

Order in the Underground – How to Automate the Drawing of Metro Maps

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Karlsruhe University

GD 2005



Outline

- 1 Modeling the Metro Map Problem
 - What is a metro map?
 - Hard and soft constraints
- 2 Our Solution
 - Mixed-integer programming formulation
 - Experiments
 - Labeling
- 3 NP-Hardness
 - Rectilinear vs. octilinear drawing
 - Reduction from planar 3-SAT

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What is a Metro Map?



- schematic diagram for public transport
- visualizes lines and stations
- goal: ease navigation for passengers
 - “How do I get from A to B?”
 - “Where to get off and change trains?”
- distorts geometry and scale
- improves readability
- compromise between
schematic road map ↔ abstract graph

More Formally

The Metro Map Problem

Given: planar embedded graph $G = (V, E)$, $V \subset \mathbb{R}^2$,
line cover \mathcal{L} of paths or cycles in G (the metro lines),
Goal: draw G and \mathcal{L} **nicely**.

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 - *hard* constraints – must be fulfilled,



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- What is a **nice** drawing?
- Look at real-world metro maps drawn by graphic designers and model their design principles as
 - *hard* constraints – must be fulfilled,
 - *soft* constraints – should hold as tightly as possible.



Hard Constraints

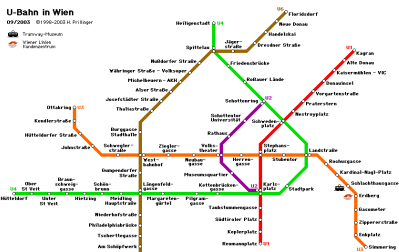
(H1) preserve embedding of G



U-Bahn in Wien

09/2003 01 990-2003 H. Prüßinger

Tramway Museum
Wiener Linien
Kundenzentrum



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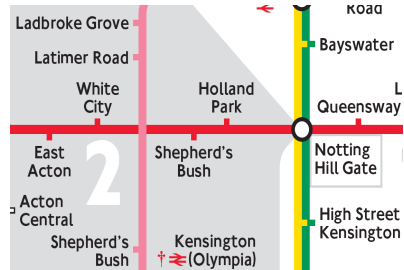
Hard Constraints

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- (H3) draw each edge e with length $\geq \ell_e$
- (H4) keep vertices d_{\min} away from non-incident edges



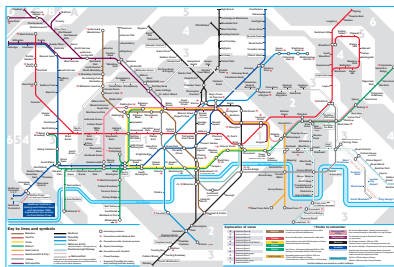
Soft Constraints

(S1) draw metro lines with few bends



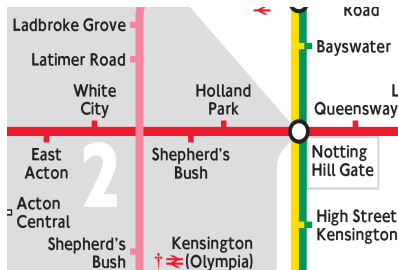
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- (S1) draw metro lines with few bends
- (S2) keep total edge length small



Soft Constraints

- (S1) draw metro lines with few bends
- (S2) keep total edge length small
- (S3) draw each octilinear edge similar to its geographical orientation: keep its **relative position**



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Mathematical Programming

- **Linear Programming**: efficient optimization method for
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Theorem (Nöllenburg & Wolff GD'05)

The problem MetroMapLayout can be formulated as a MIP s.th.

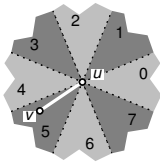
*linear constraints \rightarrow hard constraints,
objective function \rightarrow soft constraints.*



Example: Octilinearity and Relative Position



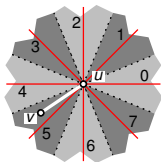
Example: Octilinearity and Relative Position



Sectors

- for each vtx. u partition plane into sectors 0–7
 - here: $\text{sec}(u, v) = 5$ (input)

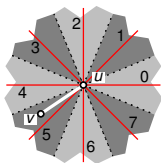
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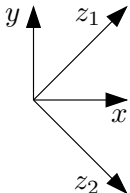
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 - e.g., $\text{dir}(u, v) = 4$ (output)

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Coordinates

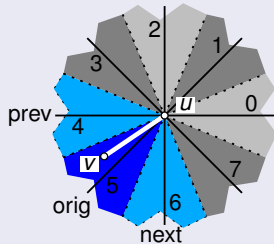
assign z_1 - and z_2 -coordinates to each vertex v :

- $z_1(v) = x(v) + y(v)$
- $z_2(v) = x(v) - y(v)$



Example: Octilinearity and Relative Position

Goal

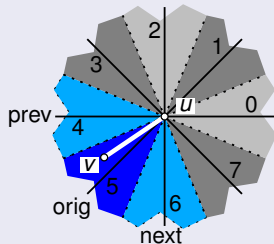


Draw edge uv

- with minimum length ℓ_{uv}
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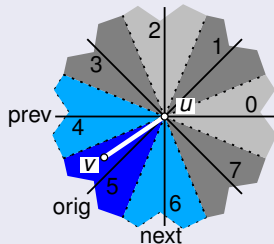
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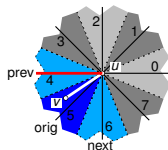
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Binary Variables

$$\alpha_{\text{prev}}(u, v) + \alpha_{\text{orig}}(u, v) + \alpha_{\text{next}}(u, v) = 1$$



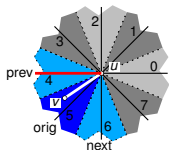
Example: Octilinearity and Relative Position



Previous Sector

$$\begin{aligned} y(u) - y(v) &\leq M(1 - \alpha_{\text{prev}}(u, v)) \\ -y(u) + y(v) &\leq M(1 - \alpha_{\text{prev}}(u, v)) \\ x(u) - x(v) &\geq -M(1 - \alpha_{\text{prev}}(u, v)) + \ell_{uv} \end{aligned}$$

Example: Octilinearity and Relative Position

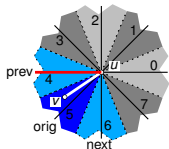


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Example: Octilinearity and Relative Position



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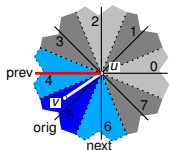
How does this work?

Case 1: $\alpha_{\text{prev}}(u, v) = 0$

$$\begin{aligned} y(u) - y(v) &\leq M \\ -y(u) + y(v) &\leq M \\ x(u) - x(v) &\geq \ell_{uv} - M \end{aligned}$$



Example: Octilinearity and Relative Position



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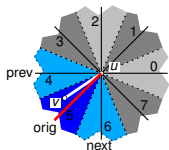
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Case 2: $\alpha_{\text{prev}}(u, v) = 1$

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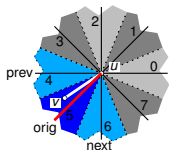
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Original Sector

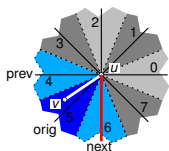
$$\begin{aligned} z_2(u) - z_2(v) &\leq M(1 - \alpha_{\text{orig}}(u, v)) \\ -z_2(u) + z_2(v) &\leq M(1 - \alpha_{\text{orig}}(u, v)) \\ z_1(u) - z_1(v) &\geq -M(1 - \alpha_{\text{orig}}(u, v)) + 2\ell_{uv} \end{aligned}$$

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Next Sector

$$\begin{aligned} x(u) - x(v) &\leq M(1 - \alpha_{\text{next}}(u, v)) \\ -x(u) + x(v) &\leq M(1 - \alpha_{\text{next}}(u, v)) \\ y(u) - y(v) &\geq -M(1 - \alpha_{\text{next}}(u, v)) + \ell_{uv} \end{aligned}$$

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Results – Vienna

Input



Input	$ V $	$ E $	lines
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reduced	44	50	

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normal	39363	9960
improved	23226	6048
heuristic 1	5703	1800
heuristic 2	1875	872



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^{*}) 29 seconds w/o proof of opt.

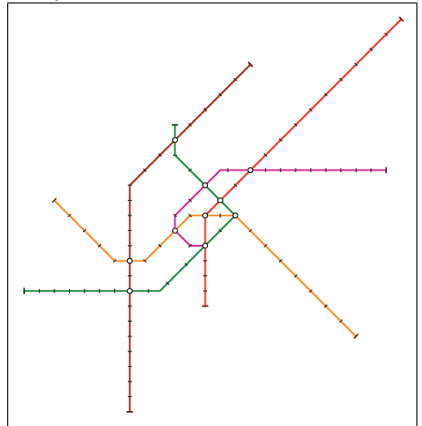


Results – Vienna

Input



Output

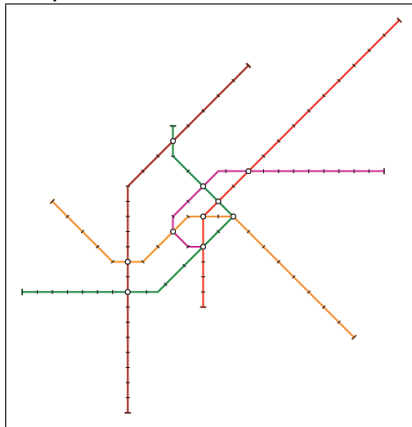


Results – Vienna

Official map

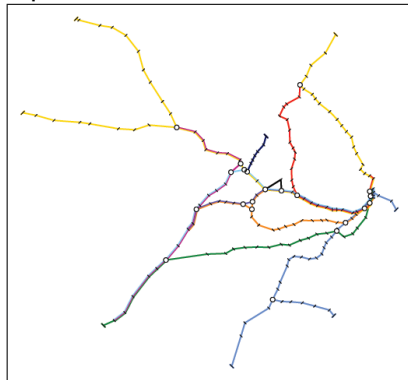


Output



Results – Sydney

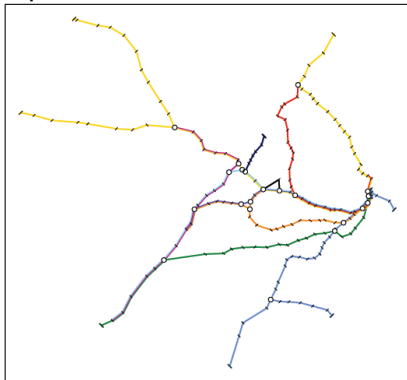
Input



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Results – Sydney

Input



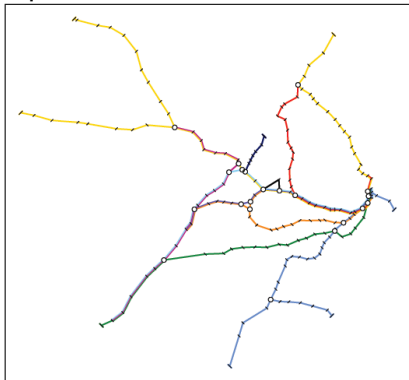
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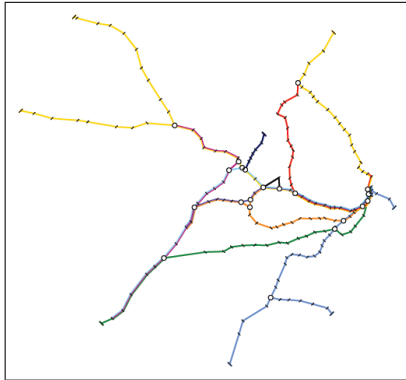
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*) 22 minutes w/o proof of opt.

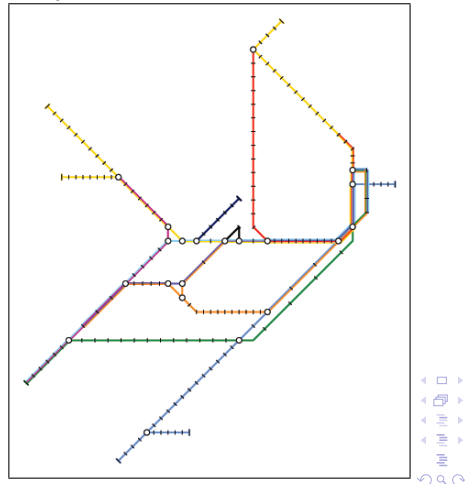


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Input

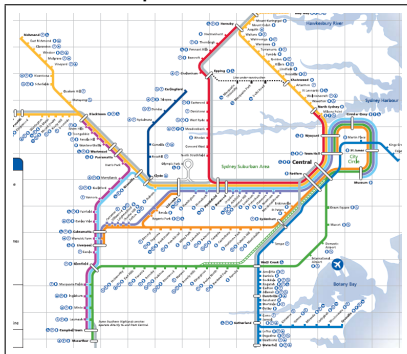


Output

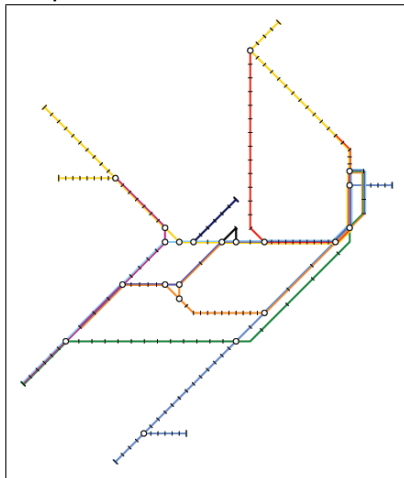


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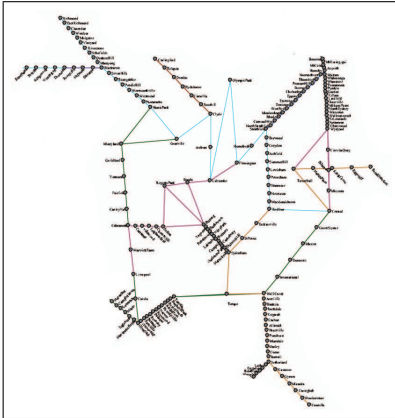


Output

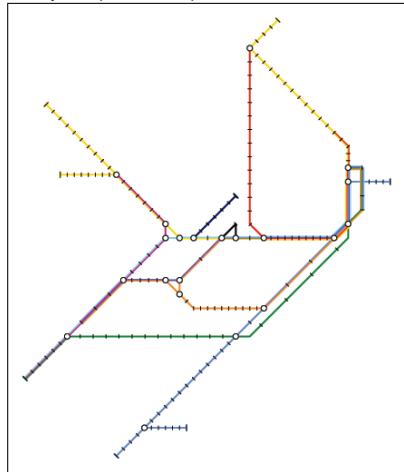


Sydney: Related Work

[Hong et al.: GD04] 7.6 sec.

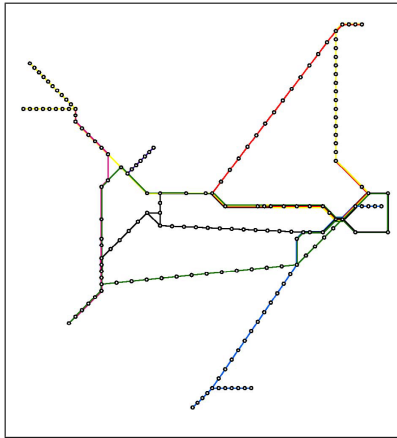


Output (22 min.)

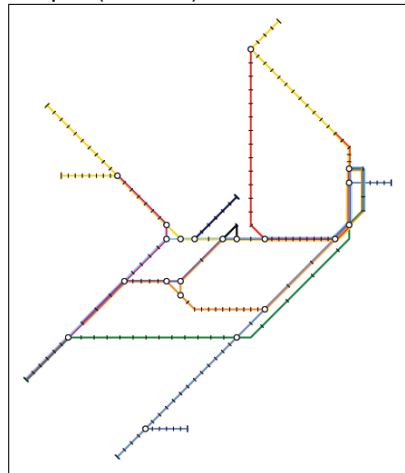


Sydney: Related Work

[Stott & Rodgers: IV04] reduced: 4 min.

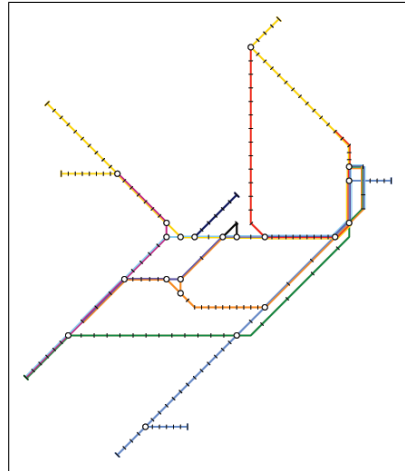
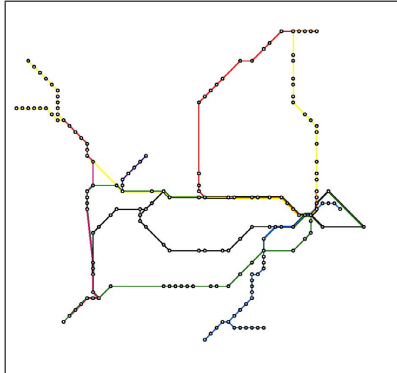


Output (22 min.)

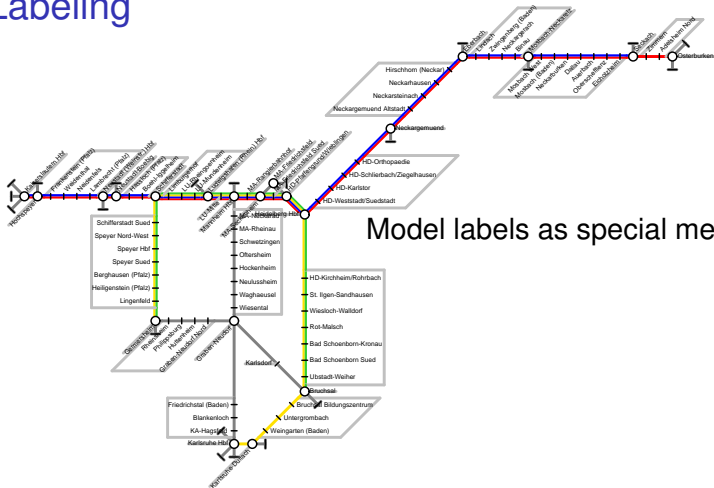


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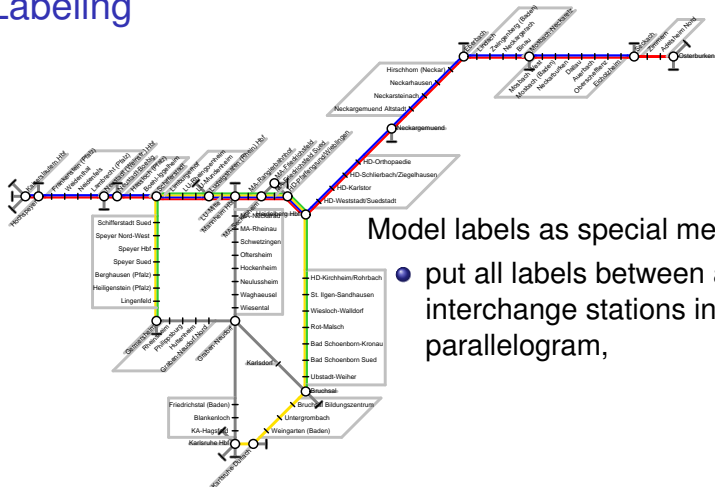
[Stott & Rodgers: IV04] normal: 28 min. Output (22 min.)



Model labels as special metro lines:



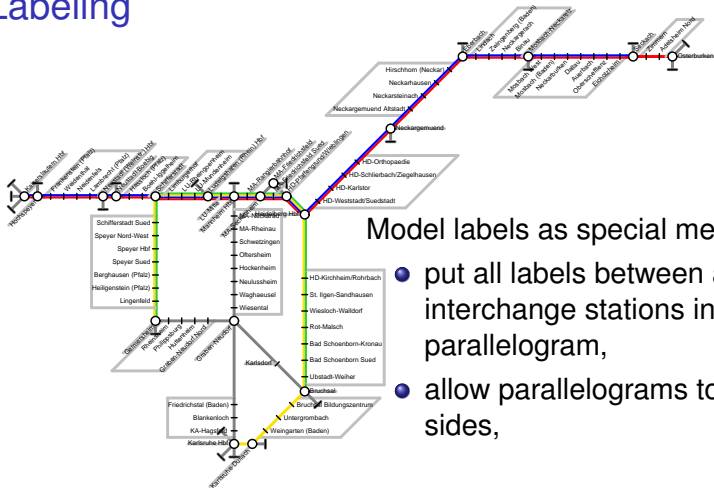
Labeling



Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,

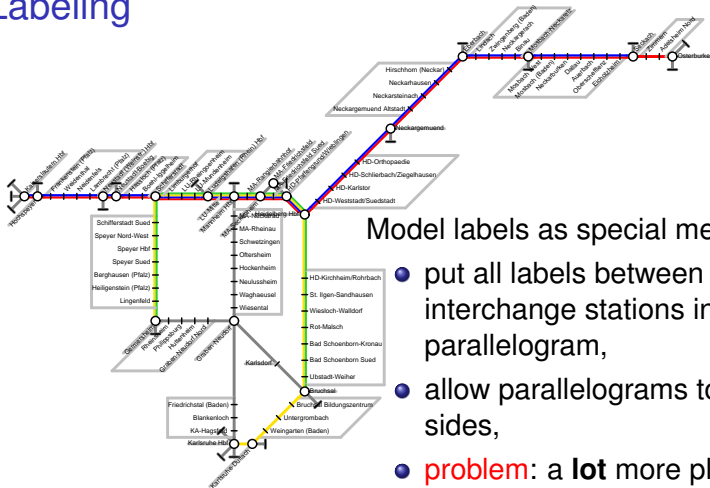
Labeling



Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,
- allow parallelograms to change sides,

Labeling

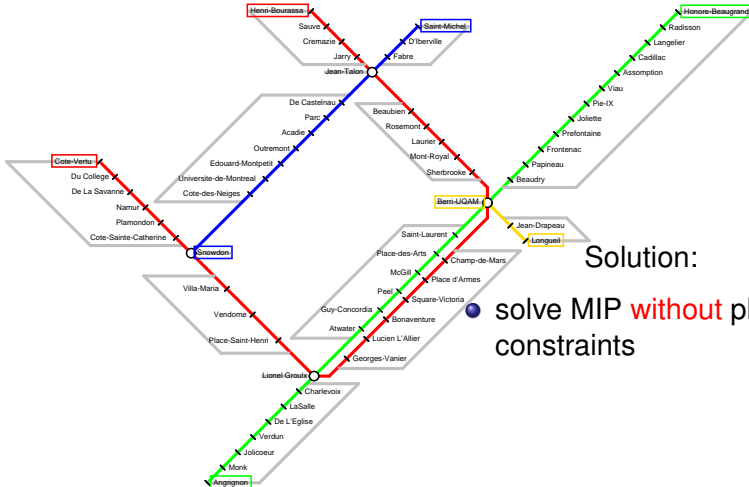


Model labels as special metro lines:

- put all labels between a pair of interchange stations into one parallelogram,
- allow parallelograms to change sides,
- **problem**: a **lot** more planarity constraints :-)



Labeling

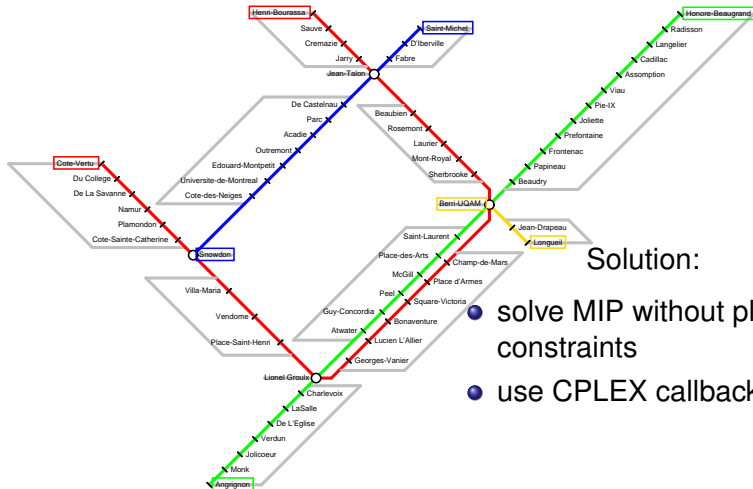


Solution:

● solve MIP **without** planarity constraints



Labeling

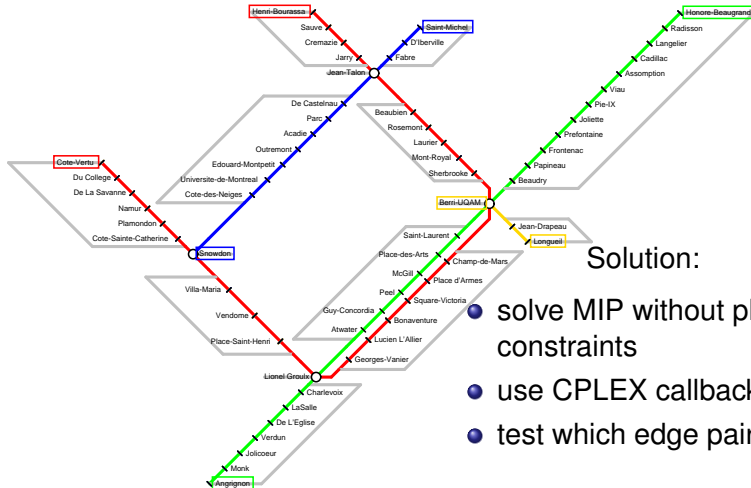


Solution:

- solve MIP without planarity constraints
- use CPLEX callback fct.



Labeling

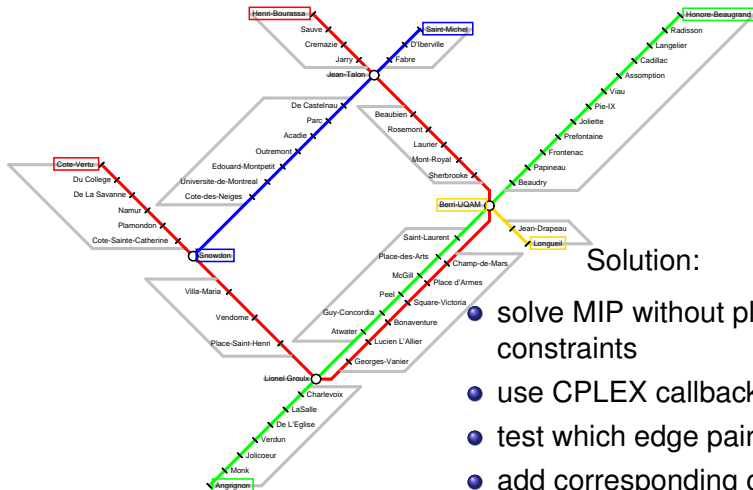


Solution:

- solve MIP without planarity constraints
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- test which edge pairs cross



Labeling

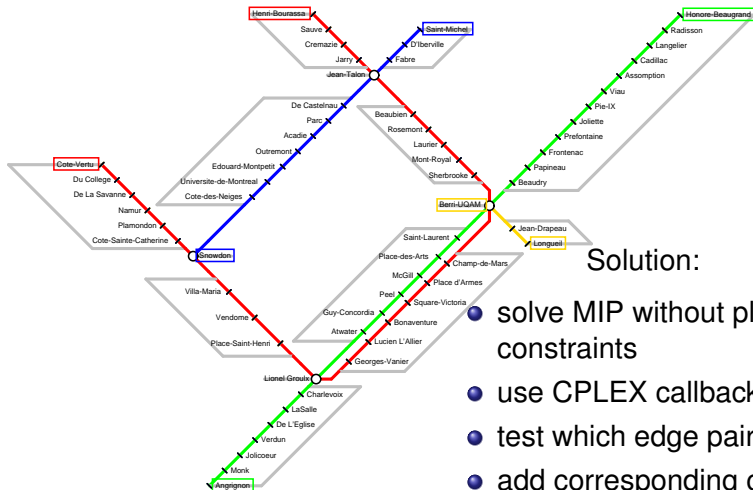


Solution:

- solve MIP without planarity constraints
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- add corresponding constr.



Labeling

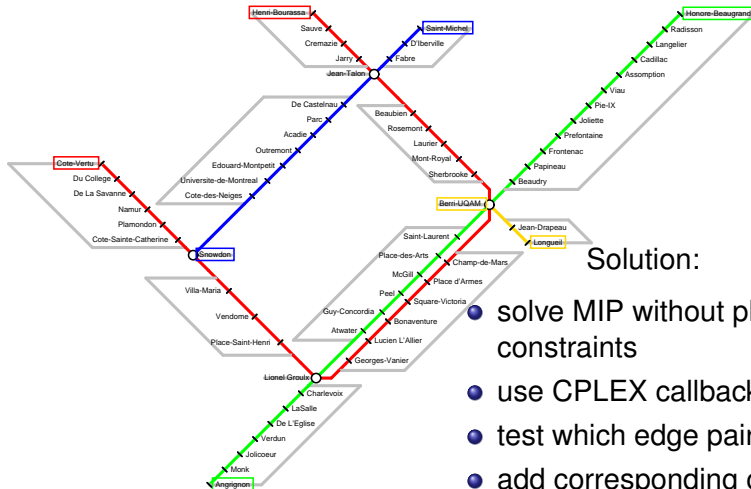


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Labeling



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Montréal: 17 min.

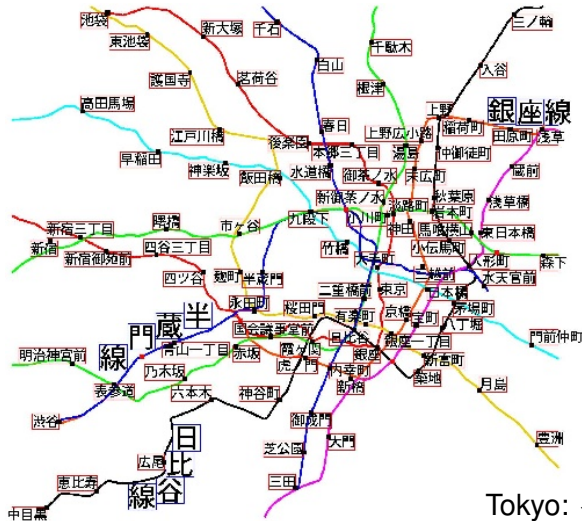
Labeling



Wien: 1 day.



Labeling



Tokyo: < 10 sec.

[Kameda & Imai: IEICE'03]



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- 2 Our Solution
 - Mixed-integer programming formulation
 - Experiments
 - Labeling
- 3 NP-Hardness
 - Rectilinear vs. octilinear drawing
 - Reduction from planar 3-SAT

Another Problem

RECTILINEARGRAPHDRAWING Decision Problem

Given a planar embedded graph G with max degree 4.
Is there a drawing of G that

- preserves the embedding,
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Our Problem

METROMAPLAYOUT Decision Problem

Given a planar embedded graph G with max degree 8.

Is there a drawing of G that

- preserves the embedding,
- uses straight-line edges,
- is **octilinear**?

Theorem (Nöllenburg Master's Thesis '05)

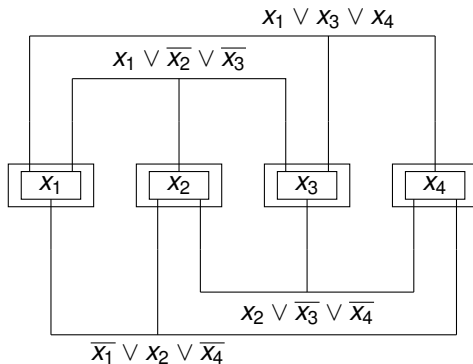
METROMAPLAYOUT is **NP-hard**.

Proof.

Reduction from PLANAR 3-SAT to METROMAPLAYOUT.

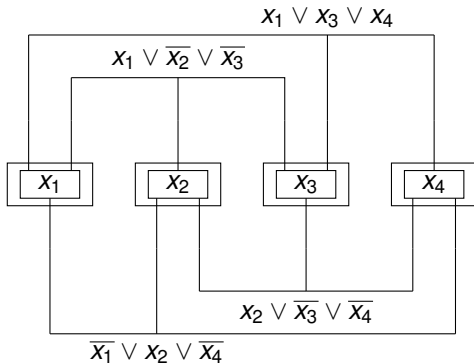


Outline of the Reduction



Input: planar 3-SAT formula $\varphi =$
 $(x_1 \vee x_3 \vee x_4) \wedge (x_1 \vee \overline{x_2} \vee \overline{x_3}) \wedge \dots$

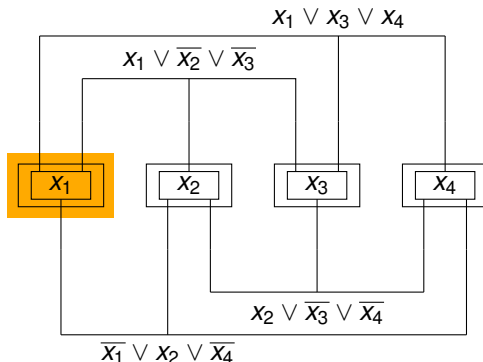
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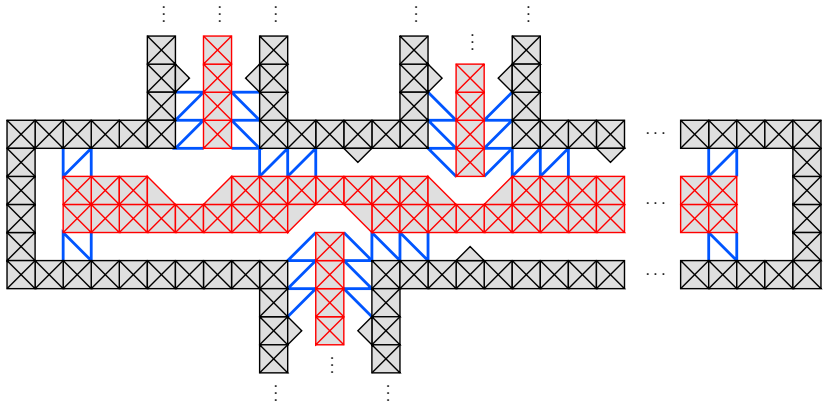
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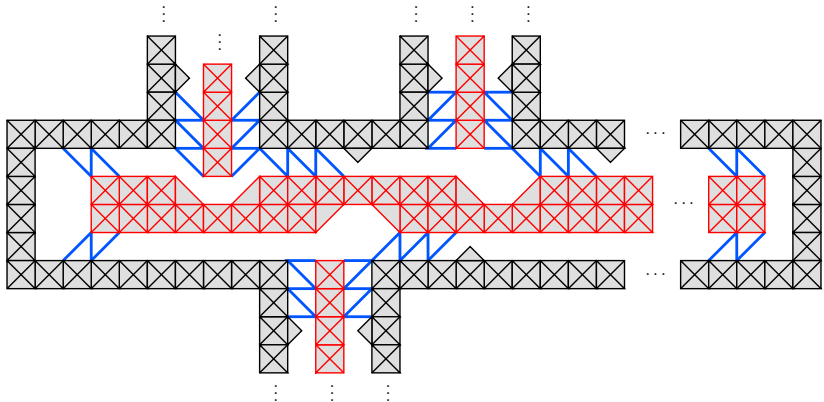
Variable Gadget



$x = \text{true}$

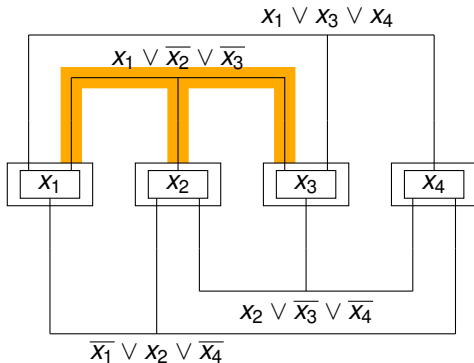


Variable Gadget



$x = \text{false}$

Outline of the Reduction

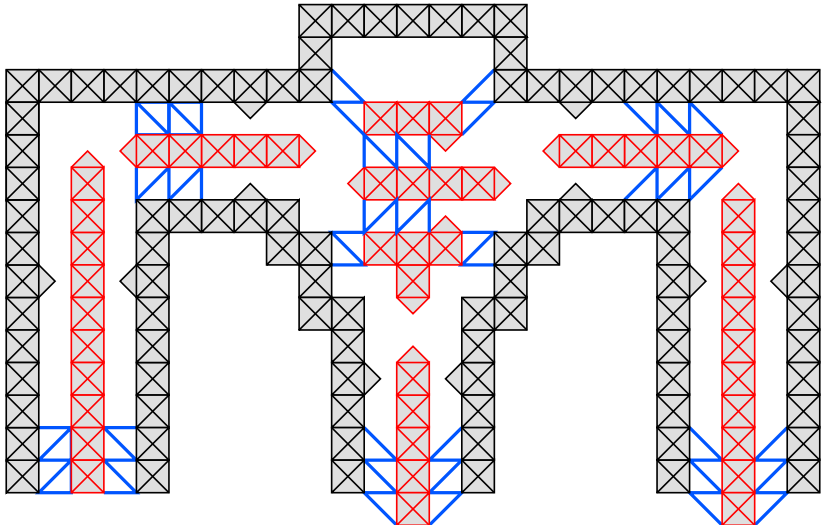


Input: planar 3-SAT formula $\varphi = (x_1 \vee x_3 \vee x_4) \wedge (x_1 \vee \overline{x_2} \vee \overline{x_3}) \wedge \dots$

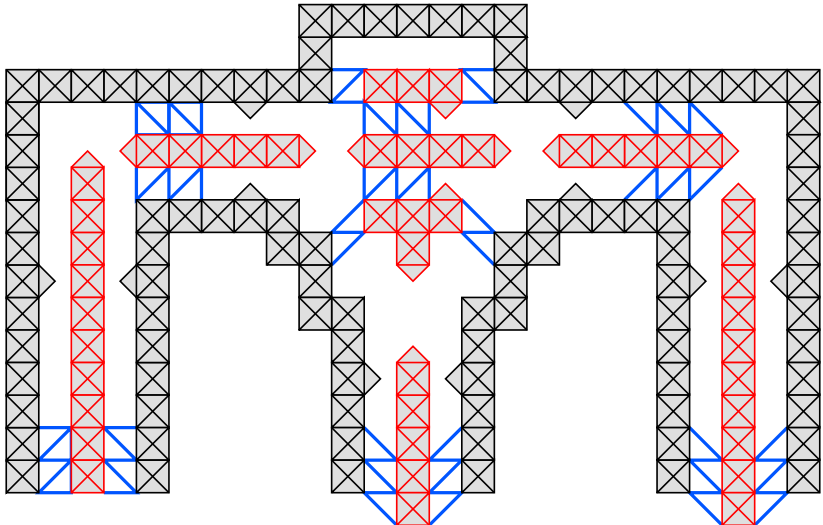
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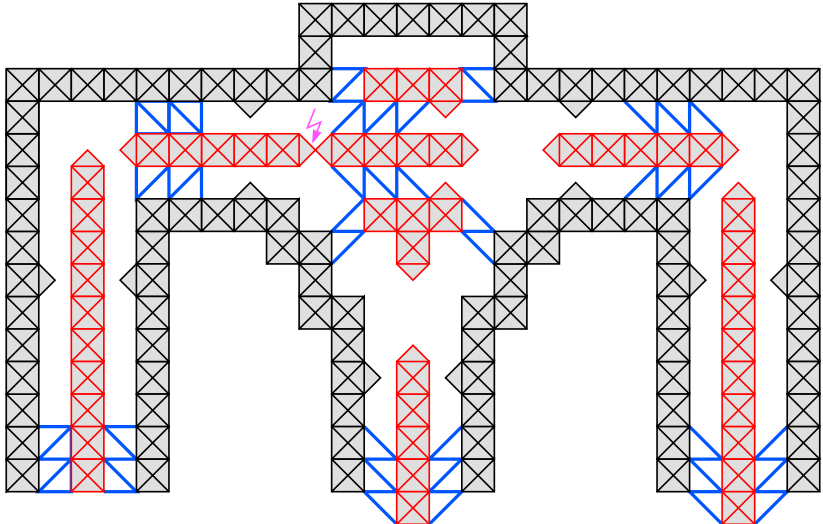
Clause Gadget



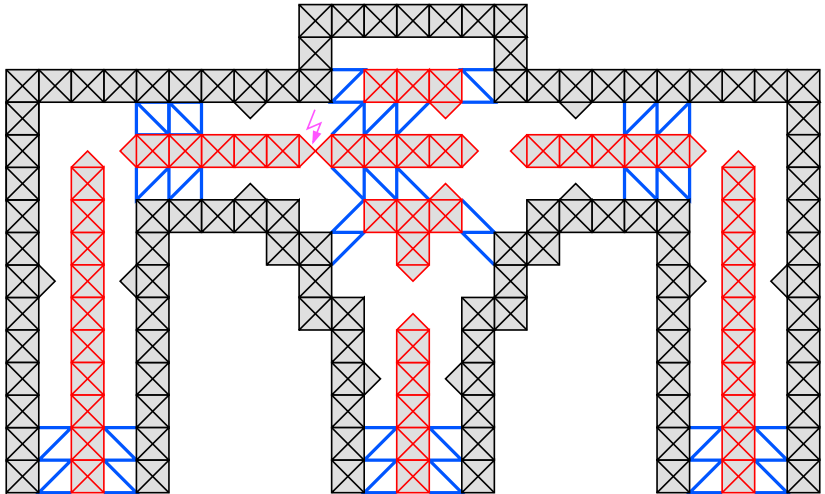
Clause Gadget



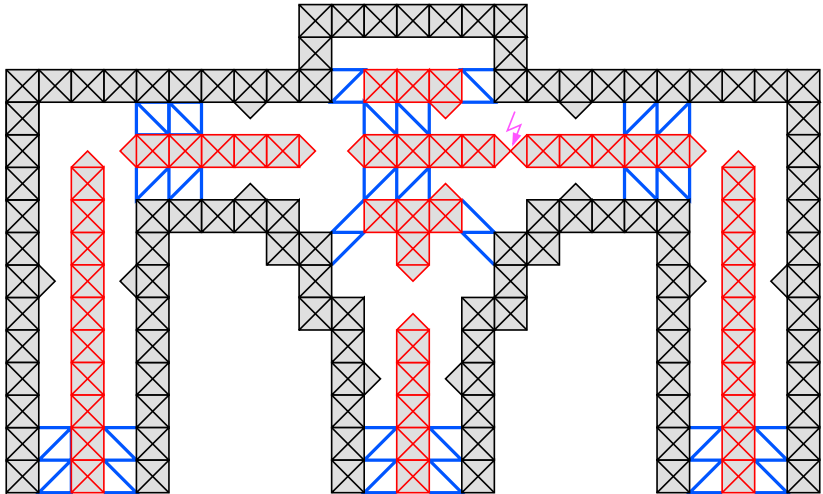
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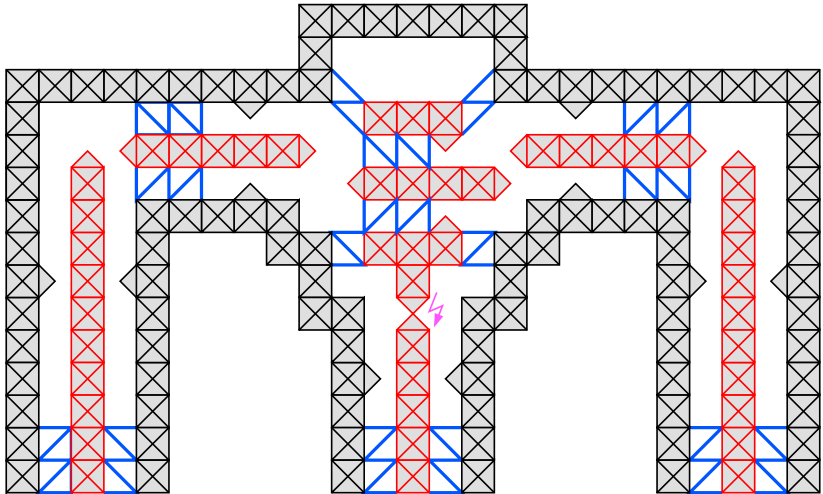
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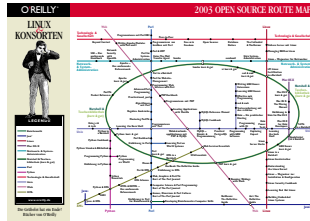
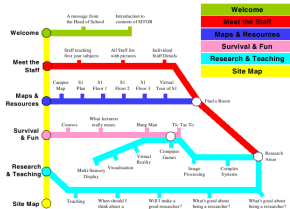
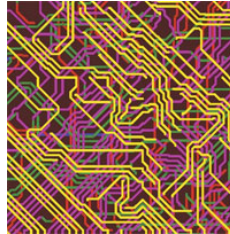
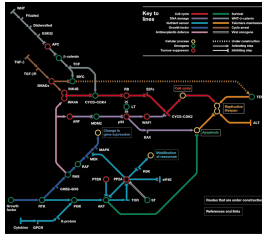
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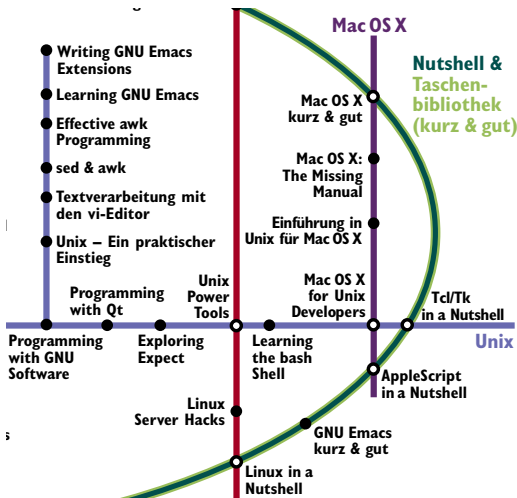
Clause Gadget



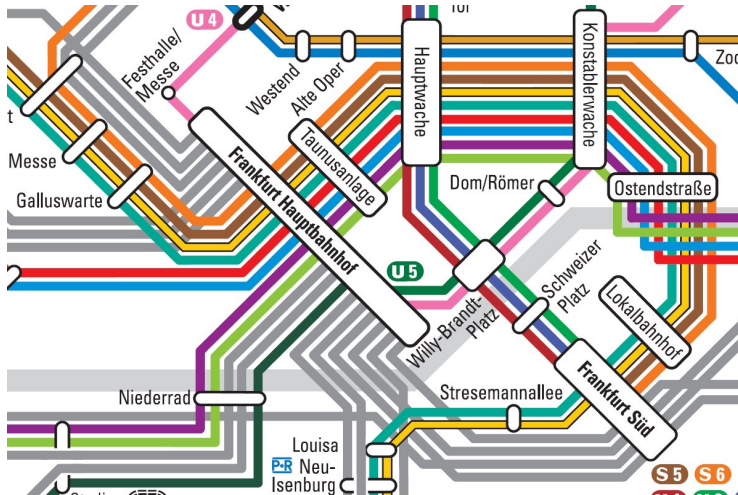
Other applications



Clipping



To do: rectangular stations & multi-edges



Summary (metro maps)

- METROMAPLAYOUT is NP-hard.
- Formulated and implemented MIP.
- Our MIP can draw *any* kind of sketch “nicely”.
- Results comparable to manually designed maps.
- Reduced MIP size & runtime drastically.

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To Do

- rectangular stations
- multi-edges
- user interaction (e.g., fixing certain edge directions)

