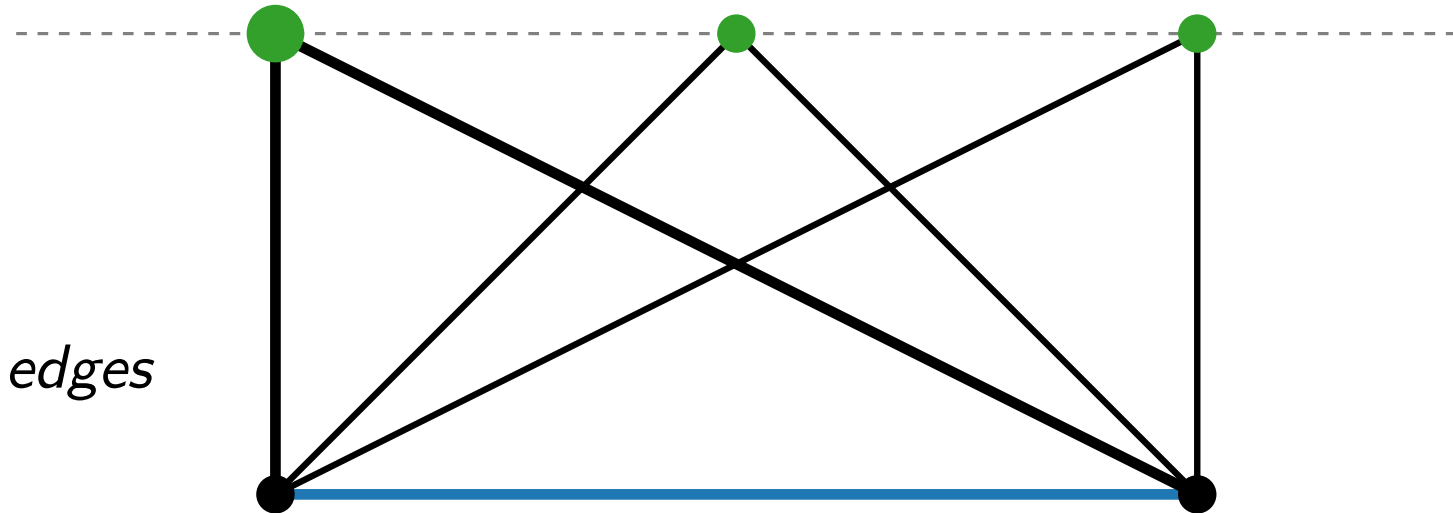
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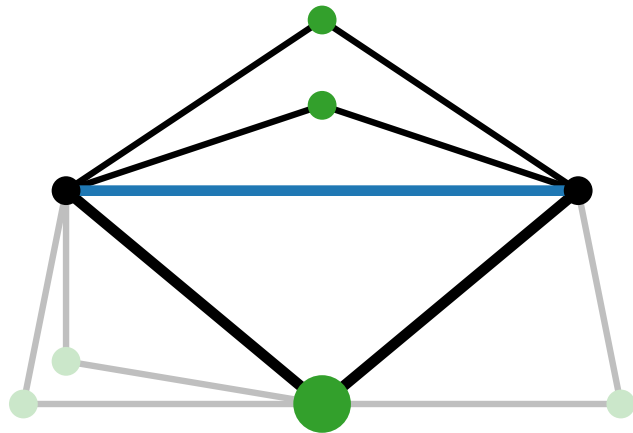
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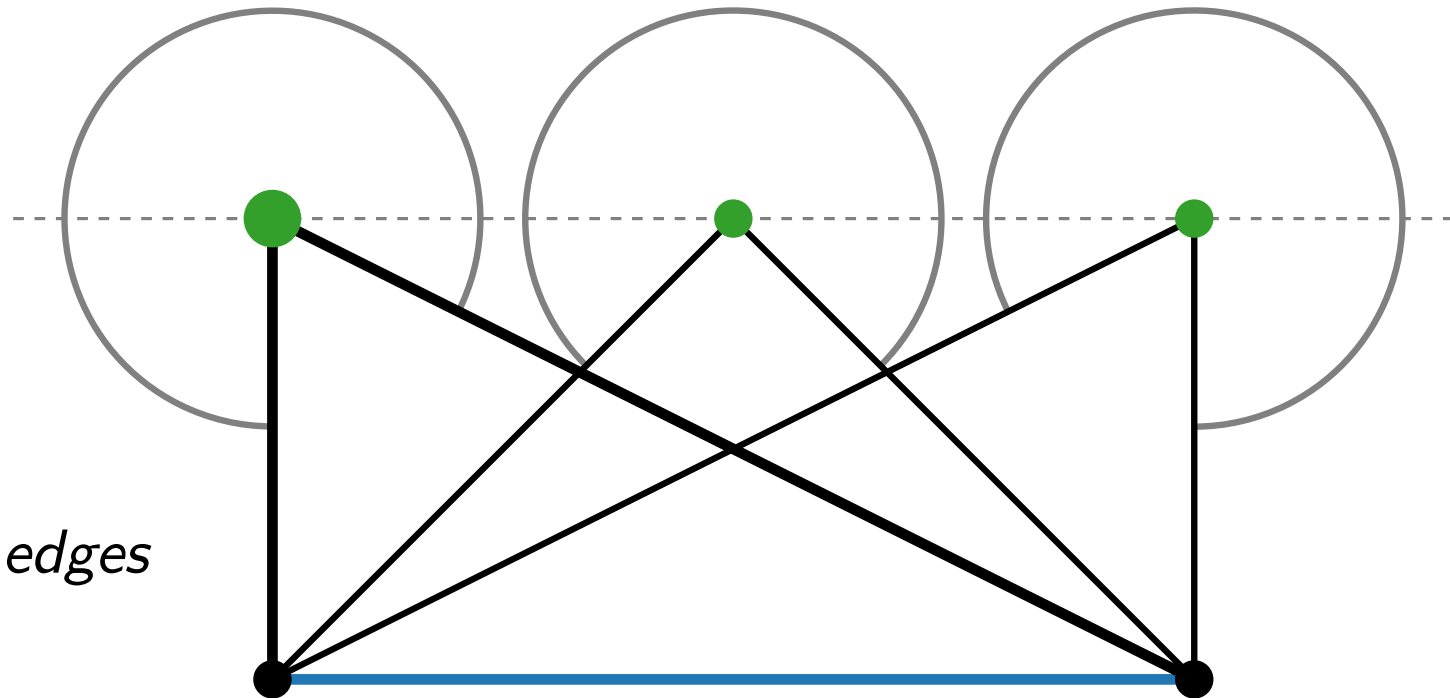
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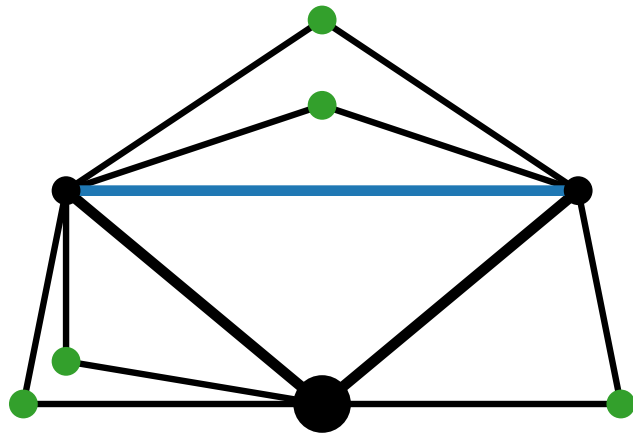
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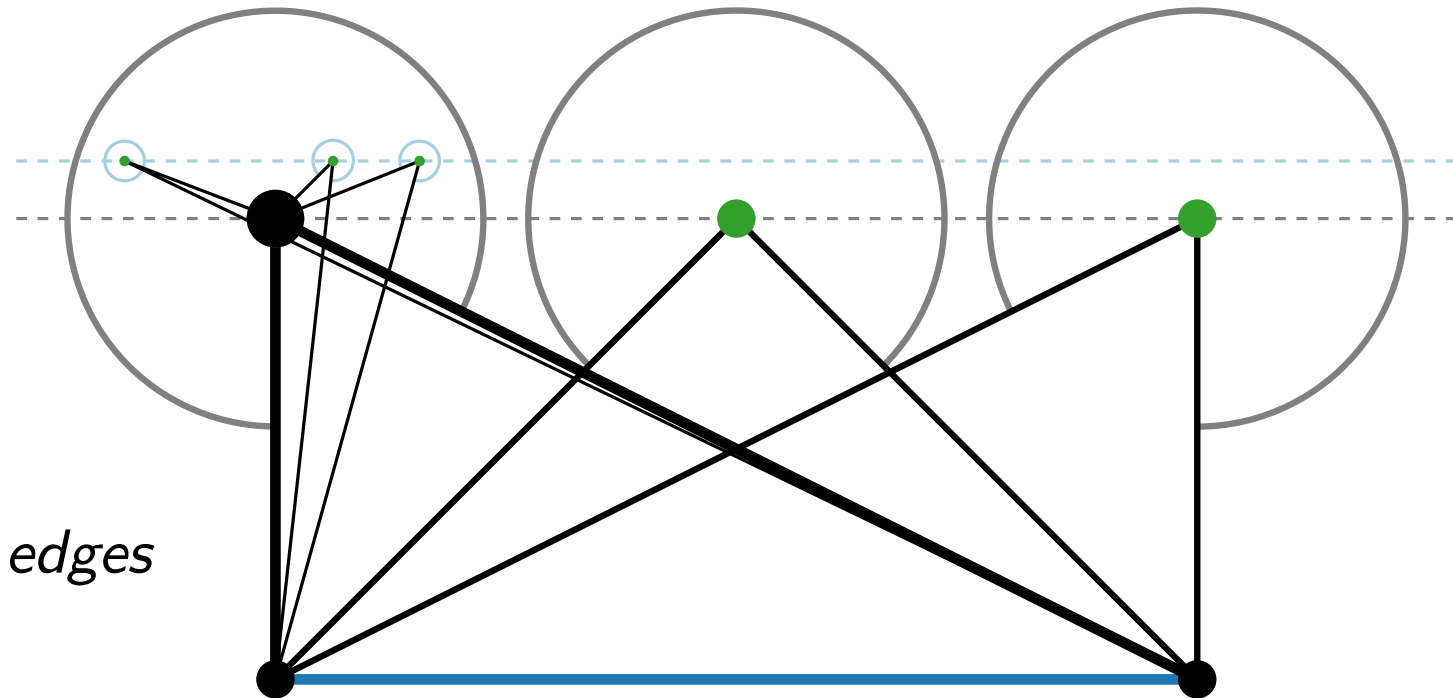
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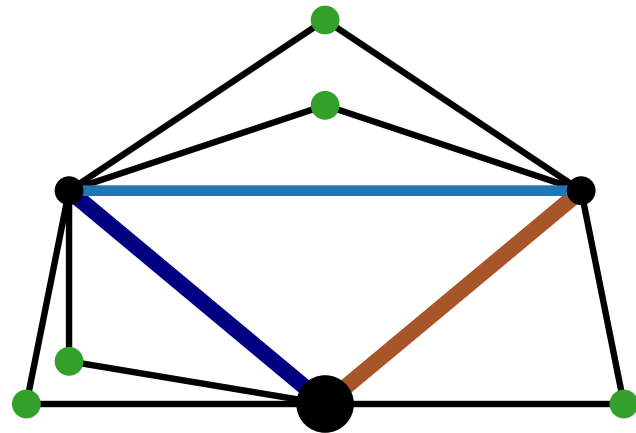
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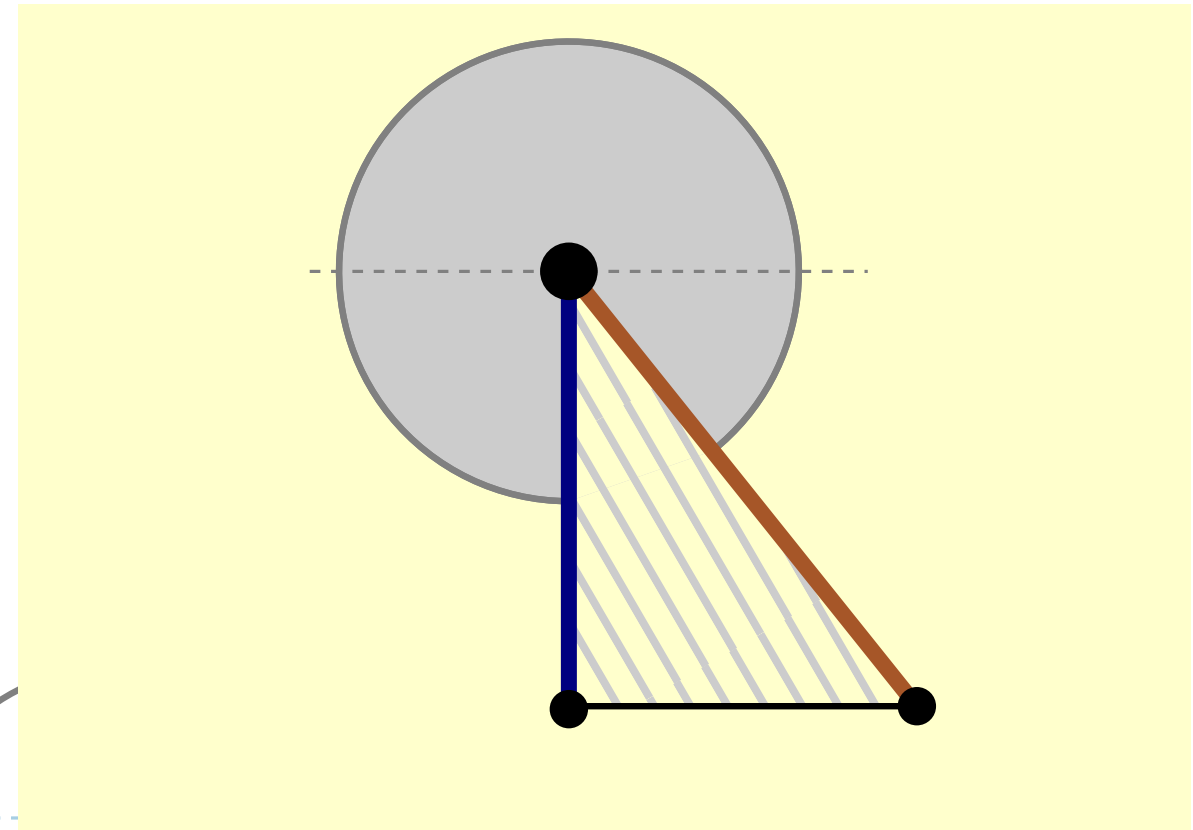
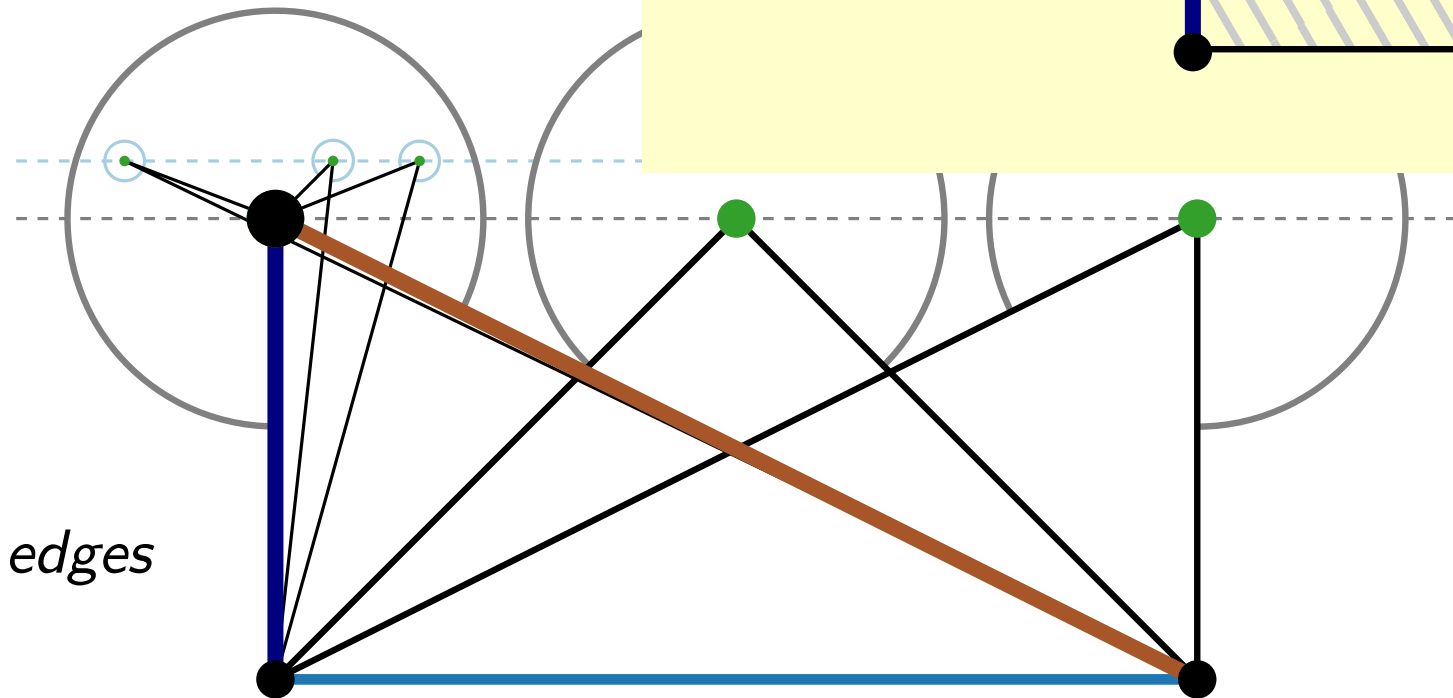
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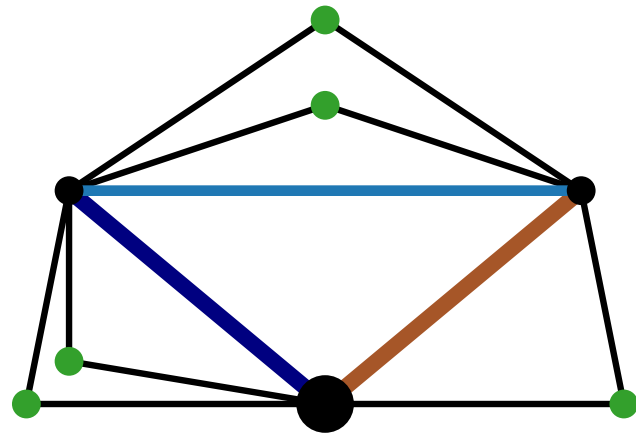
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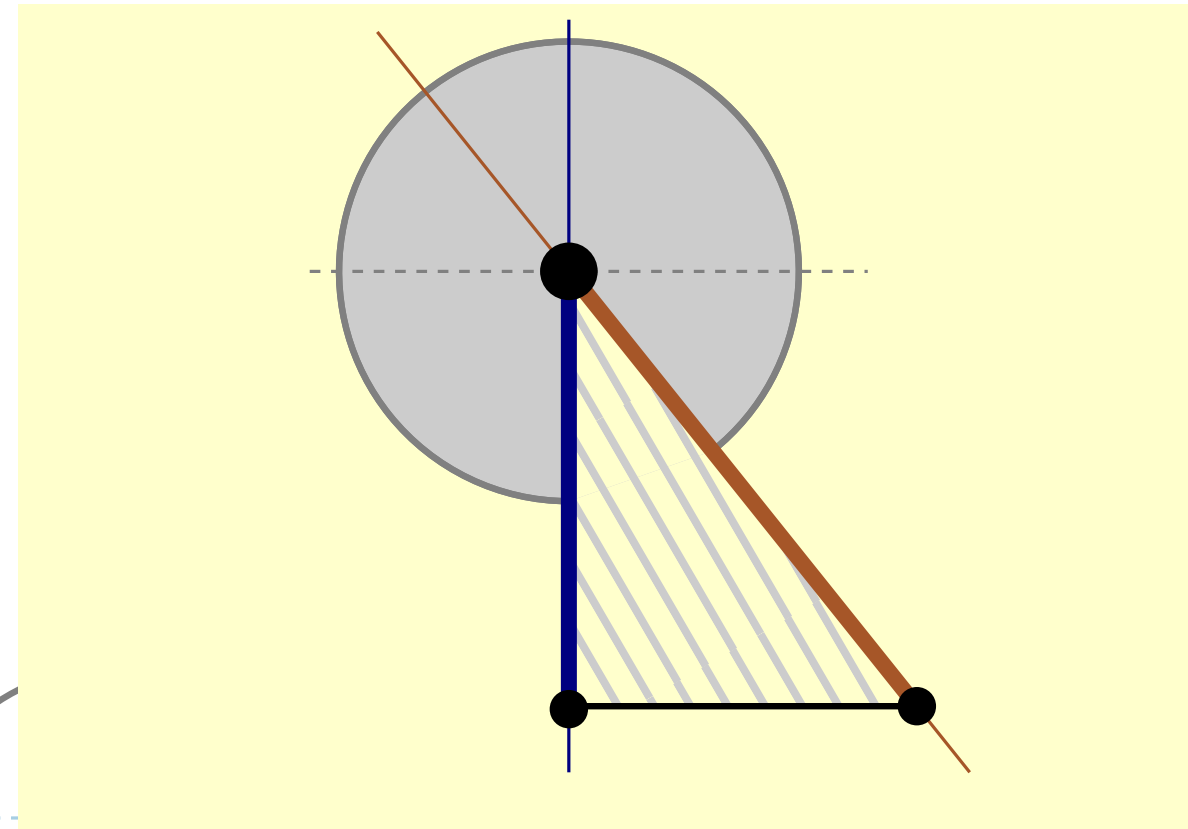
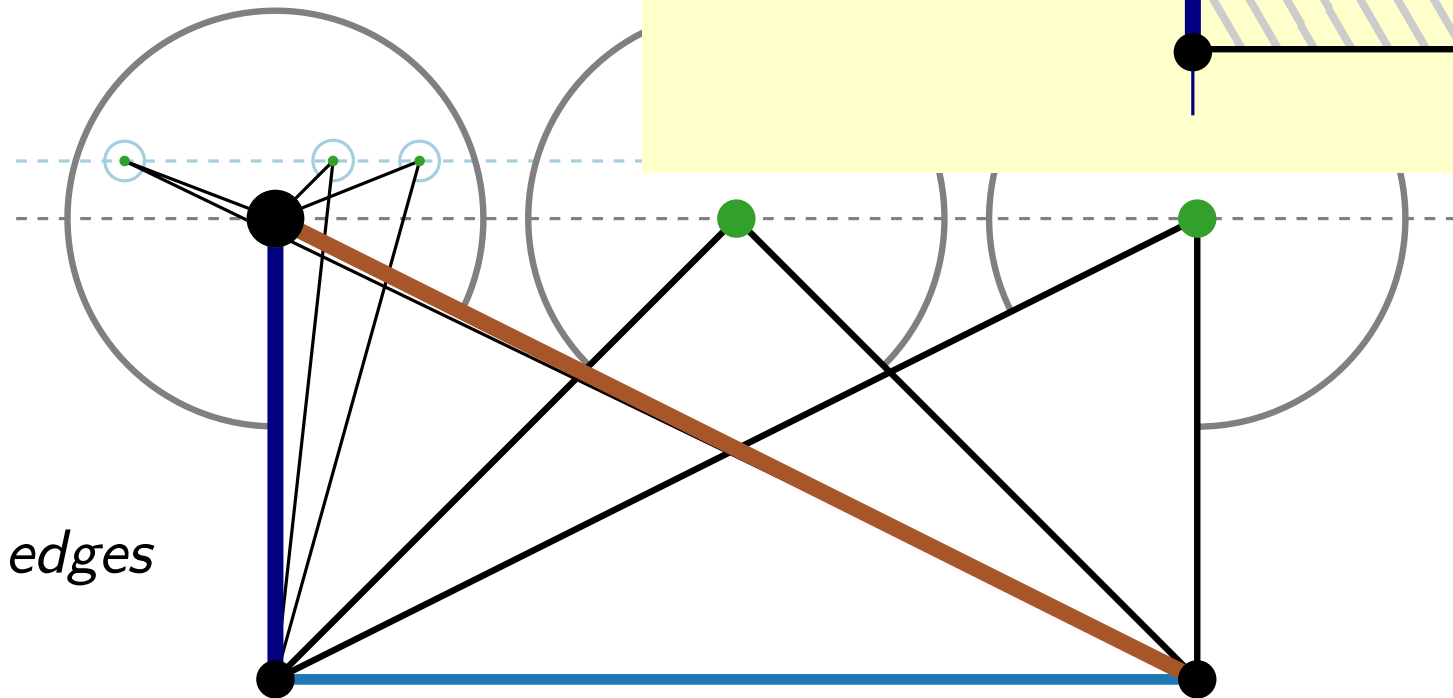
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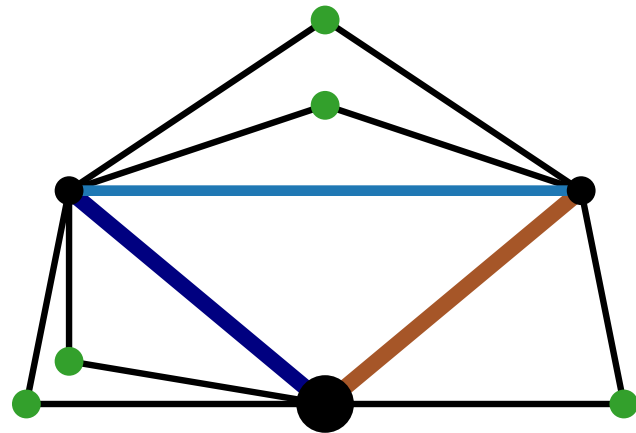
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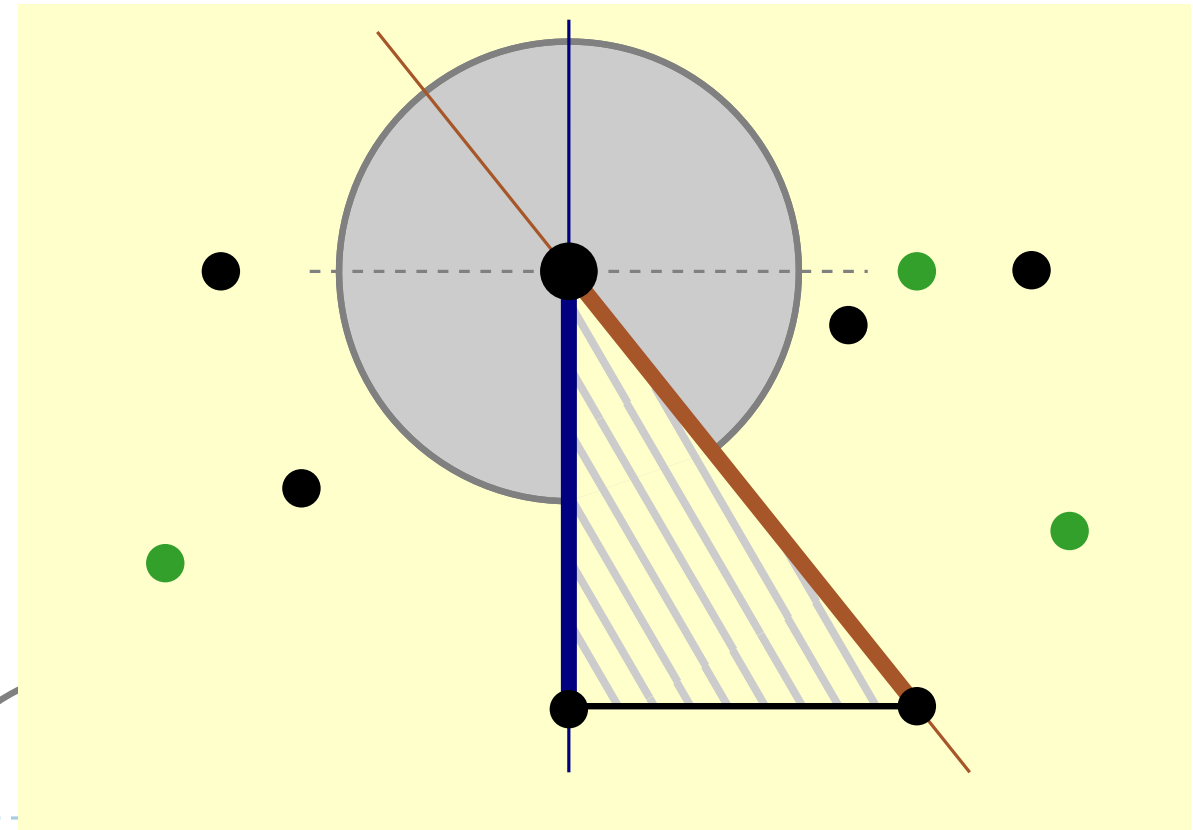
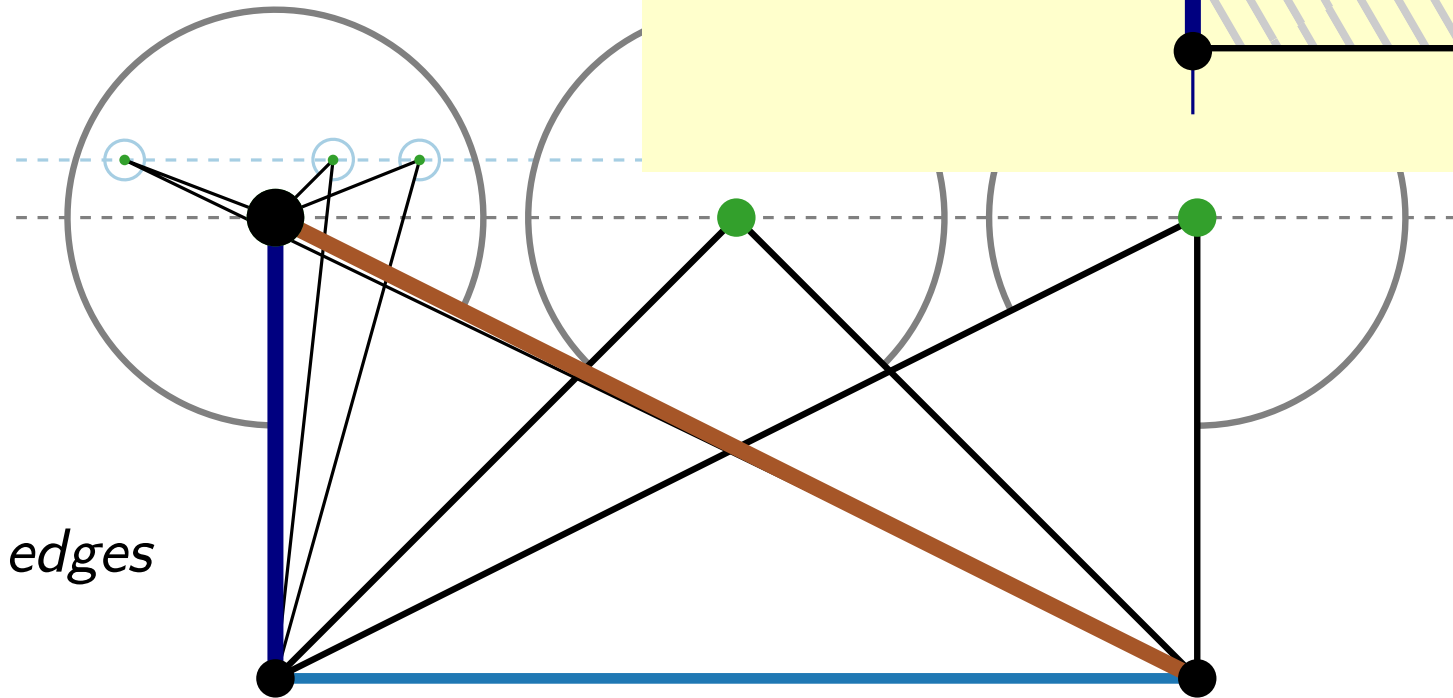
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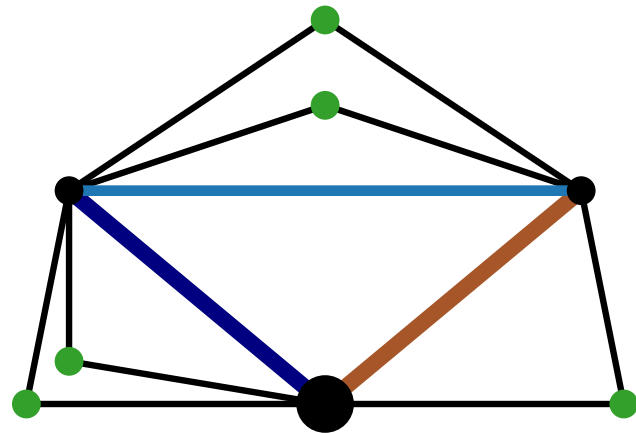
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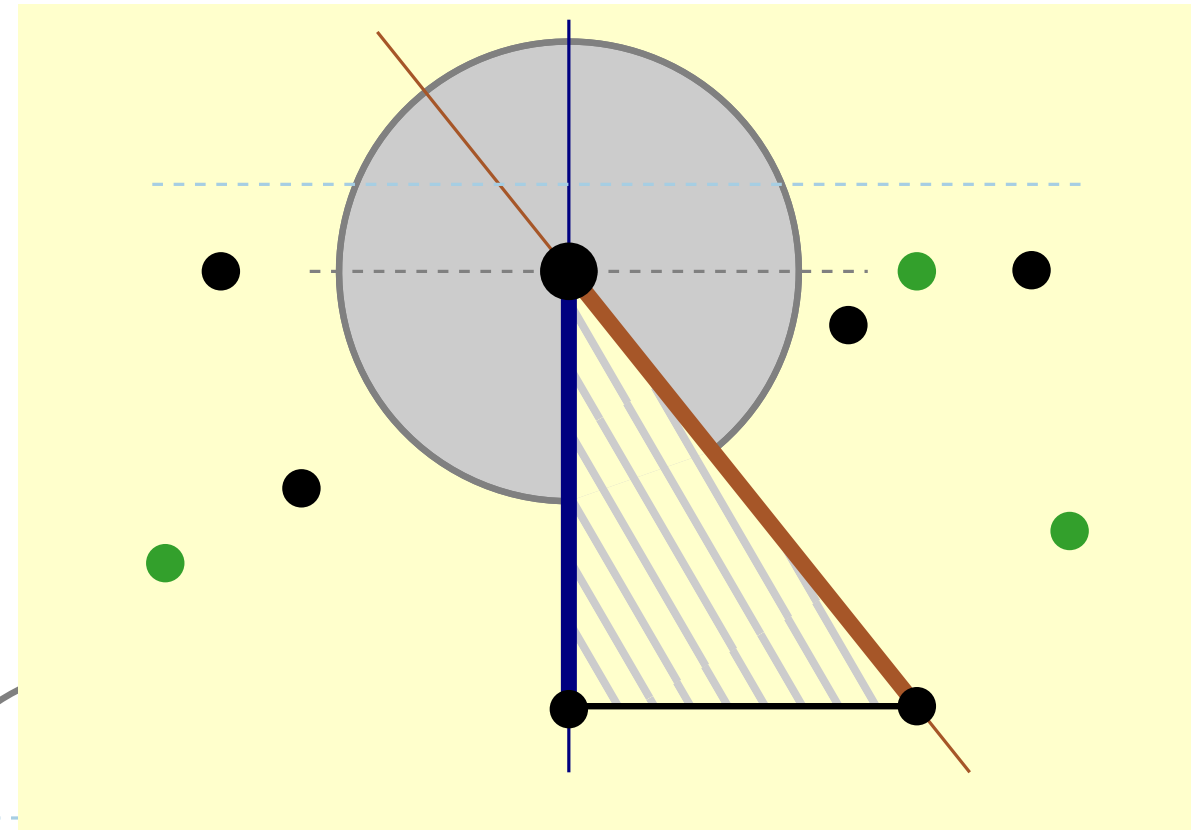
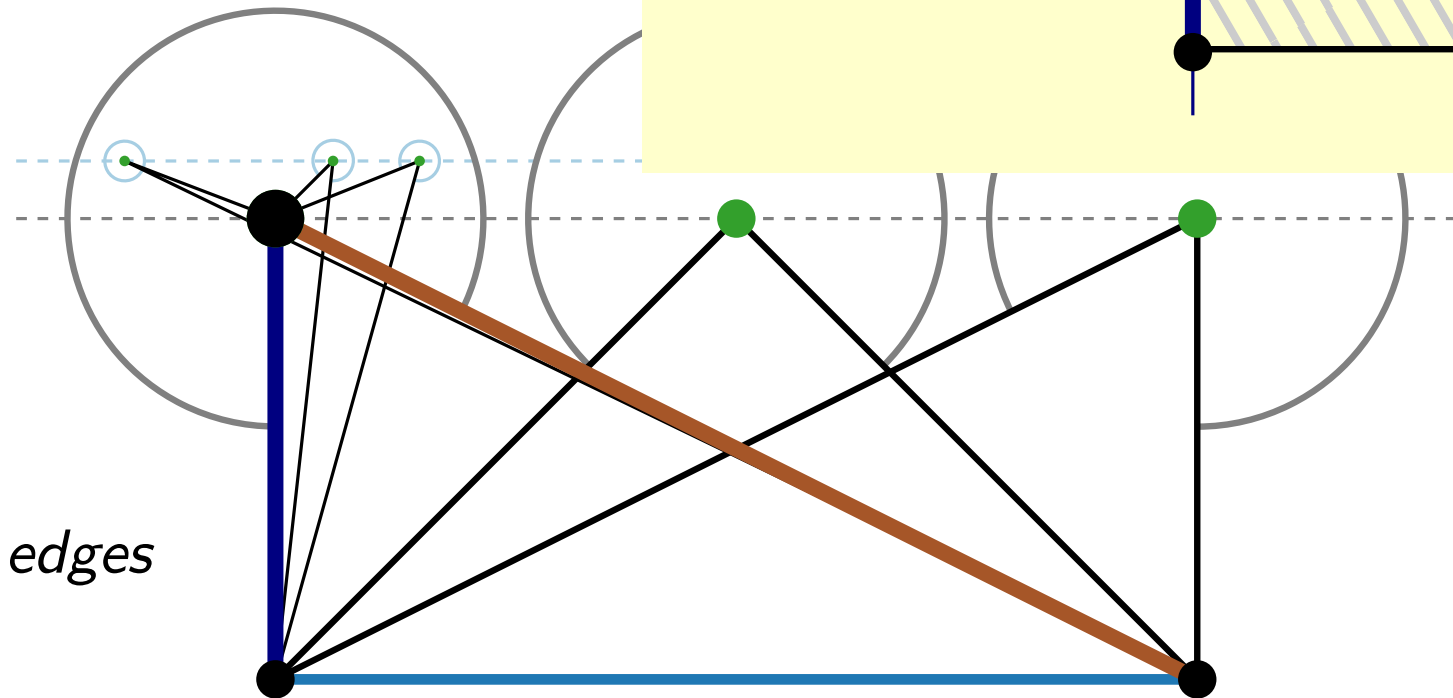
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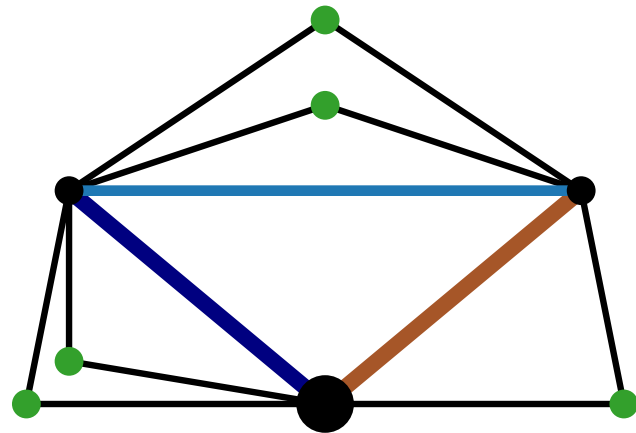
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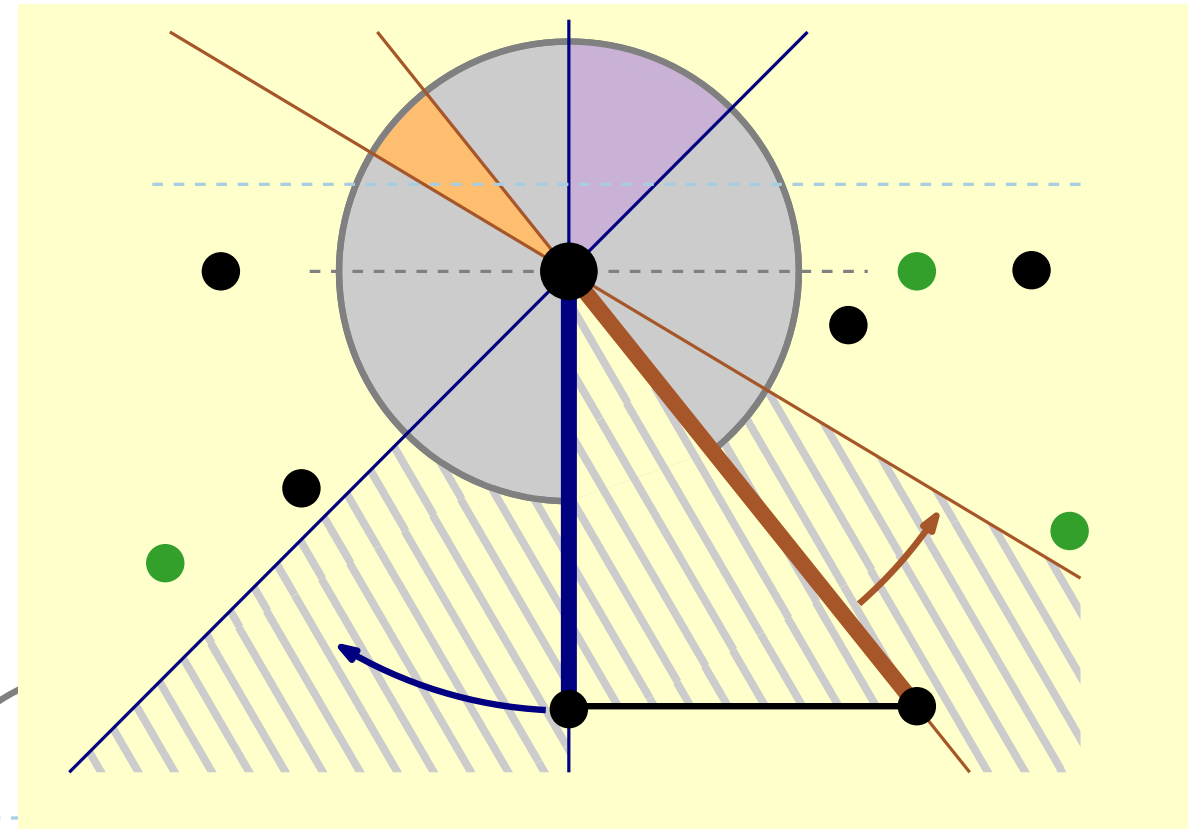
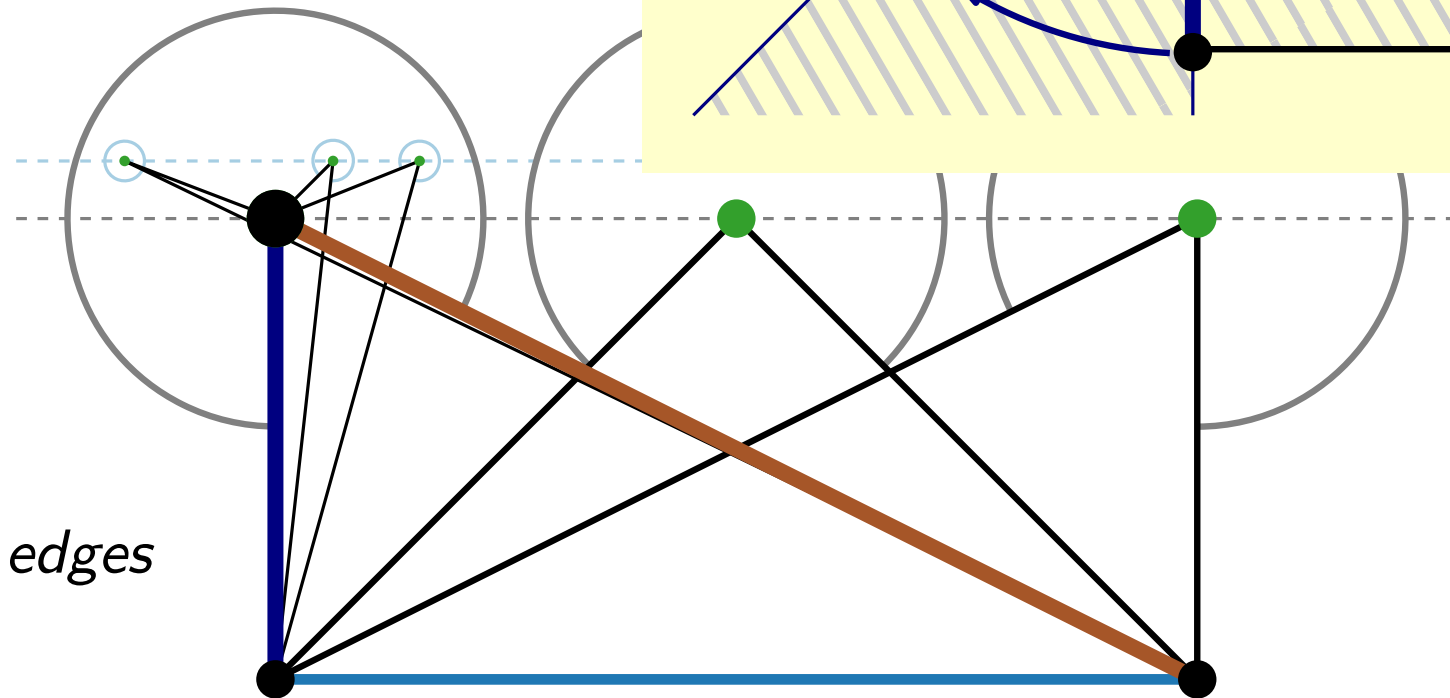
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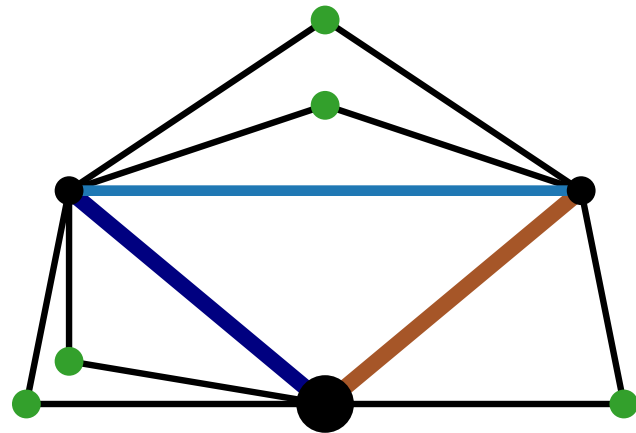
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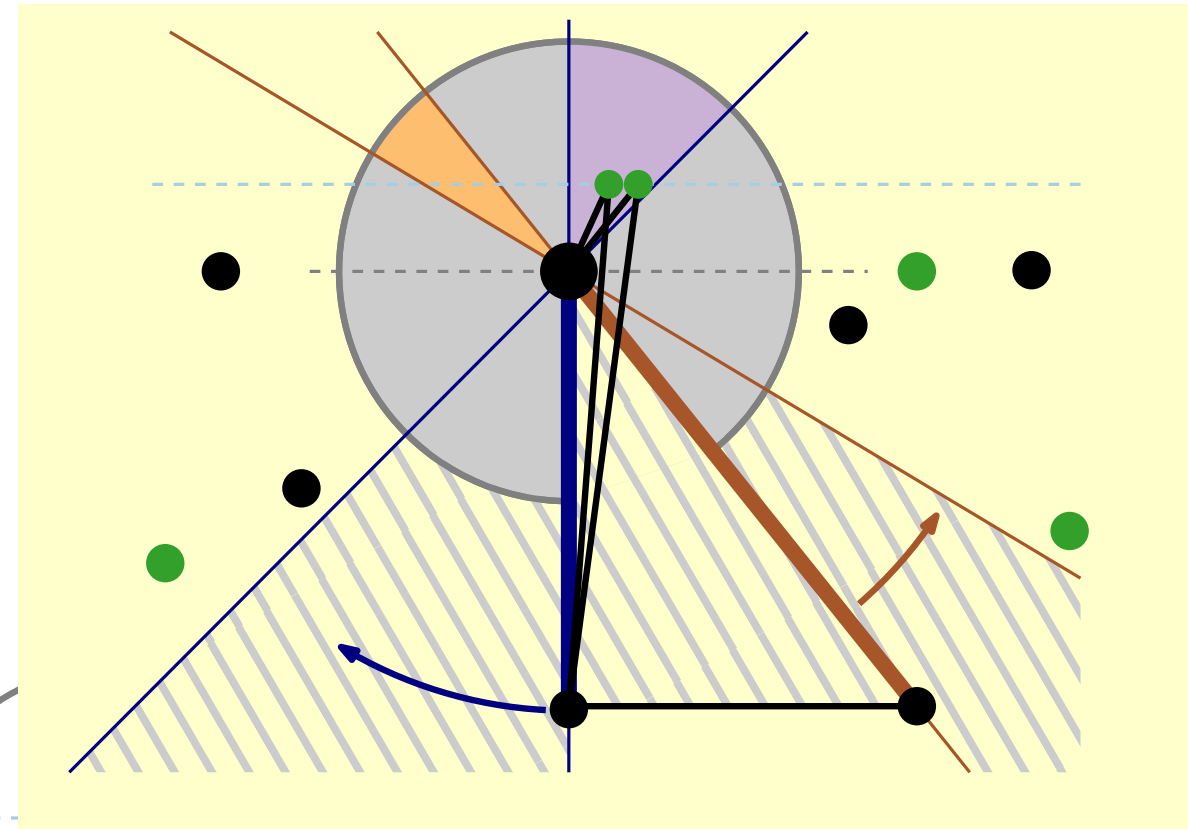
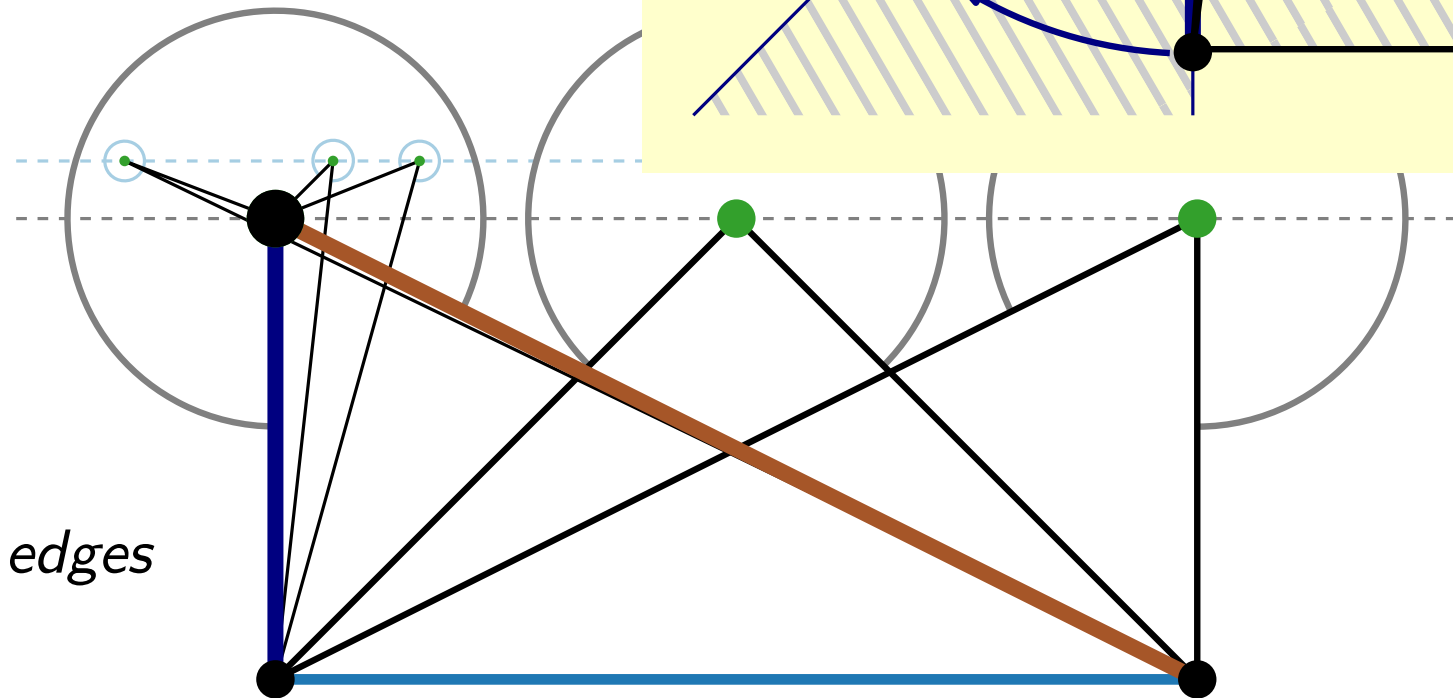
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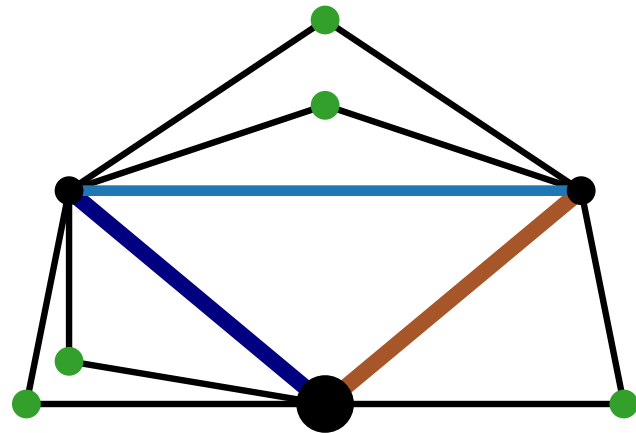
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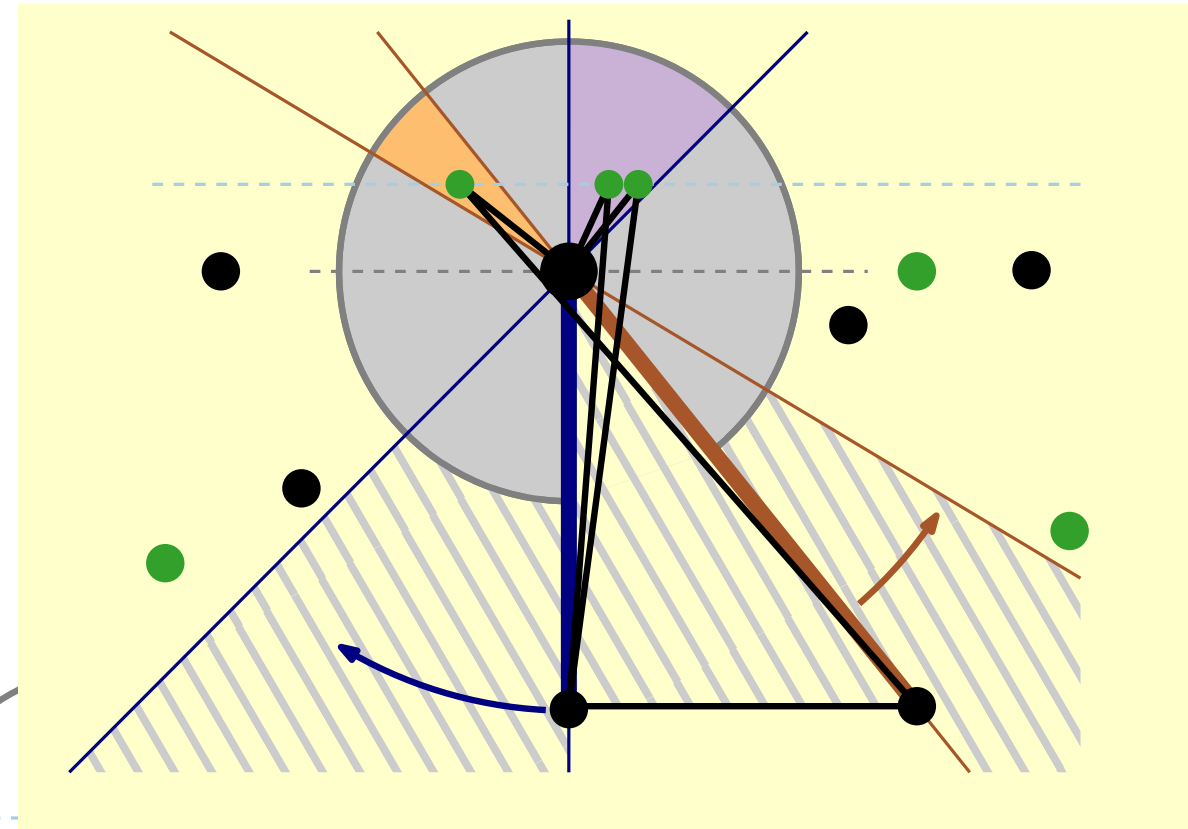
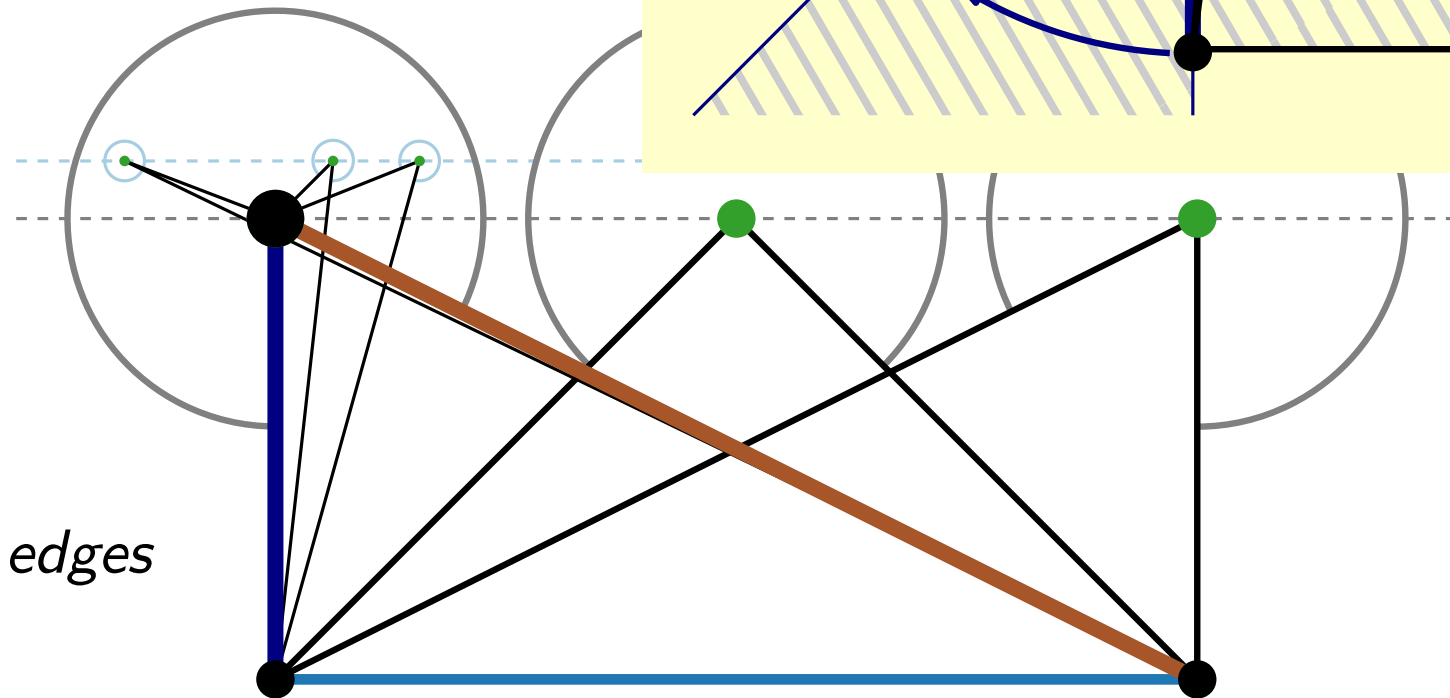
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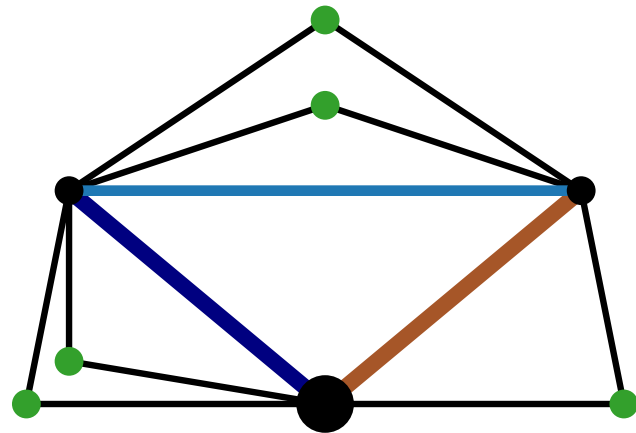
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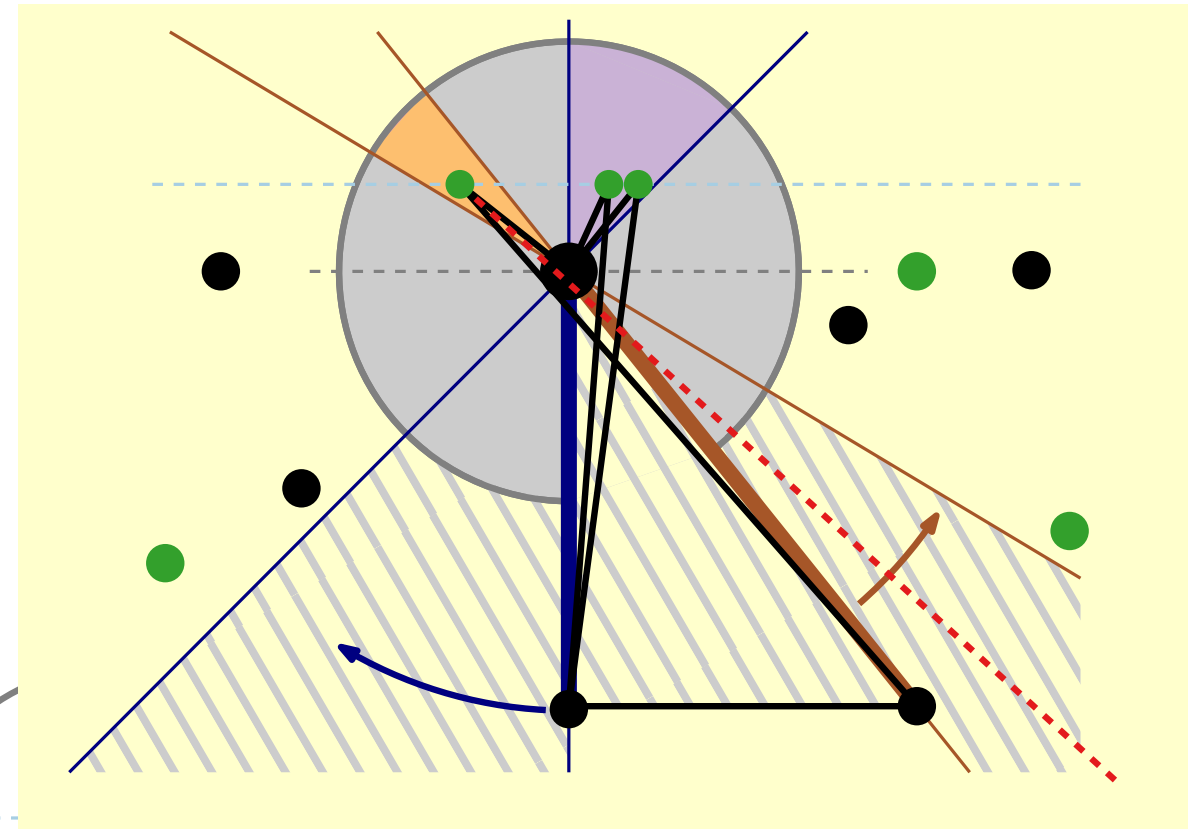
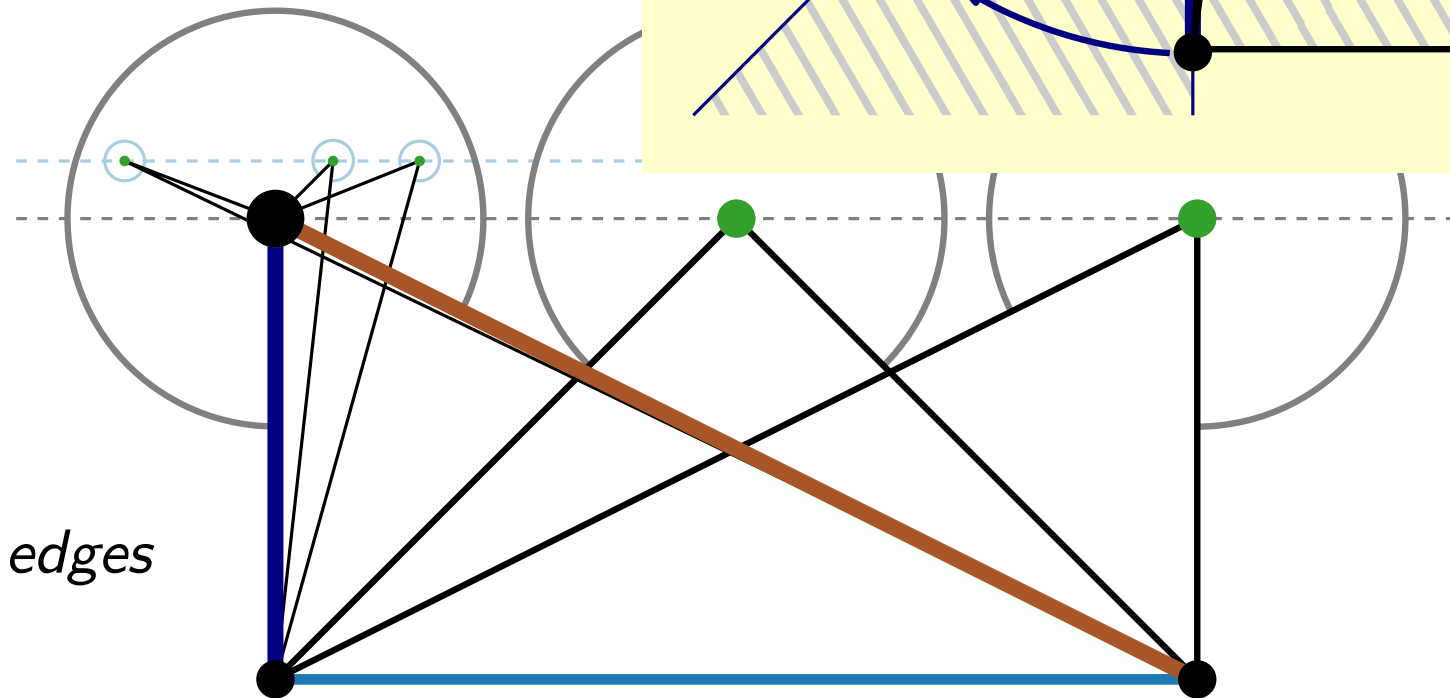
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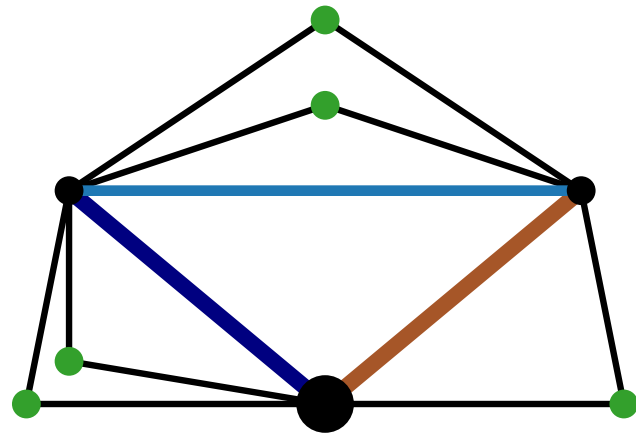
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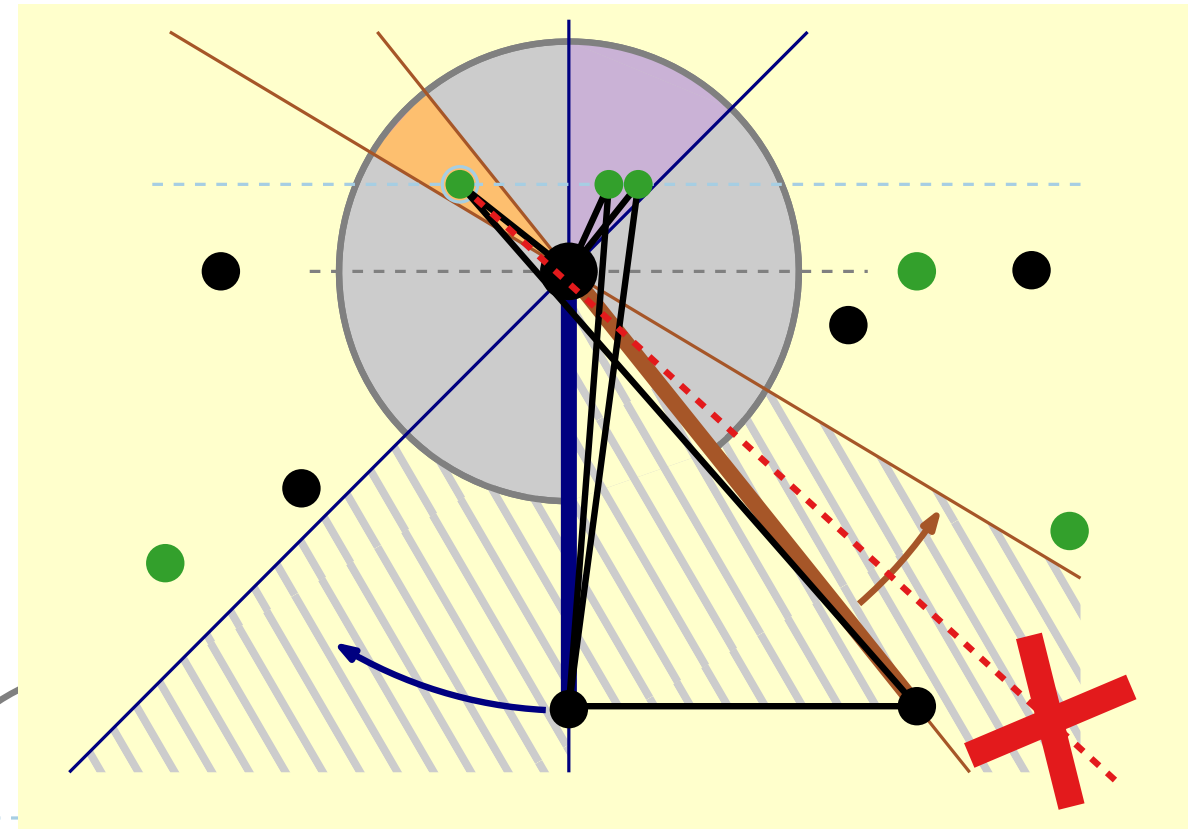
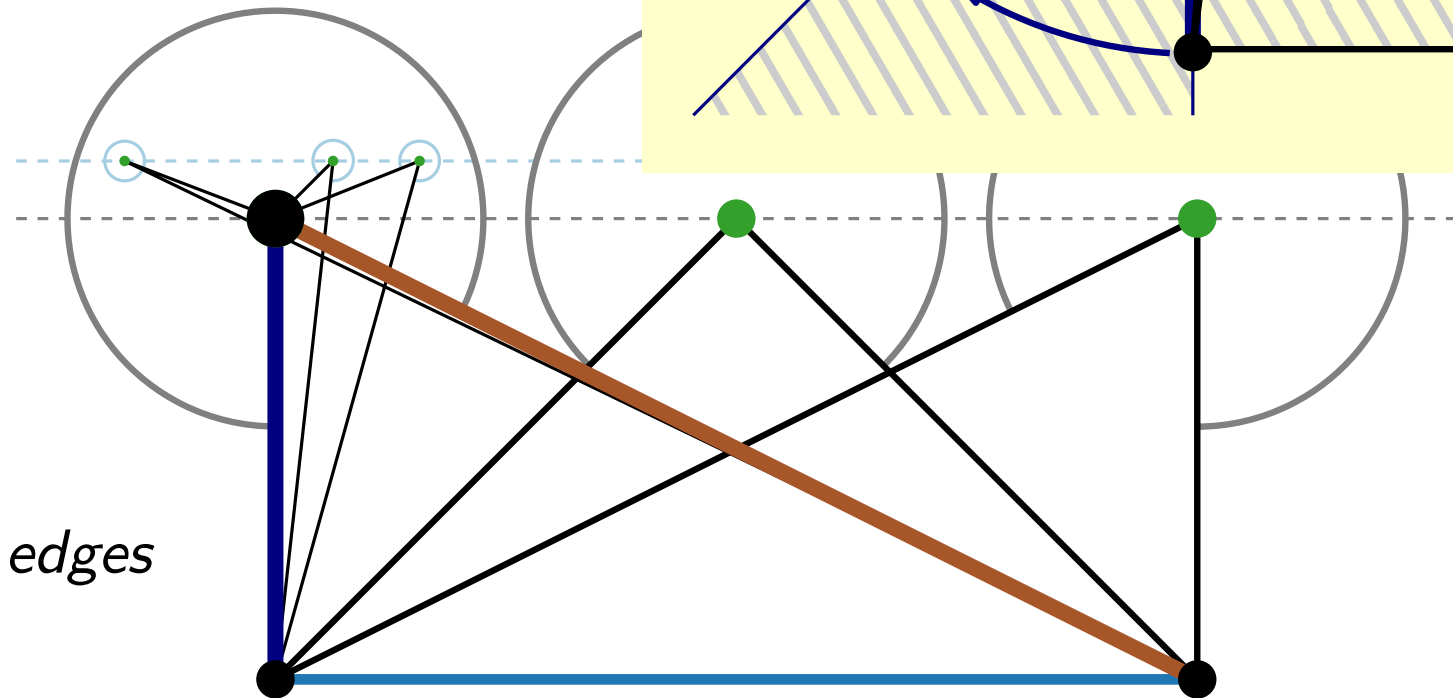
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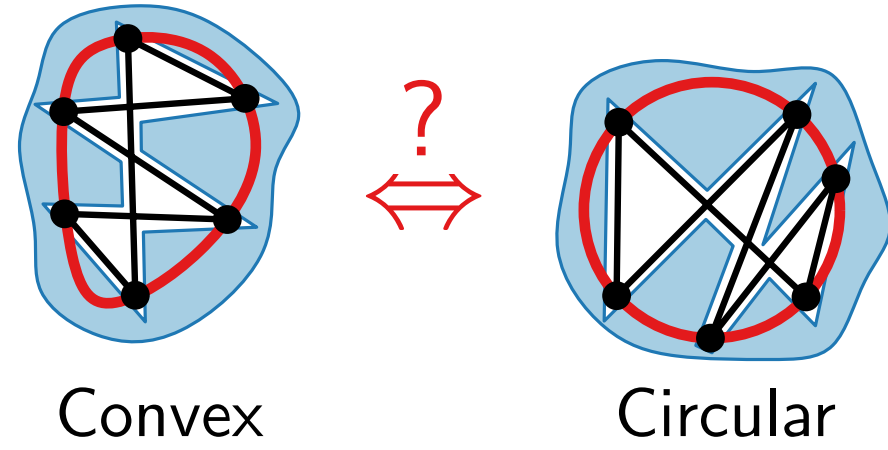
*base edge*

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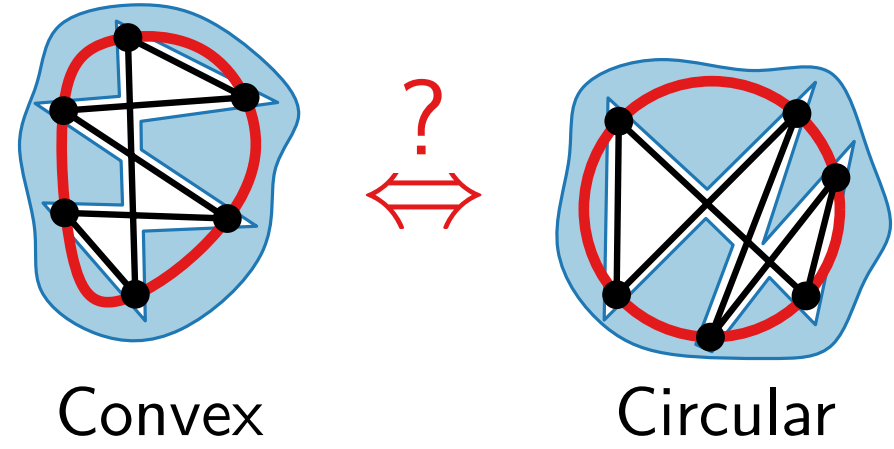
# Open Problems

- Does every graph that admits a **convex** outside-obstacle representation also admit a **circular** outside-obstacle representation?



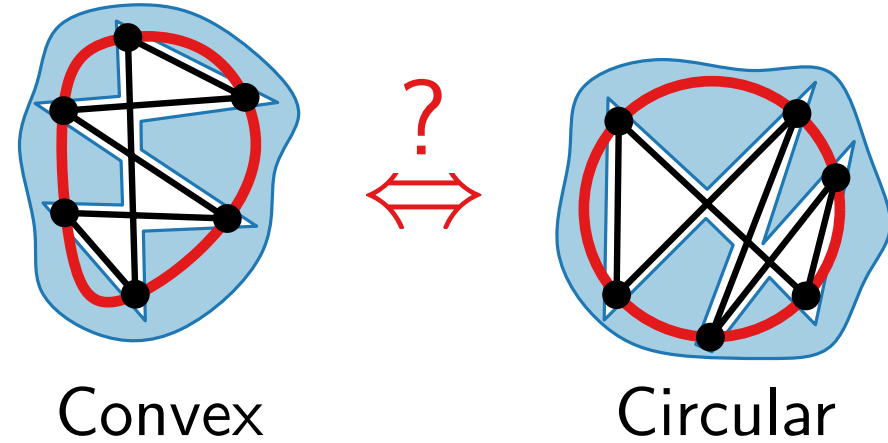
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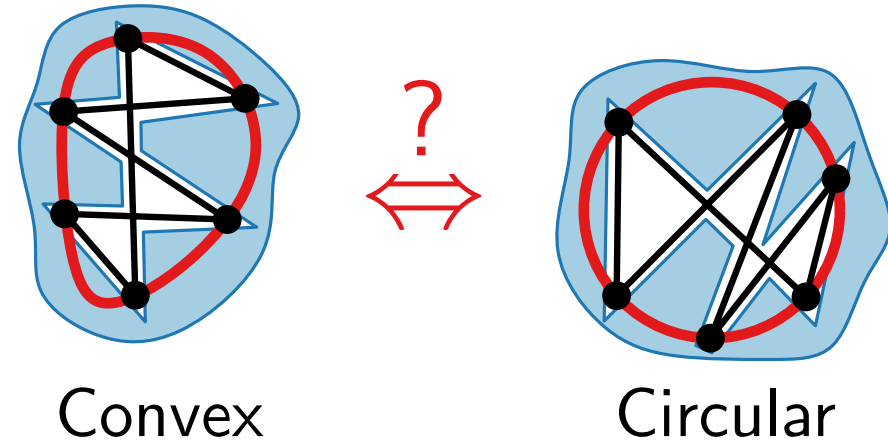
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- What is the **complexity** of deciding whether a given graph admits an outside-obstacle representation?
- Which **other classes** of graphs admit regular or circular outside-obstacle representations?



- Does every graph that admits a **convex** outside-obstacle representation also admit a **circular** outside-obstacle representation?
- Does every **outerplanar graph** admit a (reducible) convex outside-obstacle representation?
- What is the **complexity** of deciding whether a given graph admits an outside-obstacle representation?
- Which **other classes** of graphs admit regular or circular outside-obstacle representations?

**Thank you!**  
**Stand with Ukraine!**  
**Fight for truth!**