

Public Transportation in Rural Areas: The Clustered Dial-a-Ride Problem

Fabian Feitsch
November 16th, 2018



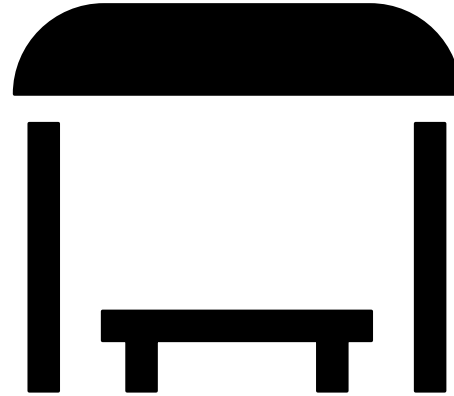
Attributions of third party images can be found on slide 12.

Public Transportation

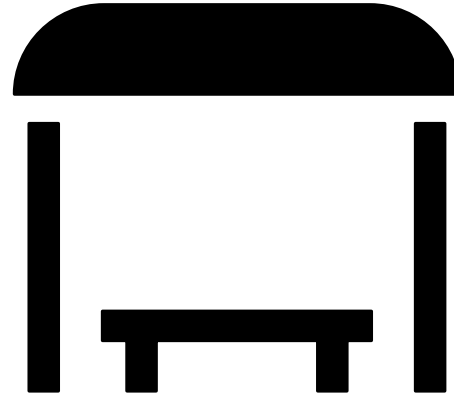
Public Transportation



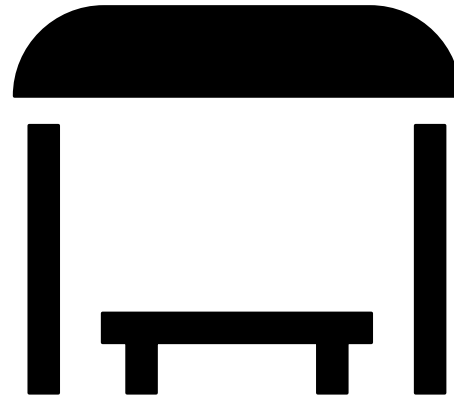
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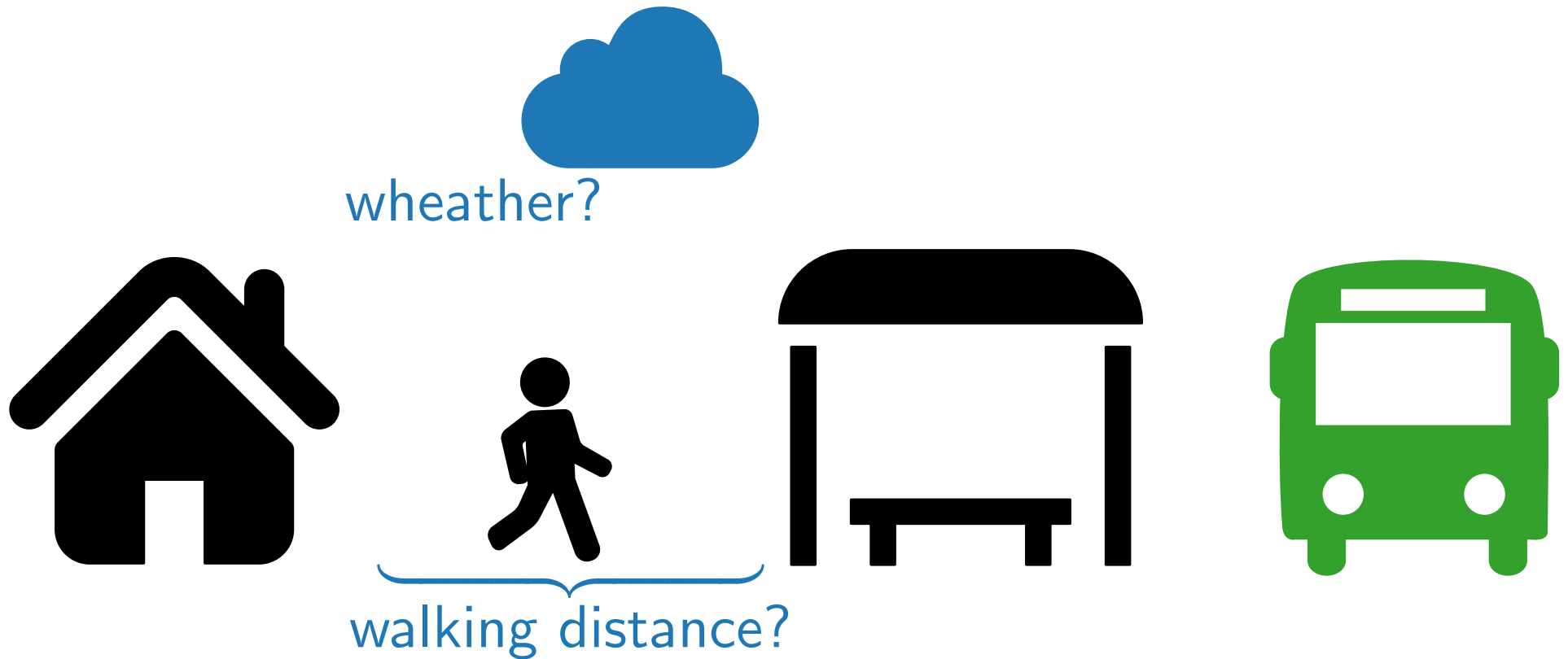
So far, so good?

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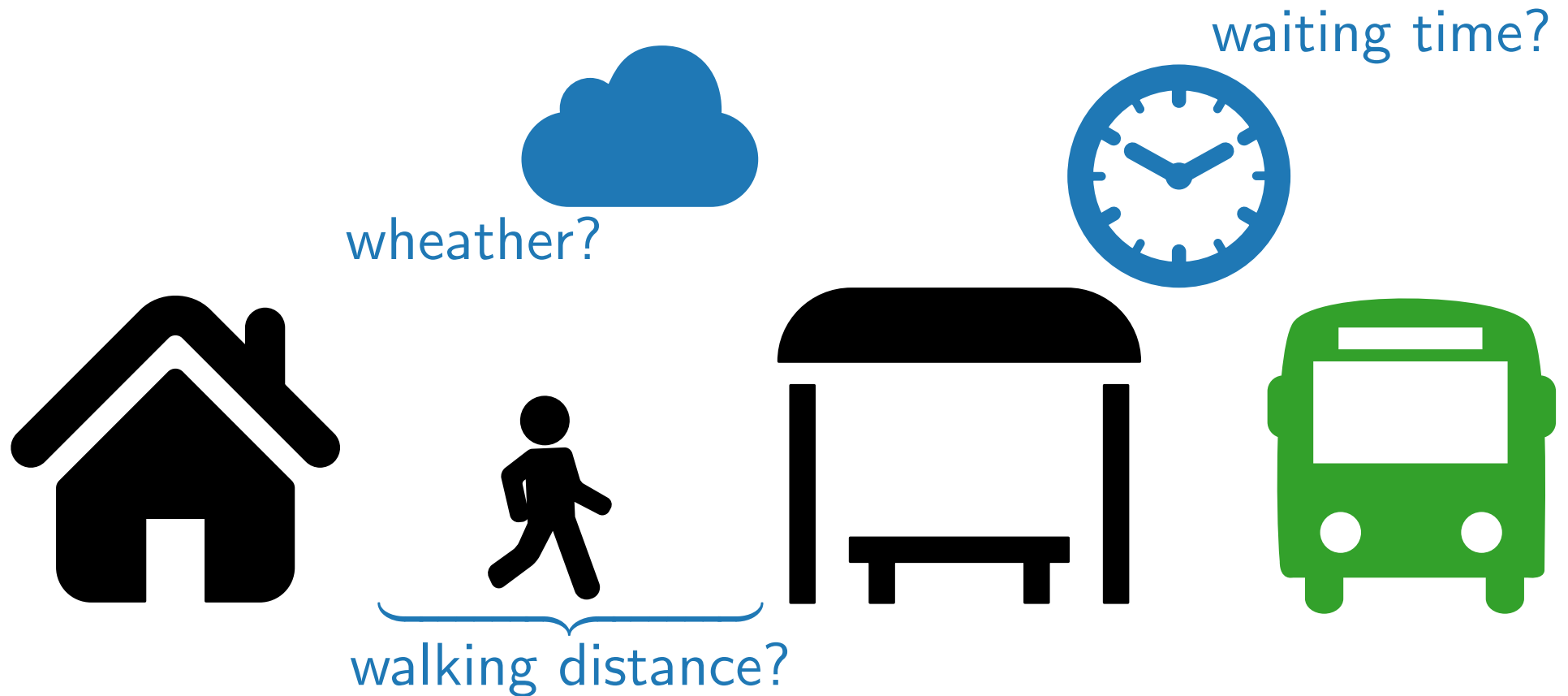
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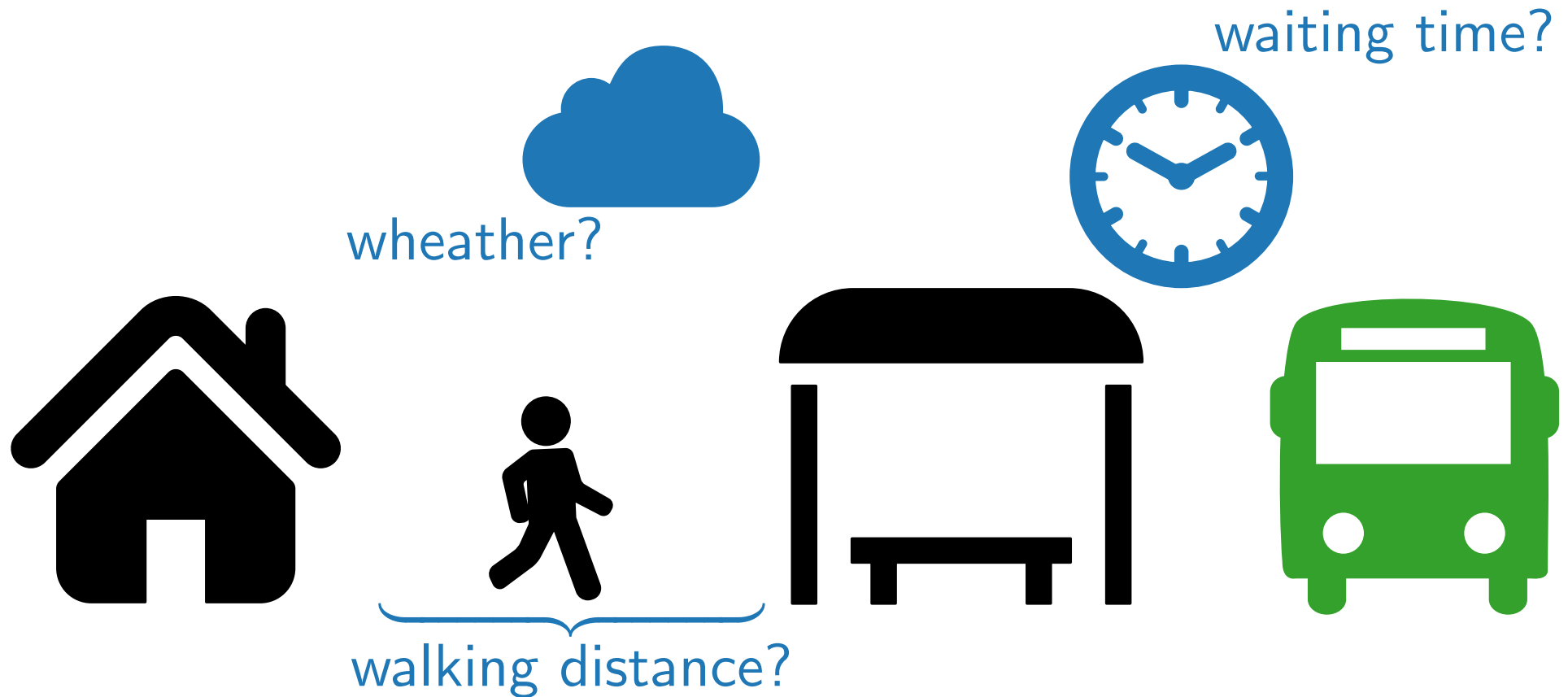
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So far, so good? → Probably in the city, but not in villages!

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→ Doorstep Service in Rural Areas

The Dial-a-Ride Problem

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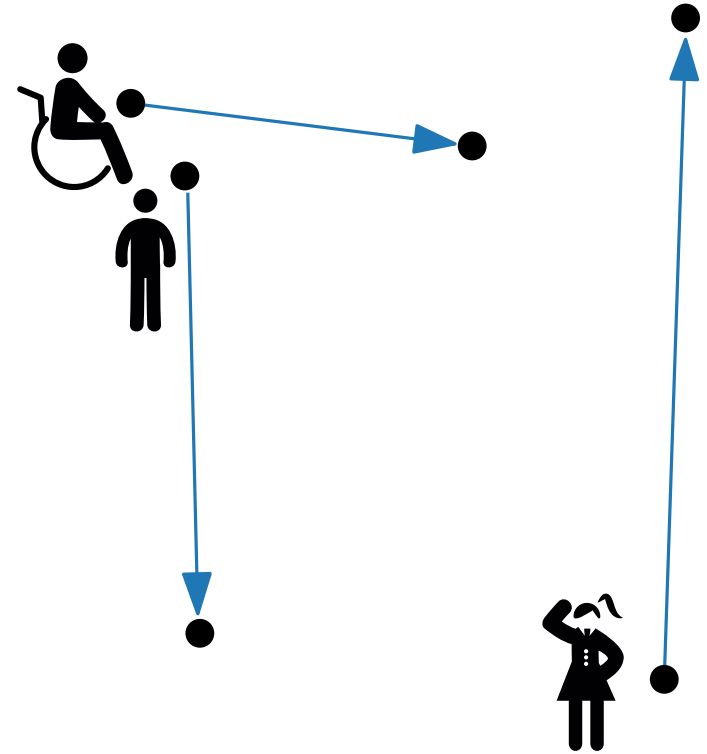
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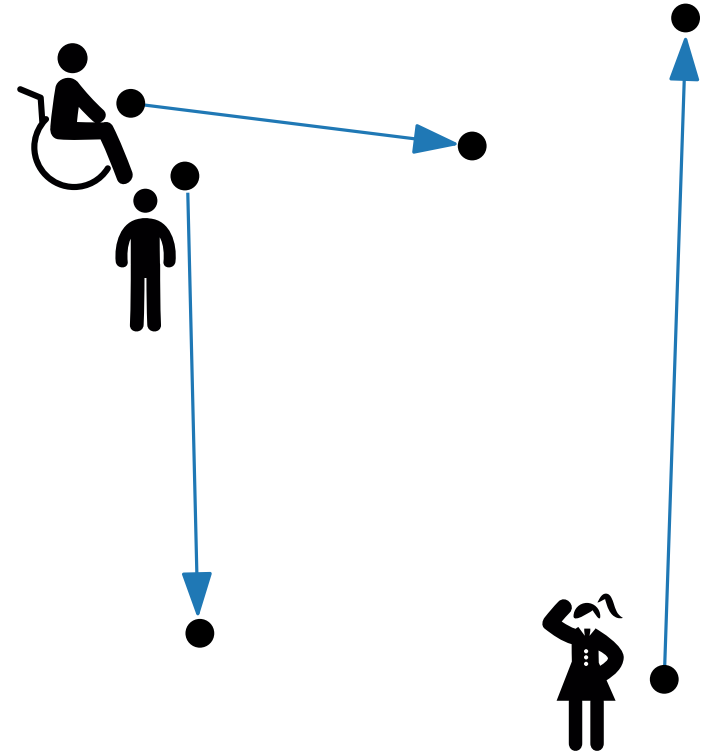


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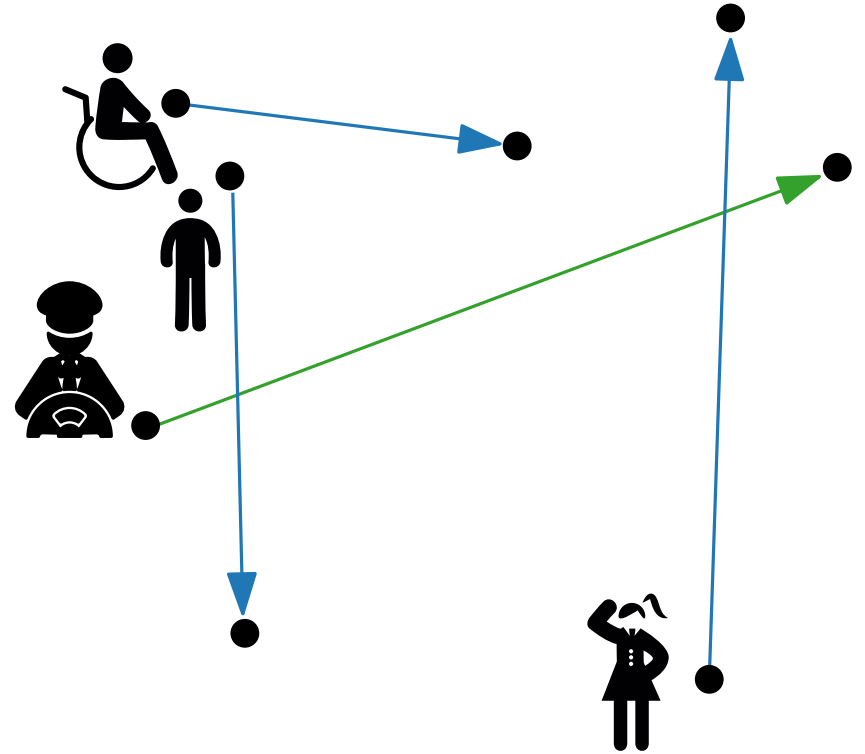


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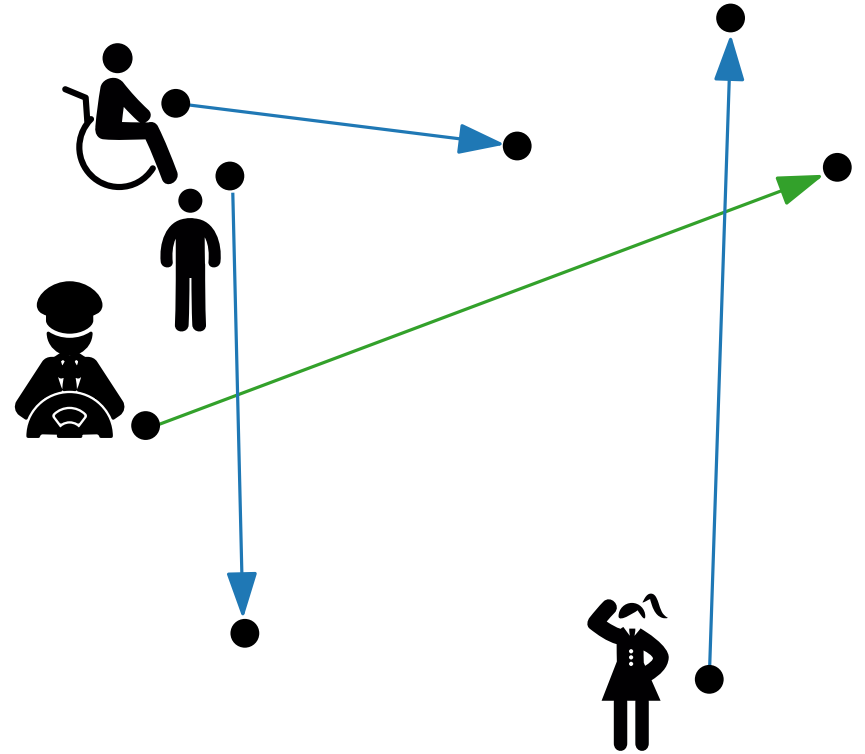
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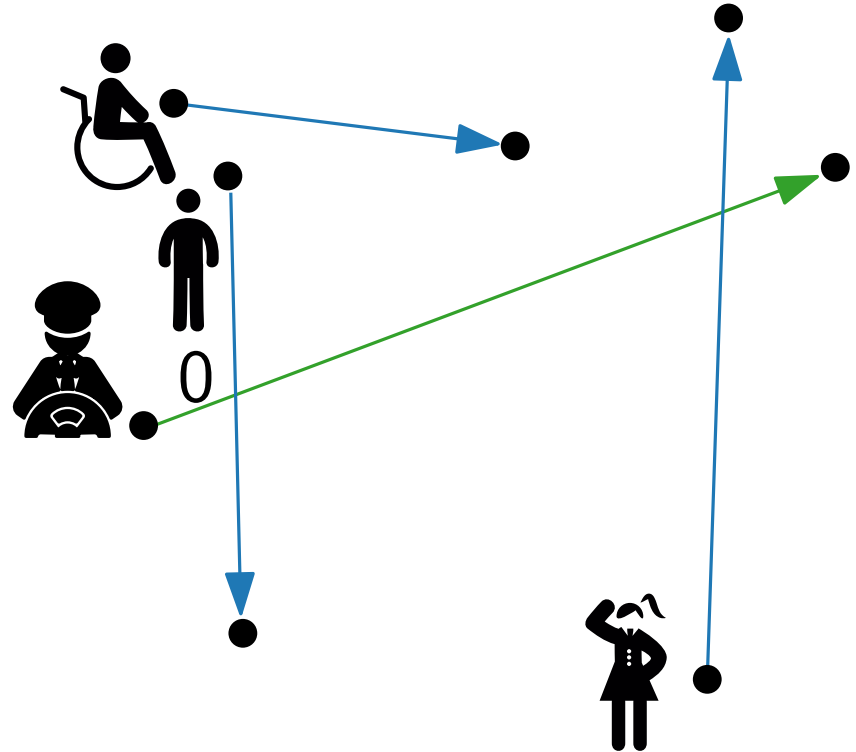
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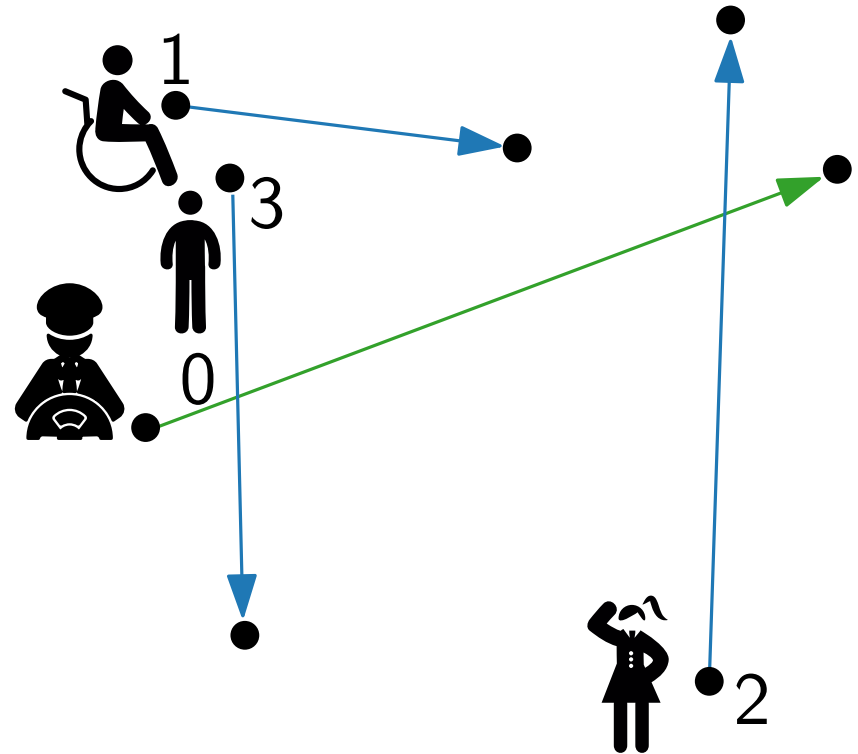
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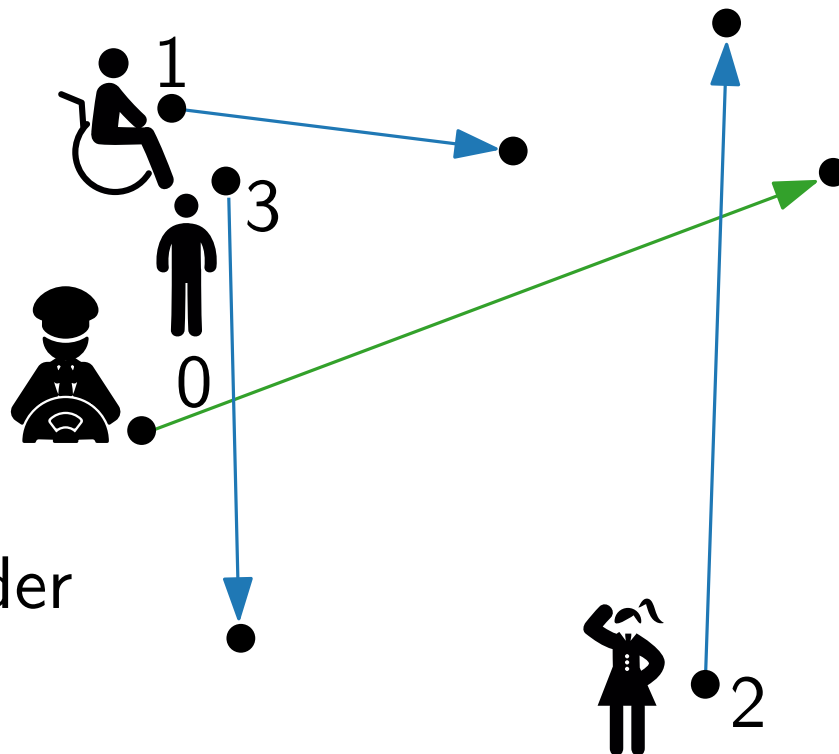
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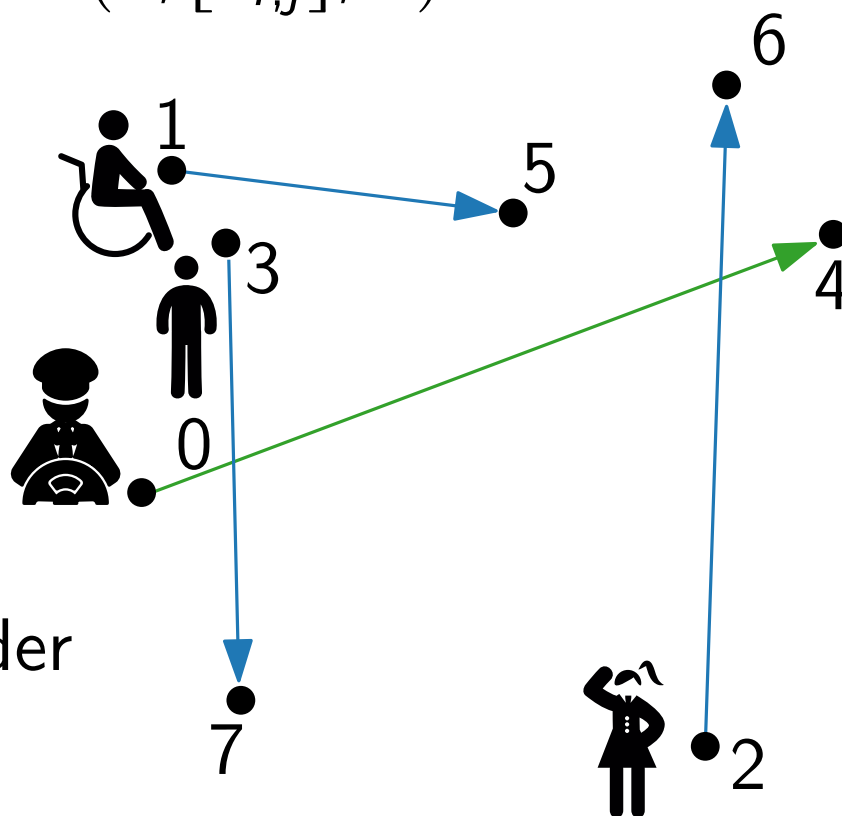
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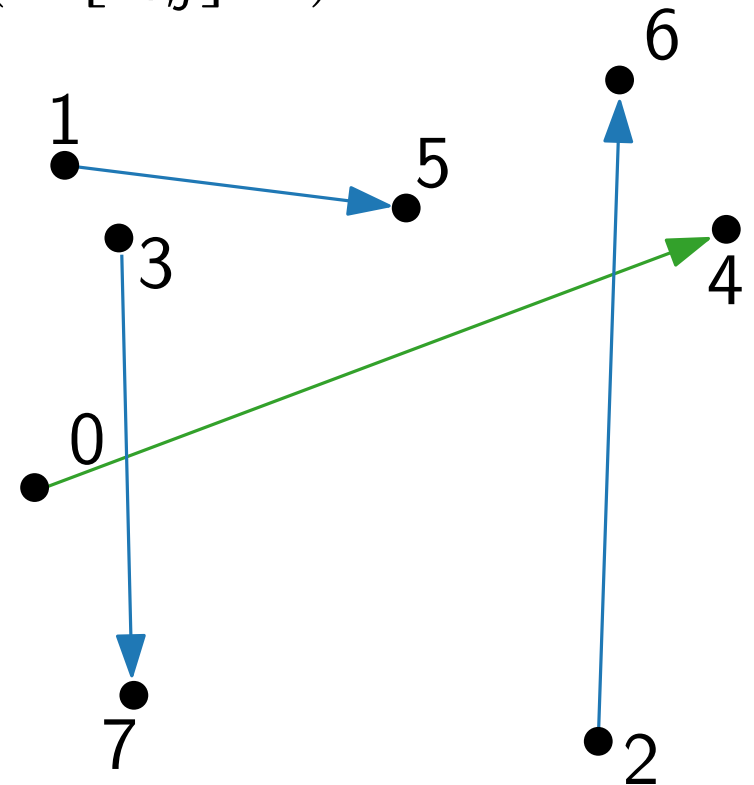
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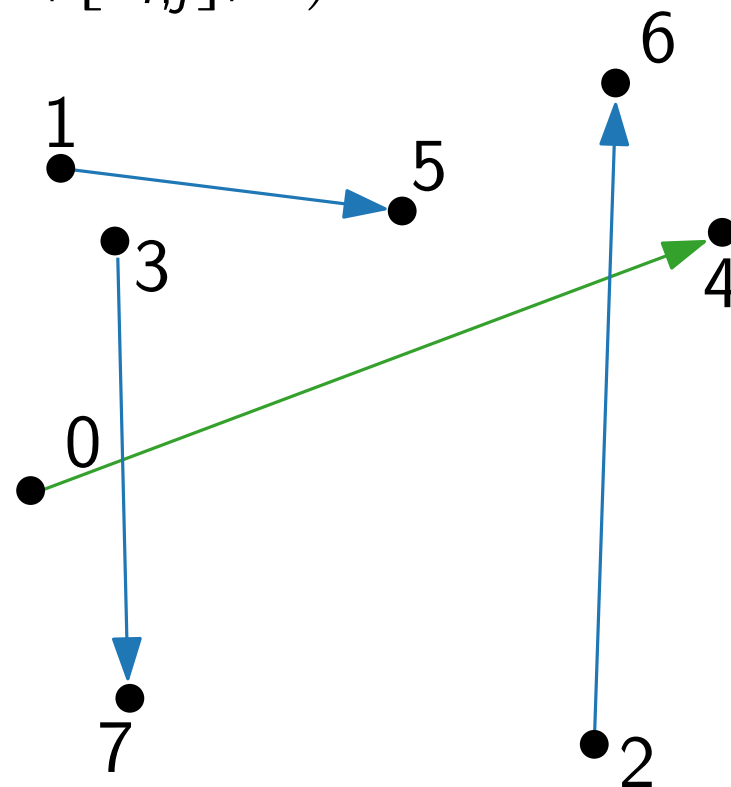
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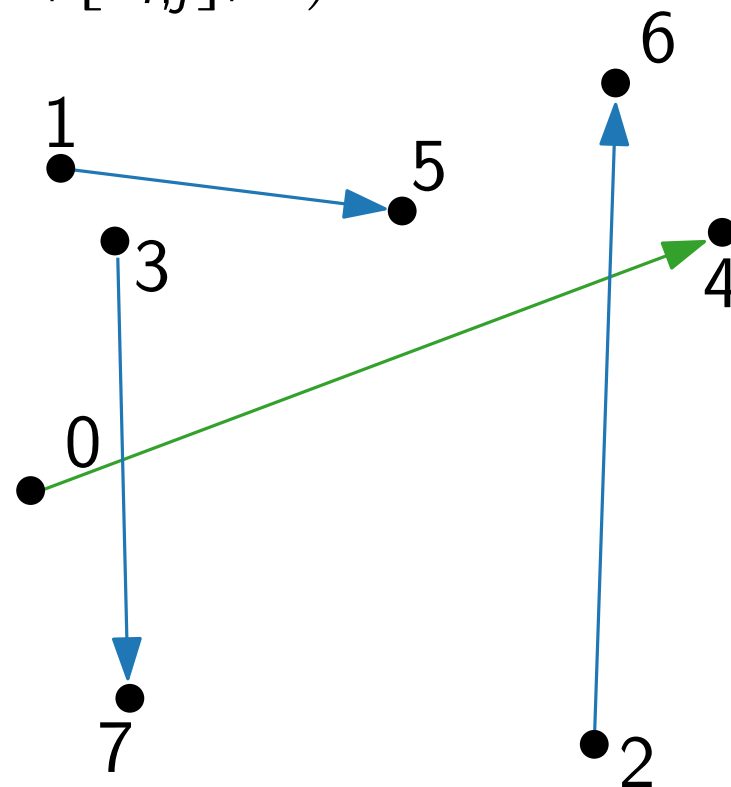
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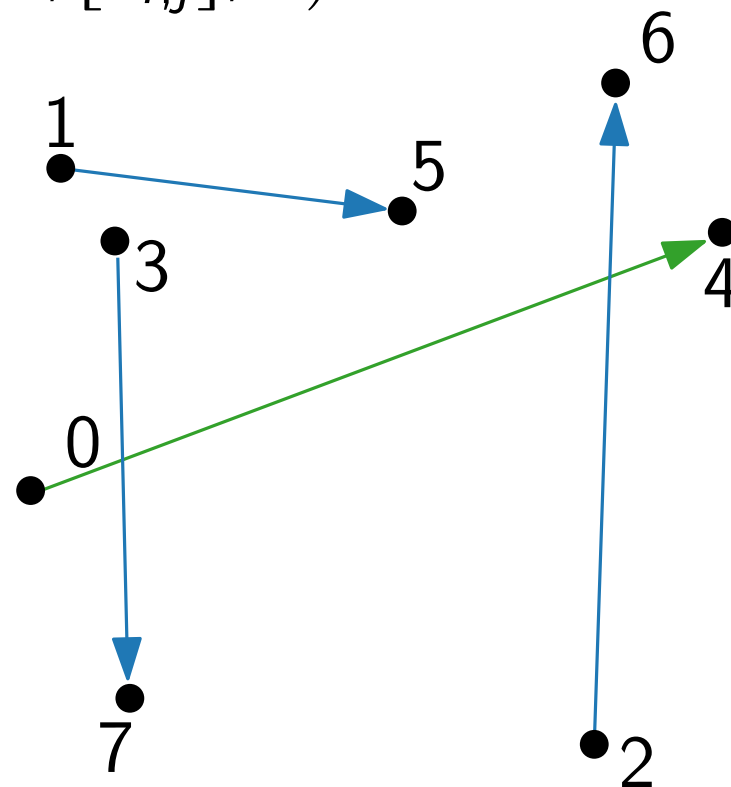
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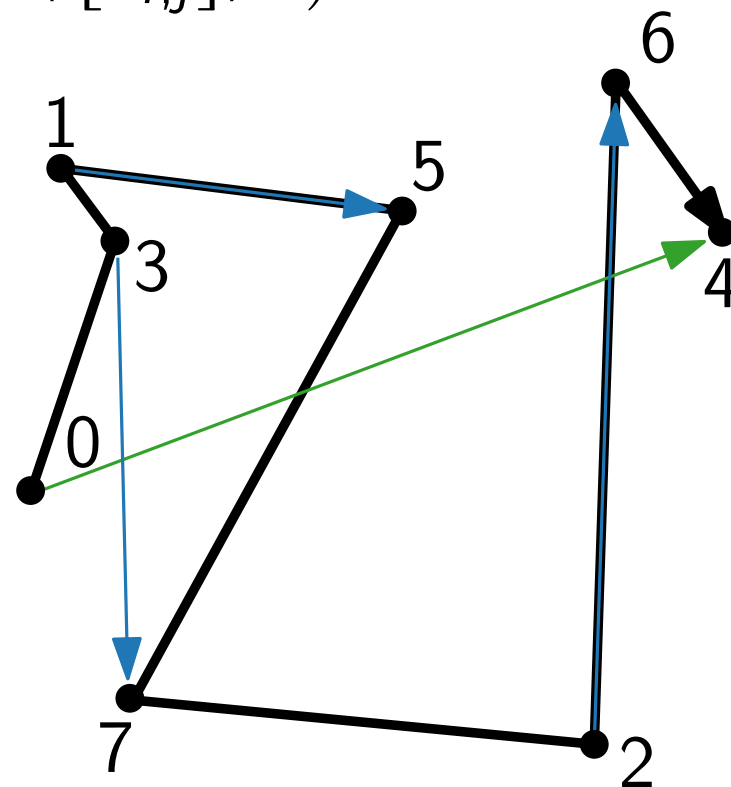
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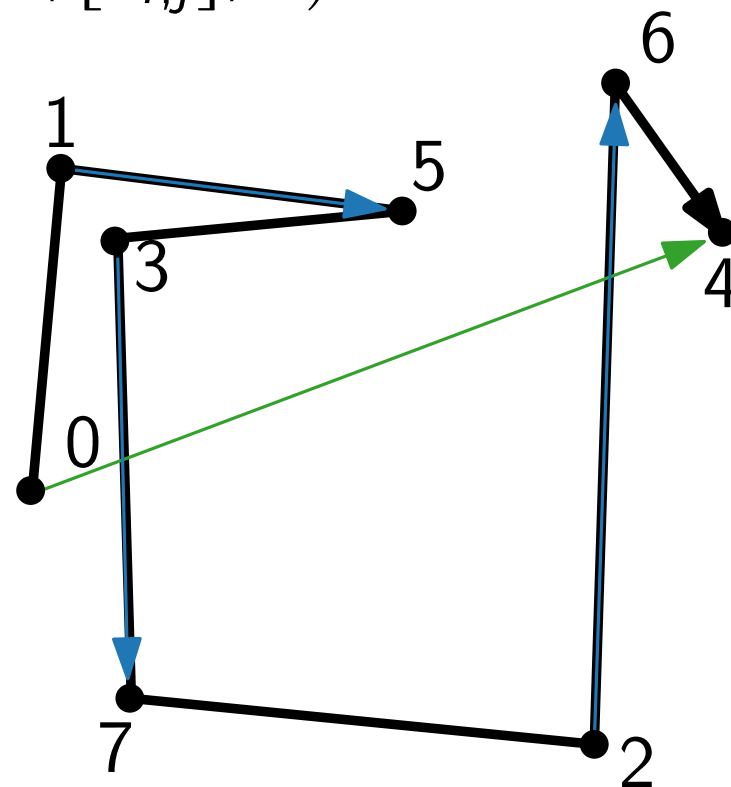
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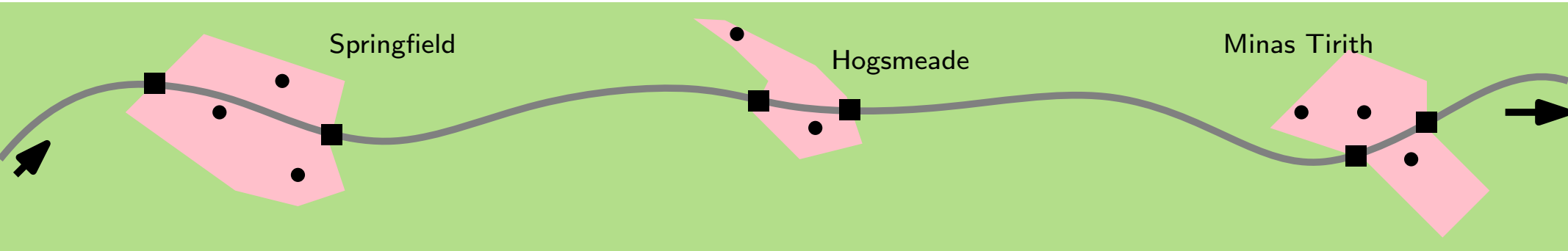
Can be generalized to solve partial instances:



- Find best tour such that
- a) girl is delivered
 - b) waiting customer is fetched
 - c) boy is still on board.

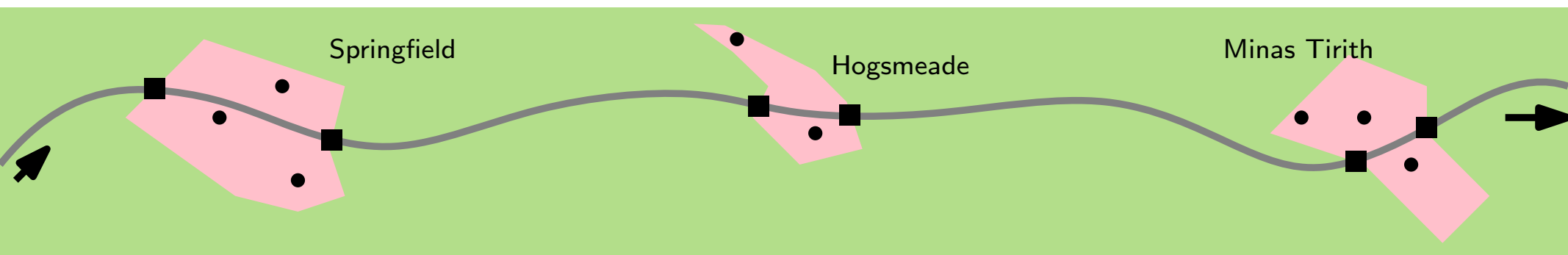


Back to Rural Areas . . .



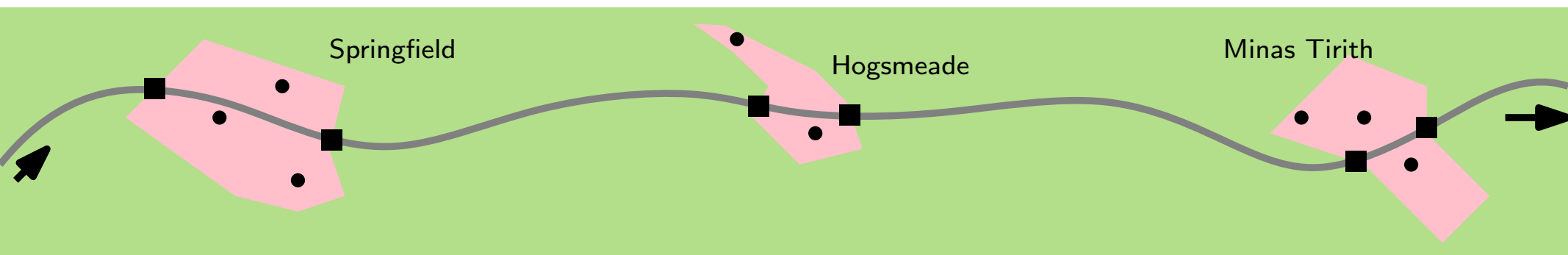
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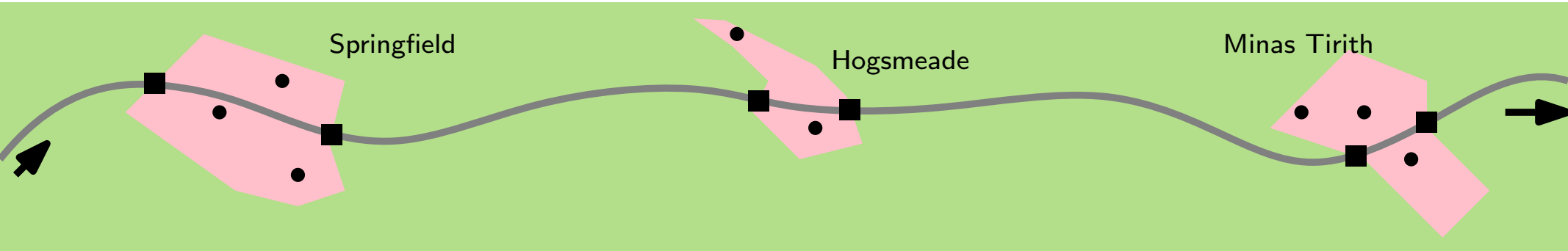
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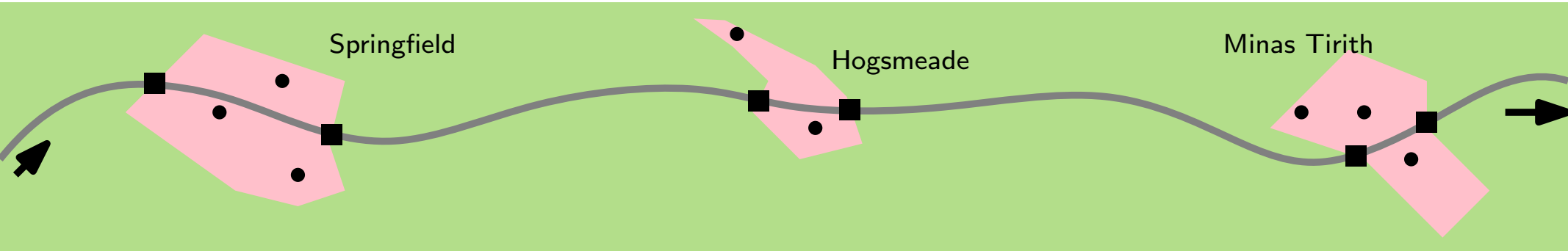


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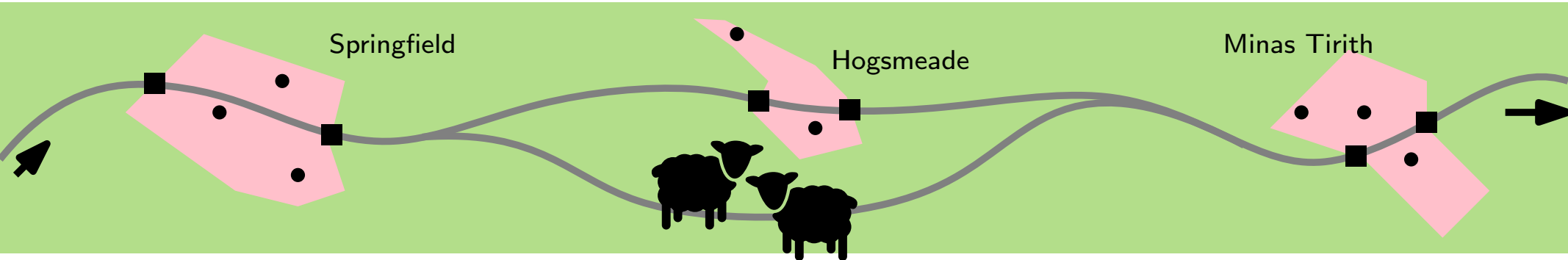


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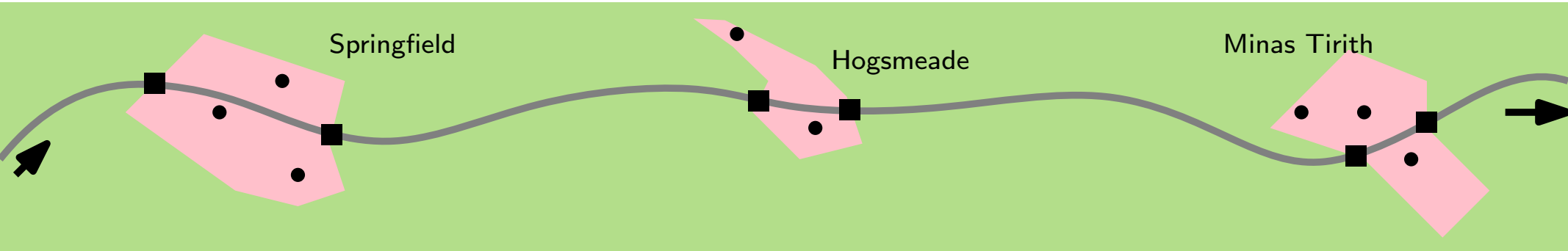


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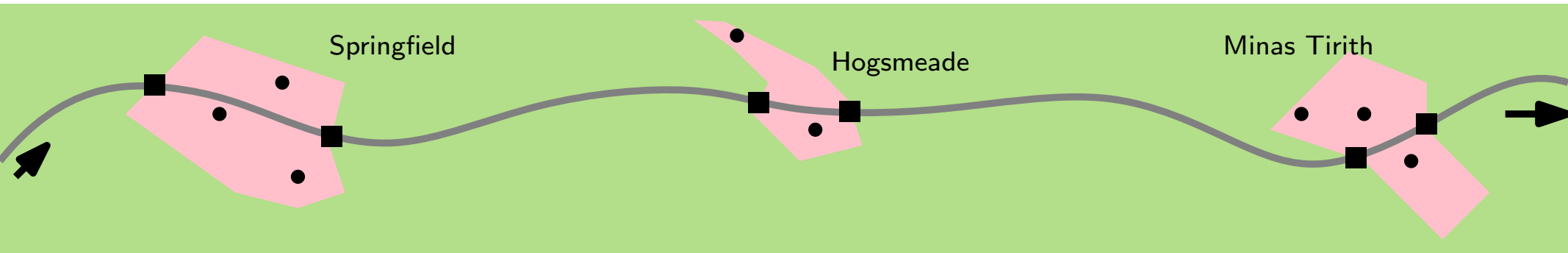


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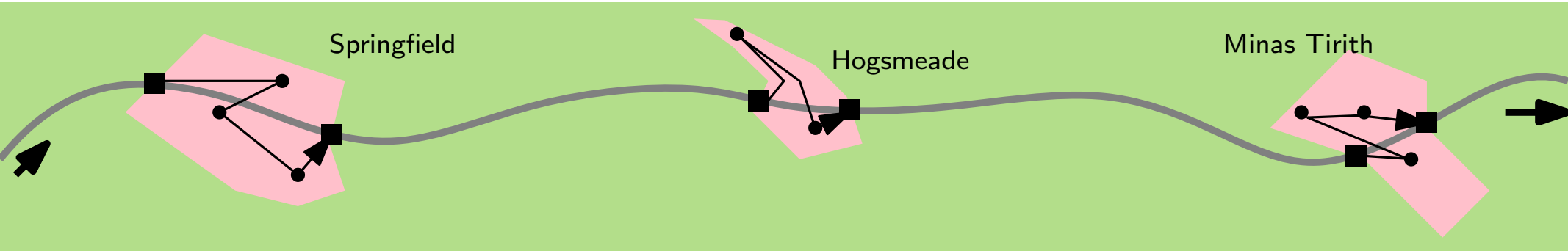
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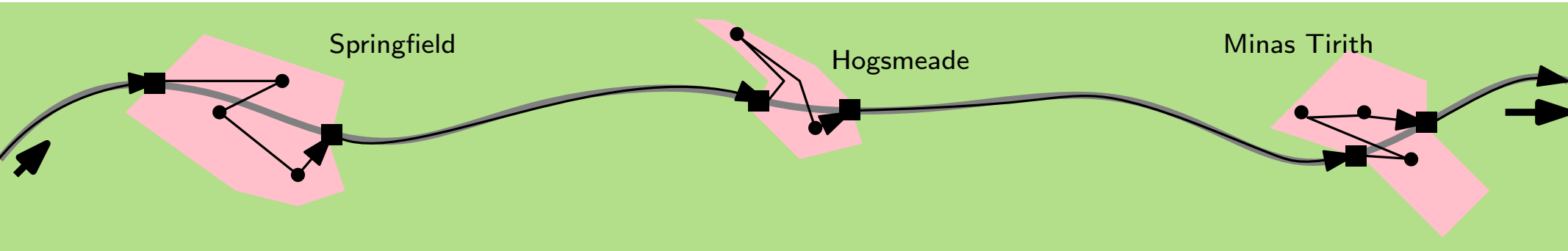
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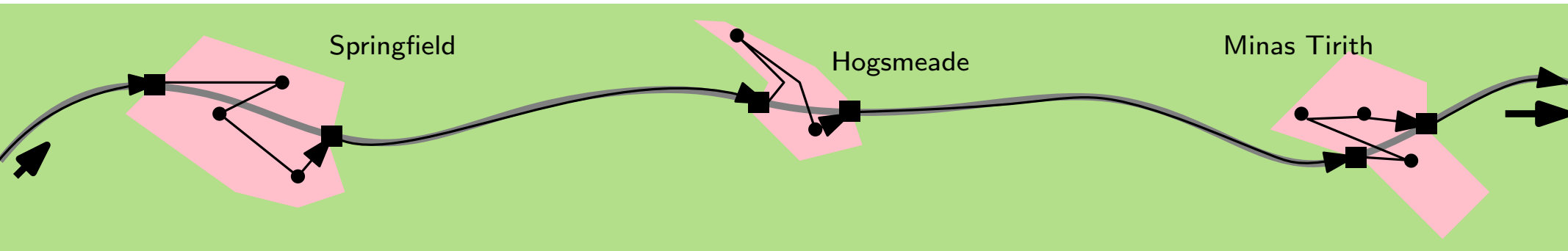
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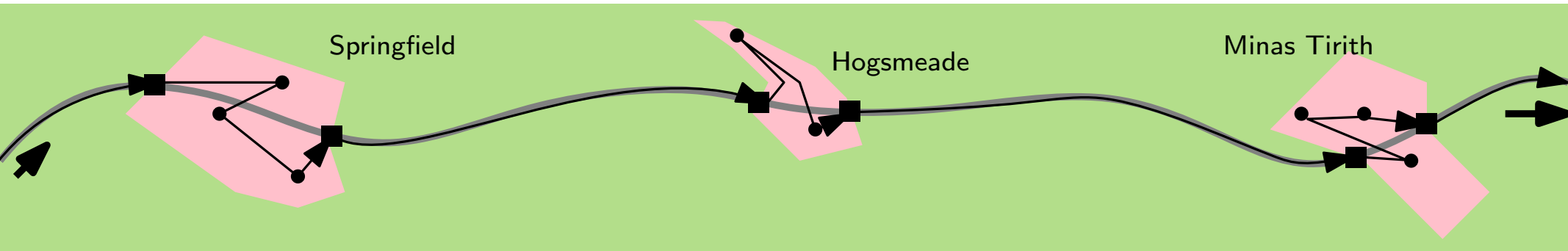
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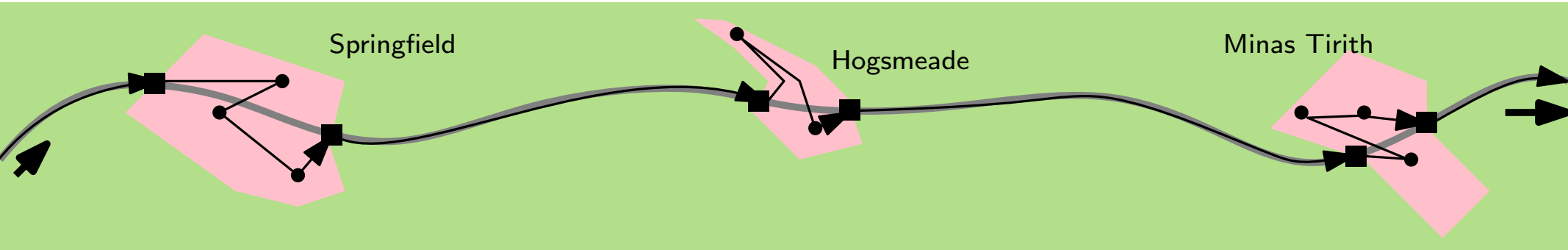
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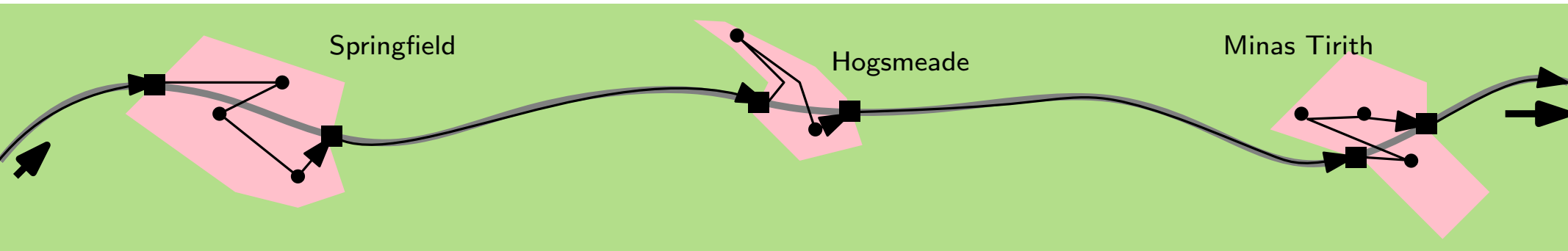
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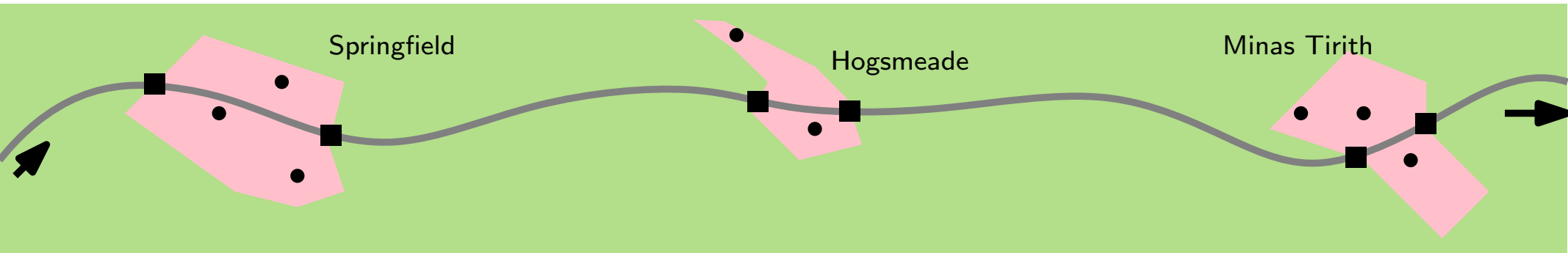
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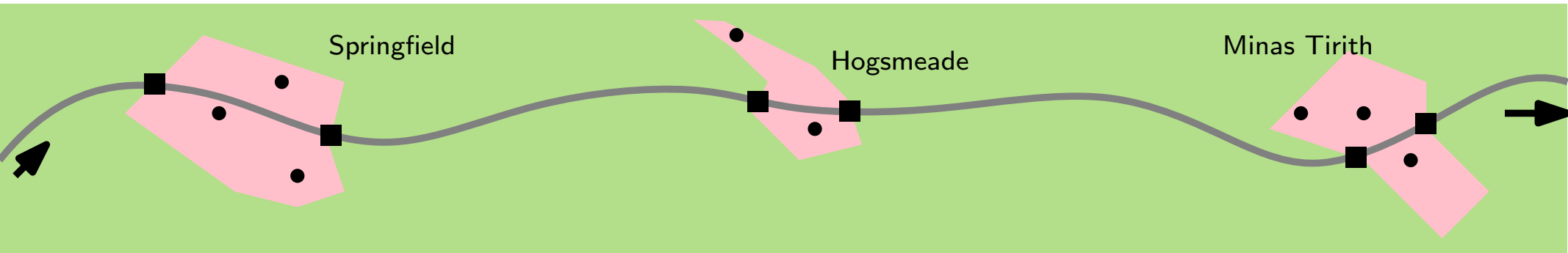
Classify instances whose optimal tour is unidirectional.
(without computing it)

A Classifier



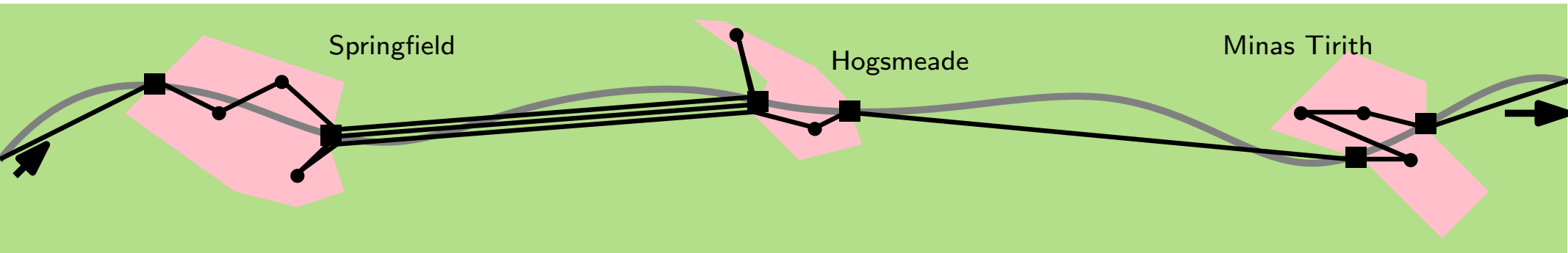
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Idea: Distribute the costs of a tour to the clusters.



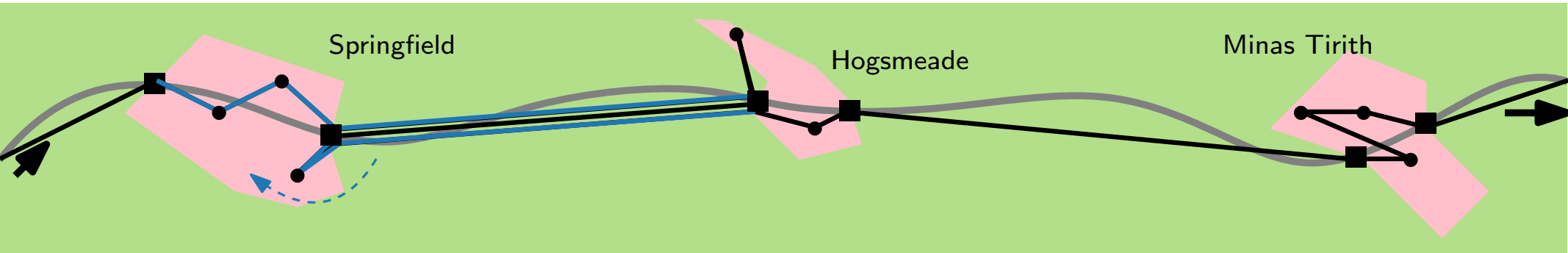
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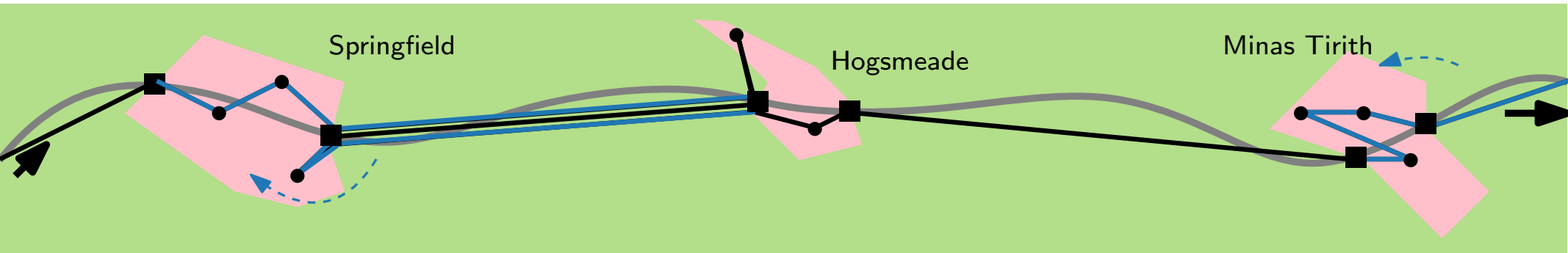
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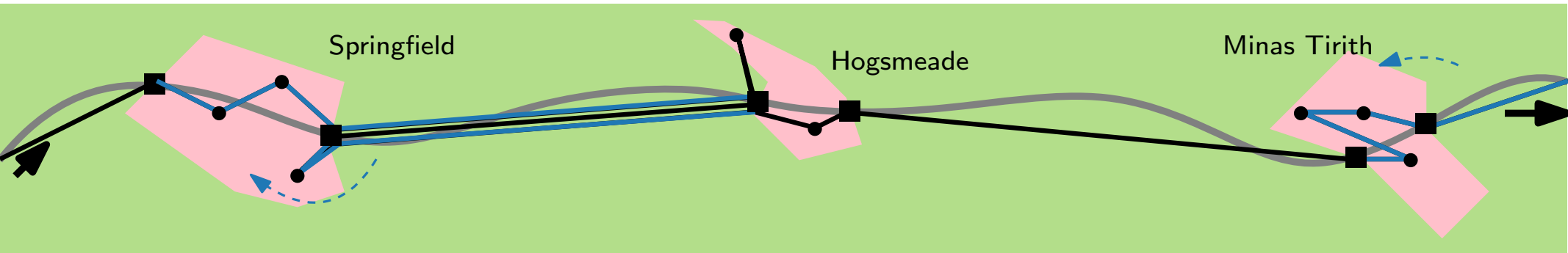
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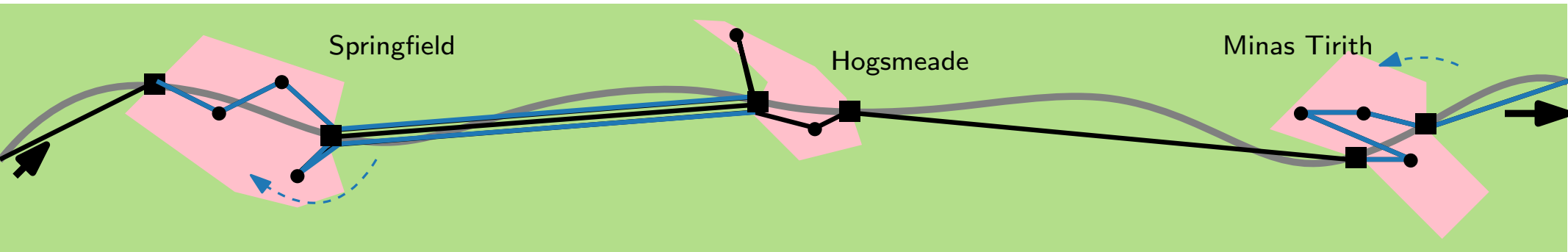
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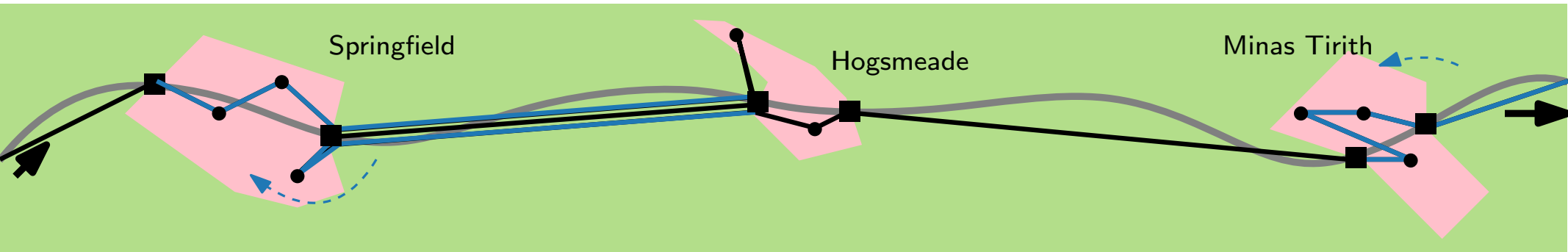


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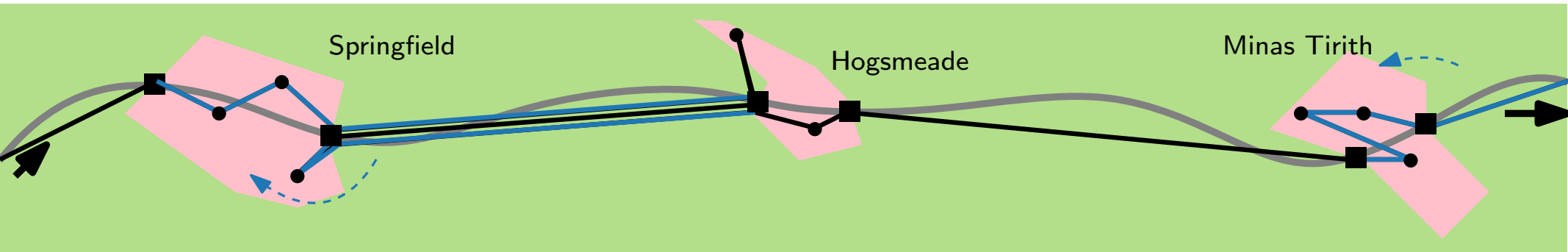


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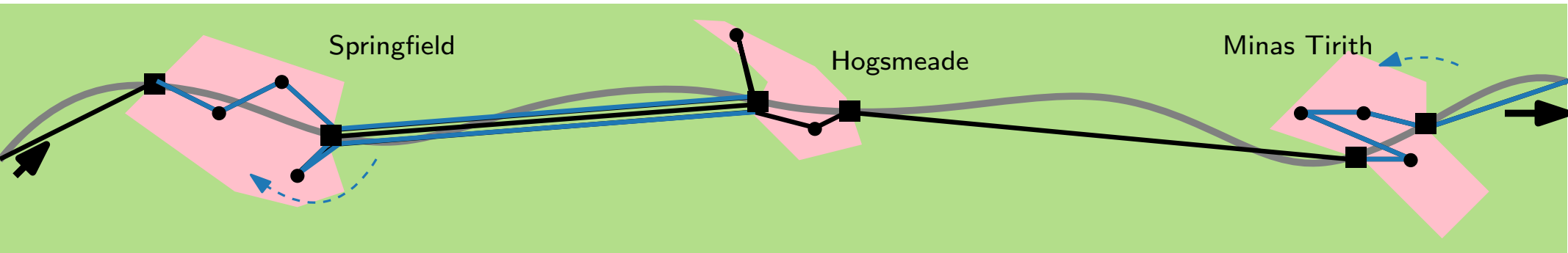
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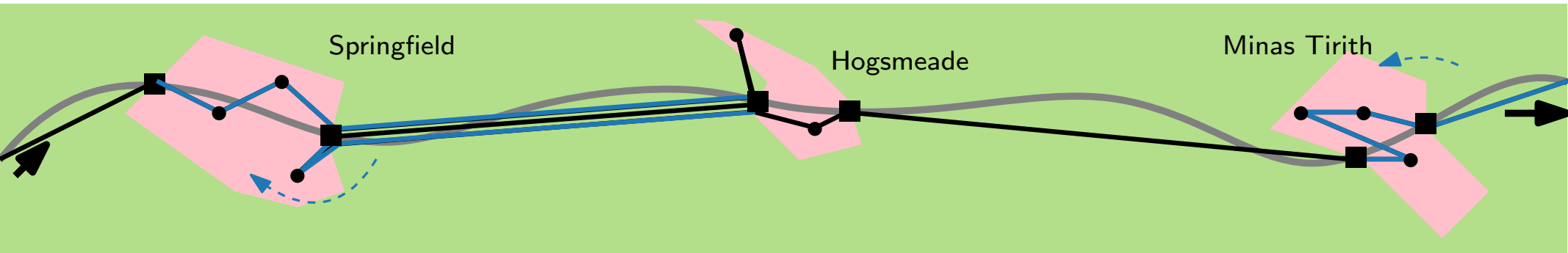
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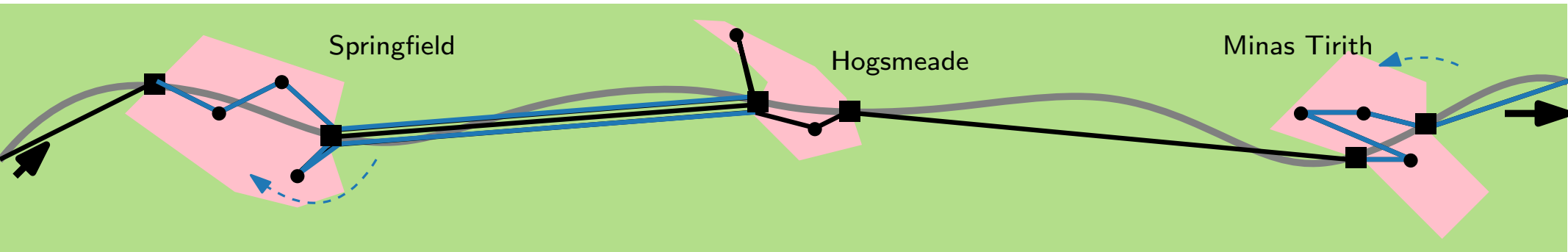
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Theorem (= Classifier): $\forall C_i: \phi(C_i) = \gamma(\overrightarrow{T^*}, C_i) \Rightarrow T^* = \overrightarrow{T^*}$

A Classifier

Idea: Distribute the costs of a tour to the clusters.



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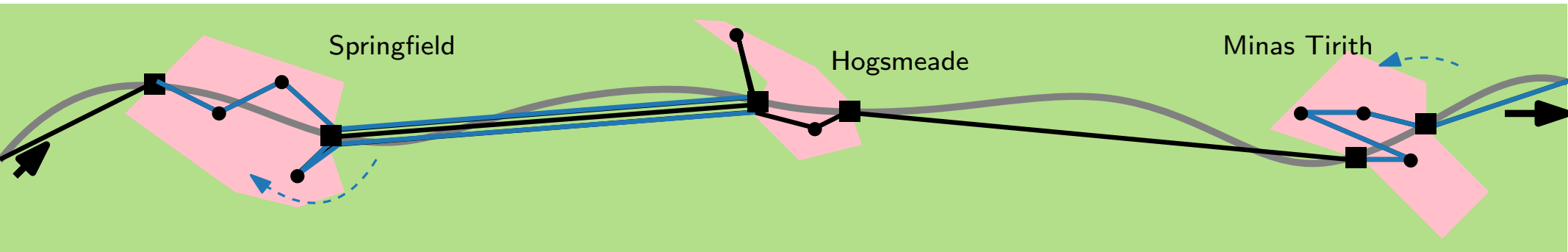
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Proof. Via exchange argument. \square

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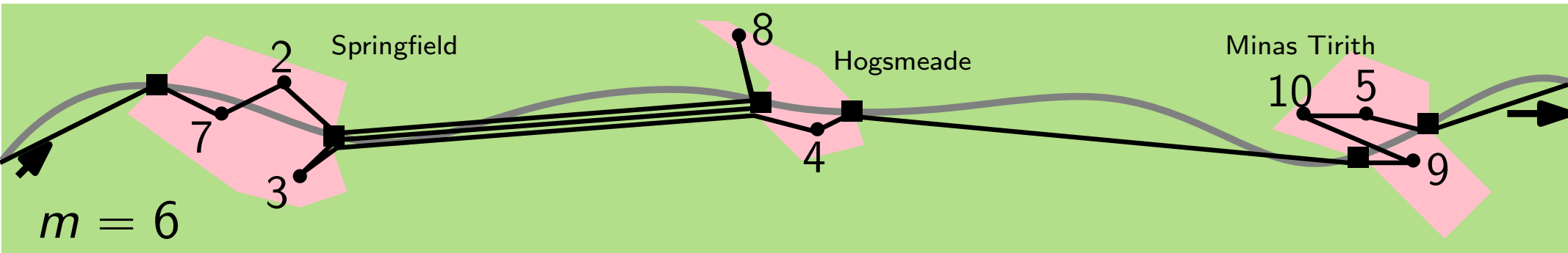
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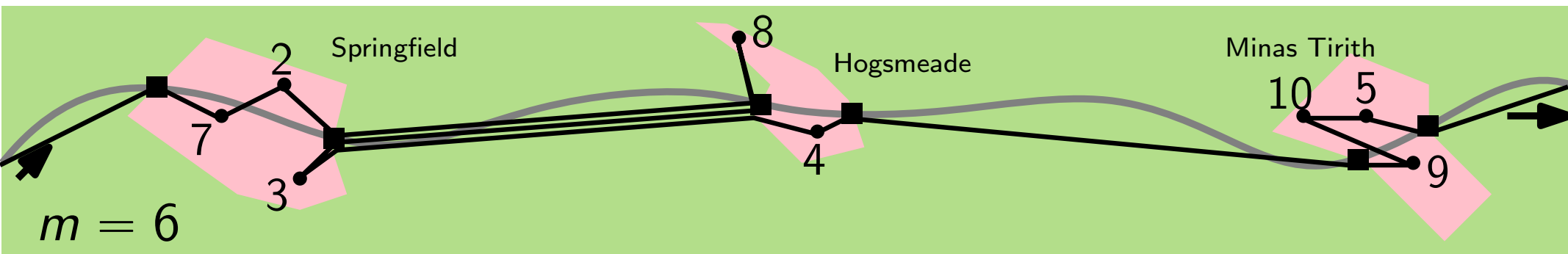
Proof. Via exchange argument. \square

Distribute Costs to Clusters



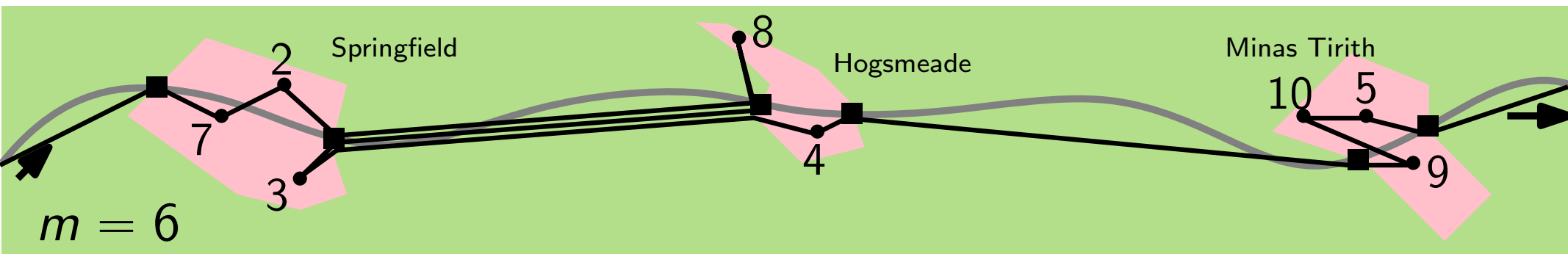
Distribute Costs to Clusters

Assign the parts of a tour to clusters.



Distribute Costs to Clusters

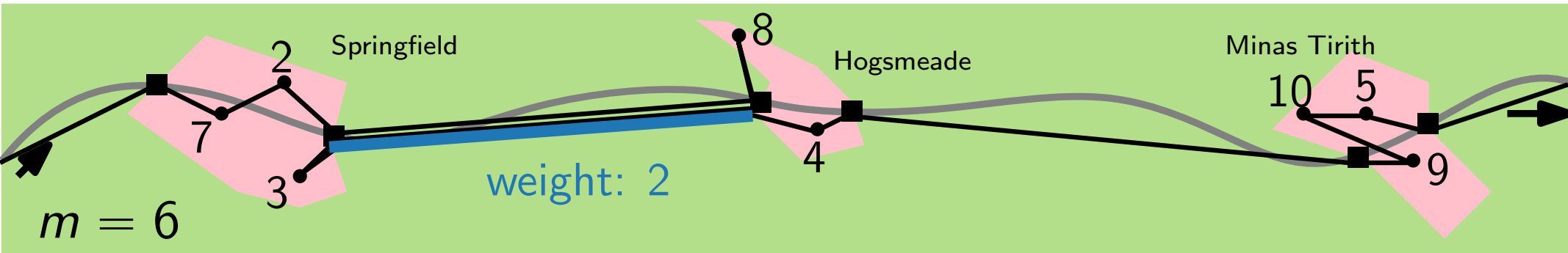
Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted.

Distribute Costs to Clusters

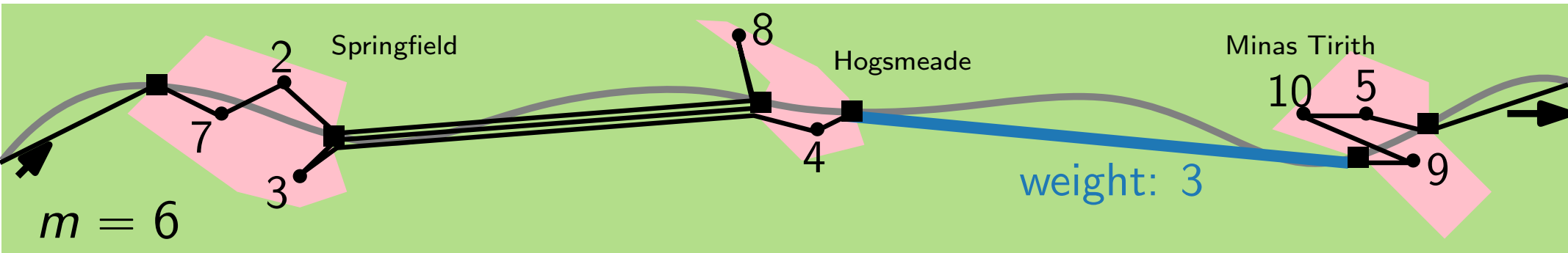
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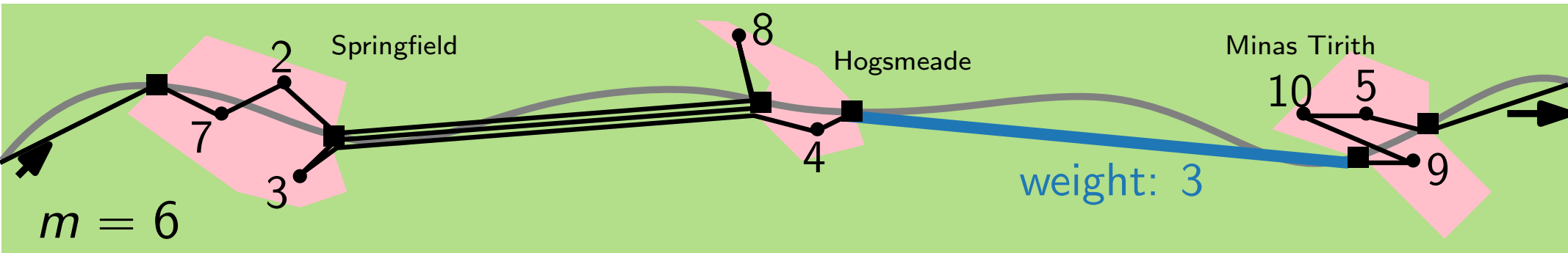
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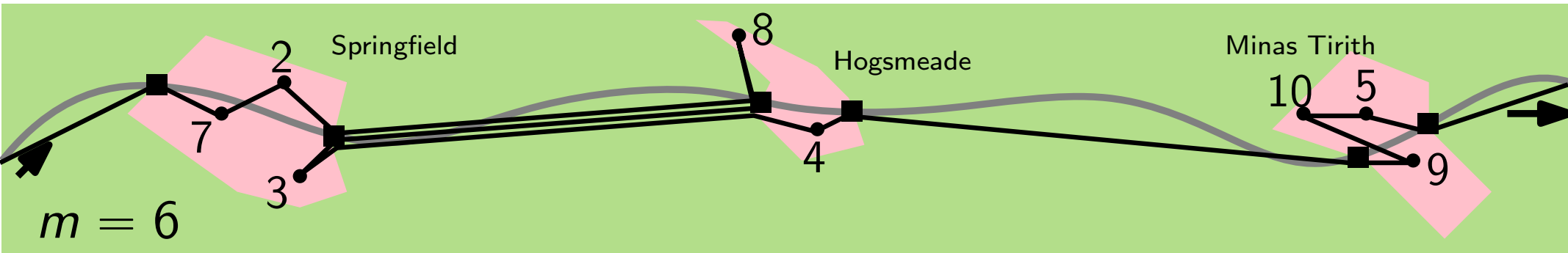
Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted. → Count atomic journeys!

Distribute Costs to Clusters

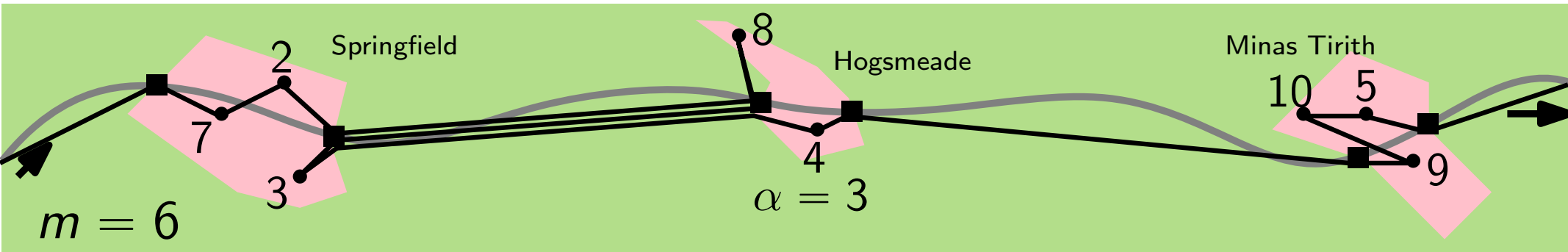
Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted. → Count atomic journeys!
Every cluster C_i has four counters:

Distribute Costs to Clusters

Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted. → Count atomic journeys!

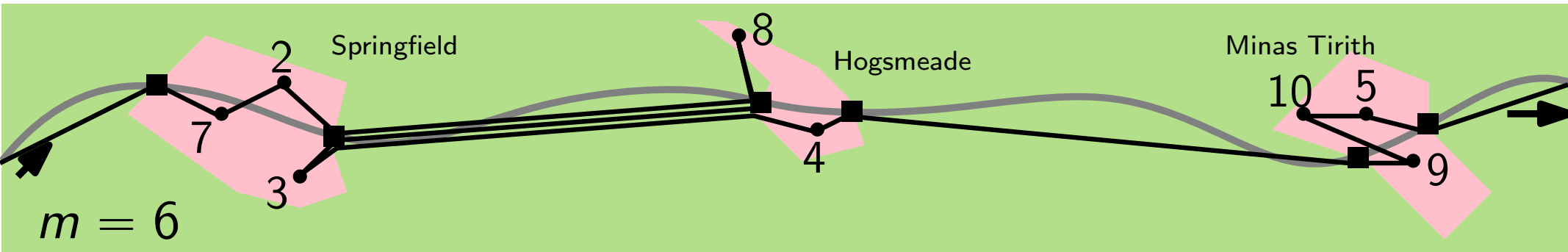
Every cluster C_i has four counters:

$\alpha := \#$ rightbound persons with $p_r \leq i$.

pickup cluster of r

Distribute Costs to Clusters

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Obs.: Edges of a tour are weighted. → Count atomic journeys!

Every cluster C_i has four counters:

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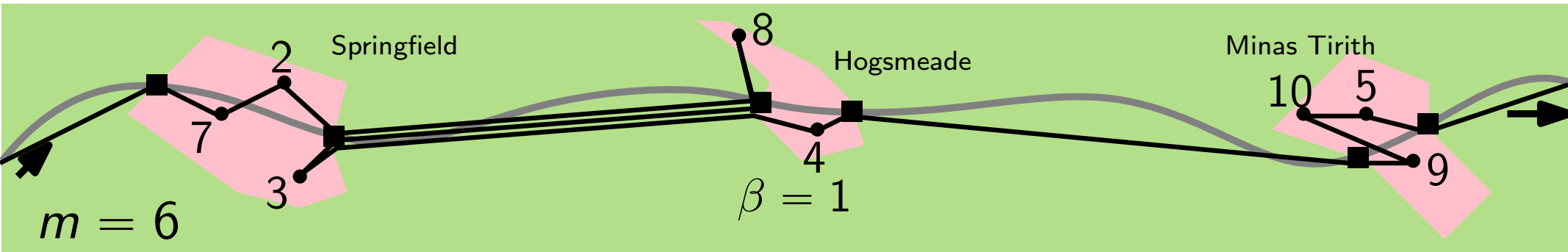
$\beta := \#$ leftbound persons with $d_r \geq i$.

pickup cluster of r

dropoff cluster of r

Distribute Costs to Clusters

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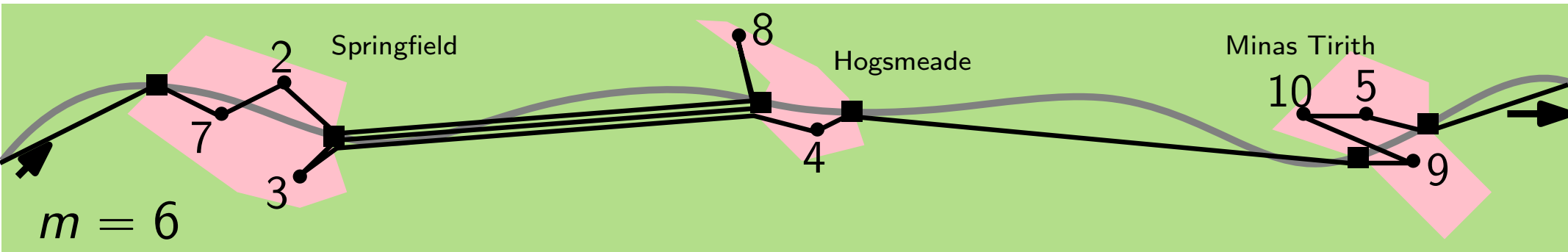
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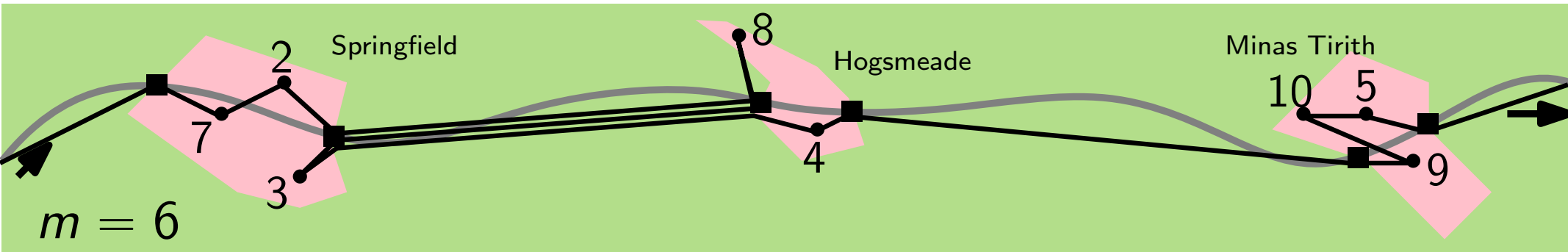
$\alpha := \#$ rightbound persons with $p_r \leq i$. pickup cluster of r

$\beta := \#$ leftbound persons with $d_r \geq i$. dropoff cluster of r

$\gamma := \#$ left-entering persons with $p_r \geq i$.

Distribute Costs to Clusters

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Every cluster C_i has four counters:

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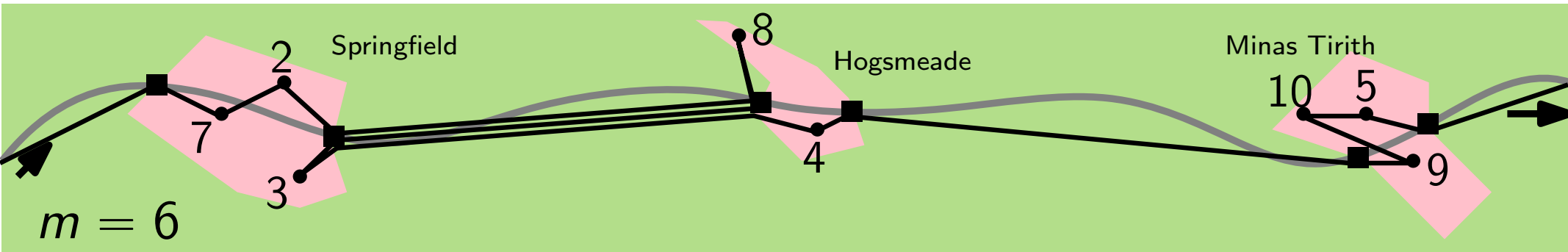
$\beta := \#$ leftbound persons with $d_r \geq i$. dropoff cluster of r

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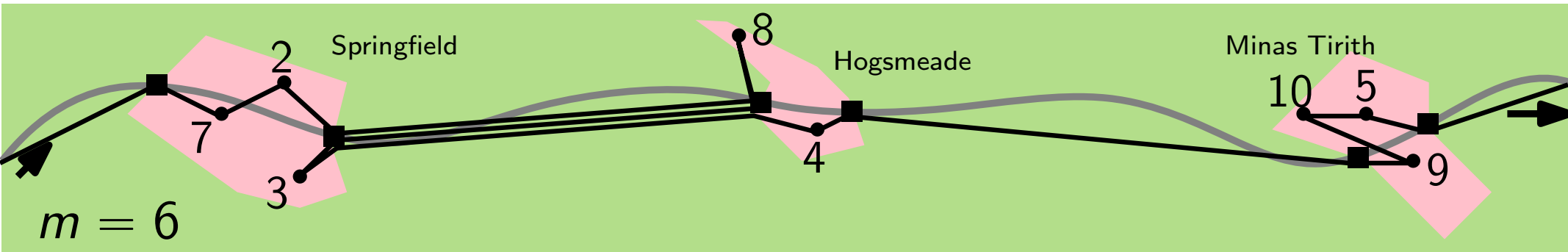
$\gamma := \#$ left-entering persons with $p_r \geq i$.

$\delta := \#$ right-entering persons with $d_r \leq i$.

$$\mathcal{Y}(T, C_i) = \text{in}(C_i)$$

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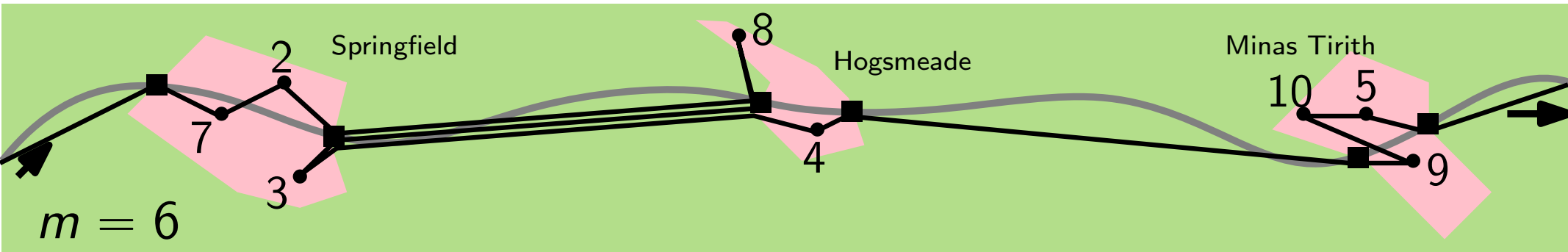
$\gamma := \#$ left-entering persons with $p_r \geq i$.

$\delta := \#$ right-entering persons with $d_r \leq i$.

$$\mathcal{Y}(T, C_i) = \text{in}(C_i) + \overline{\alpha C_i C_{i+1}}$$

Distribute Costs to Clusters

Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted. → Count atomic journeys!

Every cluster C_i has four counters:

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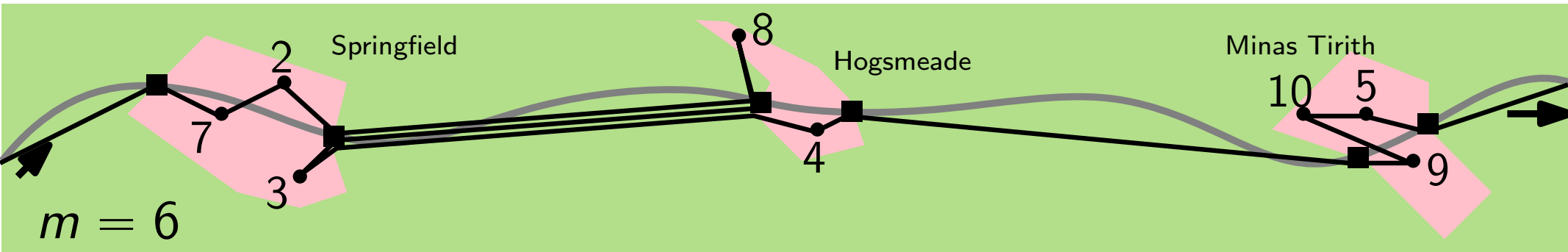
$\gamma := \#$ left-entering persons with $p_r \geq i$.

$\delta := \#$ right-entering persons with $d_r \leq i$.

$$\mathcal{R}(T, C_i) = \text{in}(C_i) + \alpha \overline{C_i C_{i+1}} + \beta \overline{C_i C_{i-1}}$$

Distribute Costs to Clusters

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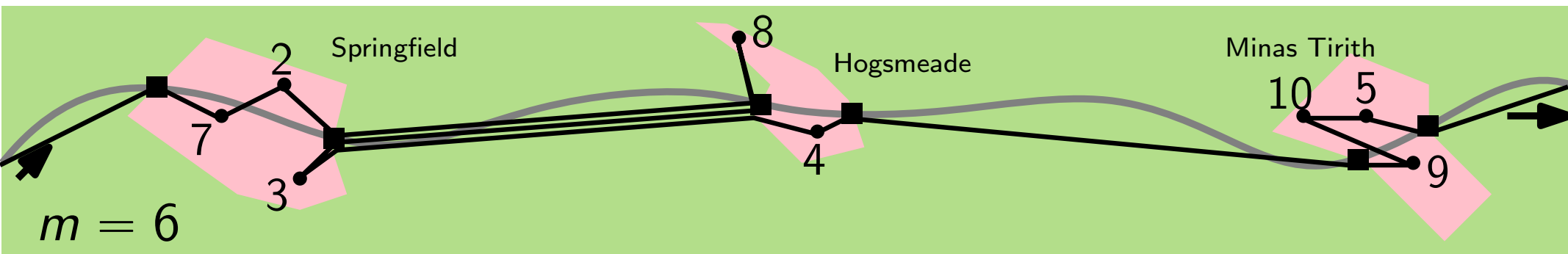
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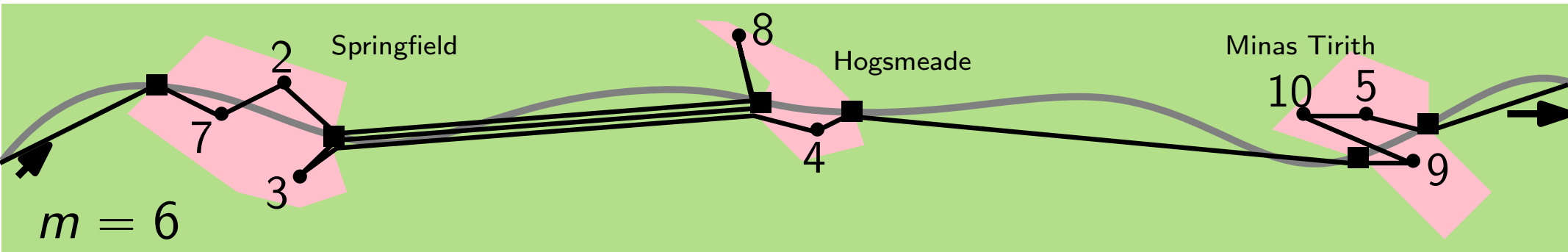
$\delta := \#$ right-entering persons with $d_r \leq i$.

$$\Upsilon(T, C_i) = \text{in}(C_i) + \alpha \overline{C_i C_{i+1}} + \beta \overline{C_i C_{i-1}} + \gamma \overline{C_{i-1} C_i} + \delta \overline{C_{i+1} C_i}$$

See thesis for proof of
 $c(T) = \sum \Upsilon(T, C_i)$.

Distribute Costs to Clusters

Assign the parts of a tour to clusters.



Obs.: Edges of a tour are weighted. → Count atomic journeys!

Every cluster C_i has four counters:

$\alpha := \#$ rightbound persons with $p_r \leq i$.

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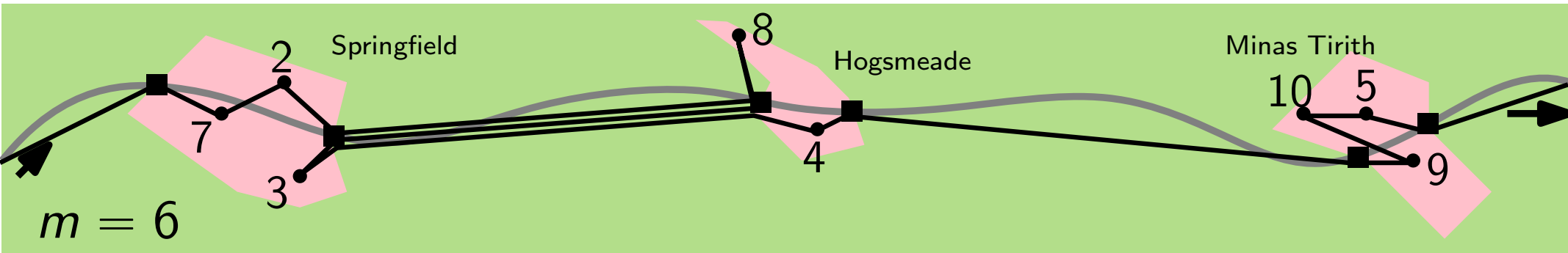
$\delta := \#$ right-entering persons with $d_r \leq i$.

See thesis for proof of
 $c(T) = \sum \gamma(T, C_i)$.

$$\gamma(T, C_i) = \text{in}(C_i) + \alpha \overline{C_i C_{i+1}} + \beta \overline{C_i C_{i-1}} + \gamma \overline{C_{i-1} C_i} + \delta \overline{C_{i+1} C_i}$$

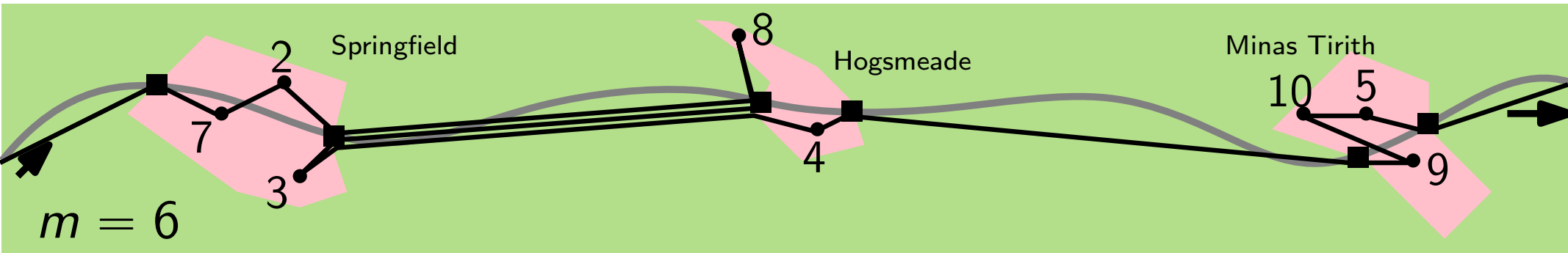
Todo: $\Phi(C_i) \leq \gamma(T^*, C_i)$

Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)



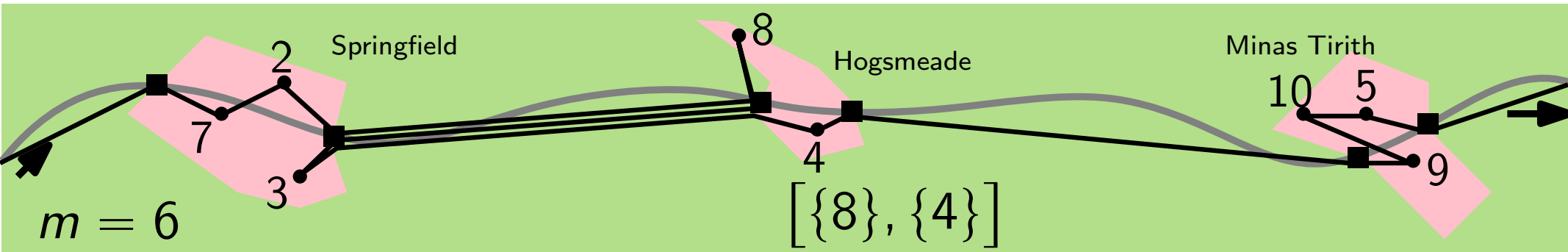
Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)

Idea: Any T induces an ordered partition on every cluster.



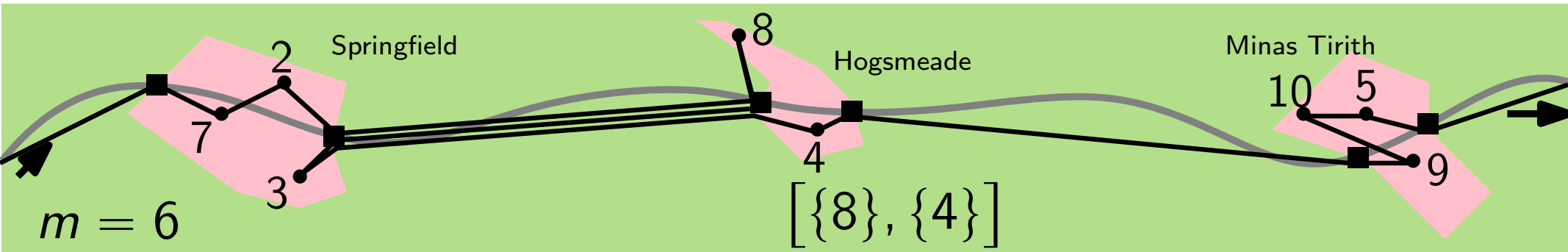
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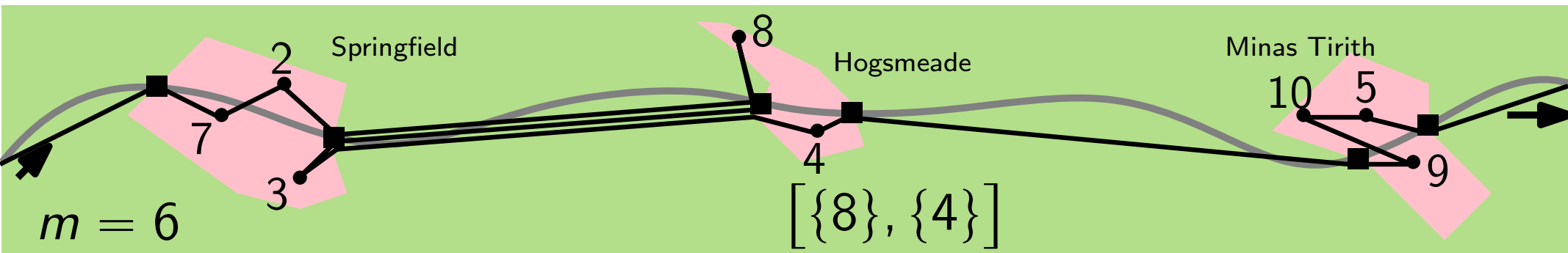
Idea: Any T induces an ordered partition on every cluster.



Other Possibilities?

Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)

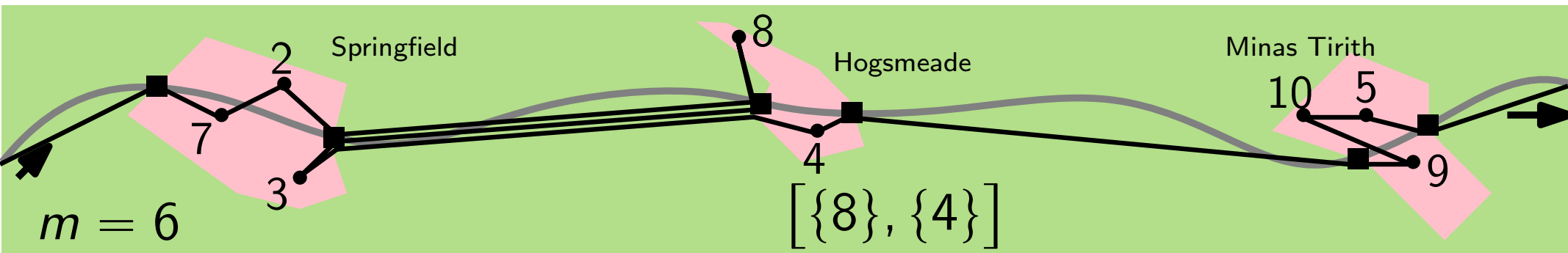
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Other Possibilities? $\mathcal{S} = [\{4\}, \{8\}]$ $\mathcal{S} = [\{4, 8\}]$

Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)

Idea: Any T induces an ordered partition on every cluster.

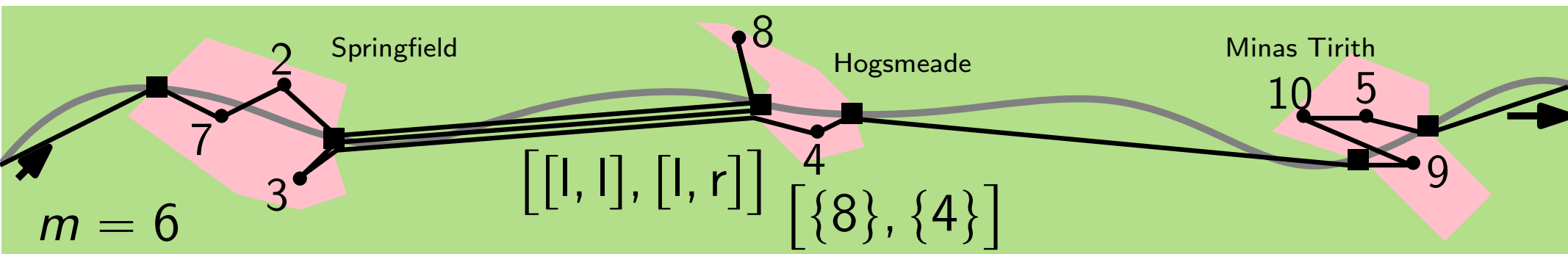


Other Possibilities? $\mathcal{S} = [\{4\}, \{8\}]$ $\mathcal{S} = [\{4, 8\}]$

Additionally: List of Portals P .

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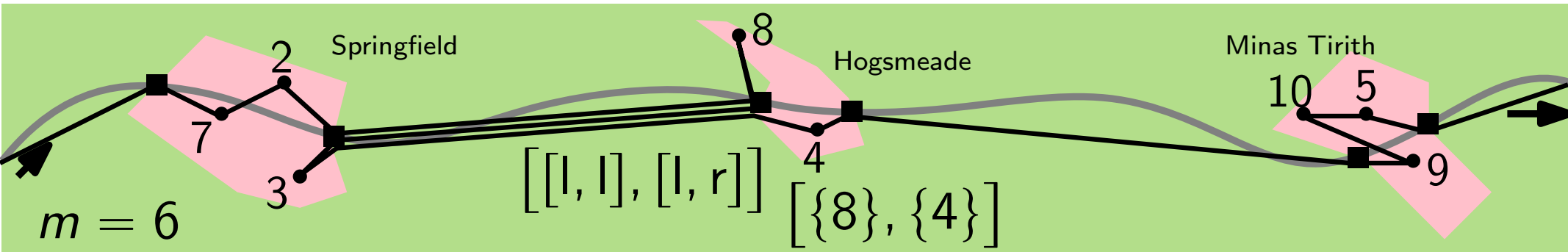


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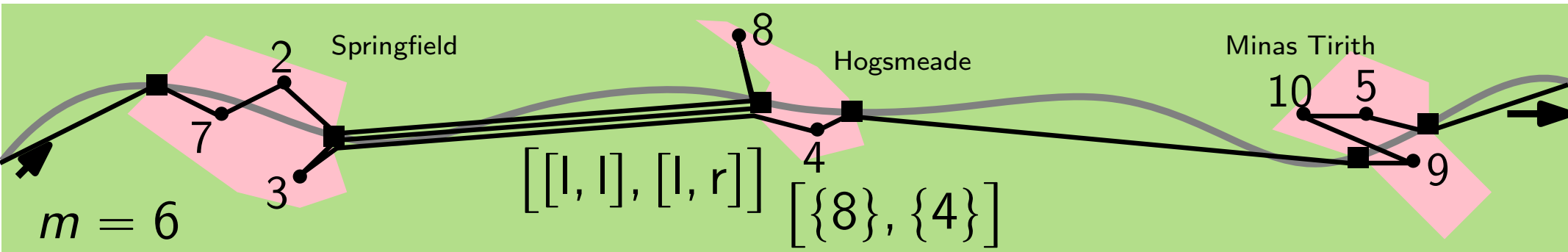
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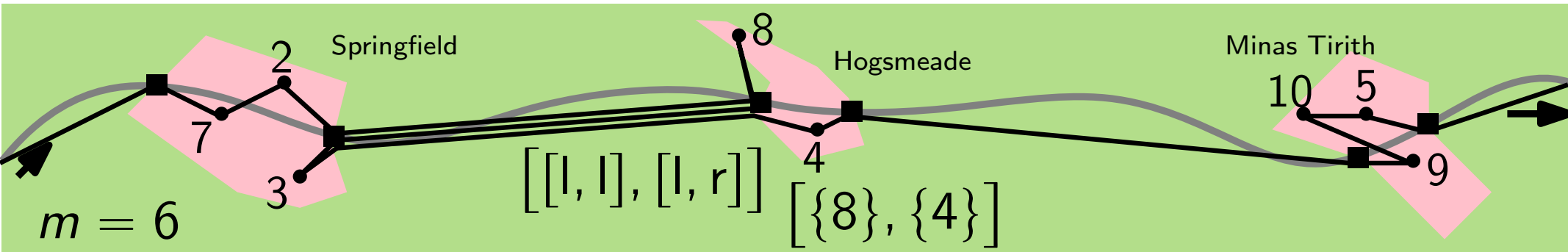
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Solve internal tours.

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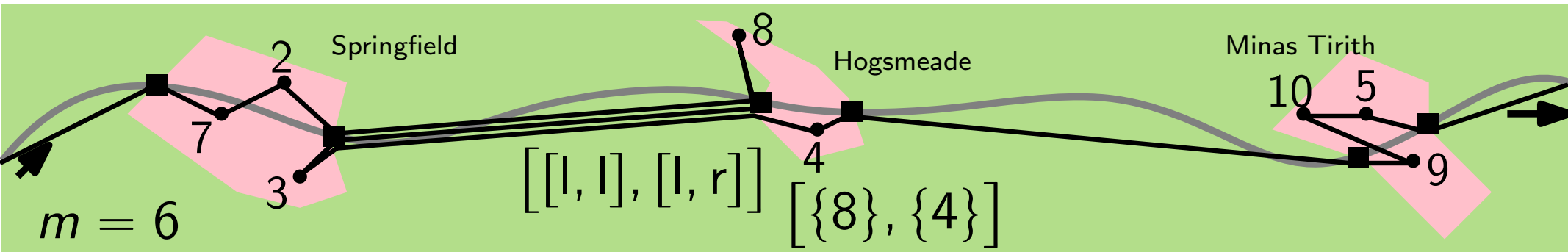
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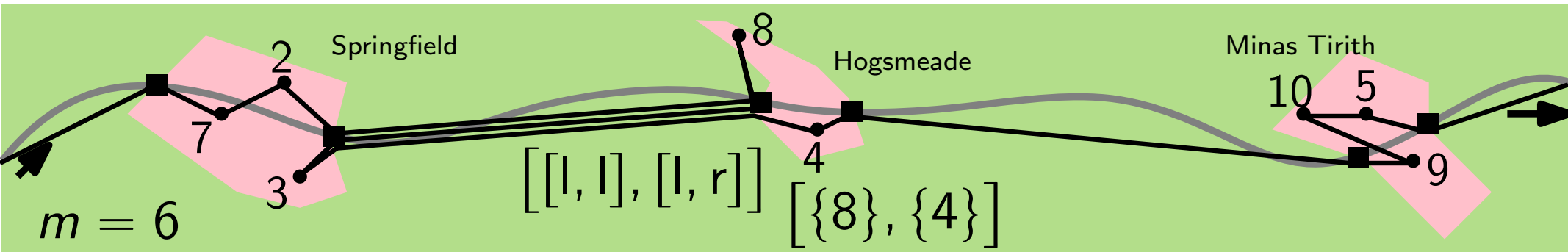
Solve internal tours.

Compute lower bounds for α, β, γ and δ .

Add costs up and obtain lower bound $\Phi_{\mathcal{S}, P}(C_i)$.

Lower Bound on $\Upsilon(T^*, C_i)$ (Sketch)

Idea: Any T induces an ordered partition on every cluster.



Other Possibilities? $\mathcal{S} = [\{4\}, \{8\}]$ $\mathcal{S} = [\{4, 8\}]$

Additionally: List of Portals P .

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Solve internal tours.

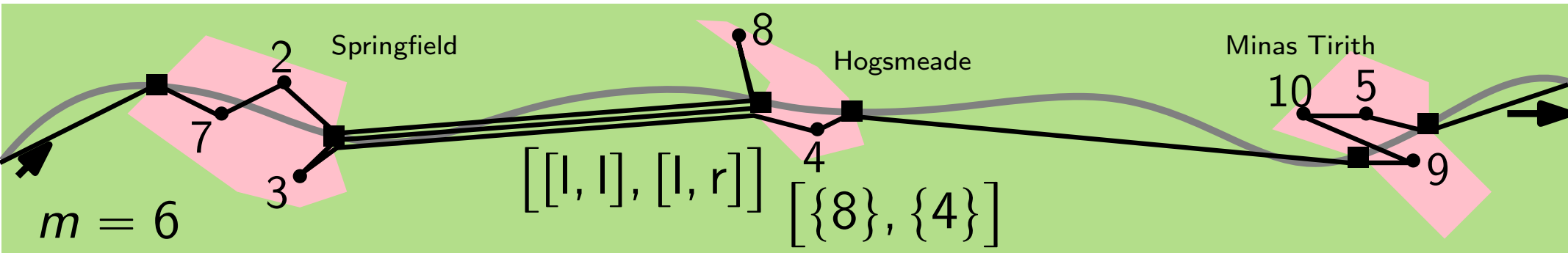
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Add costs up and obtain lower bound $\Phi_{\mathcal{S}, P}(C_i)$.

$\Rightarrow \min \Phi(C_i)_{\mathcal{S}, P} = \Phi(C_i) \leq \Upsilon(T^*, C_i)$

Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)

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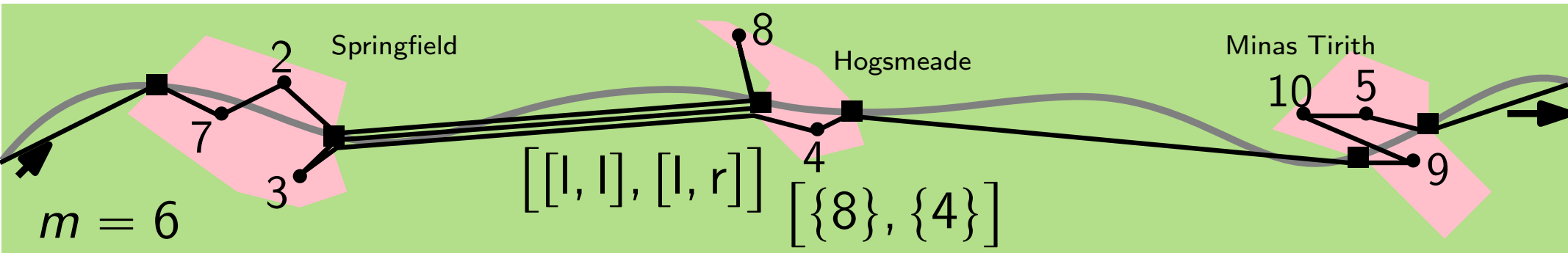
Add costs up and obtain lower bound $\Phi_{\mathcal{S}, P}(C_i)$.

$$\Rightarrow \min \Phi(C_i)_{\mathcal{S}, P} = \Phi(C_i) \leq \mathcal{R}(T^*, C_i)$$

$|C_i| = 6$:
5 227 236 choices

Lower Bound on $\mathcal{R}(T^*, C_i)$ (Sketch)

Idea: Any T induces an ordered partition on every cluster.



Other Possibilities? $\mathcal{S} = [\{4\}, \{8\}]$ $\mathcal{S} = [\{4, 8\}]$

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$|C_i| = 6:$
5 227 236 choices
Practical Limit!

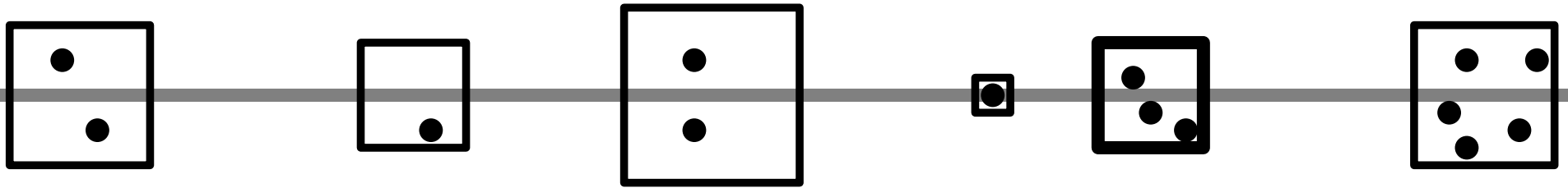
Evaluation

Evaluation

→ First artificial instances, then realistic instances.

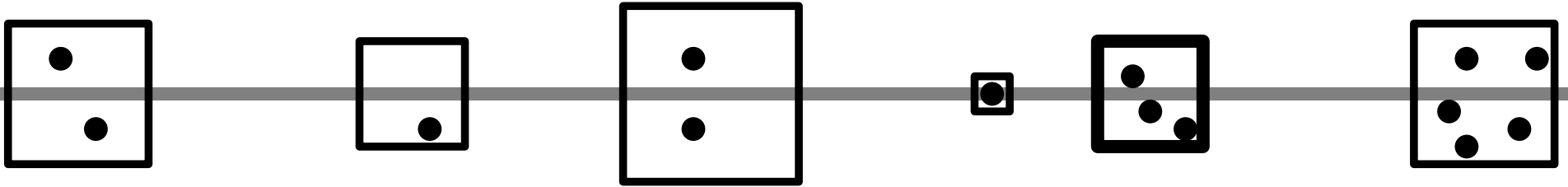
Evaluation

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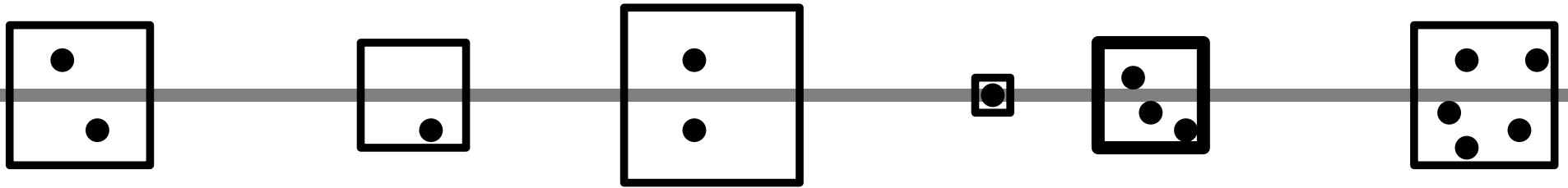
Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Evaluation

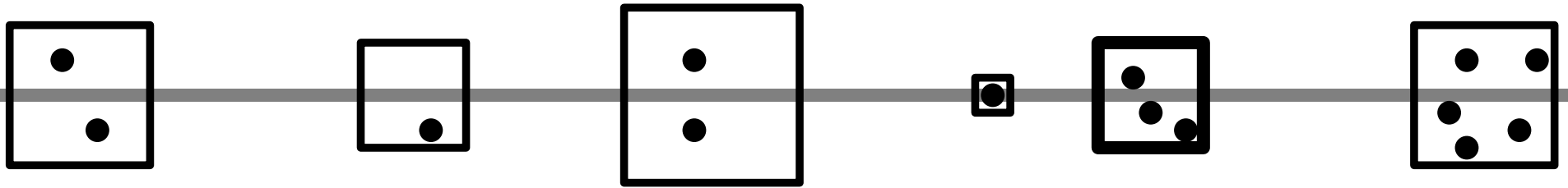
for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

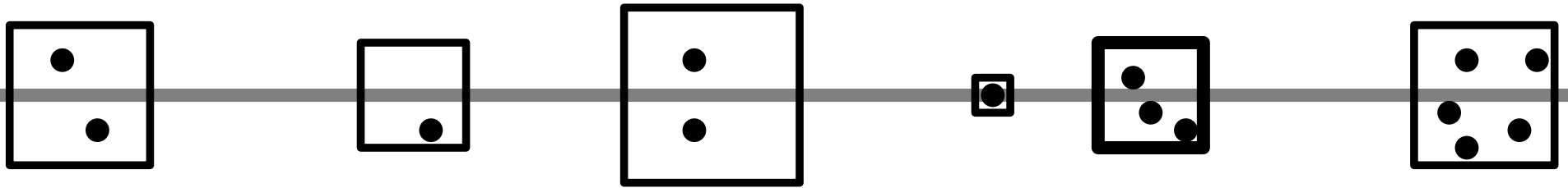
Exact: 120 s

$\overrightarrow{T^*}$ -Algorithm: 3 ms

Classifier: 4 s

Evaluation

→ First artificial instances, then realistic instances.
for $n = 12$



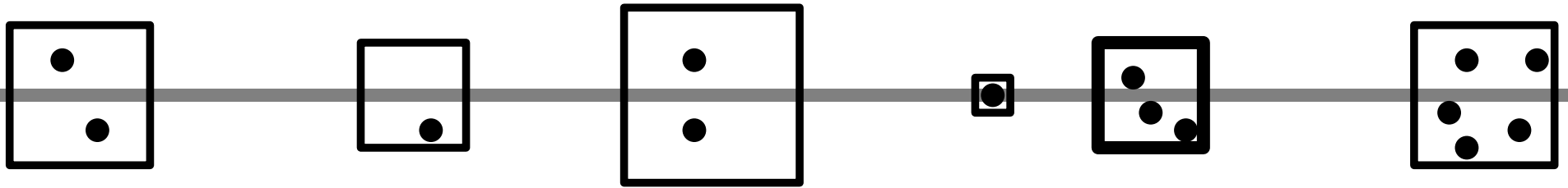
Runtimes:

Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

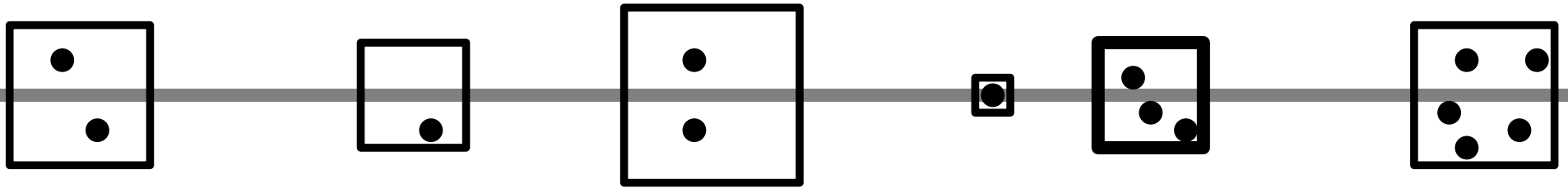
Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

$$\text{Ratio } T^* = \overrightarrow{T^*}$$

Evaluation

→ First artificial instances, then realistic instances.
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Runtimes:

Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

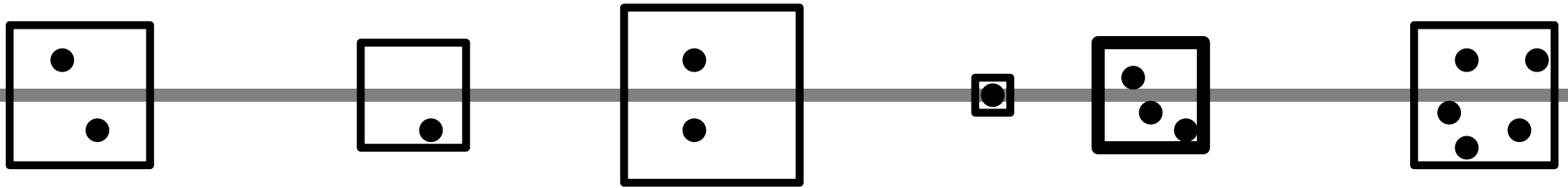
Classifier's Accuracy:

$$\text{Ratio } T^* = \overrightarrow{T^*}$$

Clusters close together ($\sim 6\text{km}$): 59 %

Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

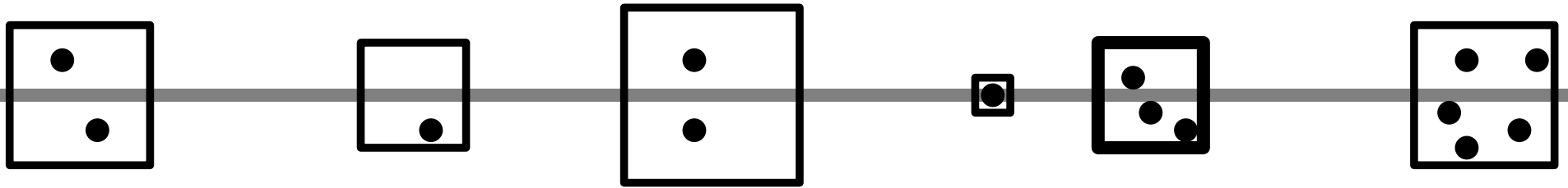
Classifier's Accuracy:

$$\text{Ratio } T^* = \overrightarrow{T^*}$$

Clusters close together ($\sim 6\text{km}$):	59 %
far apart ($\geq 16\text{ km}$):	100 %

Evaluation

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for $n = 12$



Runtimes:

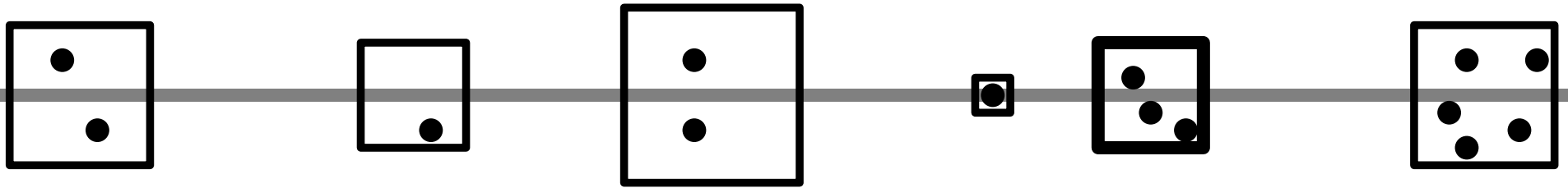
Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

	Ratio $T^* = \overrightarrow{T^*}$	Recall
Clusters close together (~ 6 km):	59 %	
far apart (≥ 16 km):	100 %	

Evaluation

→ First artificial instances, then realistic instances.
for $n = 12$



Runtimes:

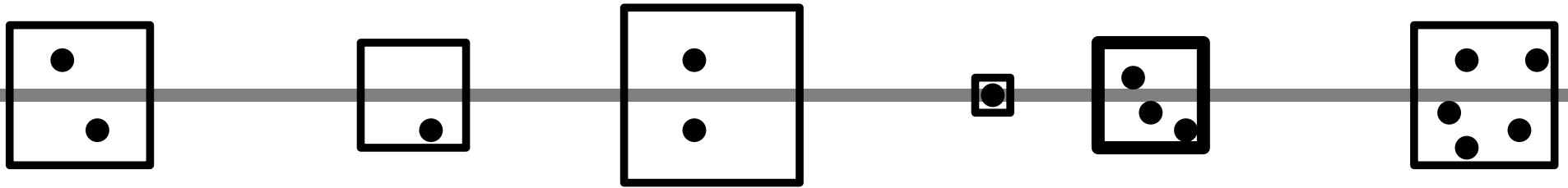
Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

	Ratio $T^* = \overrightarrow{T^*}$	Recall
Clusters close together (~ 6 km):	59 %	0.4
far apart (≥ 16 km):	100 %	

Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

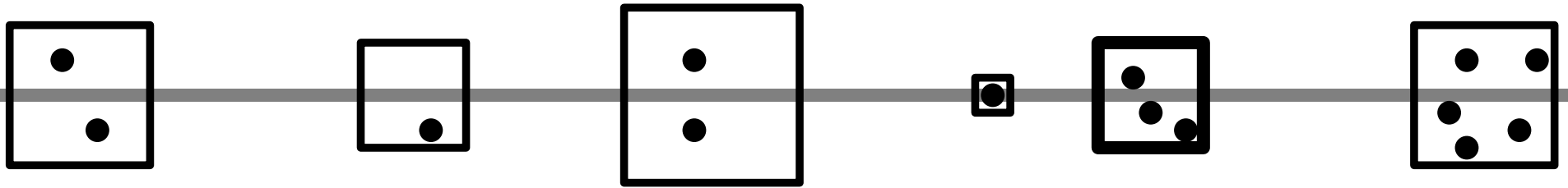
Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

	Ratio $T^* = \overrightarrow{T^*}$	Recall
Clusters close together (~ 6 km):	59 %	0.4
far apart (≥ 16 km):	100 %	0.9

Evaluation

→ First artificial instances, then realistic instances.
for $n = 12$



Runtimes:

Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

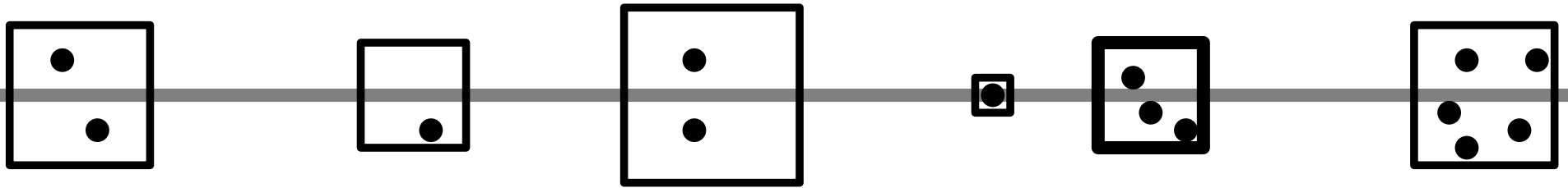
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far apart (≥ 16 km):	100 %	0.9

$\overrightarrow{T^*}$ -Algorithm as Heuristic:

Evaluation

for $n = 12$
→ First artificial instances, then realistic instances.



Runtimes:

Exact: 120 s $\overrightarrow{T^*}$ -Algorithm: 3 ms **Classifier:** 4 s

Classifier's Accuracy:

	Ratio $T^* = \overrightarrow{T^*}$	Recall
Clusters close together (~ 6 km):	59 %	0.4
far apart (≥ 16 km):	100 %	0.9

$\overrightarrow{T^*}$ -Algorithm as Heuristic:

Approximation Quality (empiric): ≤ 1.1

Topology of Street Networks

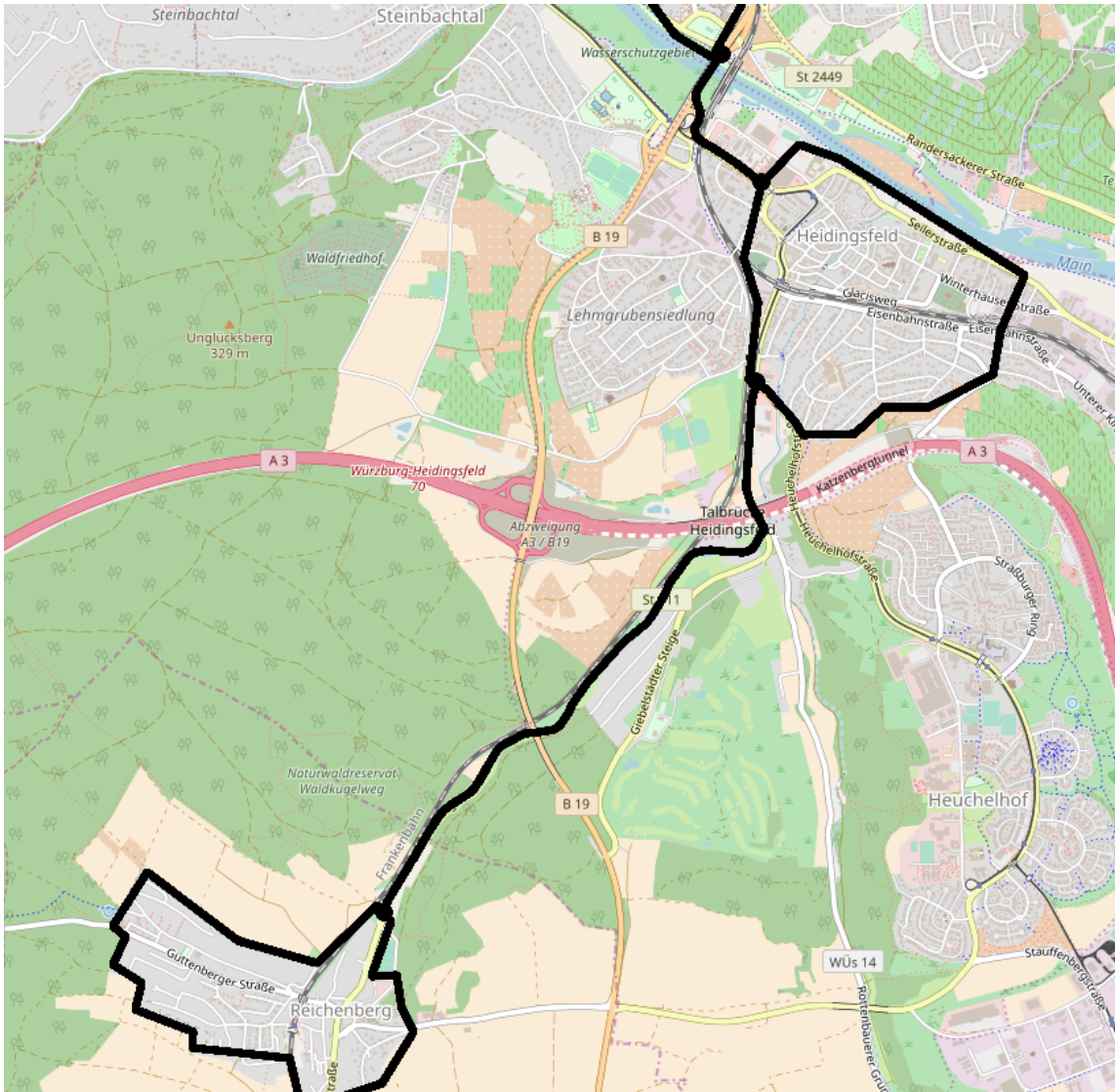
Topology of Street Networks

Street Networks often do not meet the assumptions.

Topology of Street Networks

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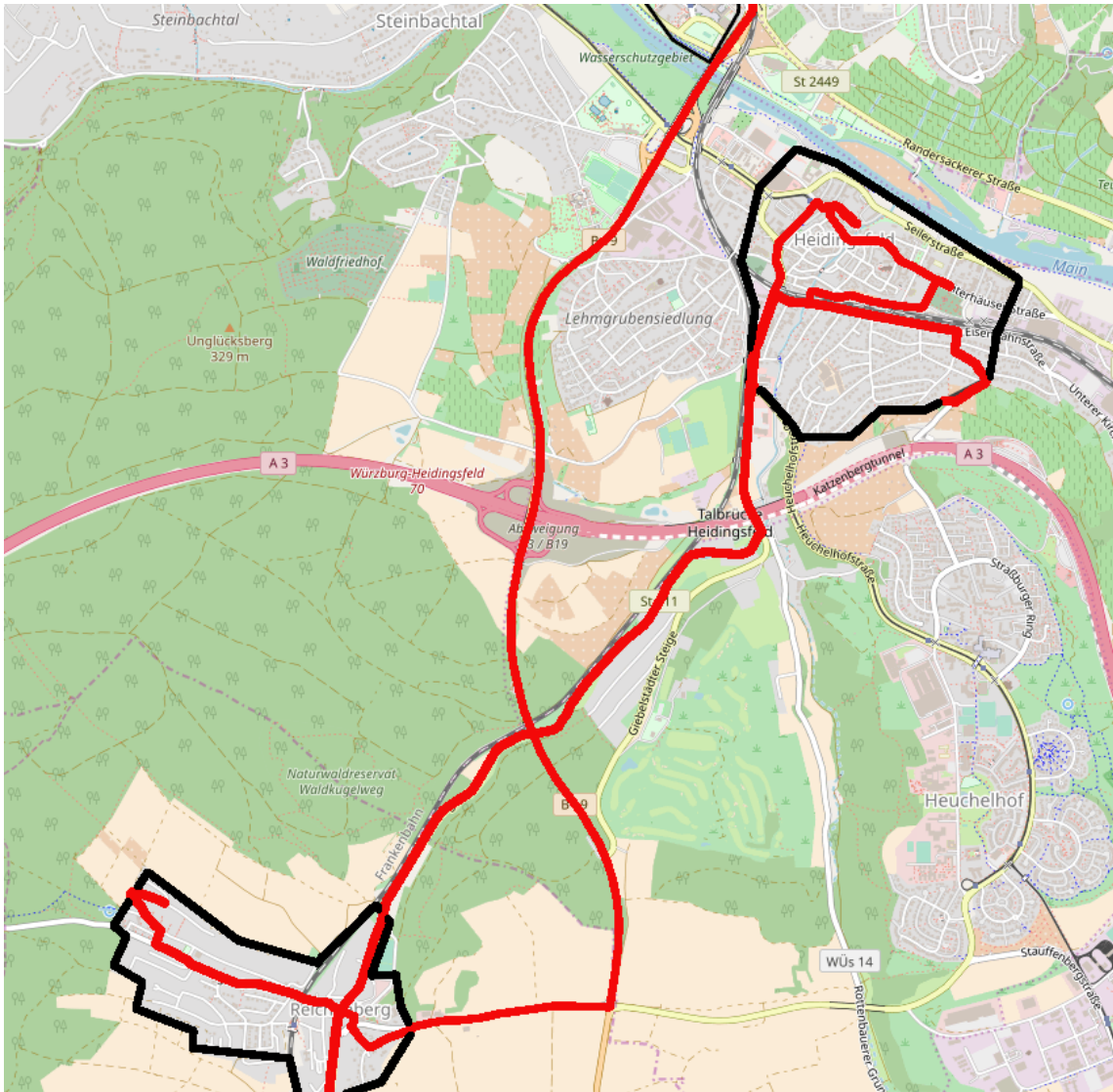
Example #1:
Rural Instance



Topology of Street Networks

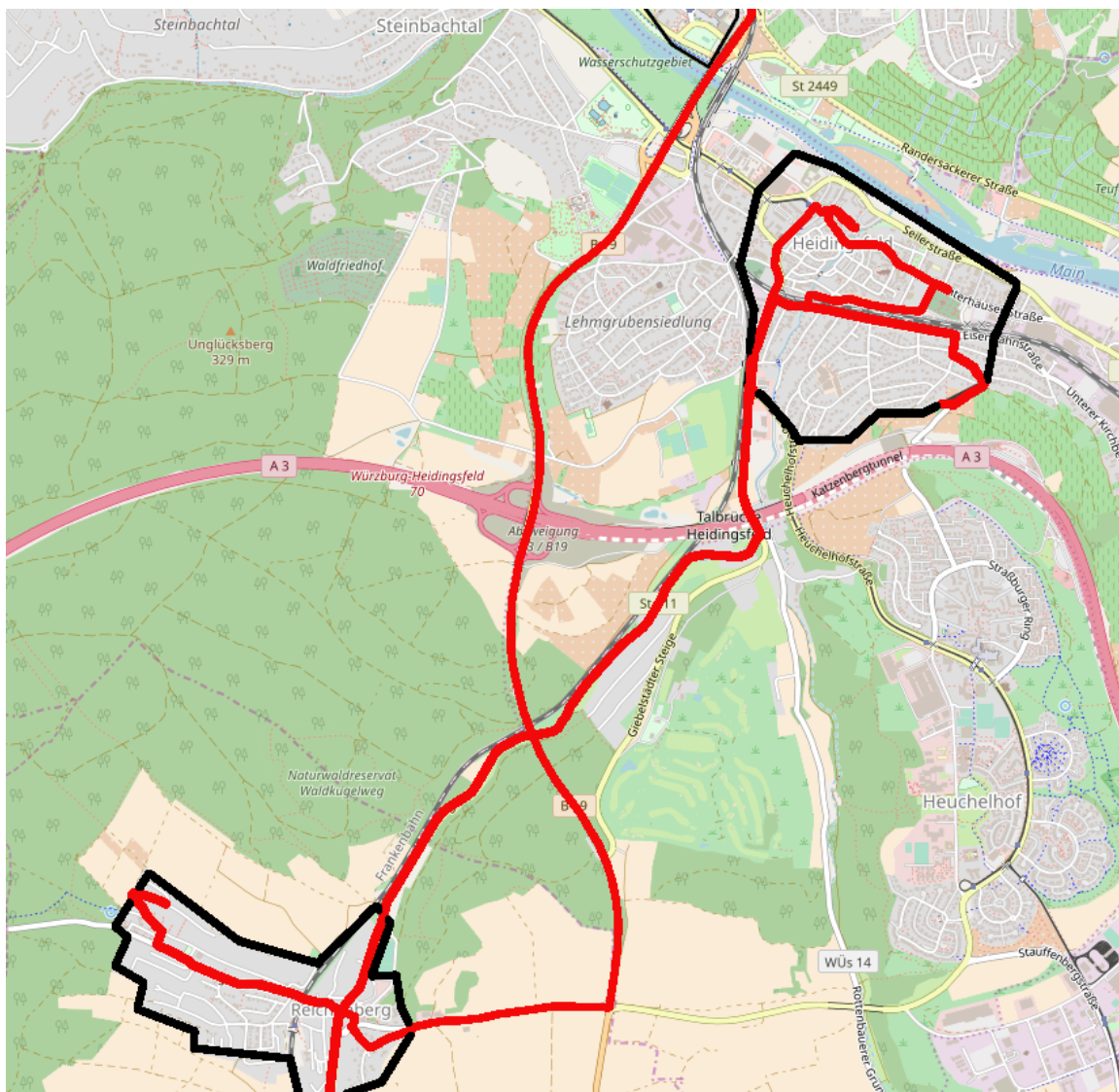
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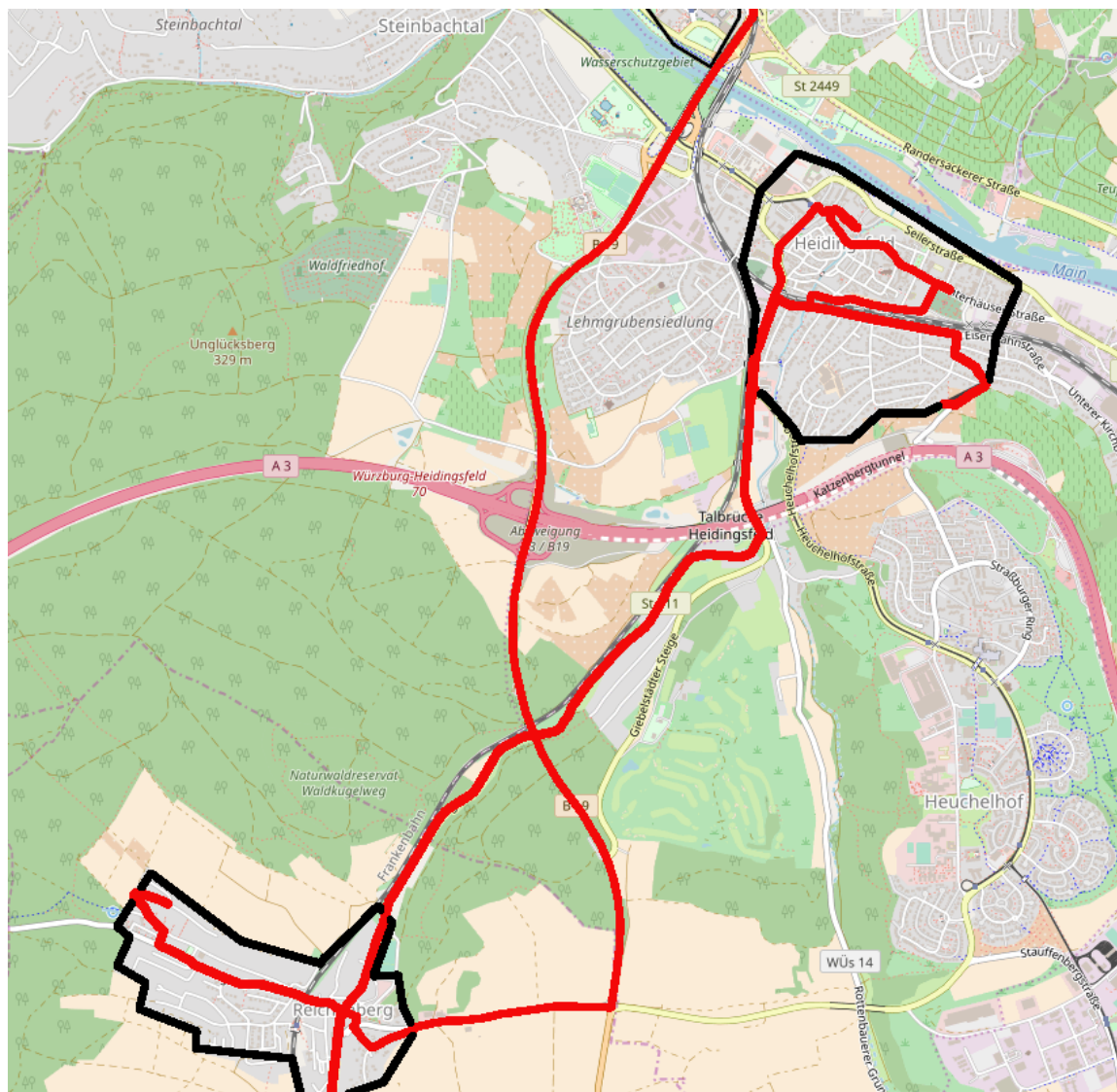


Example #1:
Rural Instance

T^* bypasses a cluster!

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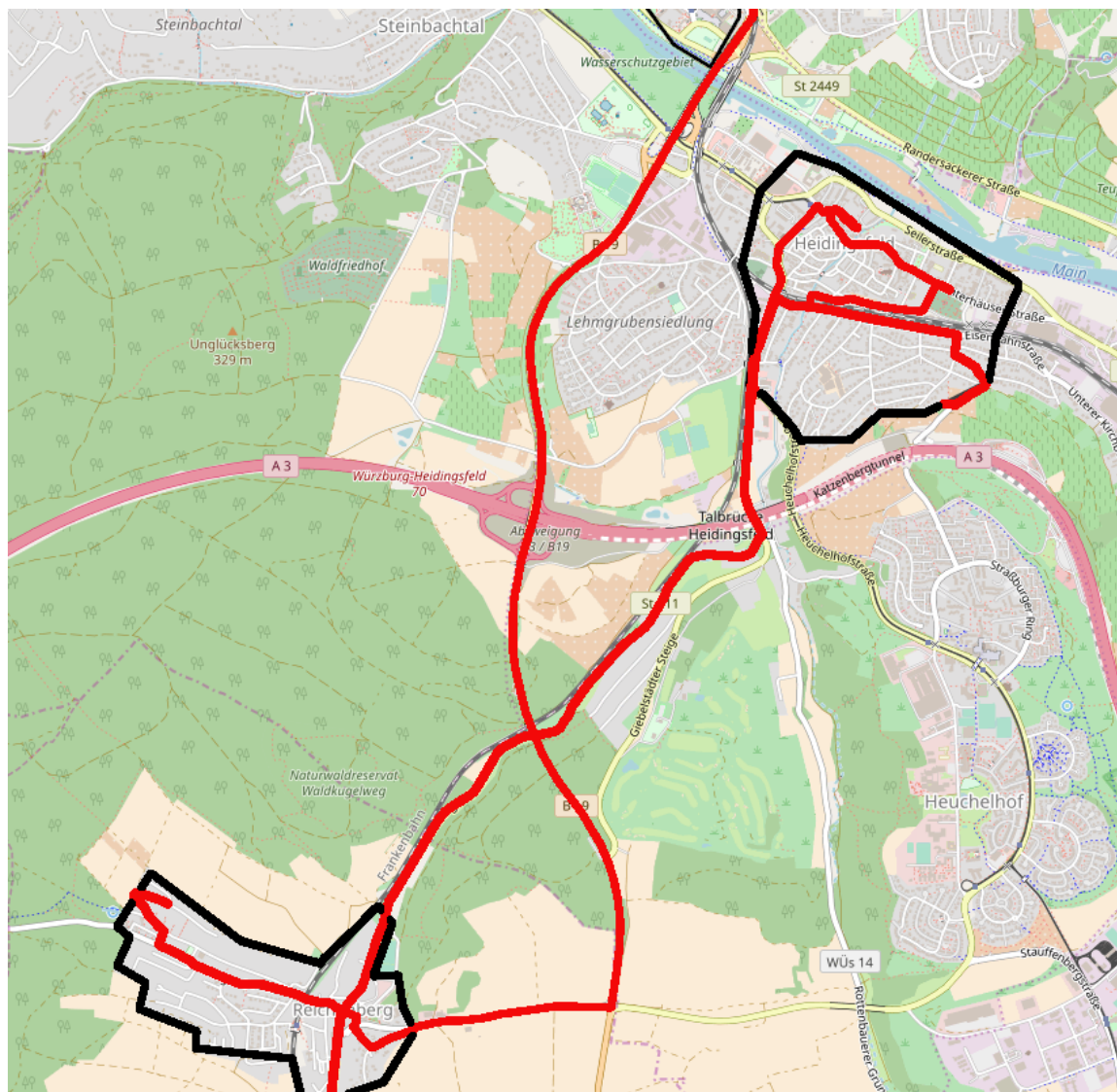
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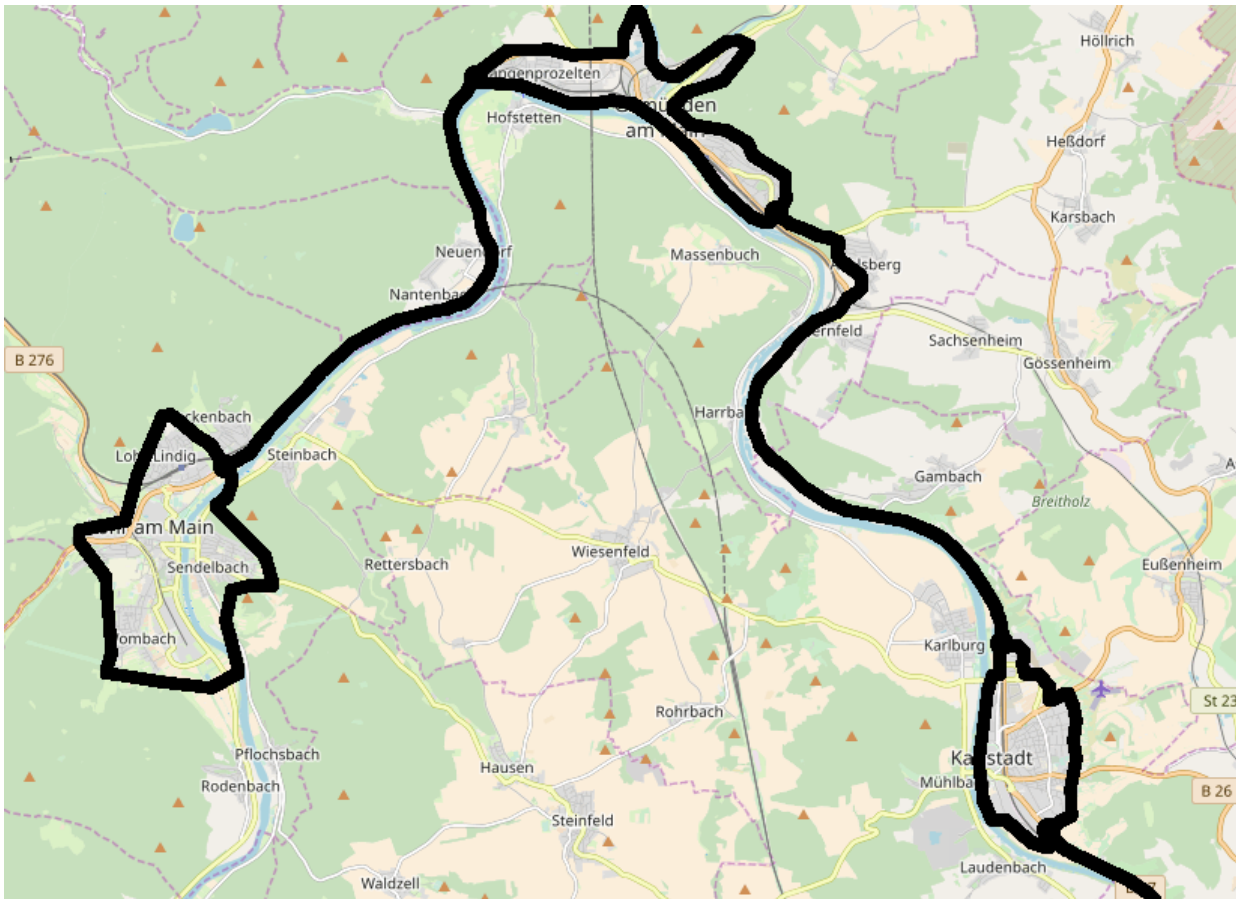
Yet, no false positive.

⇒ Classifier is robust to
some extent.

Topology of Street Networks

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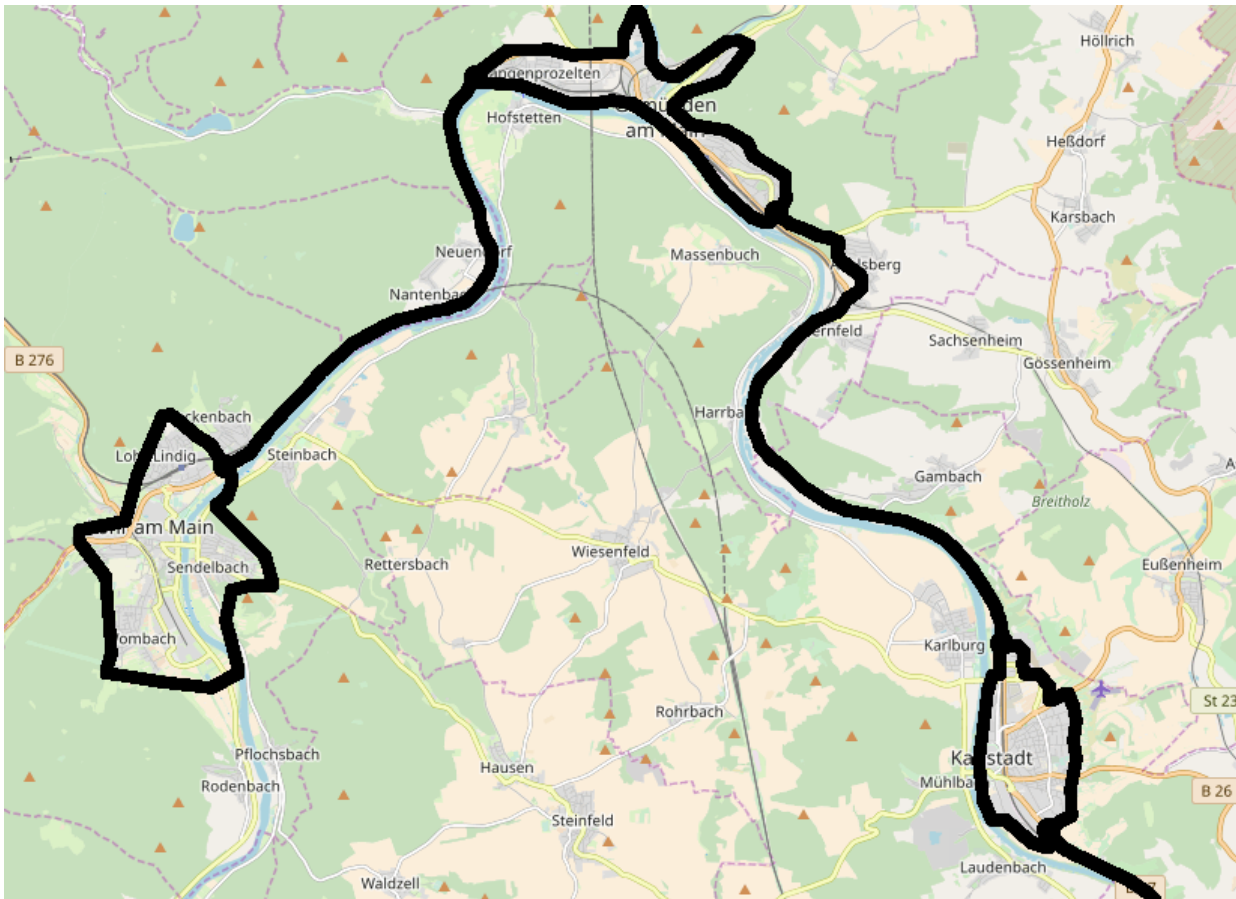
Example #2:
Regional Instance



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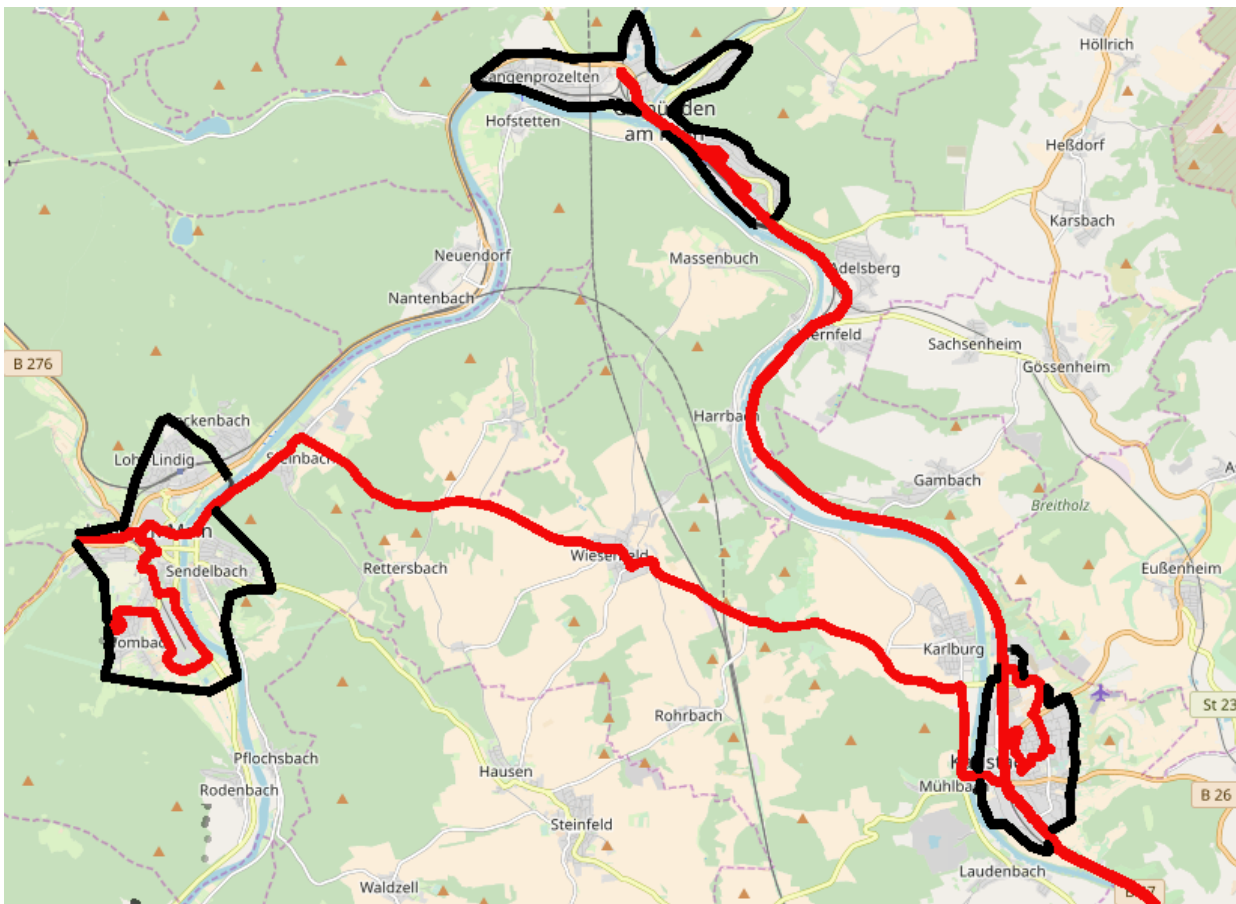
Example #2:
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Really hard scenario . . .



Topology of Street Networks

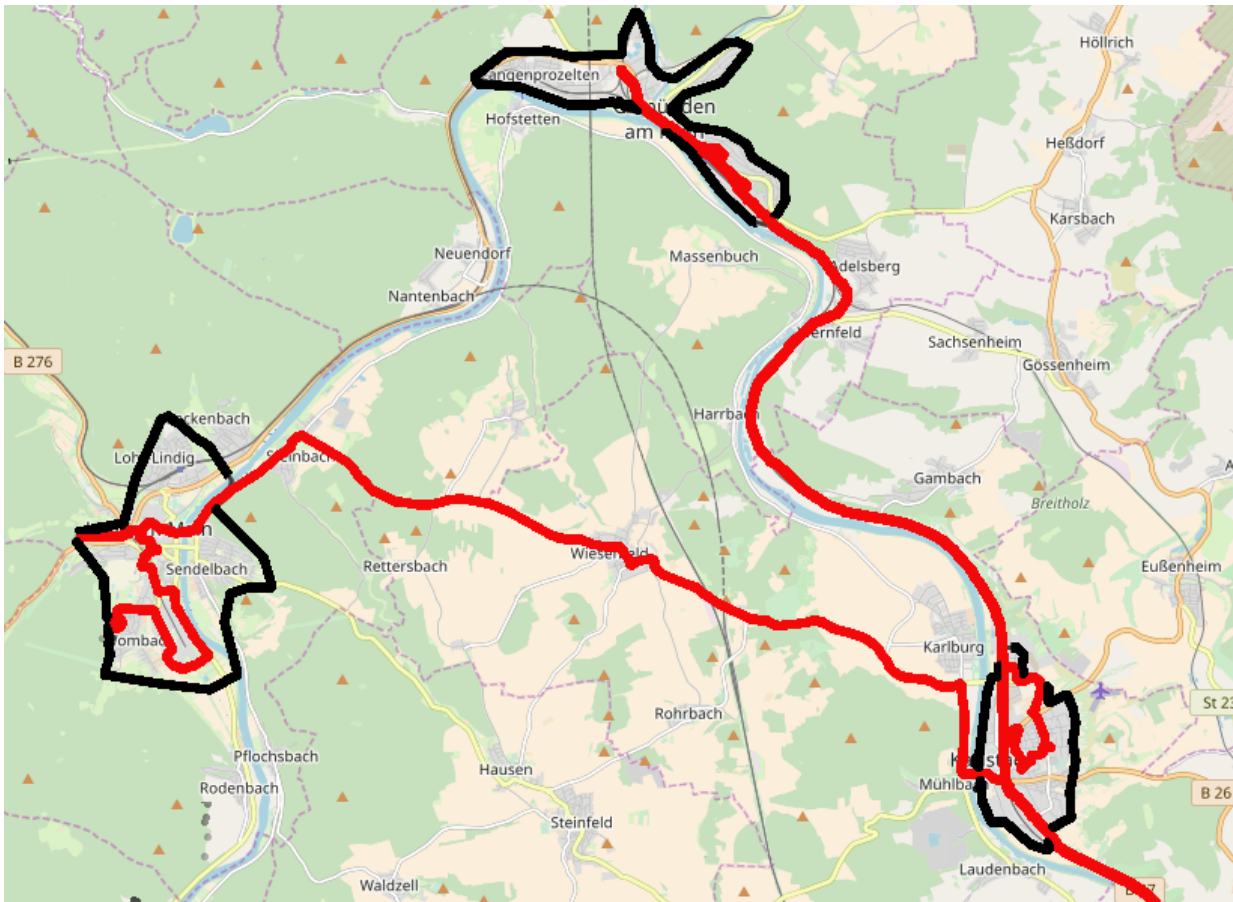
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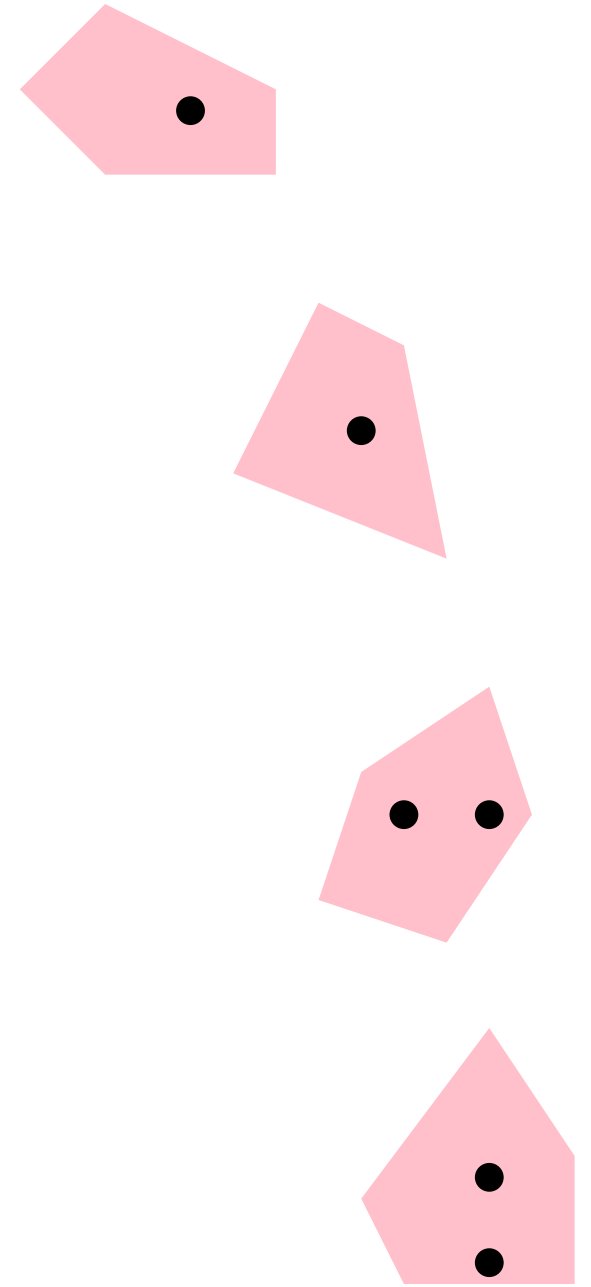


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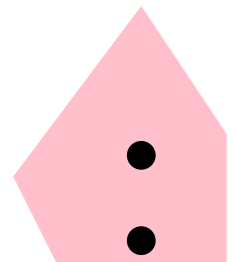
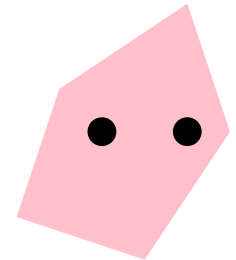
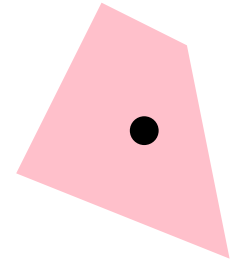
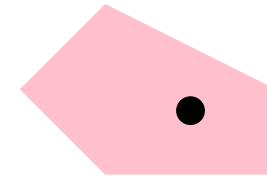
False positives are to be
expected in this case.

Conclusion



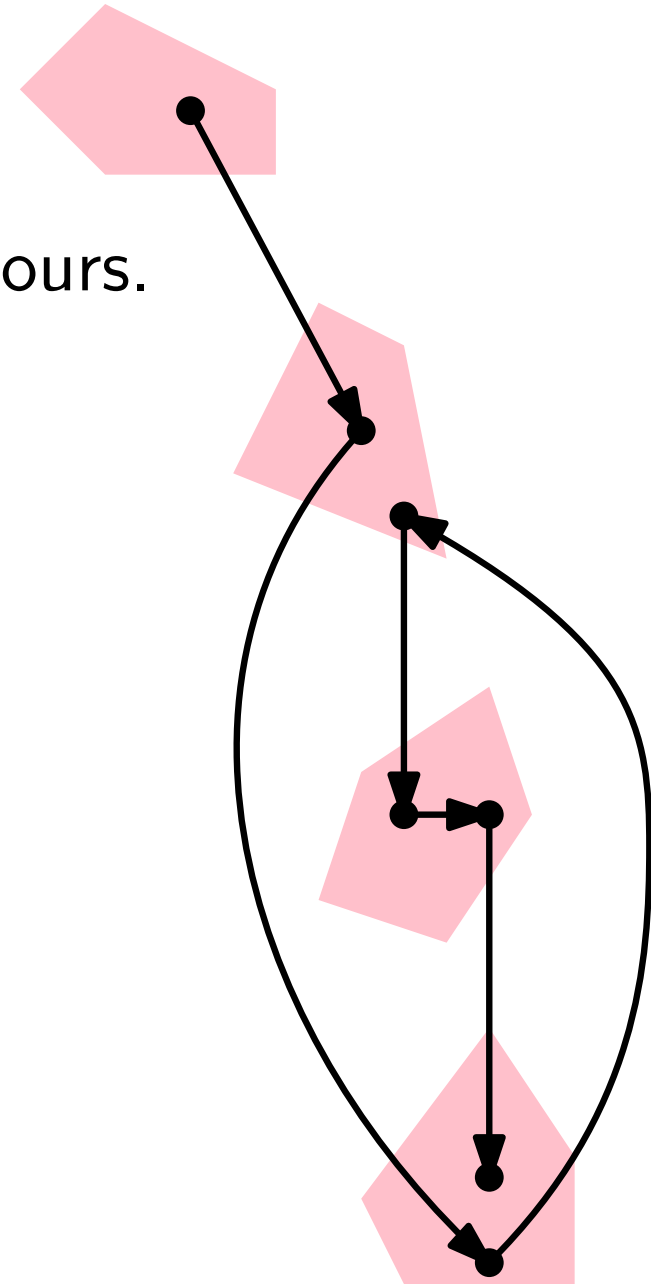
Conclusion

The Exact Algorithm considers unsensible tours.



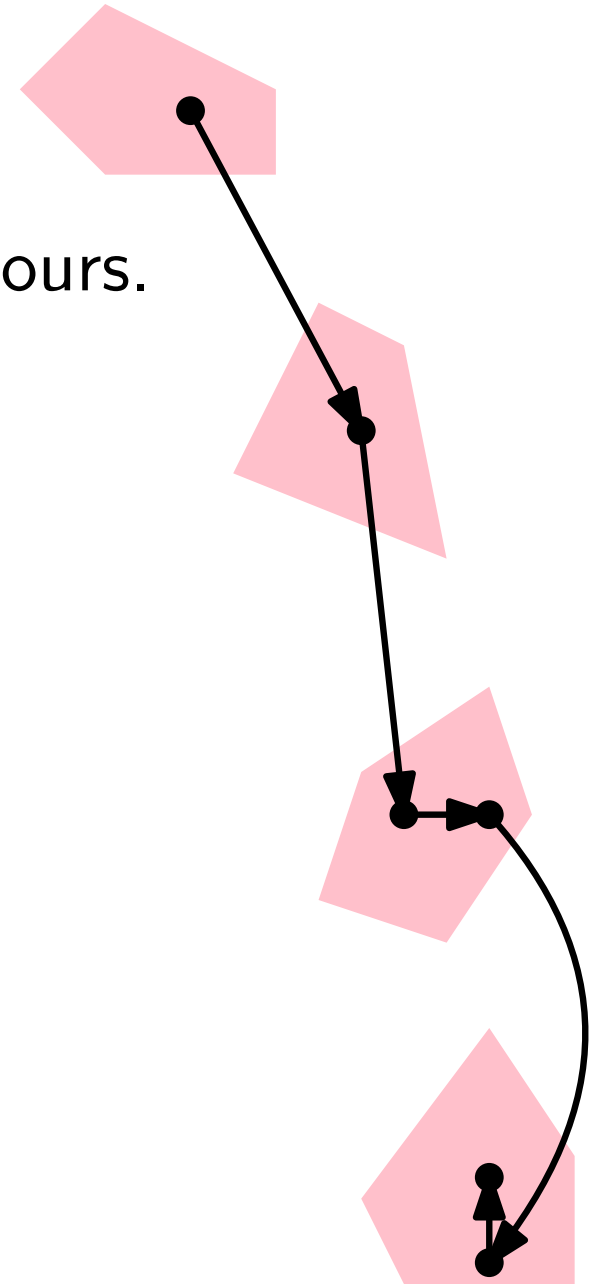
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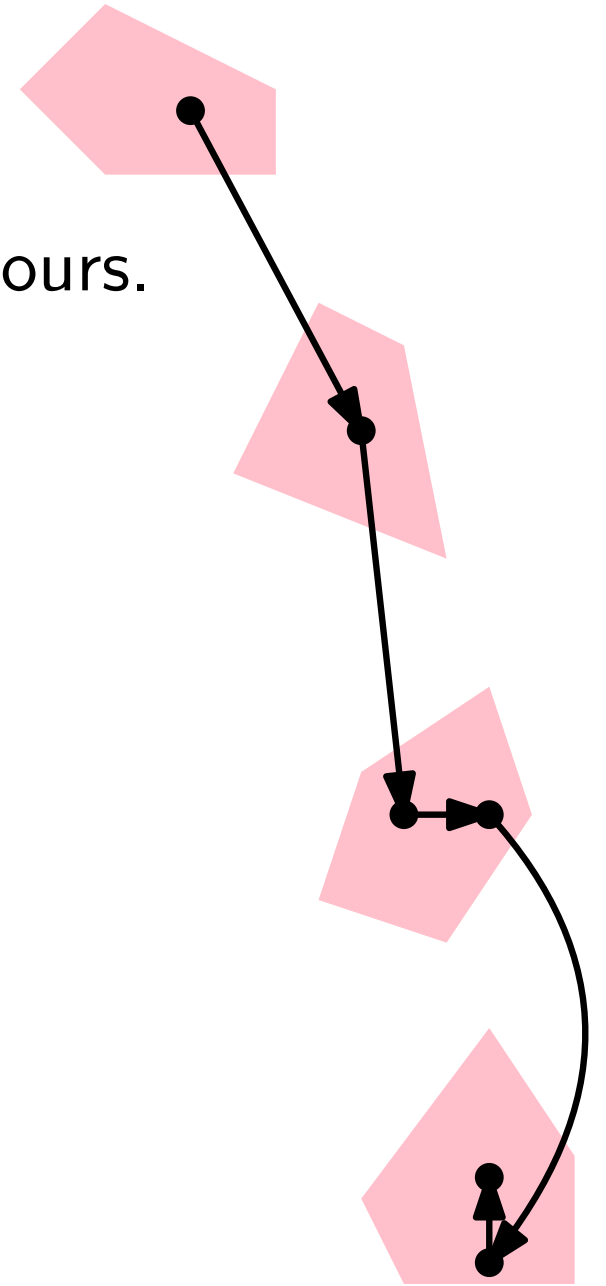
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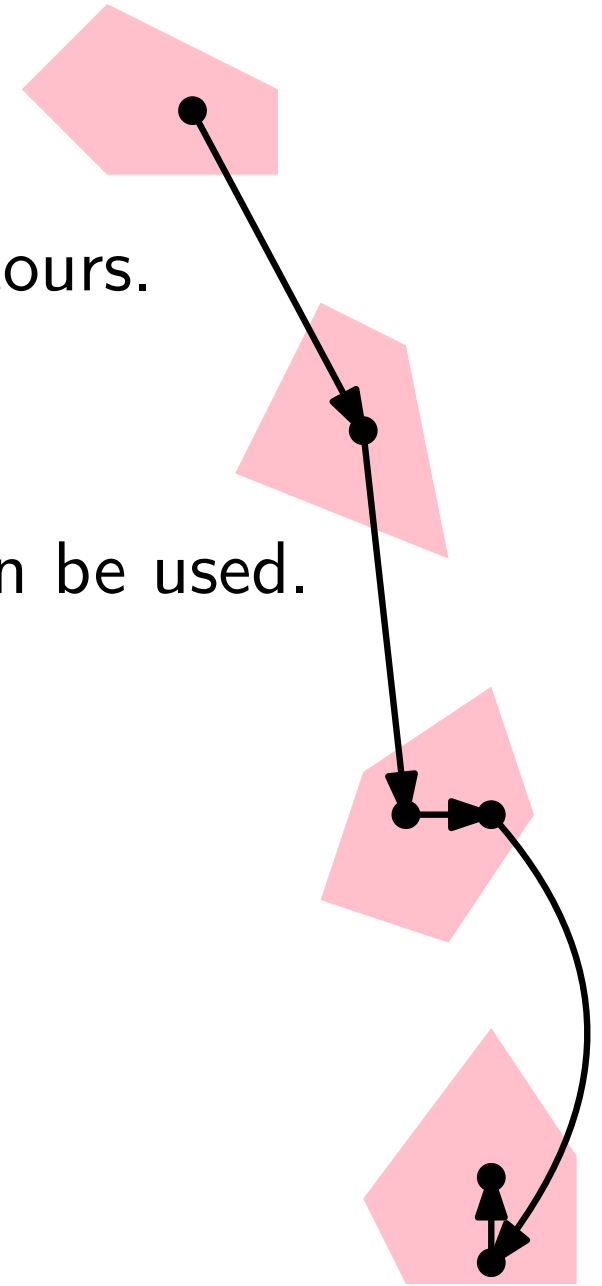


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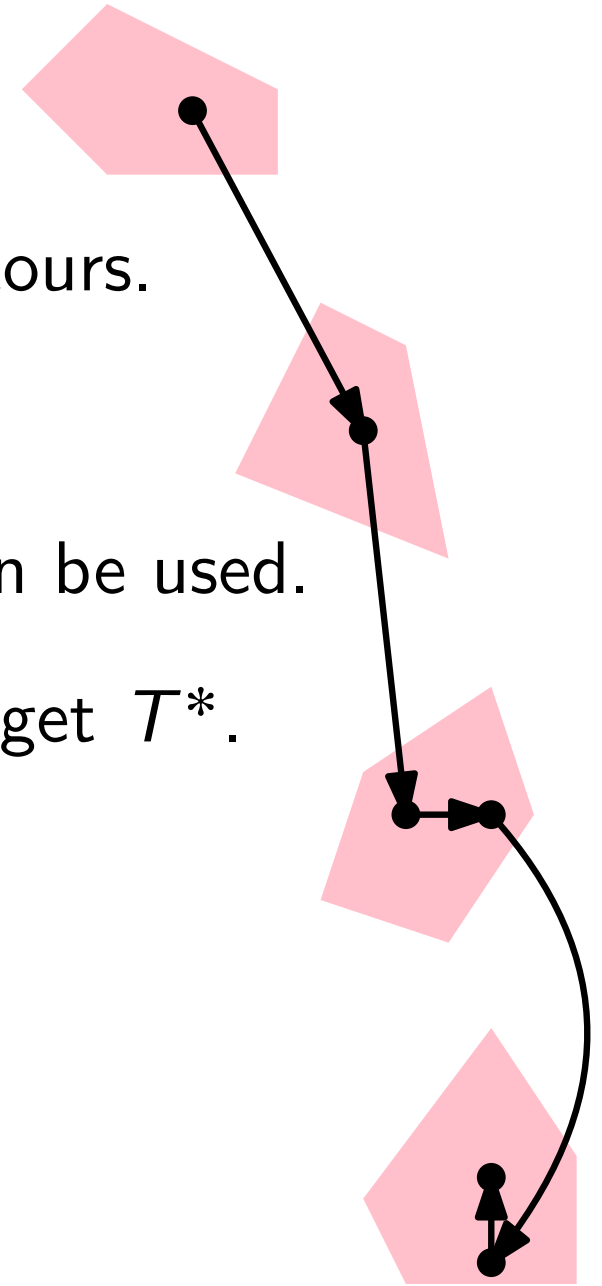
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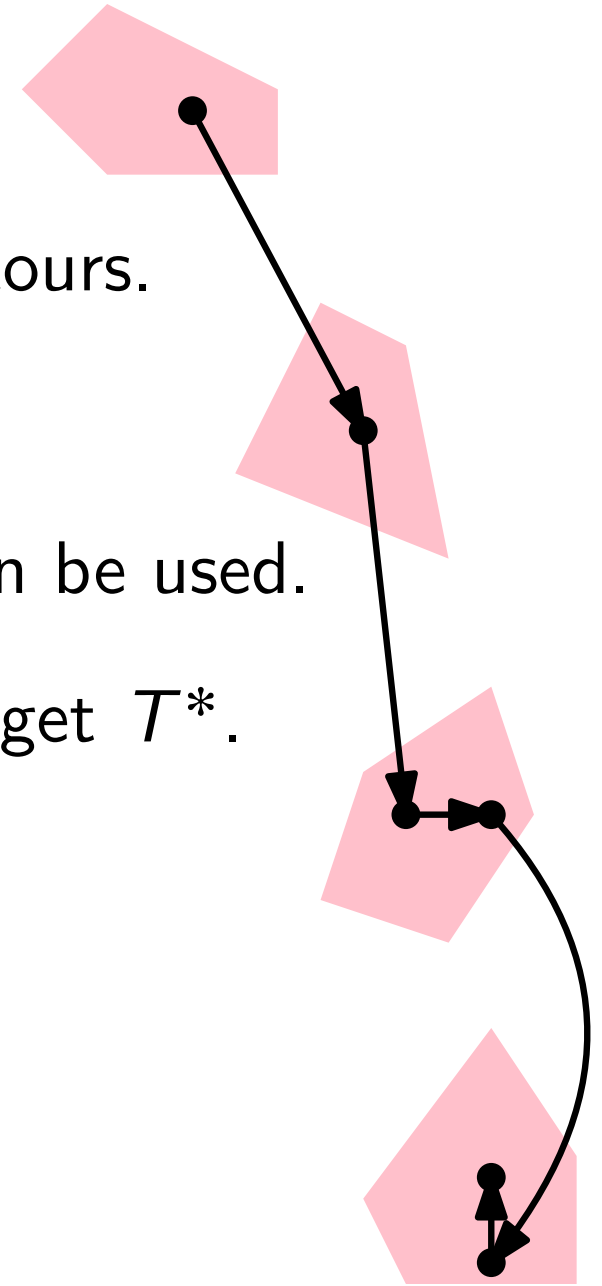
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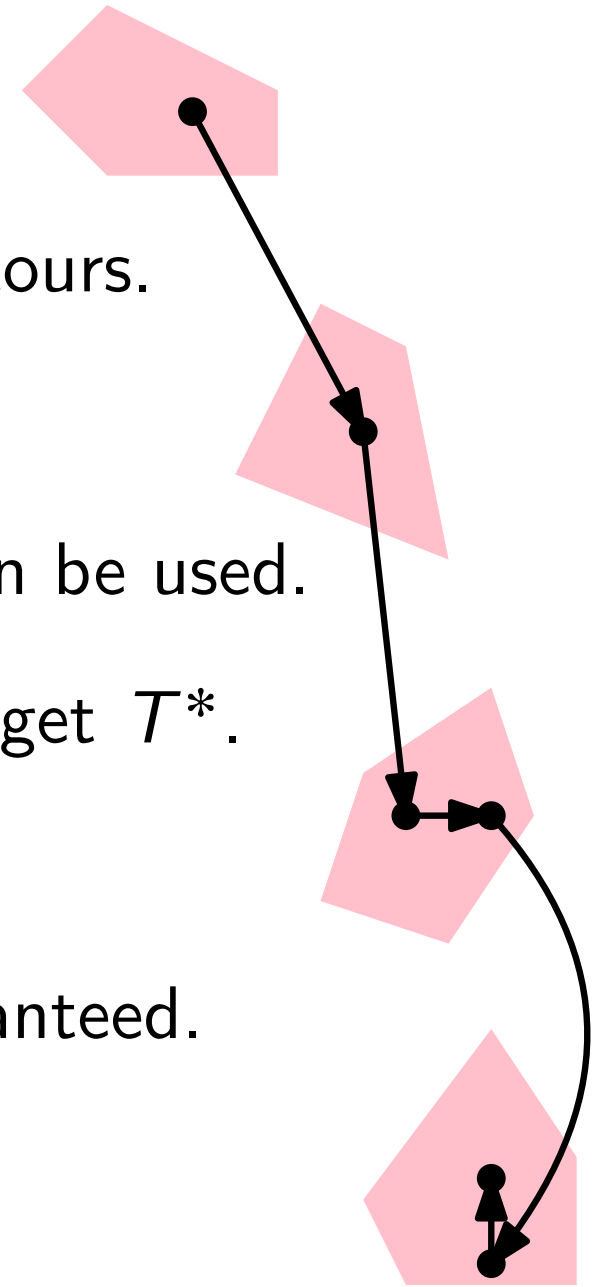
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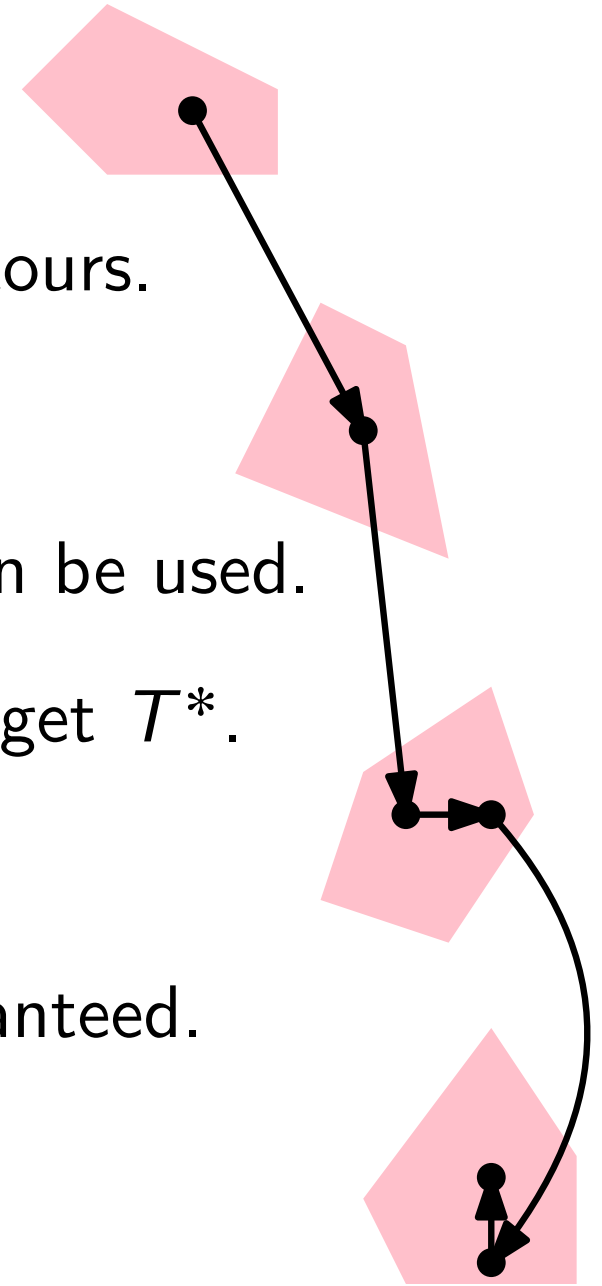
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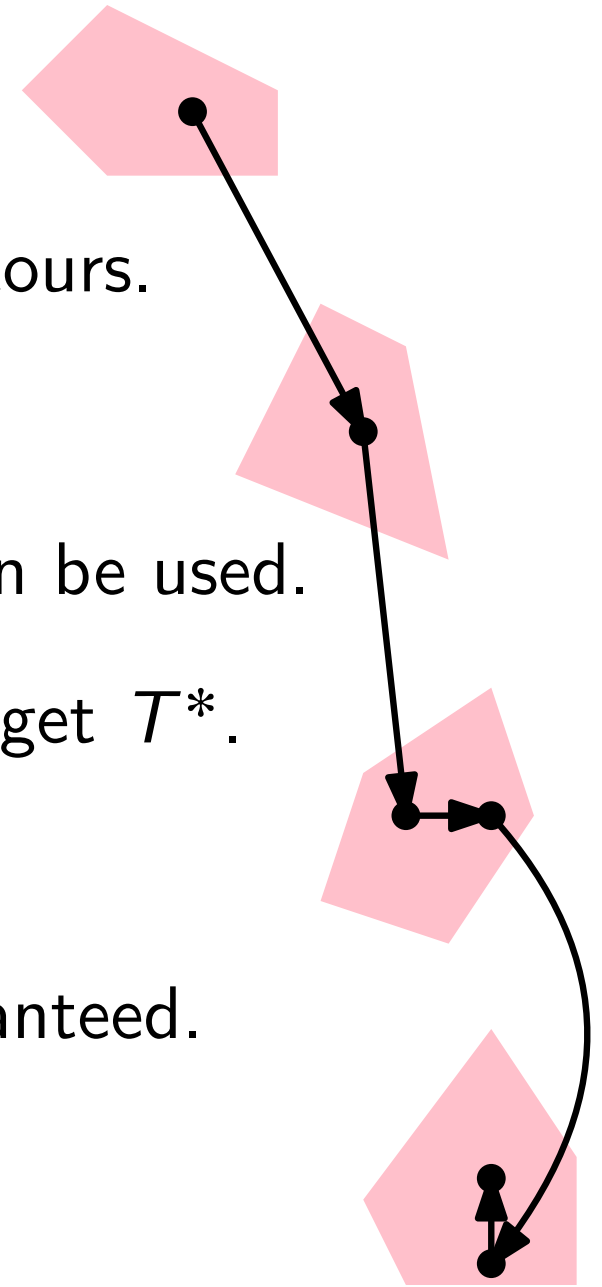
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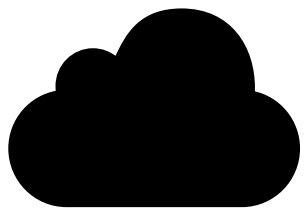
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Attributions



The above icons are made by Freepik from flaticon.com

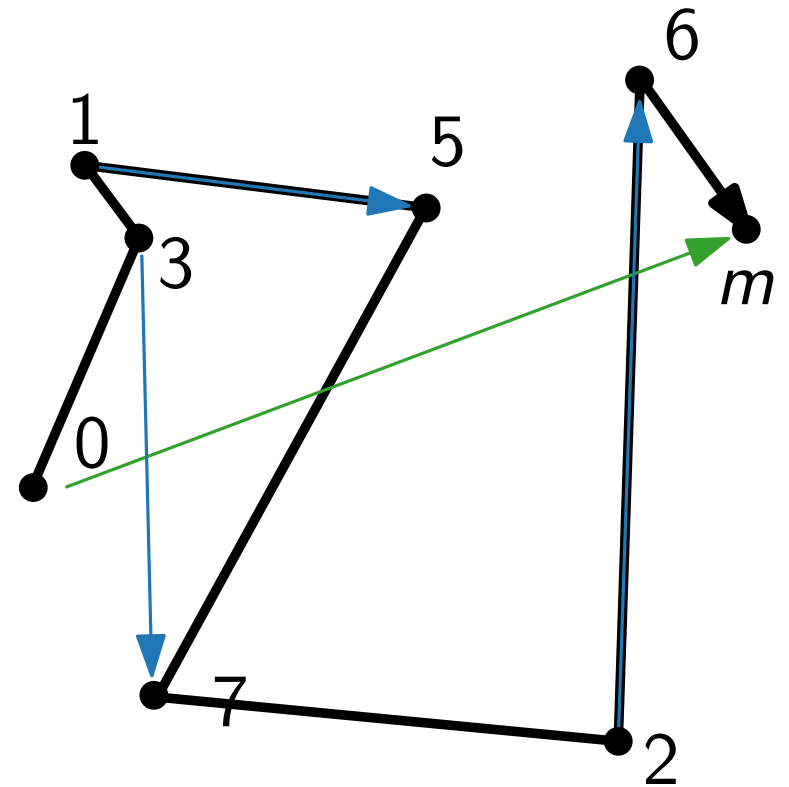


← CC 3.0 BY by SimpleIcon from flaticon.com

(c) Map Images from OpenStreetMap (osm.org)

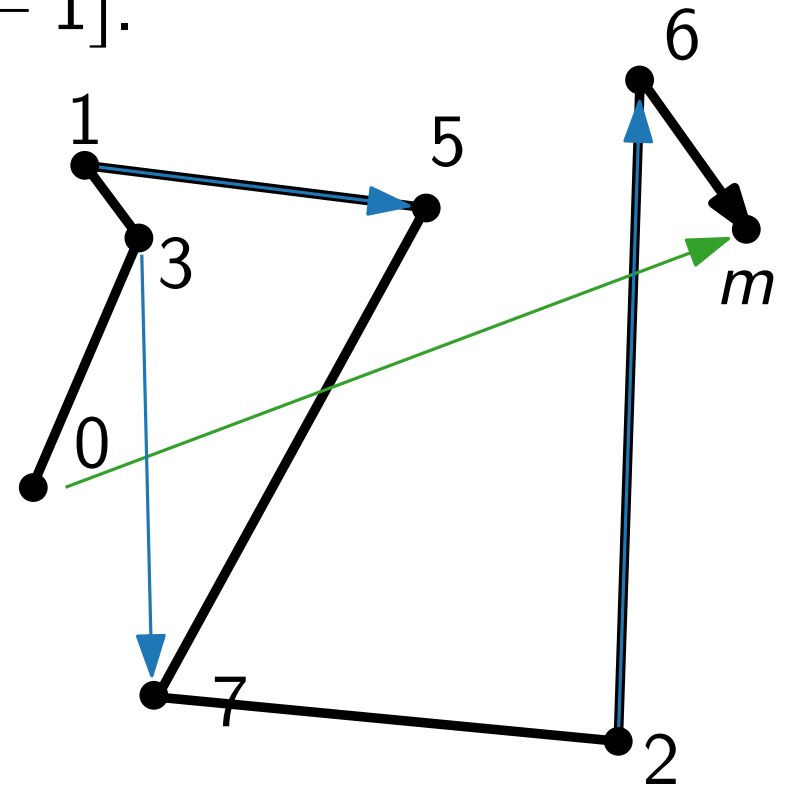
The following slides were abandoned at some point and not officially shown at the presentation. They may contain errors or are incomplete. Maybe they help you nonetheless.

The Objective Function



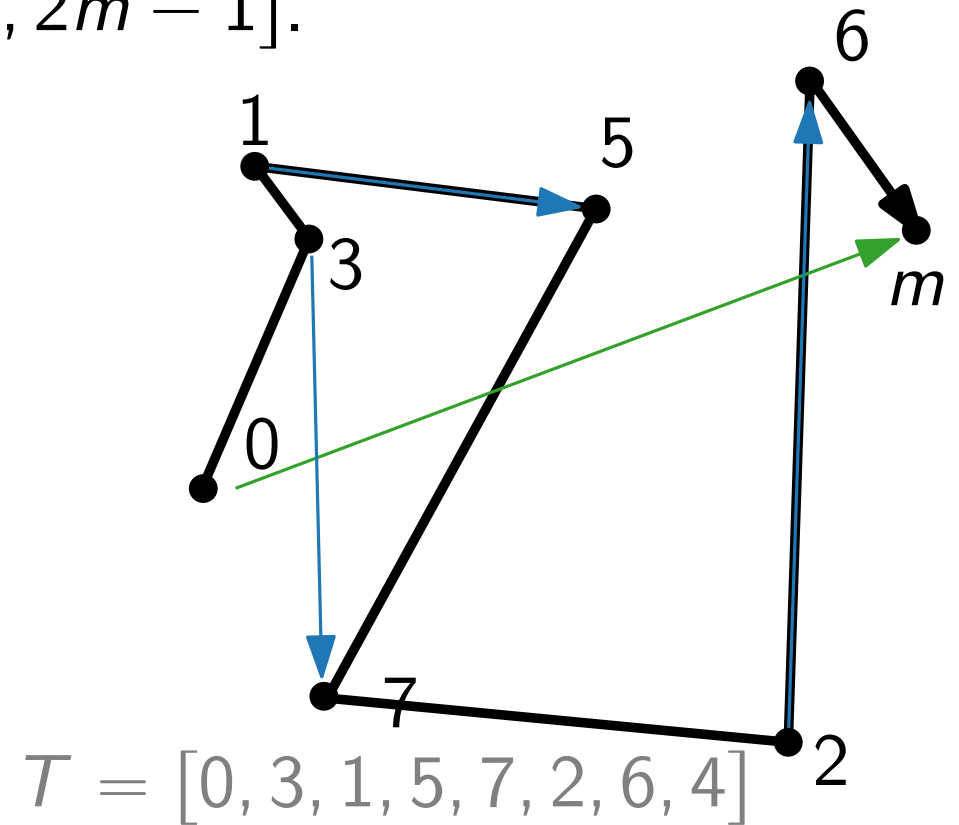
The Objective Function

A *tour* T is a permutation of $[0, 2m - 1]$.



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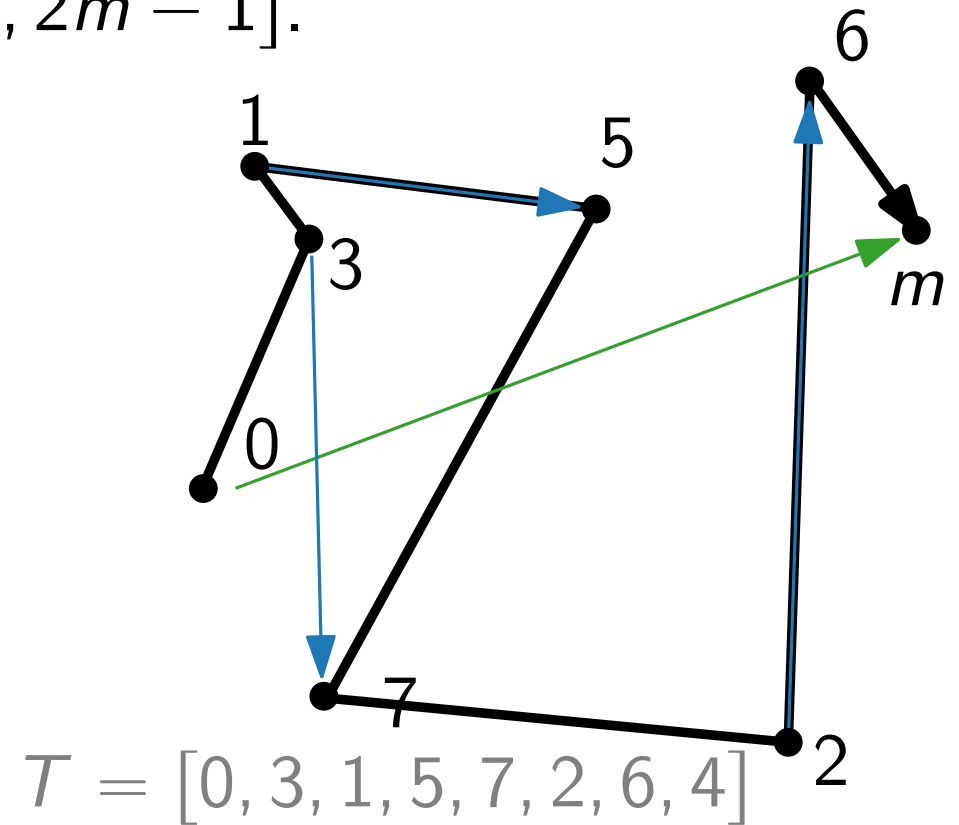
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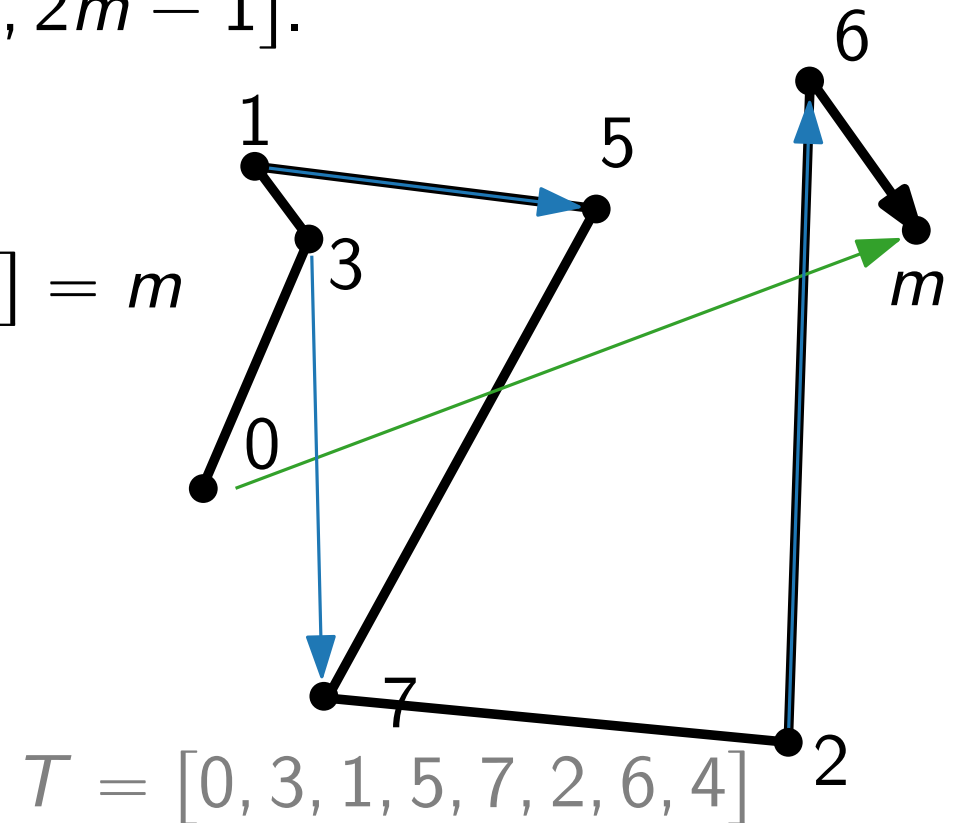
T feasible \Leftrightarrow



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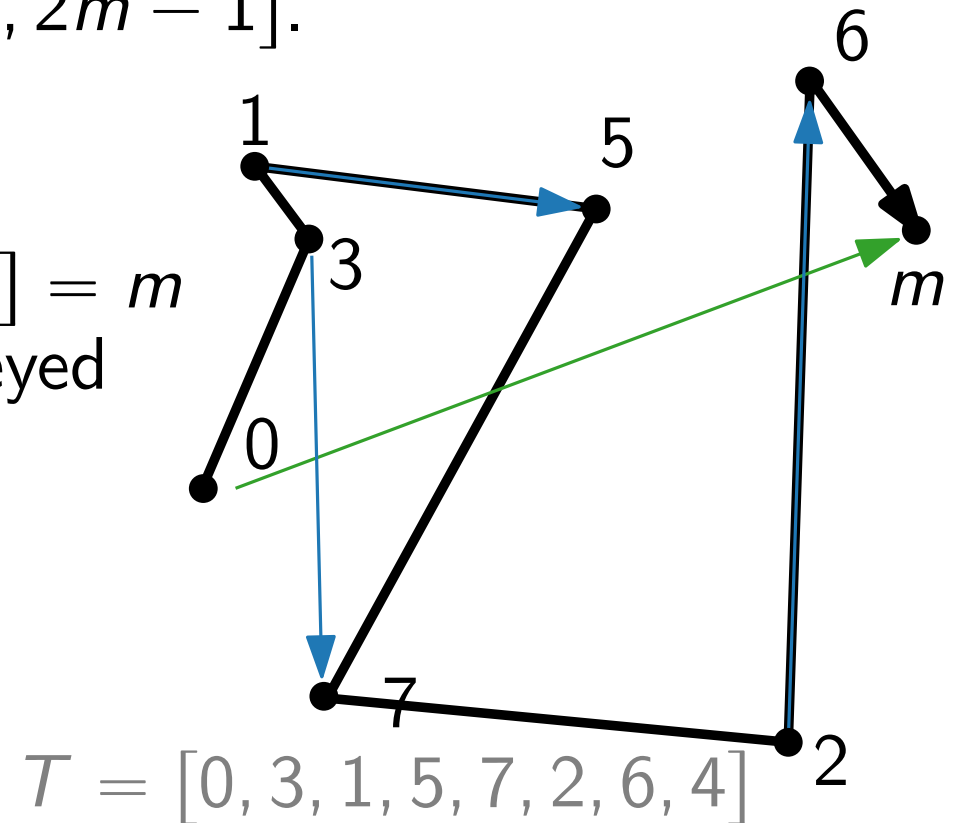
T feasible $\Leftrightarrow T[1] = 0$ & $T[2m] = m$



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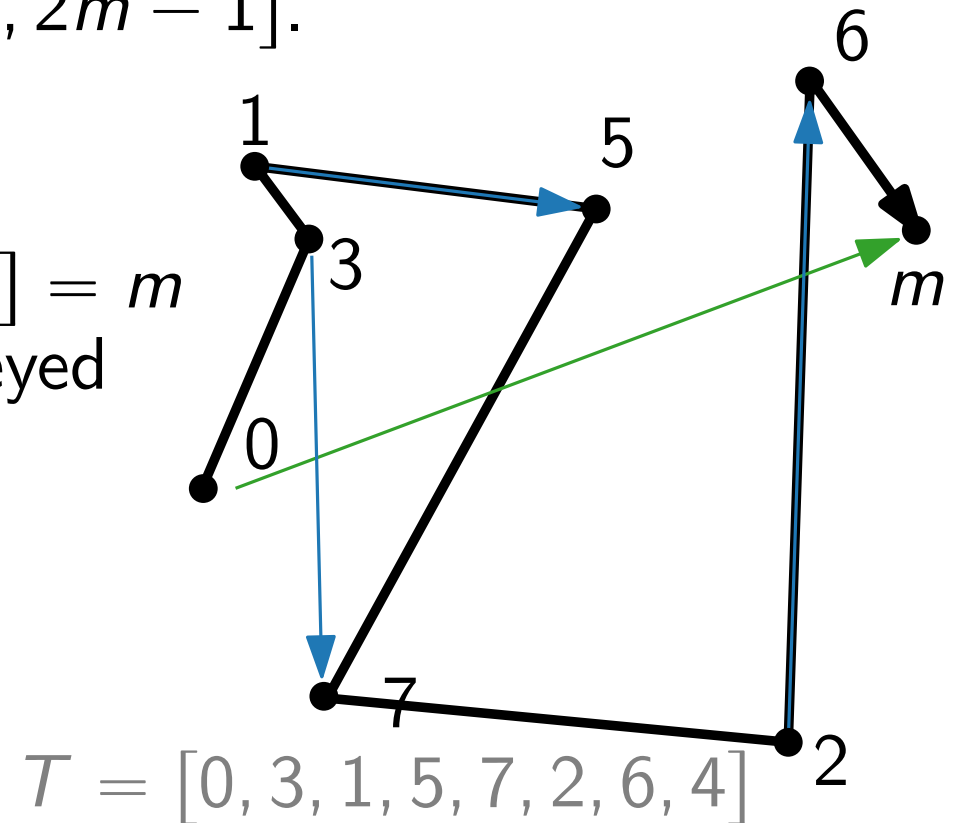
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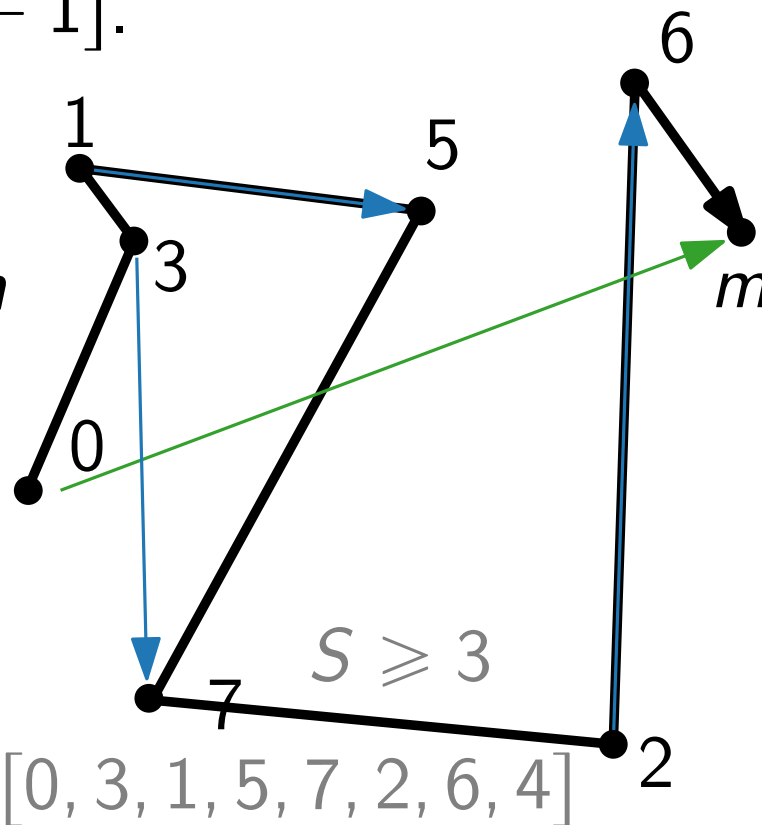
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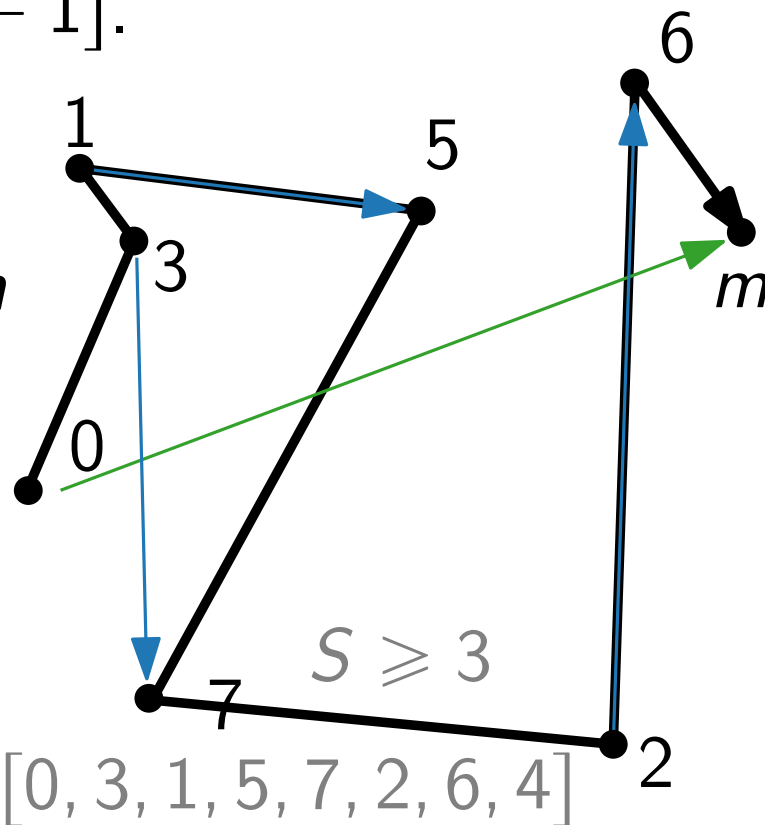
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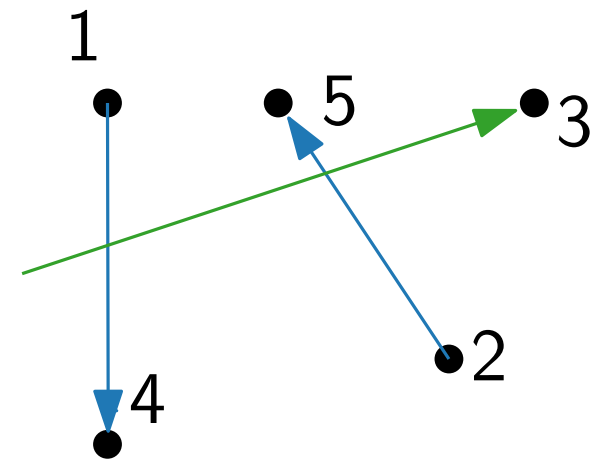
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$k(j)$ is the number of persons after step j of T .

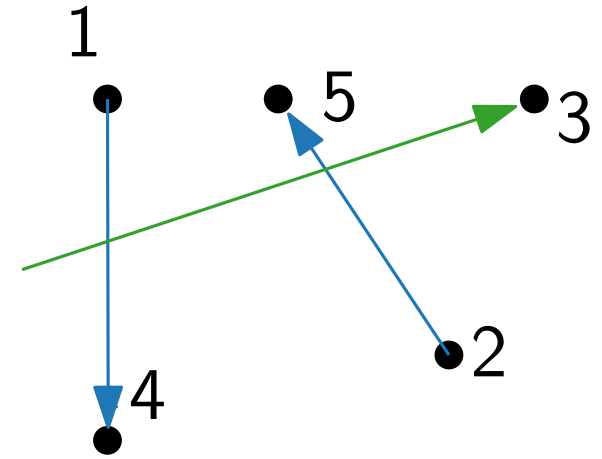
An Exact Algorithm

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An Exact Algorithm

Find a tour with 6 steps:



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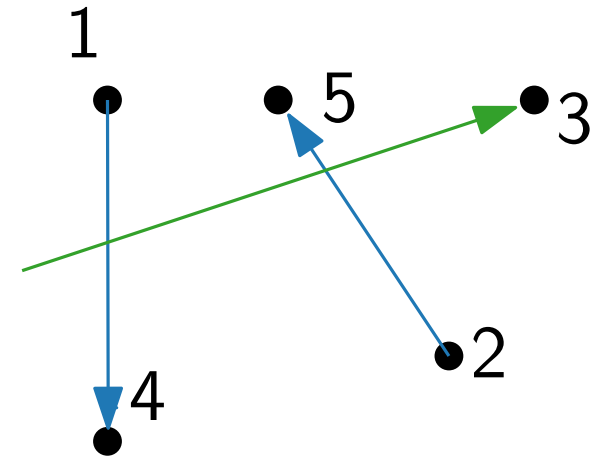
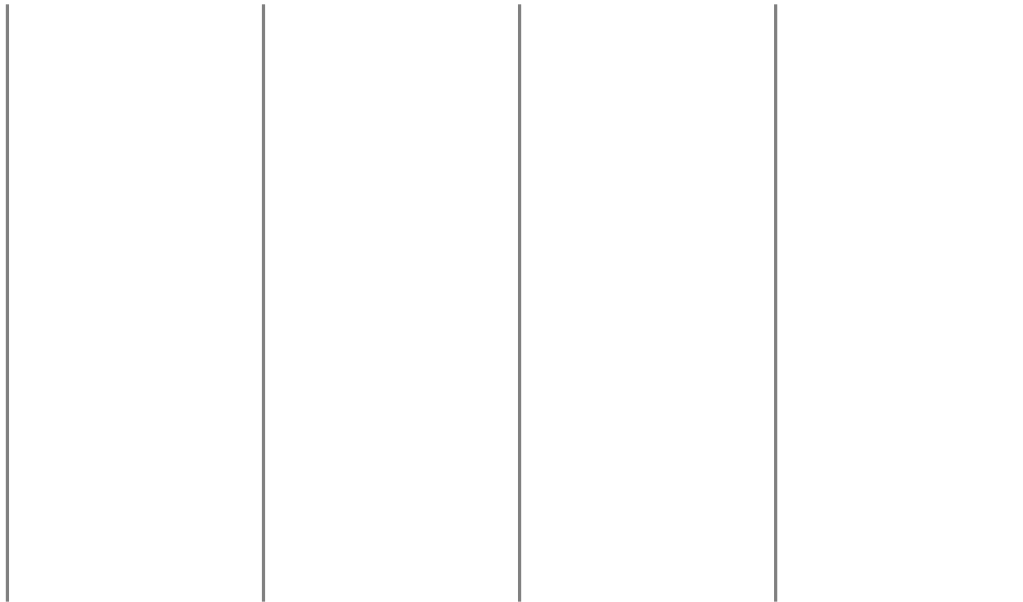
1

2

3

4

5



An Exact Algorithm

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1

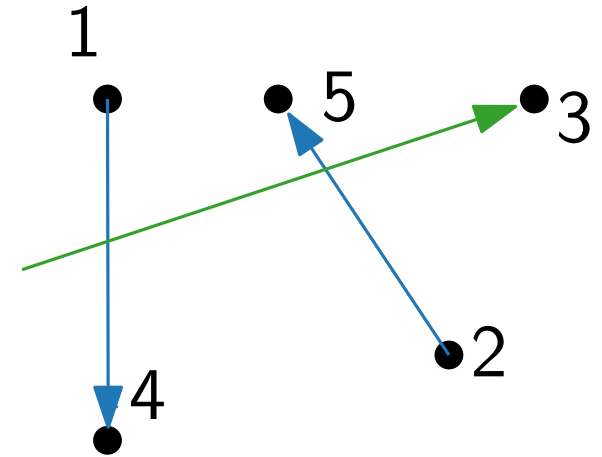
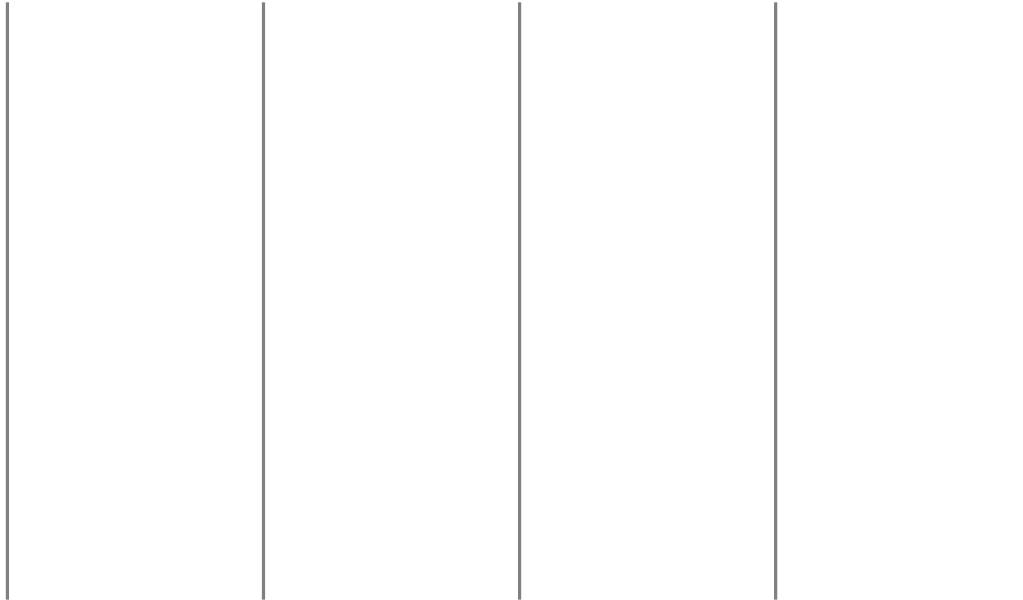
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3

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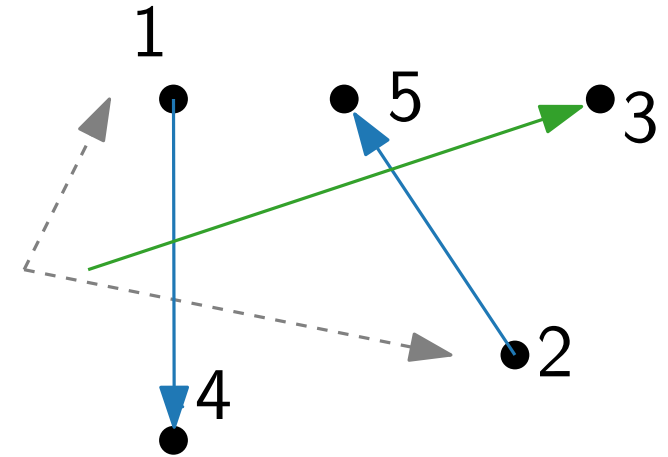
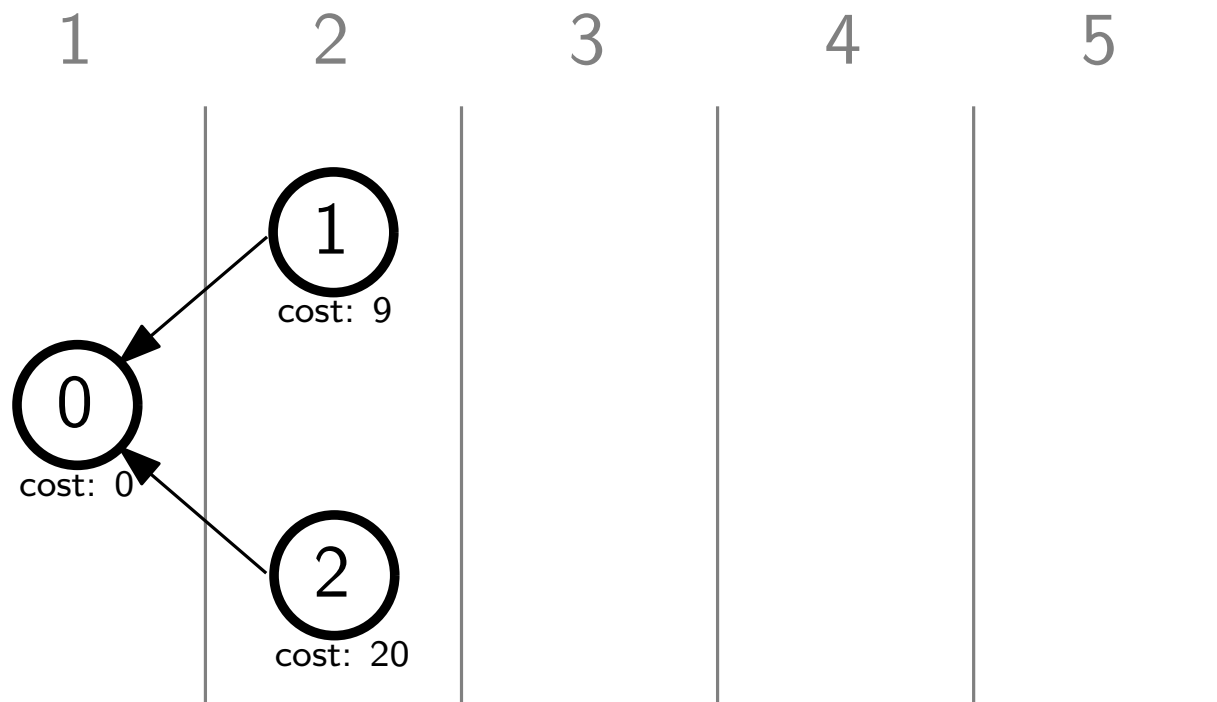
5

0
cost: 0



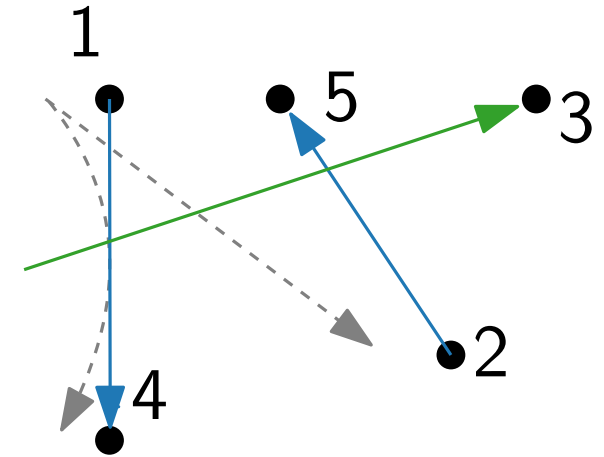
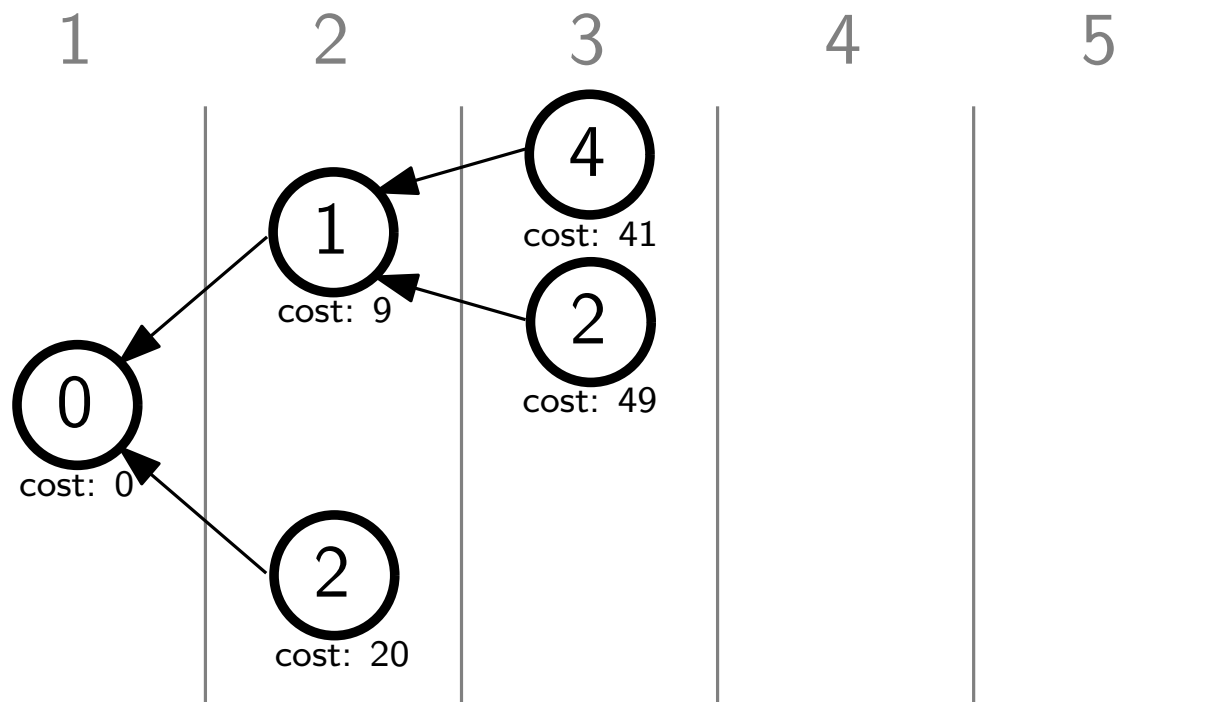
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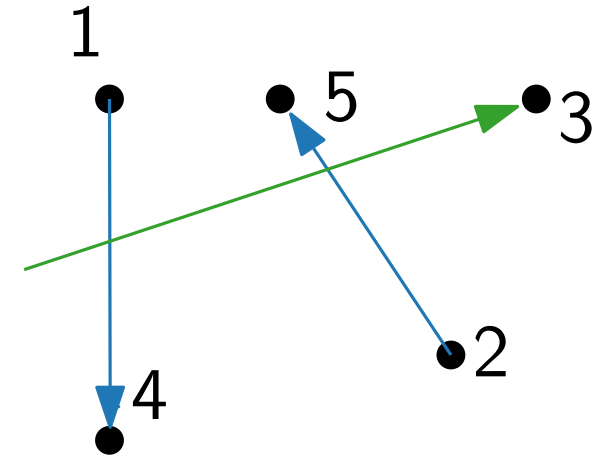
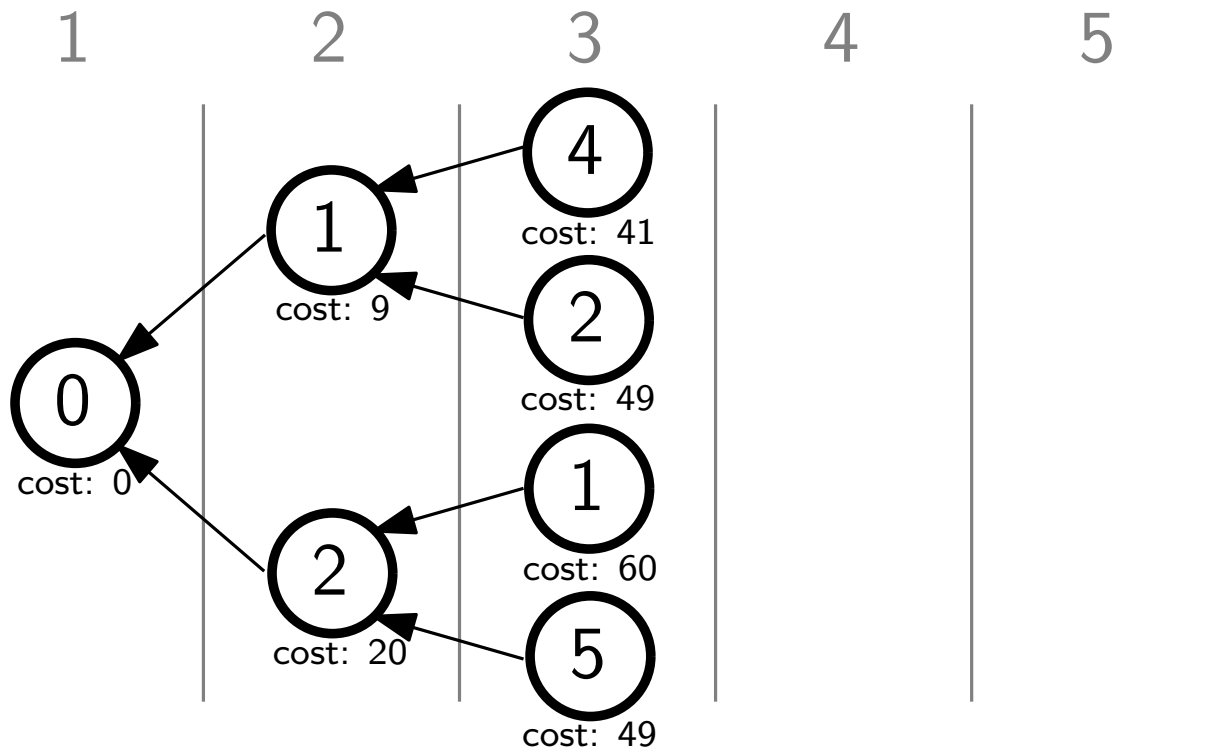
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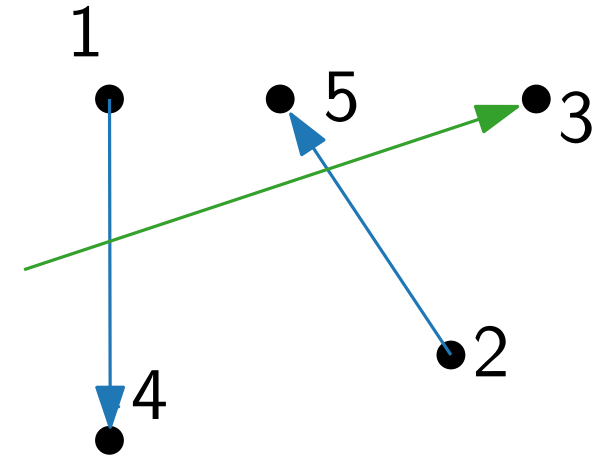
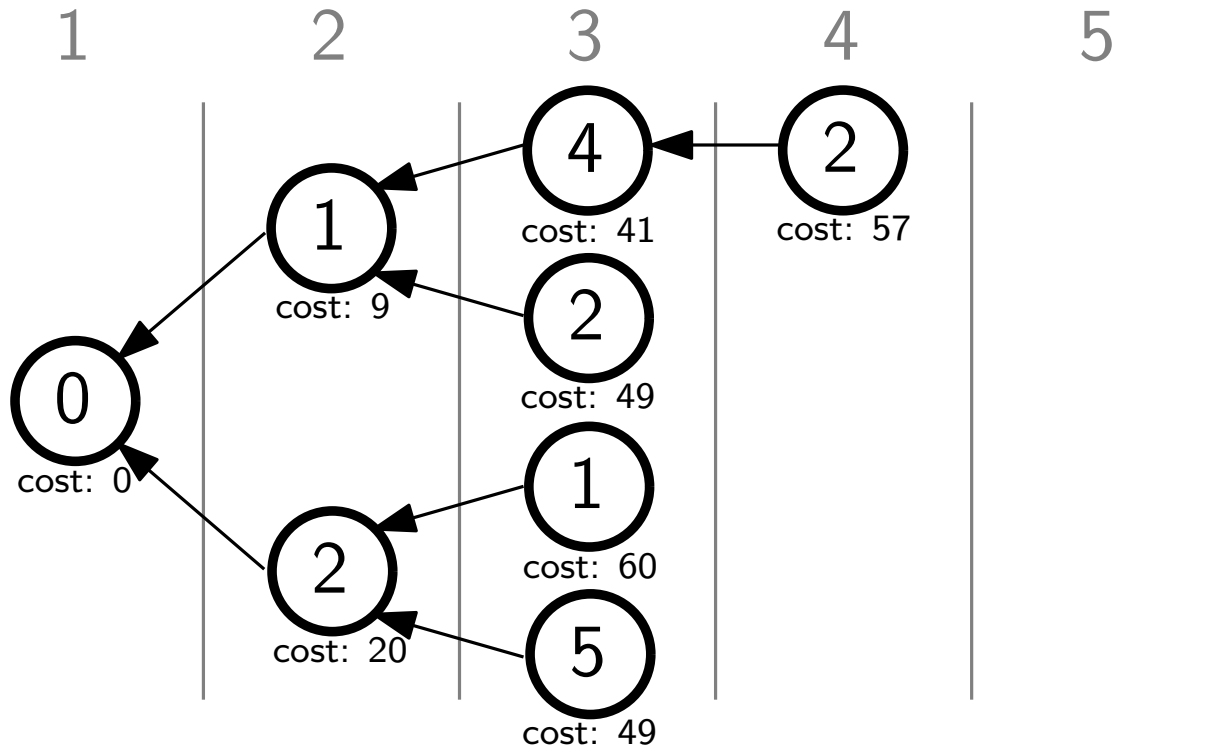
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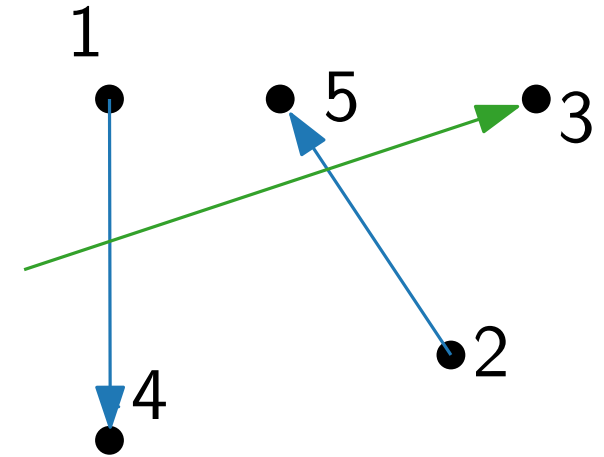
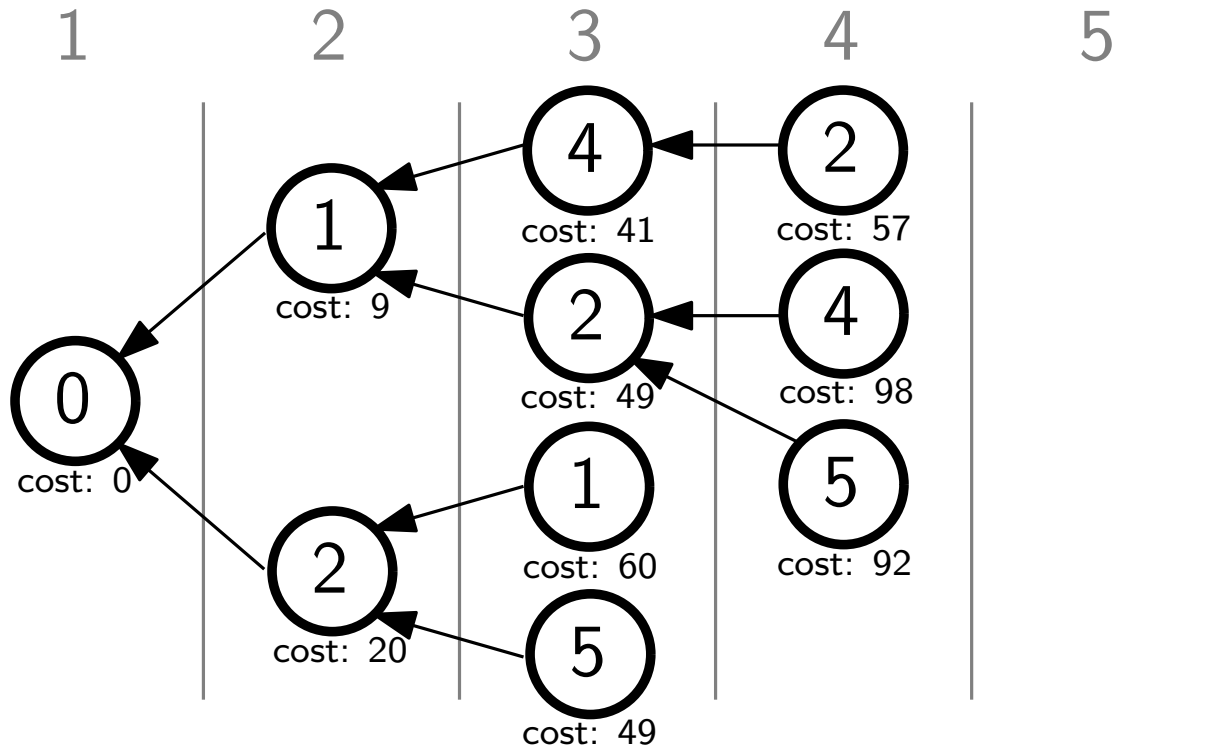
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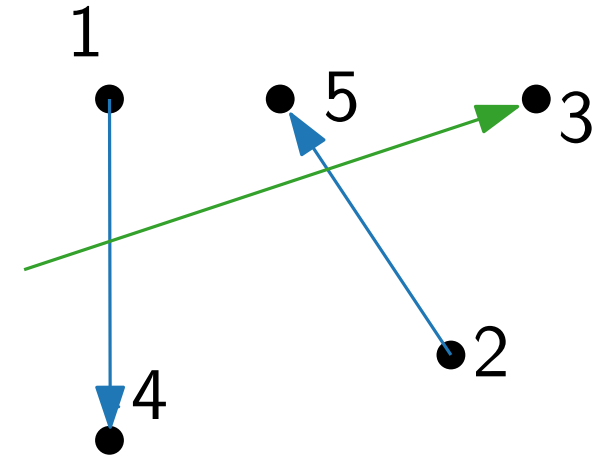
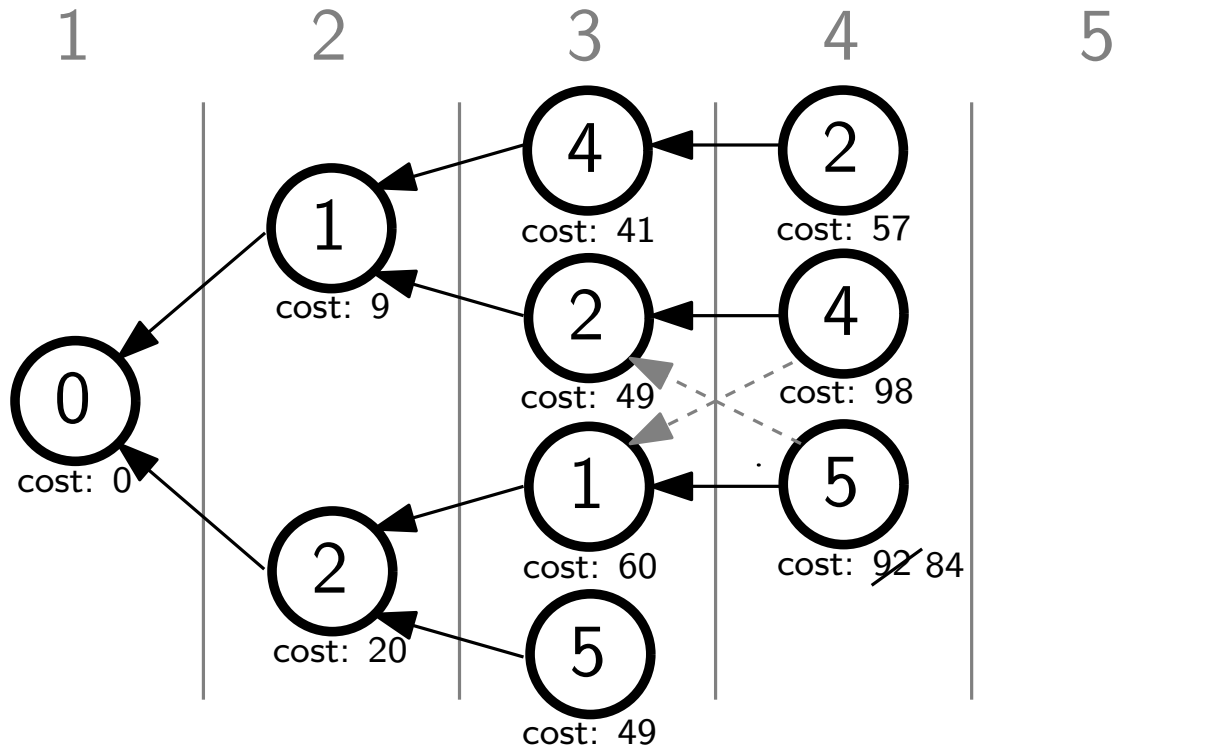
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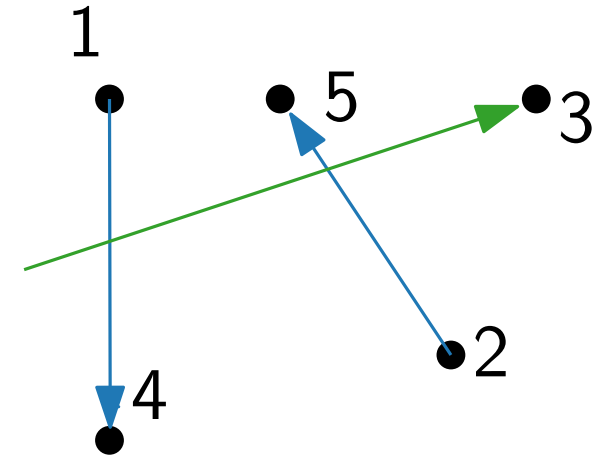
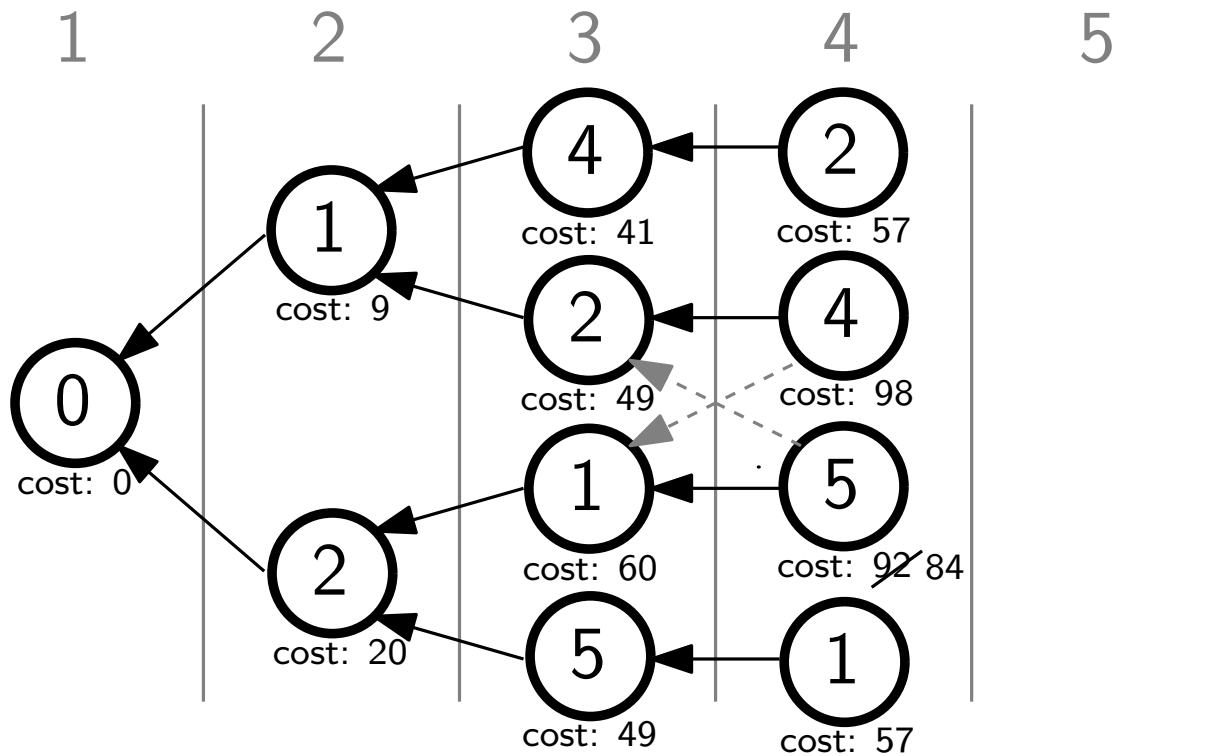
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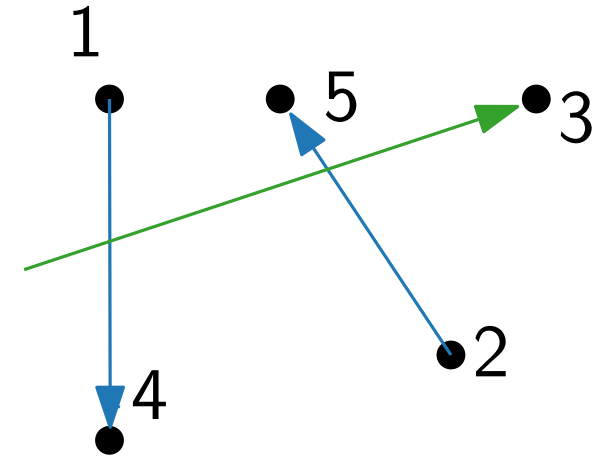
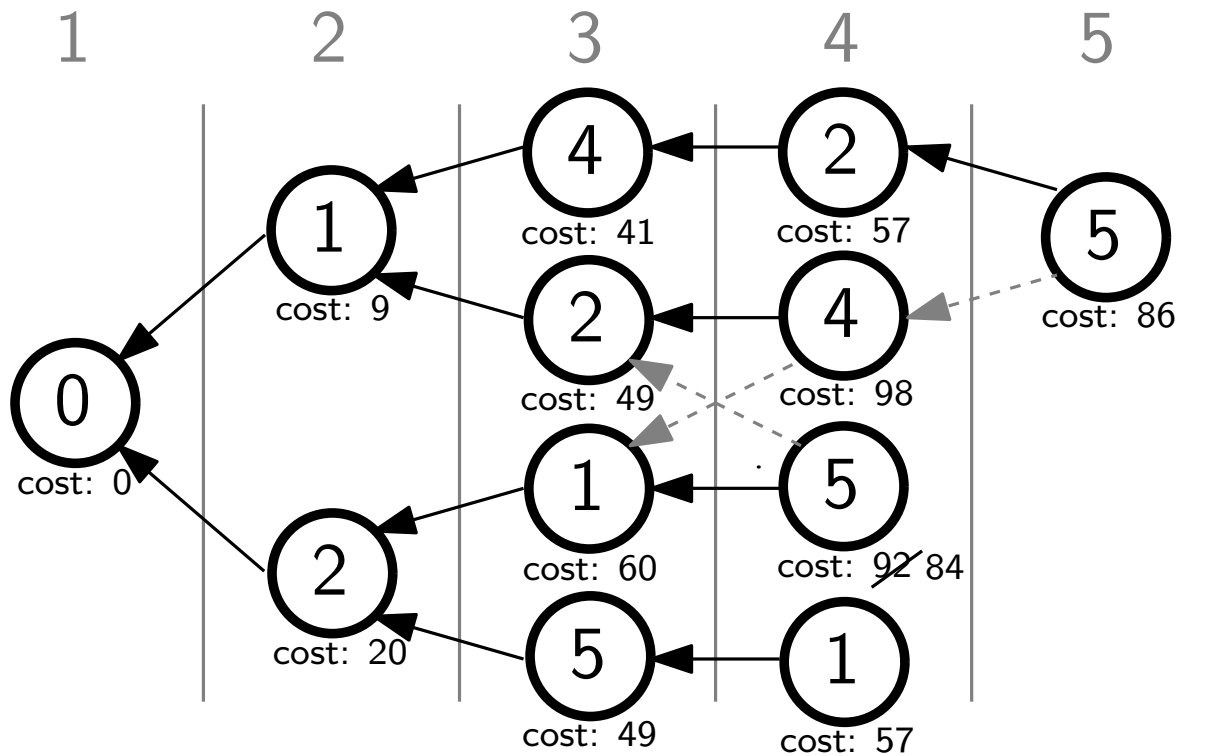
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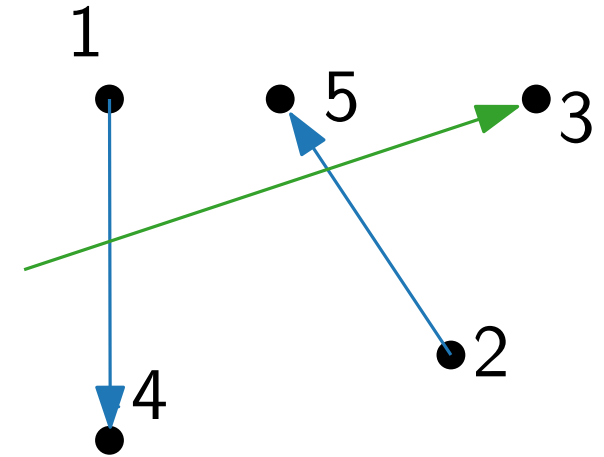
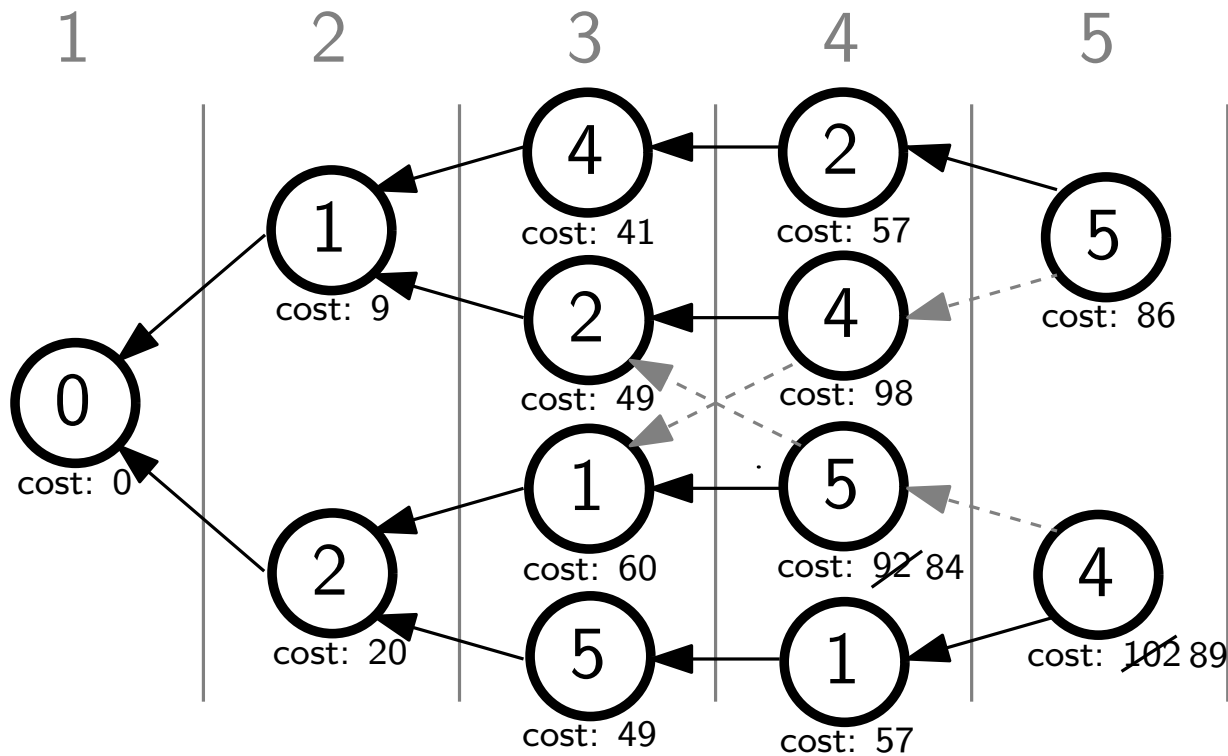
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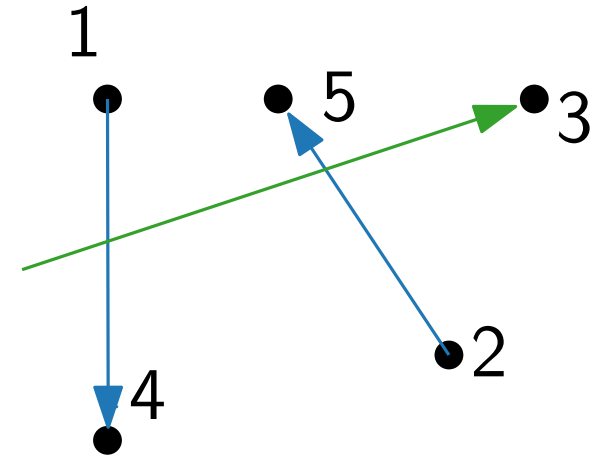
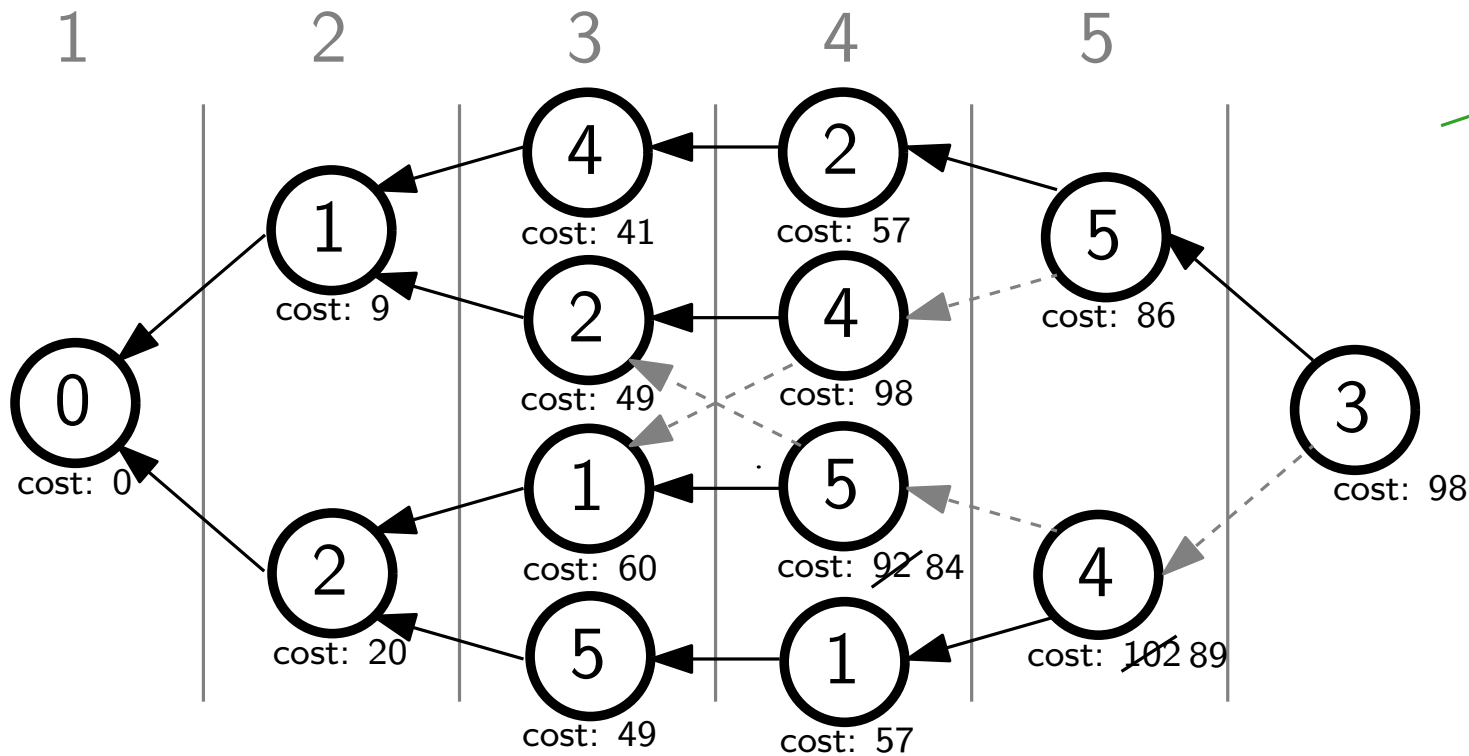
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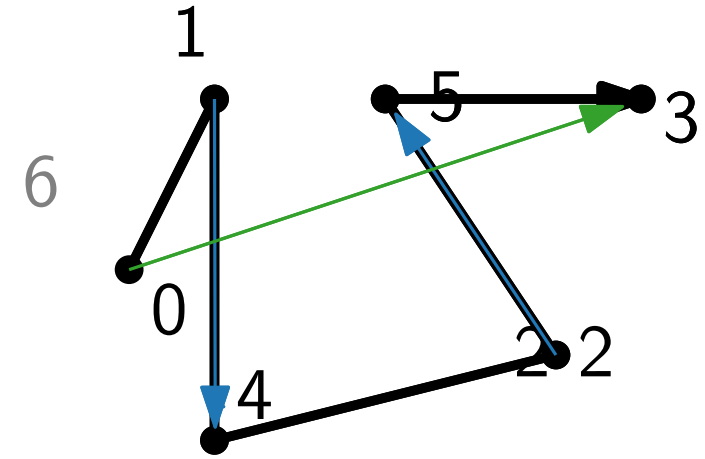
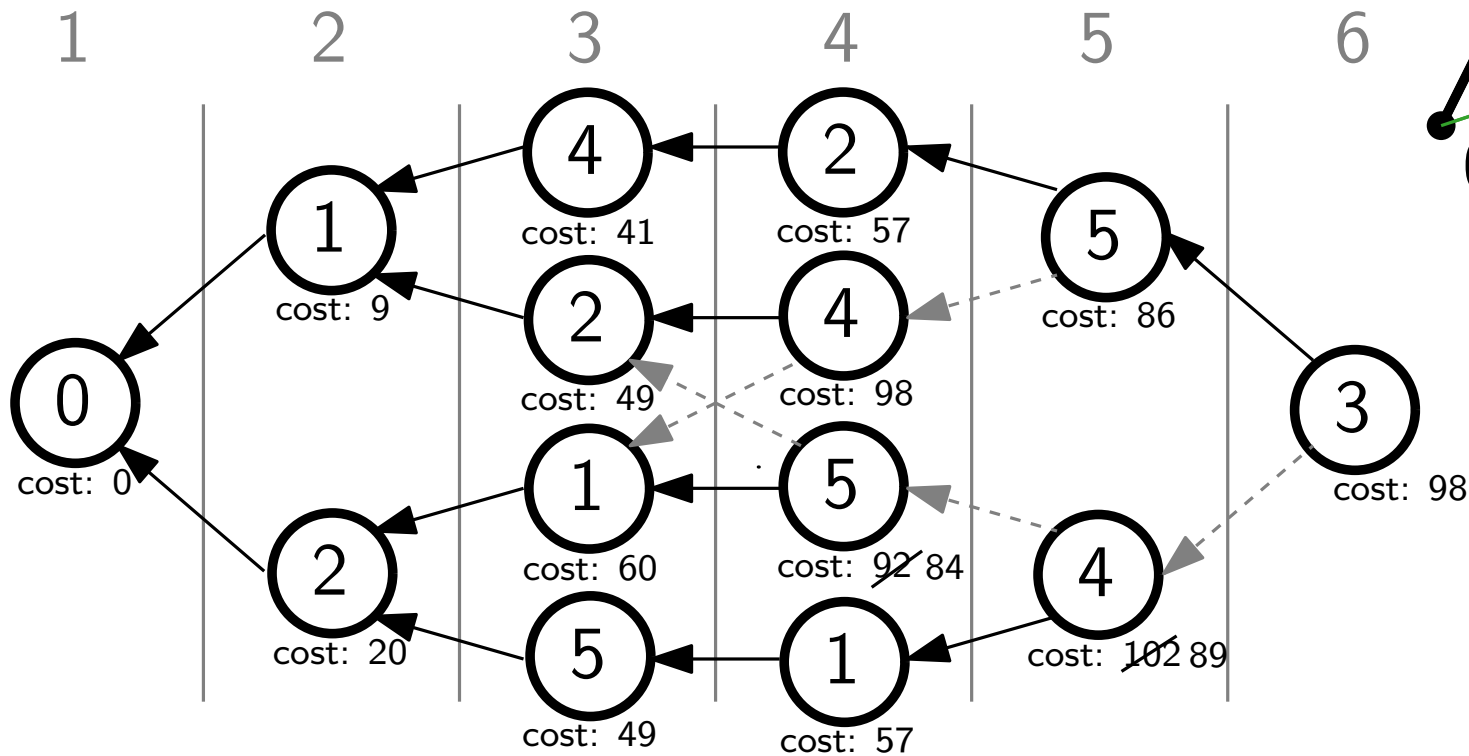
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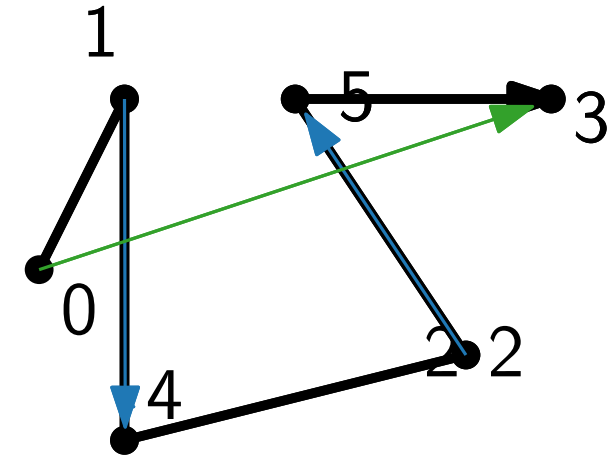
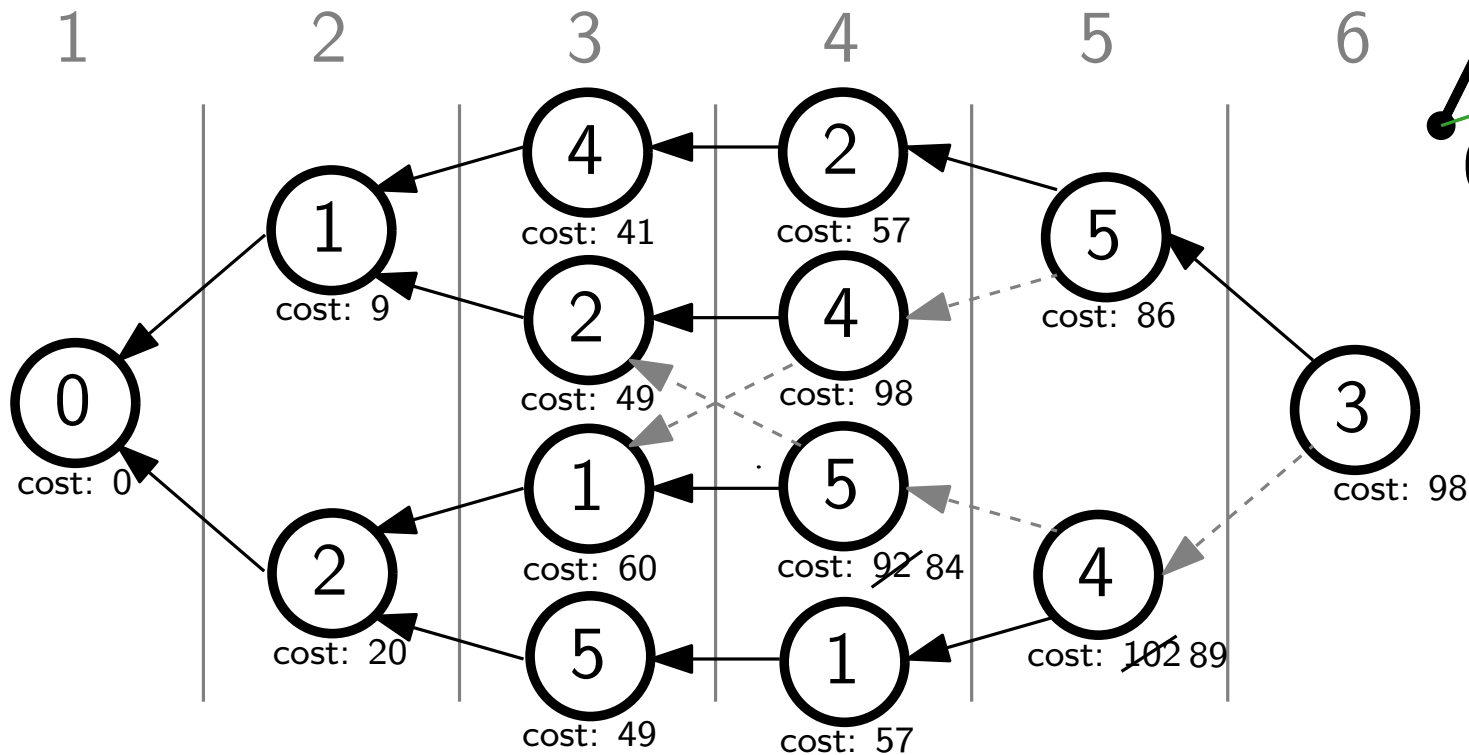
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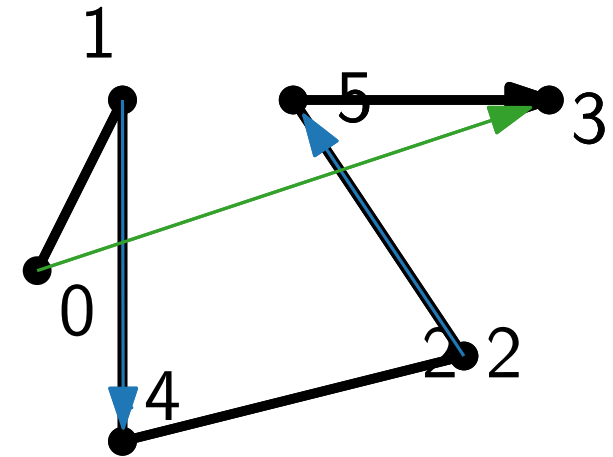
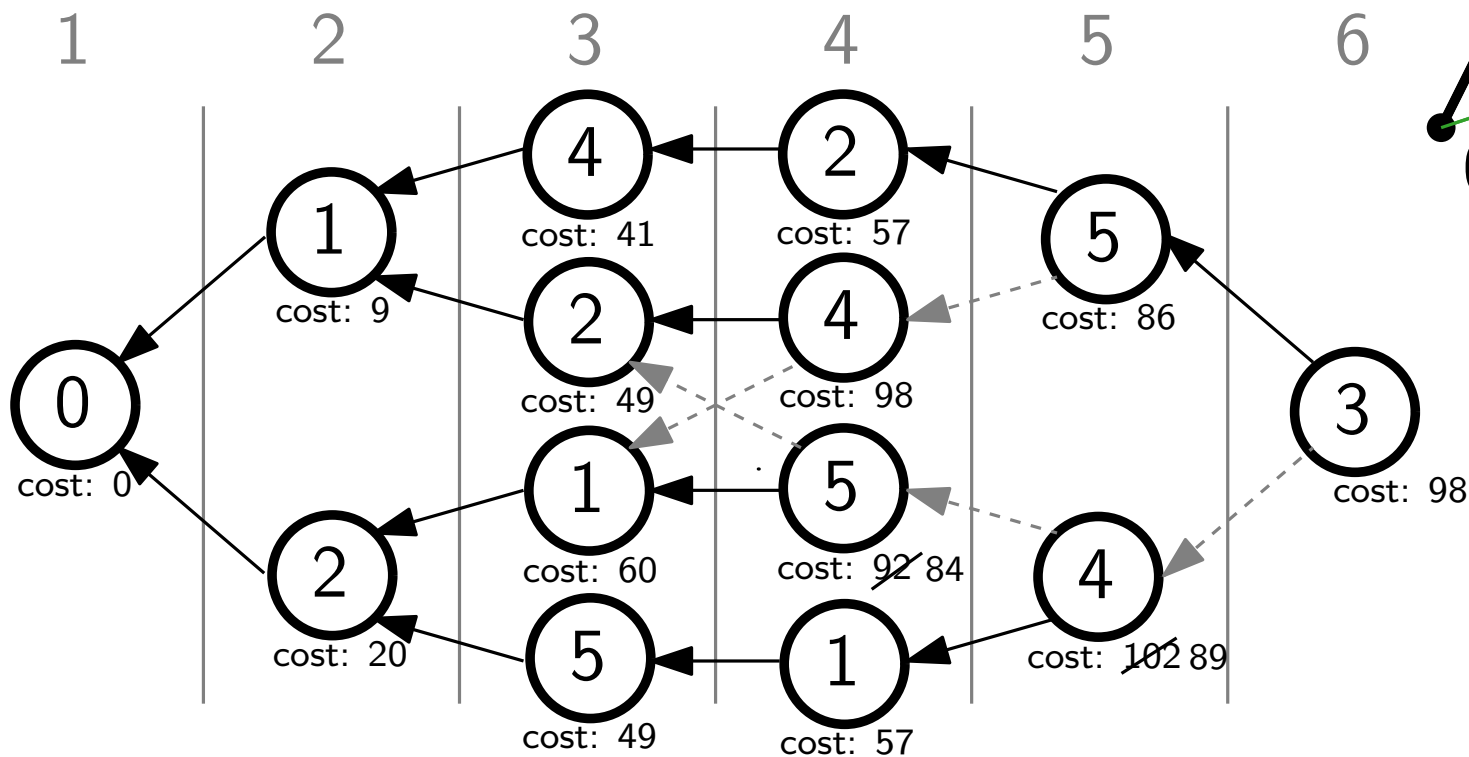
Find a tour with 6 steps:



→ Generalizes to an algorithm with exchangeable objective

An Exact Algorithm

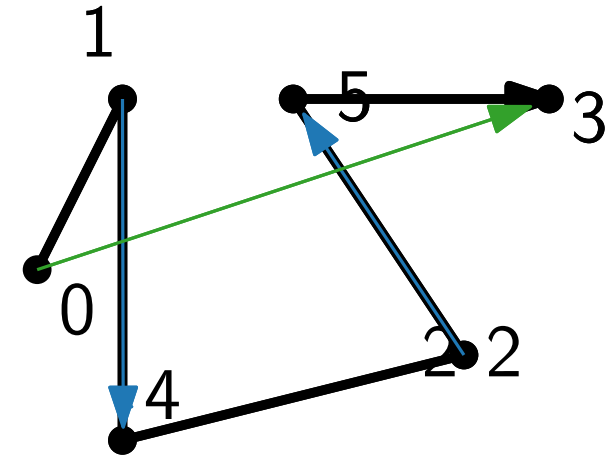
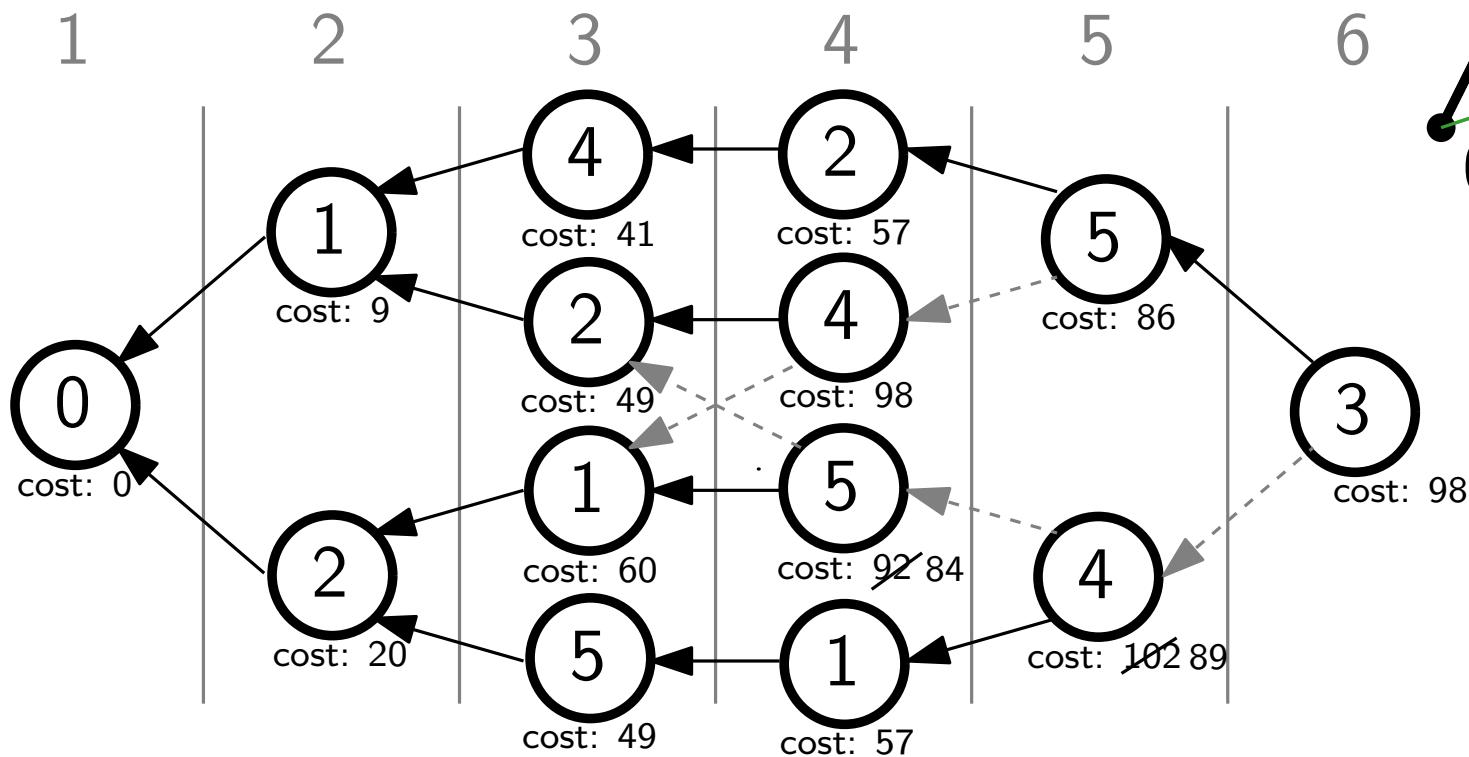
Find a tour with 6 steps:



- Generalizes to an algorithm with exchangeable objective
- DFS-like traversal also possible [Psaraftis 1980]

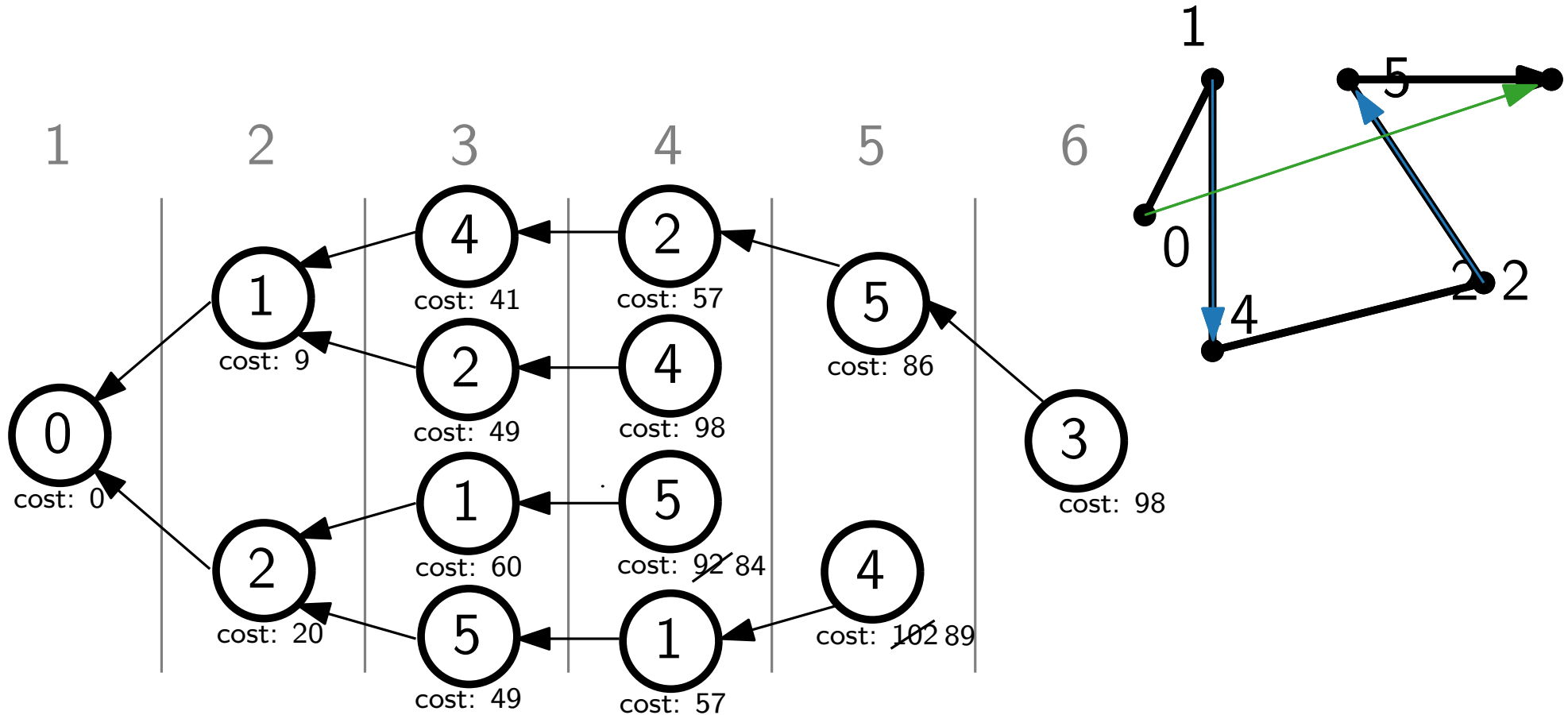
An Exact Algorithm

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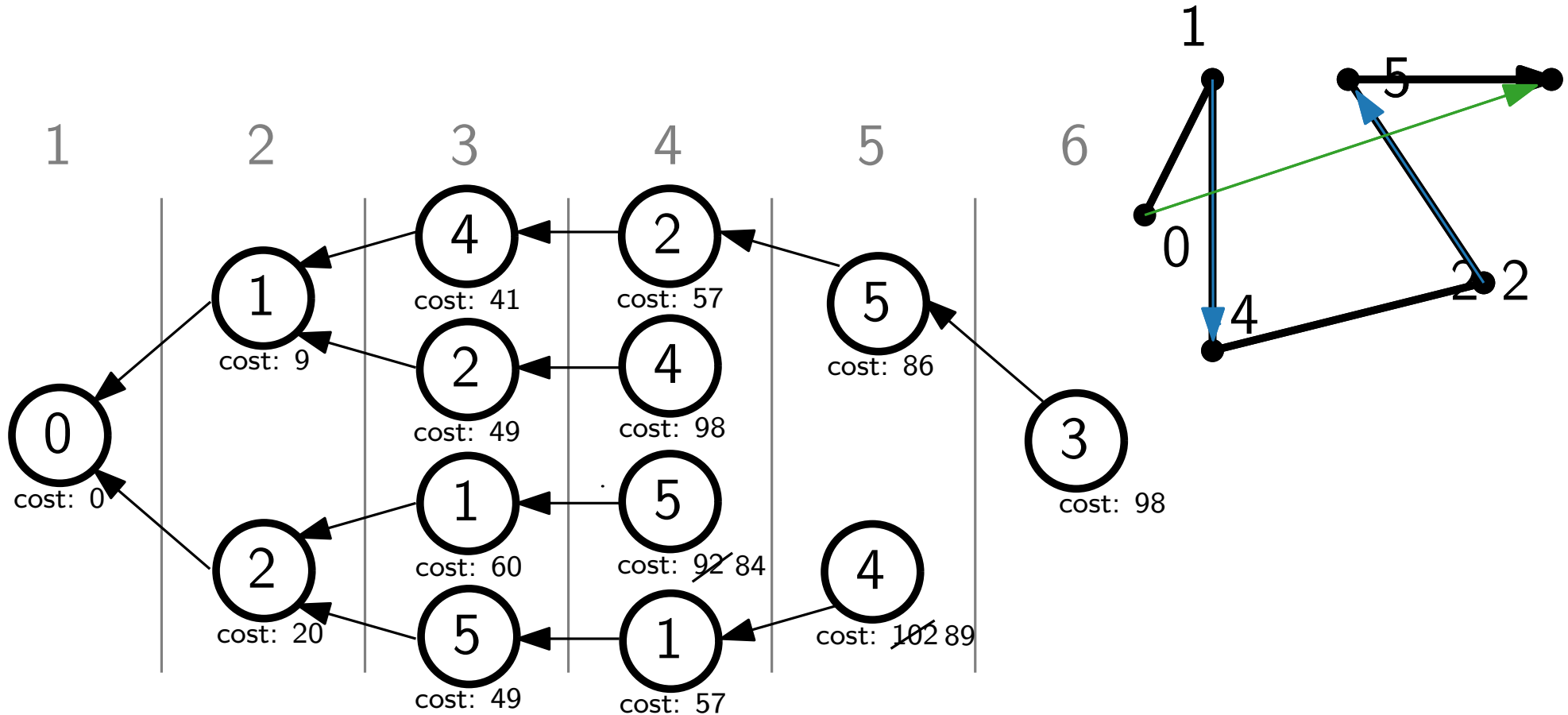


- Generalizes to an algorithm with exchangeable objective
- DFS-like traversal also possible [Psaraftis 1980]
- BFS-like traversal can save storage

Running Time and Partial Execution

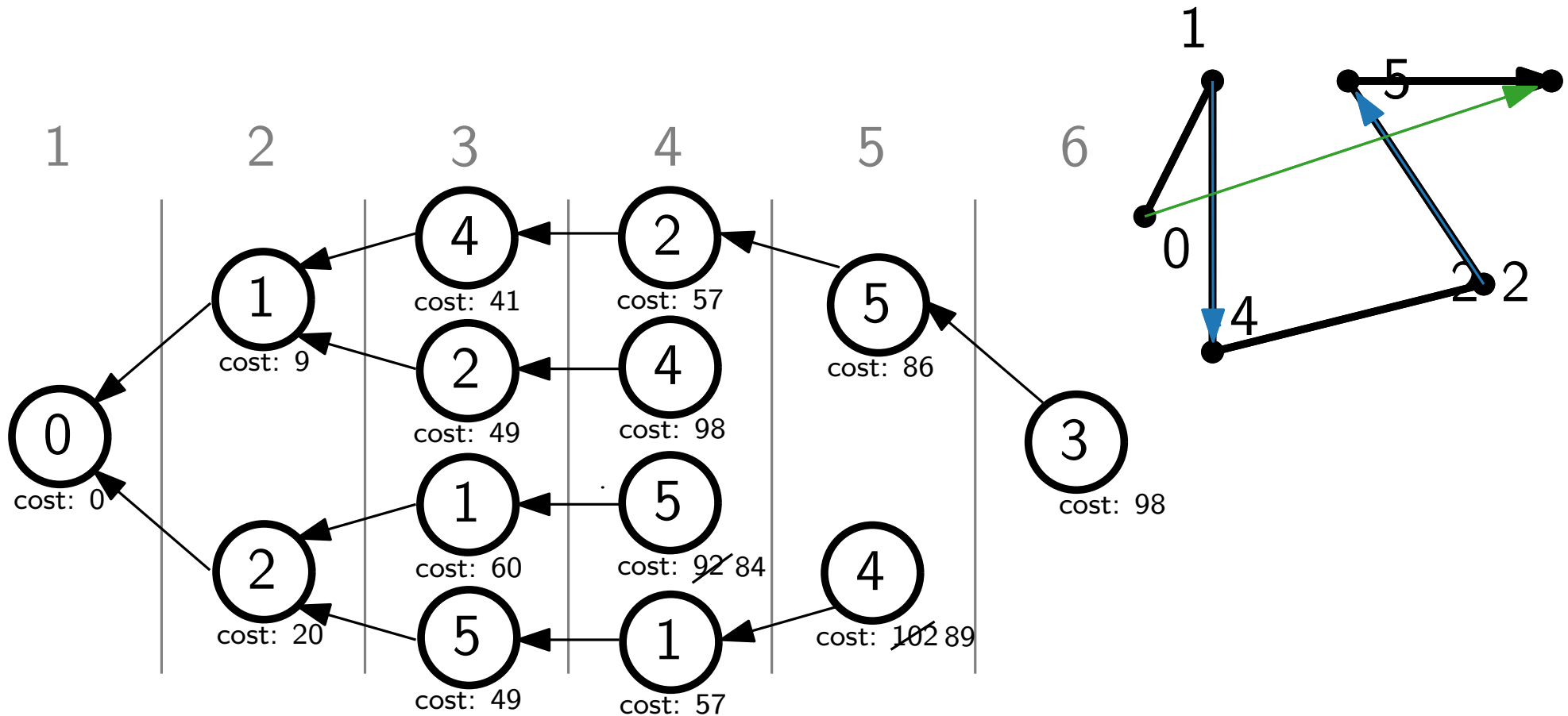


Running Time and Partial Execution



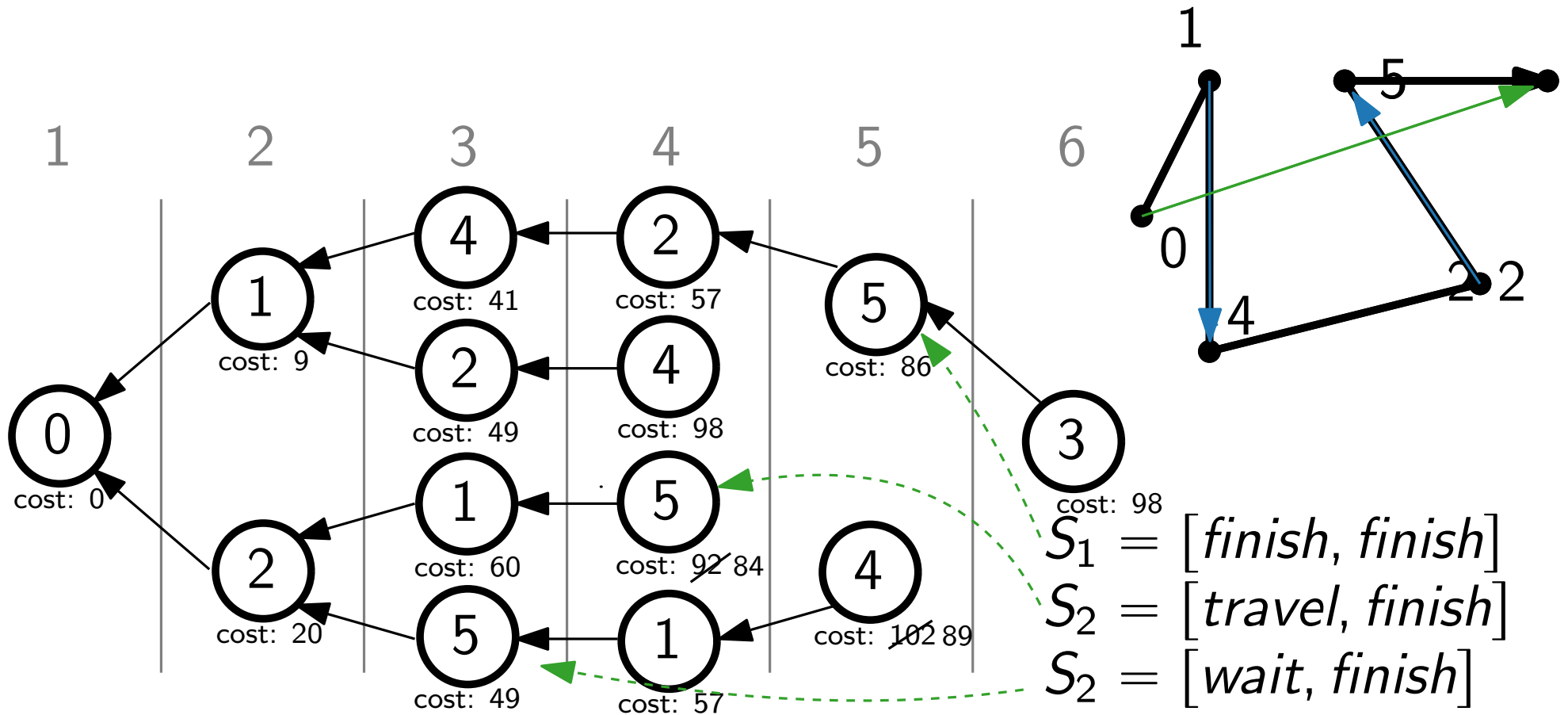
At every step, a rider can have three steps: *wait*, *travel*, *finish*.

Running Time and Partial Execution



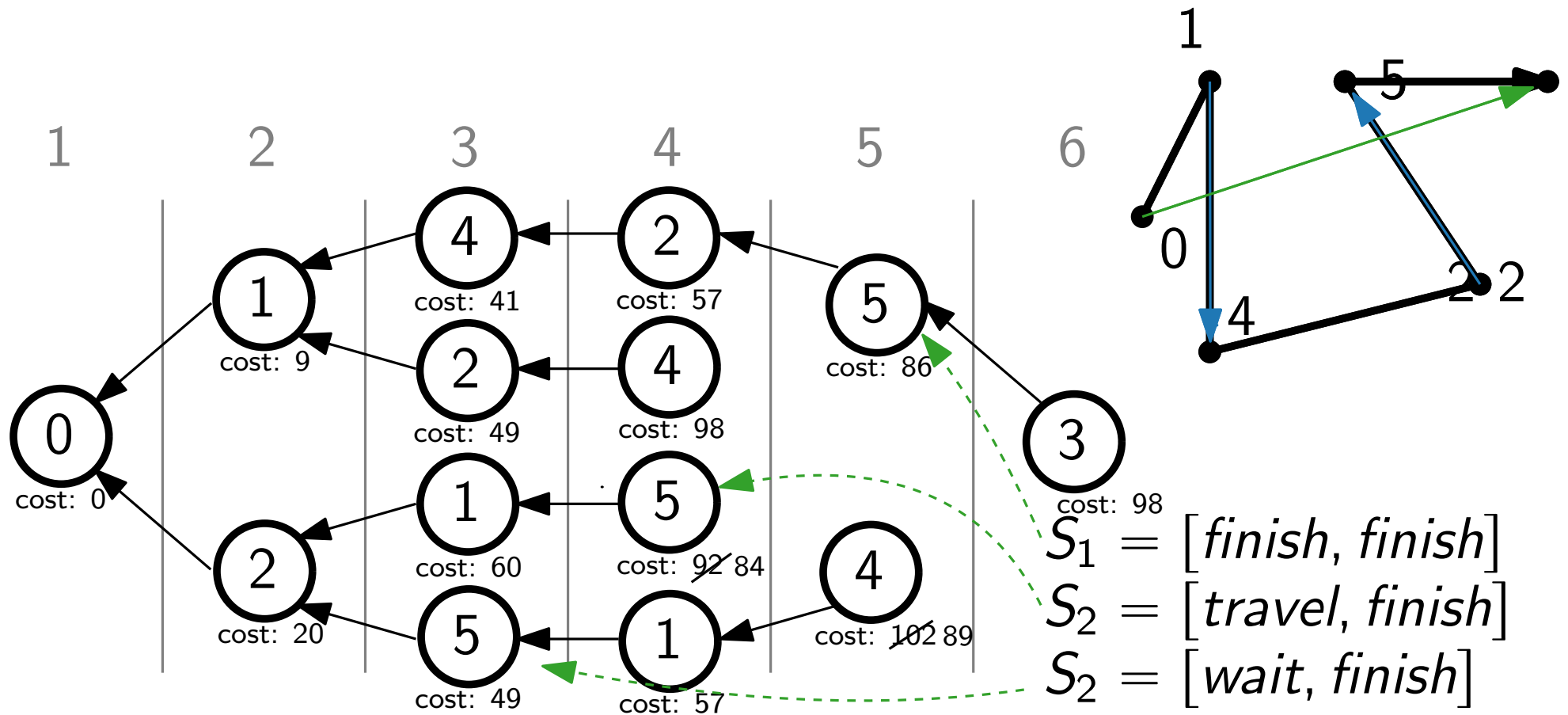
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 \Rightarrow for a fixed location $\notin \{0, m\}$ there are 3^{n-1} states.

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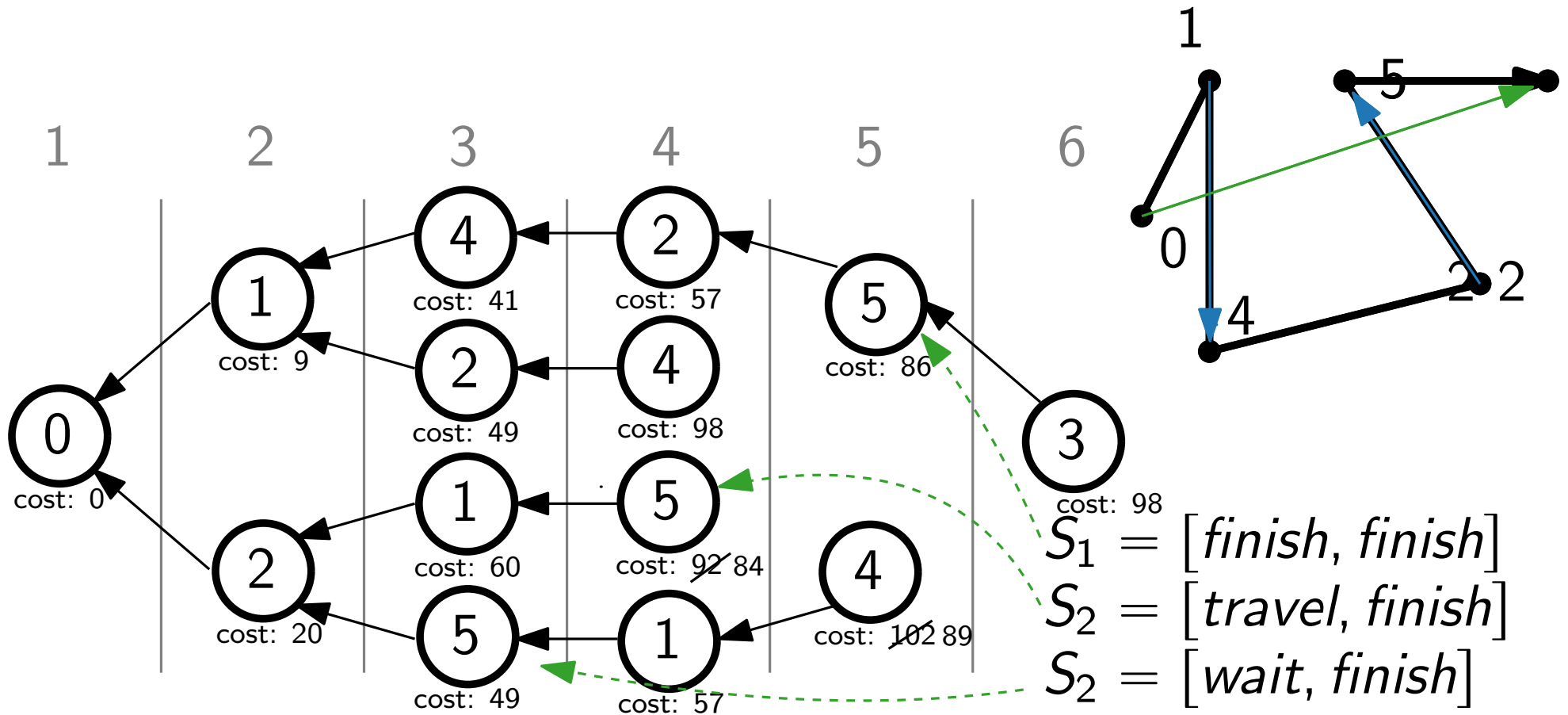


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\Rightarrow for a fixed location $\notin \{0, m\}$ there are 3^{n-1} states.

$\Rightarrow 2n3^{n-1} + 2$ vertices, which yields $O^*(3^{n-1})$ running time.

Running Time and Partial Execution



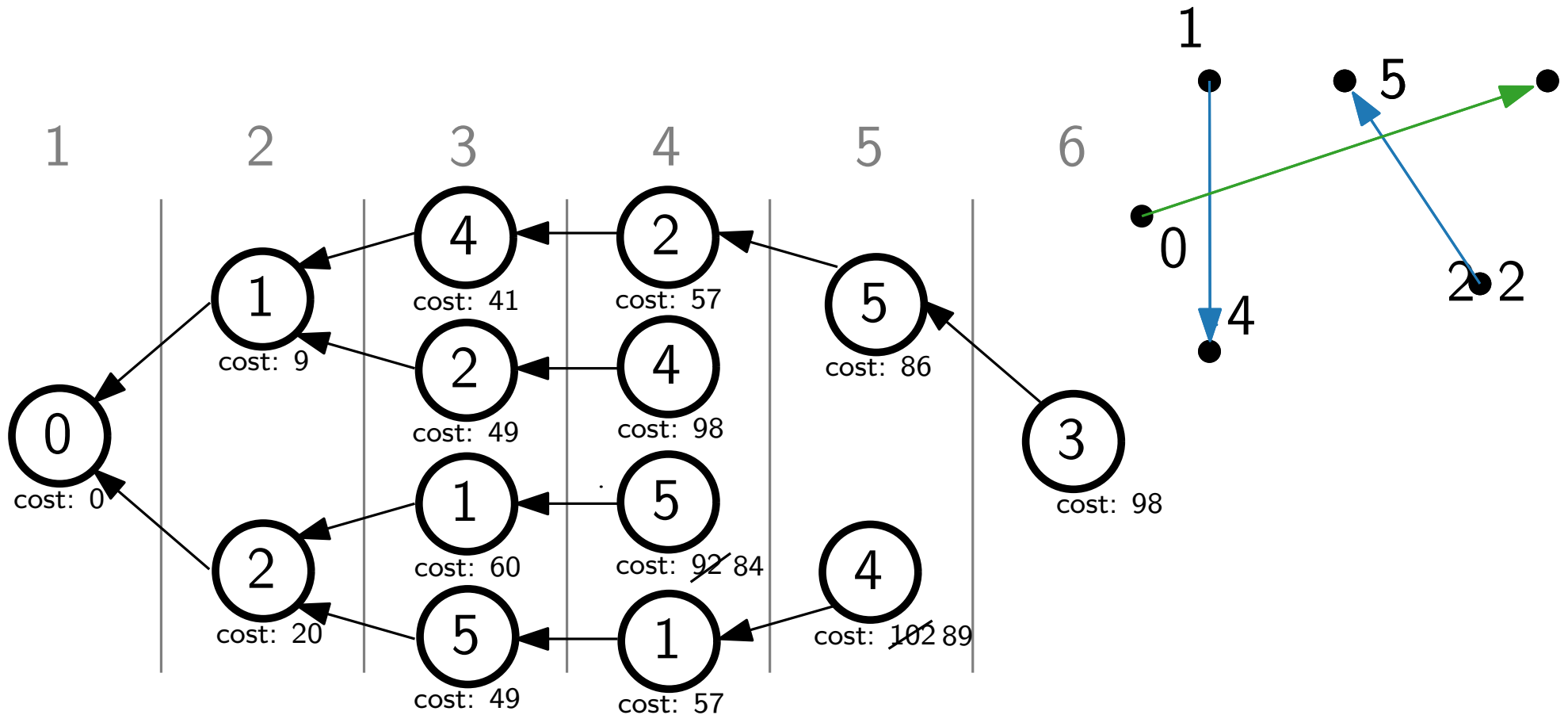
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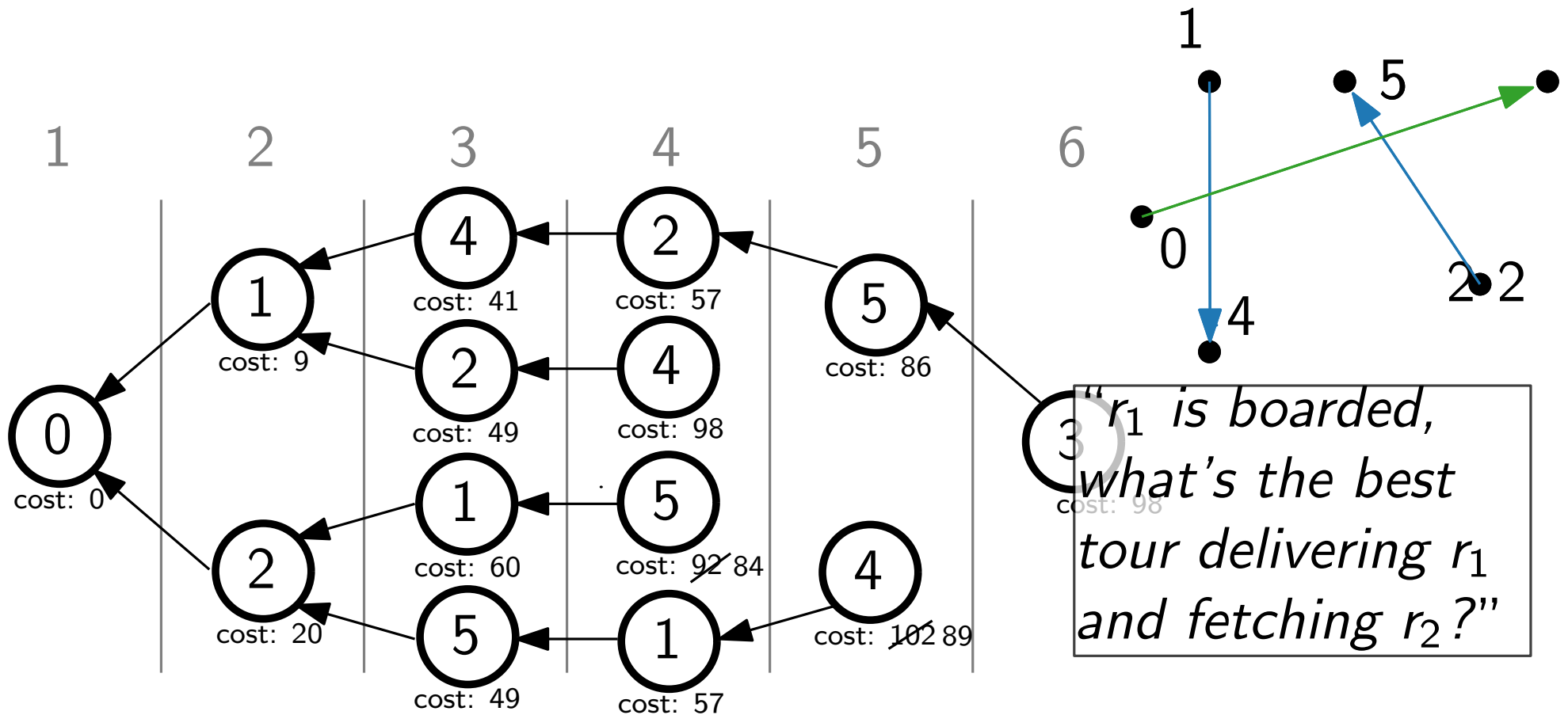
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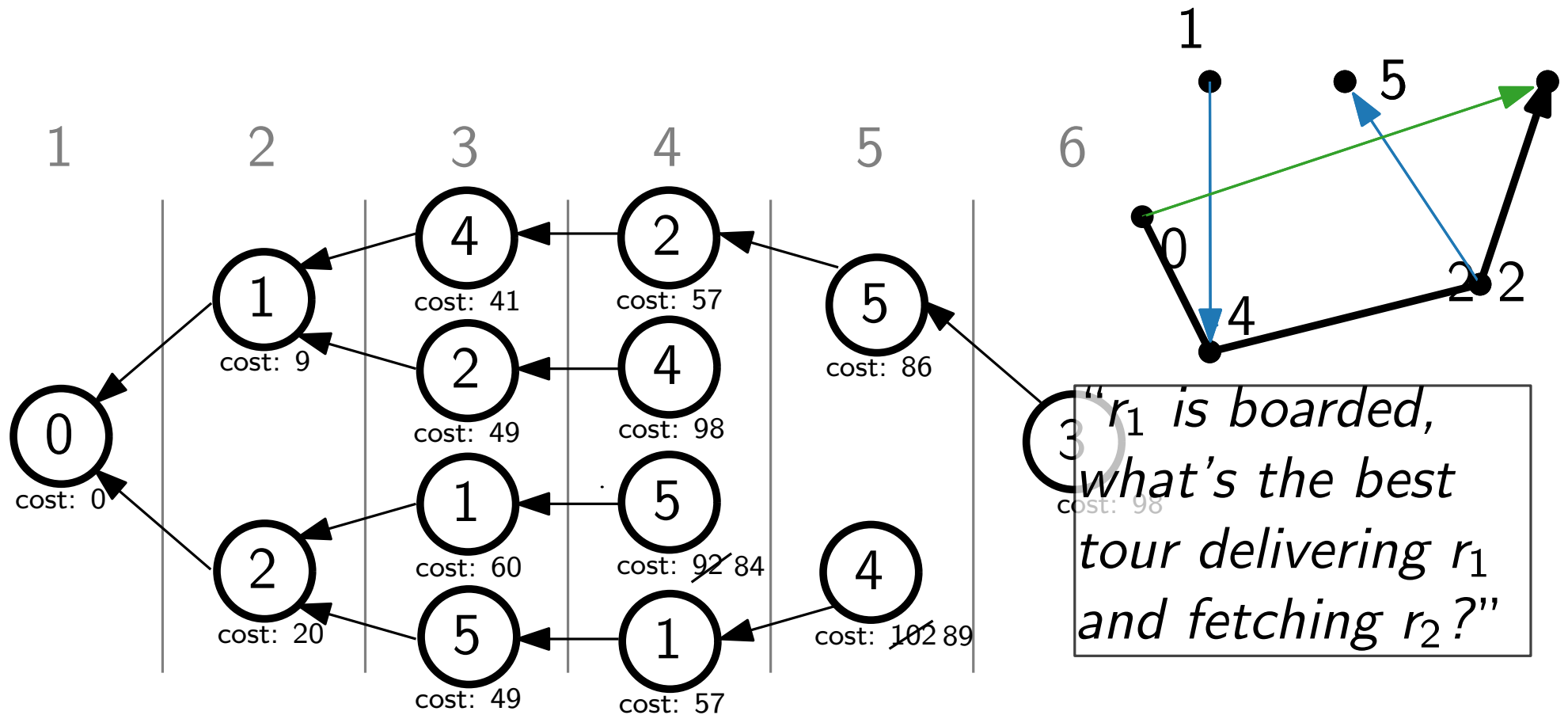
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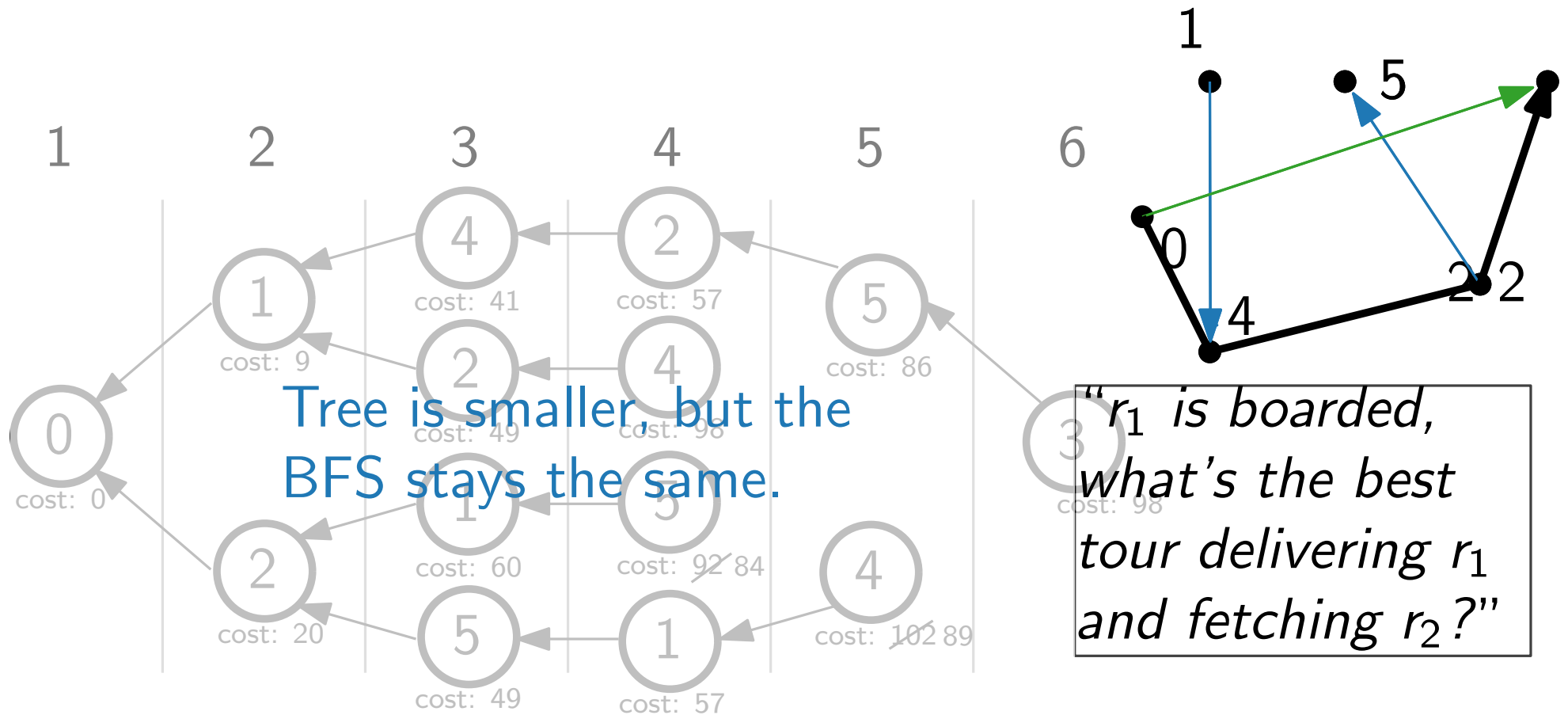
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Evaluation of Realistic Examples

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Rural Scenario

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Regional Scenario

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Intercity Scenario

Evaluation of Realistic Examples

Rural Scenario

Six small villages with \varnothing 1.2 km distance.

Regional Scenario

Intercity Scenario

Evaluation of Realistic Examples

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Six small villages with \varnothing 1.2 km distance.

Regional Scenario

Six small towns with \varnothing 7.2 km distance.

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All optimal tours are unidirectional, recall > 0.9 .

Evaluation of Realistic Examples

Rural Scenario

Six small villages with $\varnothing 1.2$ km distance.

> 70% optimal tours unidirectional, recall < 0.1.

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Six major german cities with $\varnothing 129$ km distance.

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Wait . . . What?!

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