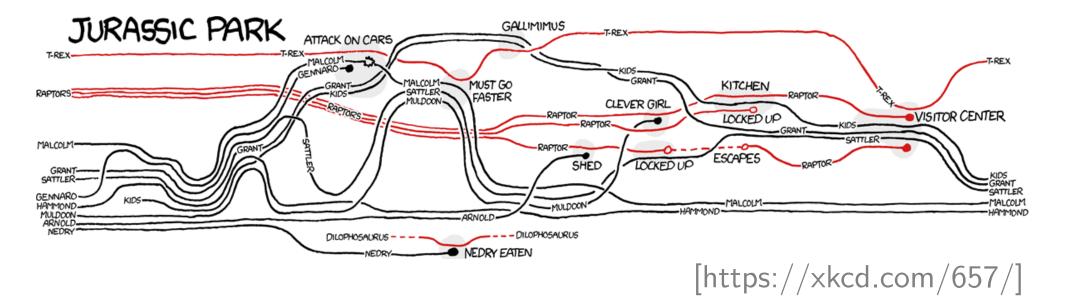


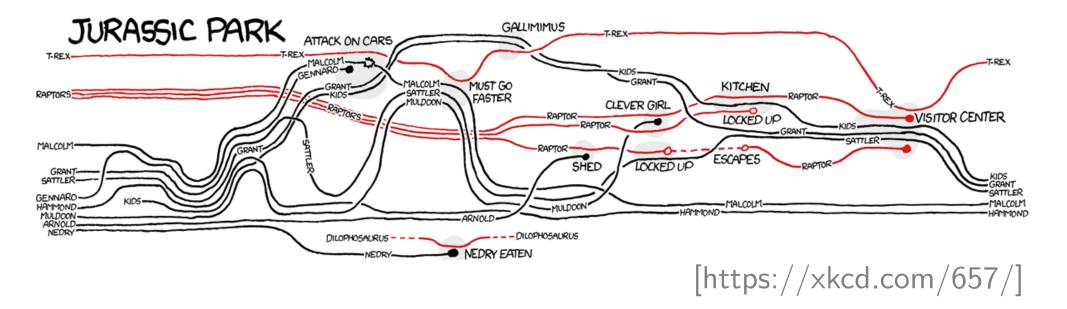
Computing Storyline Visualizations with Few Block Crossings

Thomas C. van Dijk Peter Markfelder **Fabian Lipp** Alexander Wolff

Storyline Visualizations



Storyline Visualizations

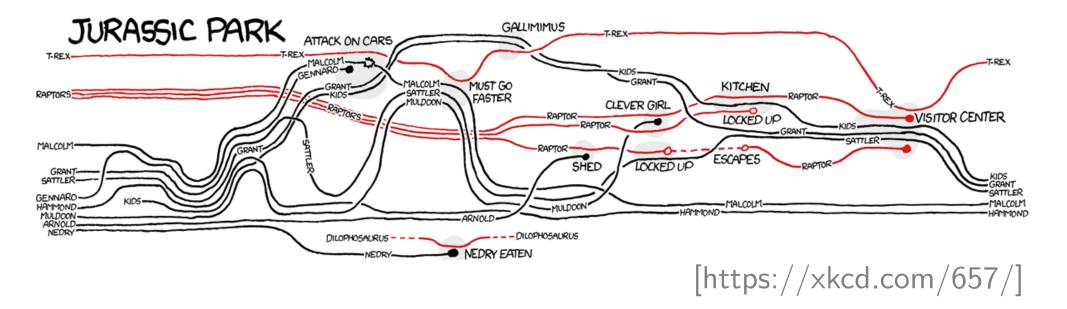


Design considerations for storyline drawings:

- Line wiggles
- White space gaps
- Line crossings

[Tanahashi & Ma, TVCG12]

Storyline Visualizations



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Aim: Drawing with a minimum number of crossings

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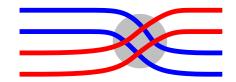
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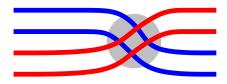
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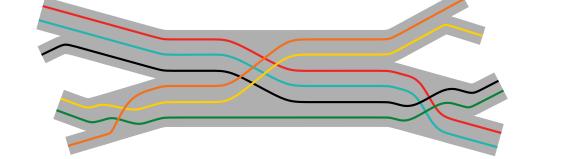
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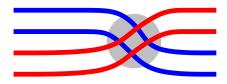




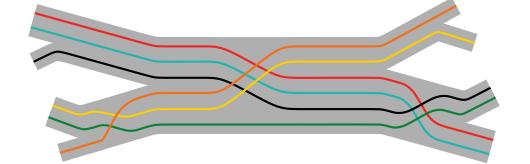
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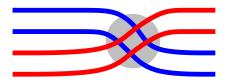


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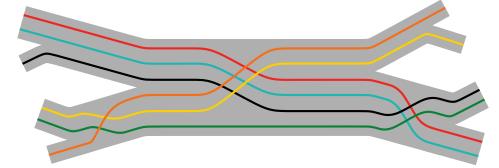


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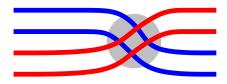
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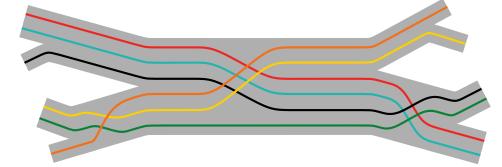
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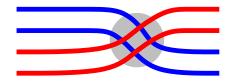


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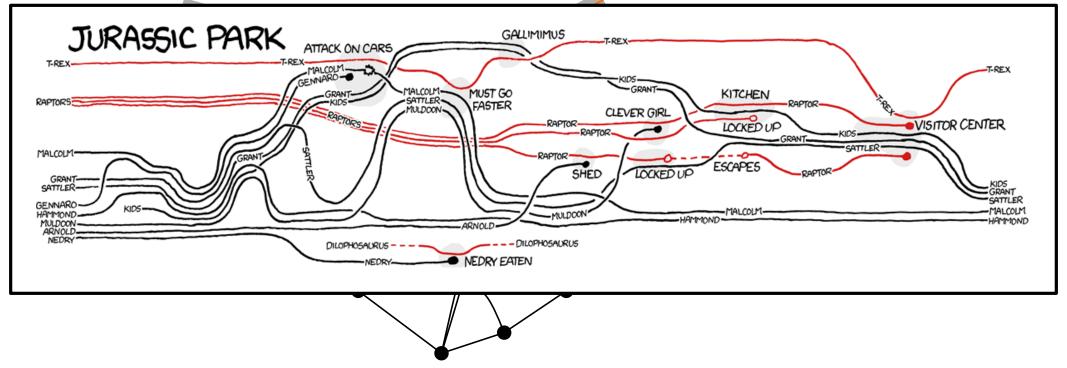
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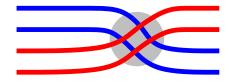
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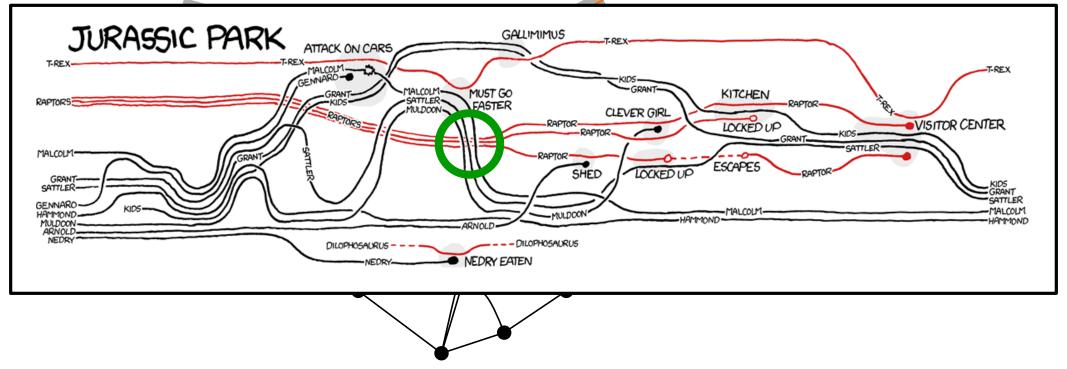
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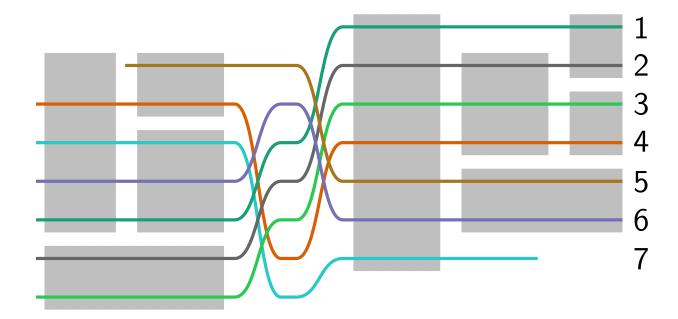


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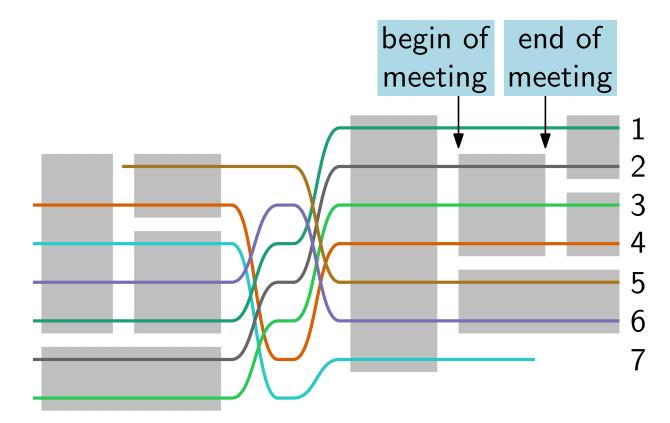
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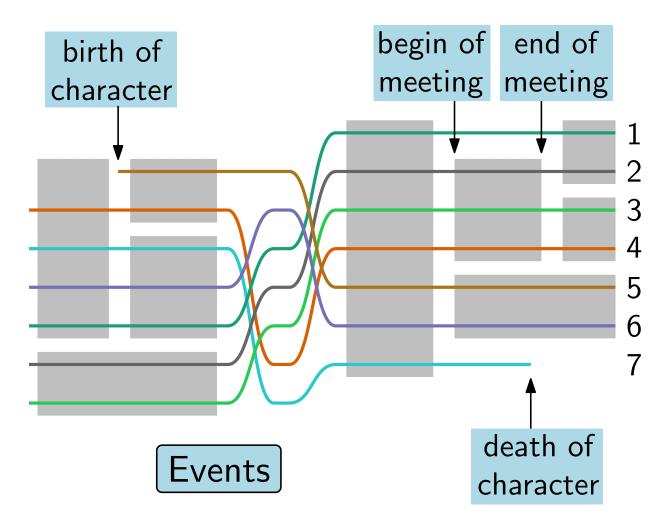
Meeting: set of characters, start and end time



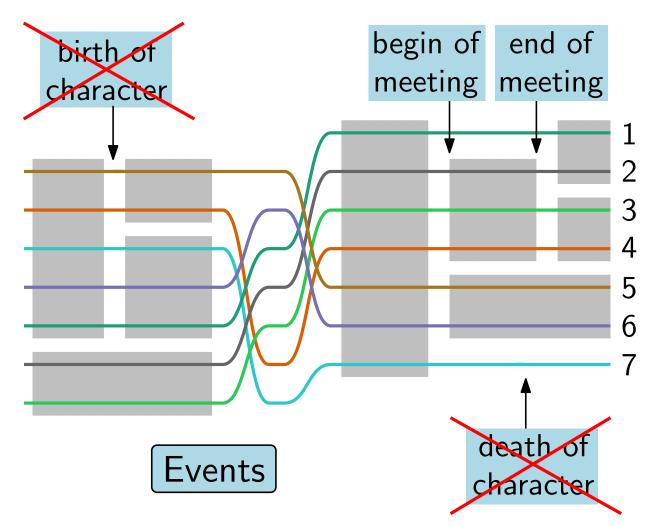
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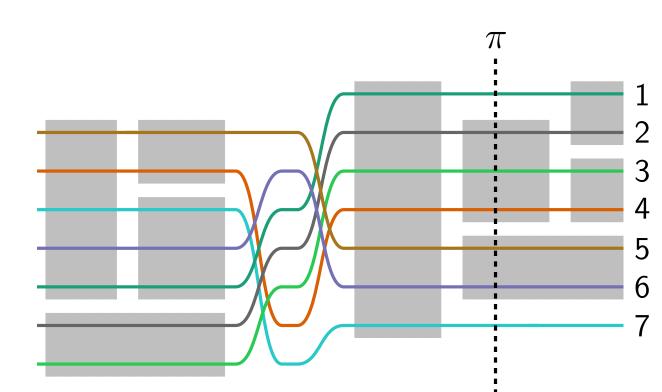


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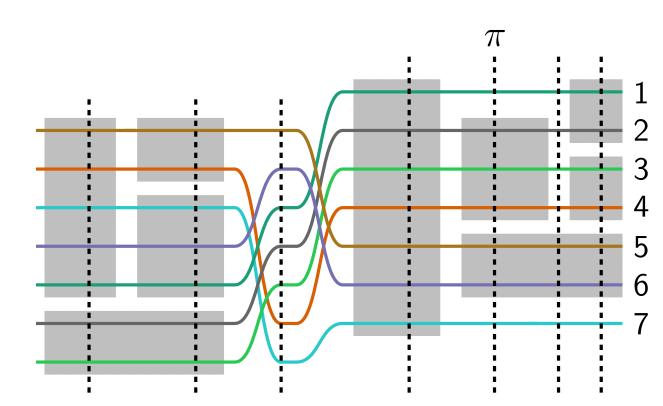
No births and deaths in this talk – but in the paper.

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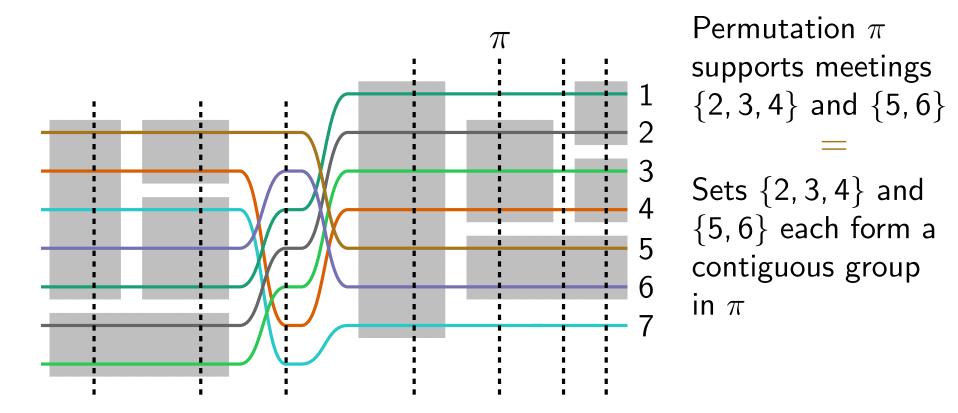
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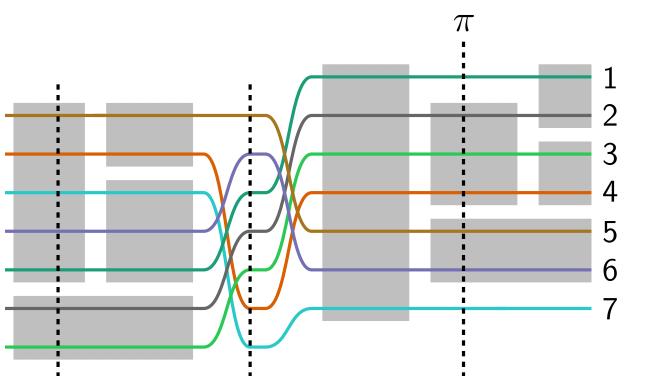
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Find a **shortest** sequence of permutations such that meetings are supported in the right order

...adjacent permutations differ by at most one block crossing

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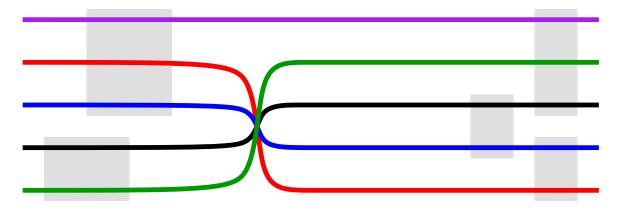


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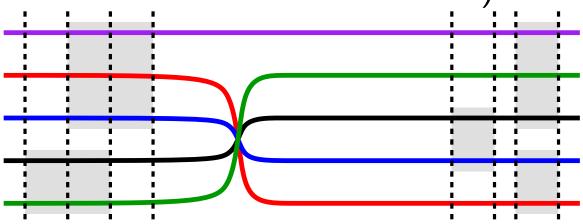
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Reduce to MLCM-TC (Multi-Layer Crossing Minimization Problem with Tree Constraints)

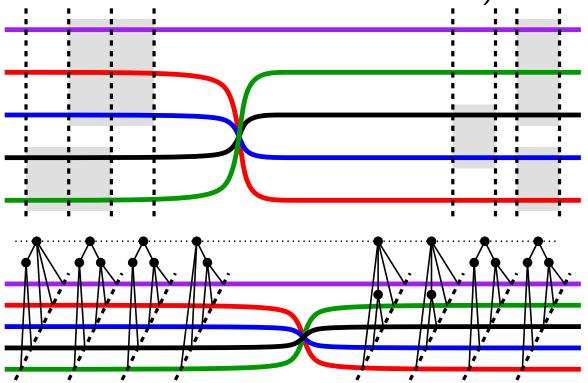


Reduce to MLCM-TC (Multi-Layer Crossing Minimization Problem with Tree Constraints)



Each event corresponds to a layer

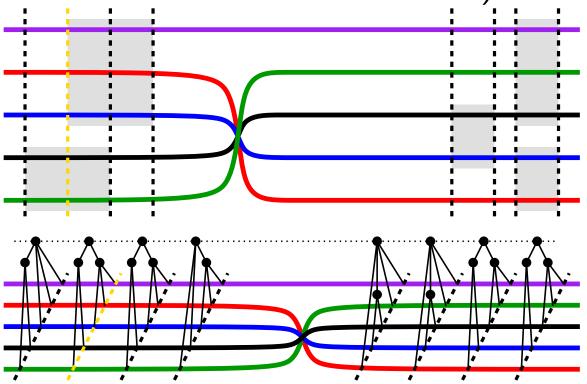
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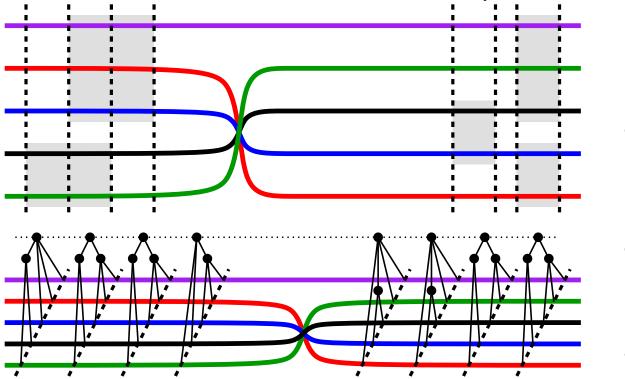
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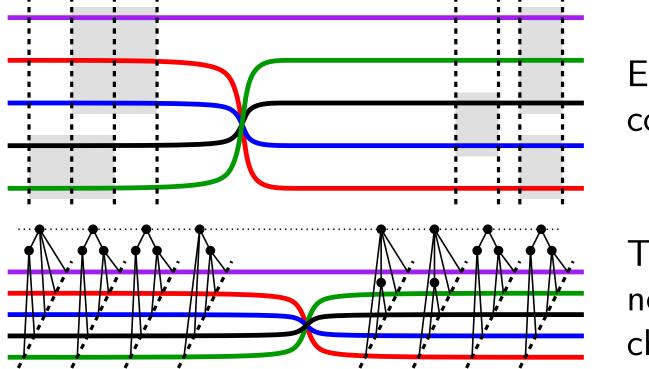


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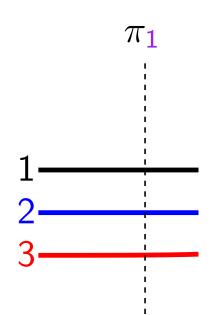
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Use ILP to solve MLCM-TC

Variables describing the order in each permutation: x_{ij}^{r} characters

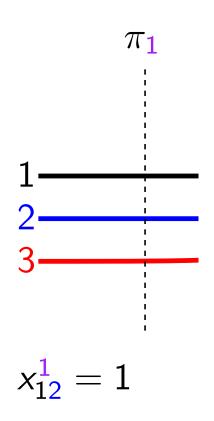
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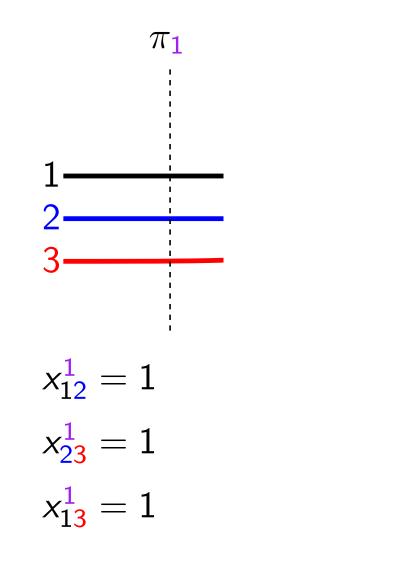
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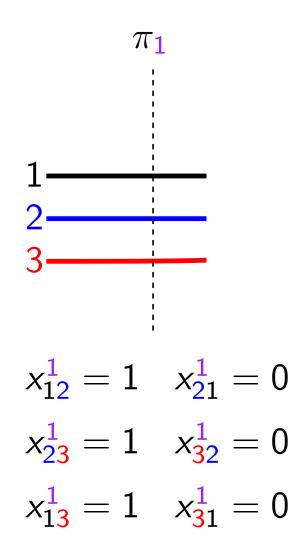
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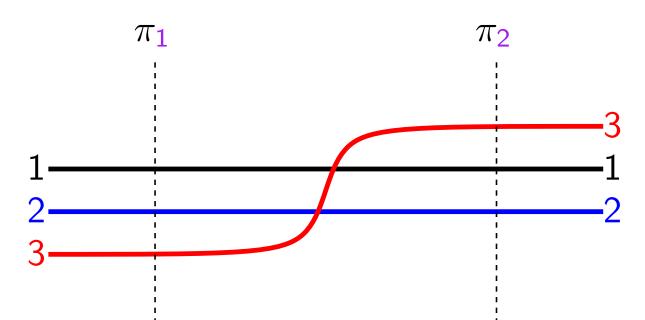
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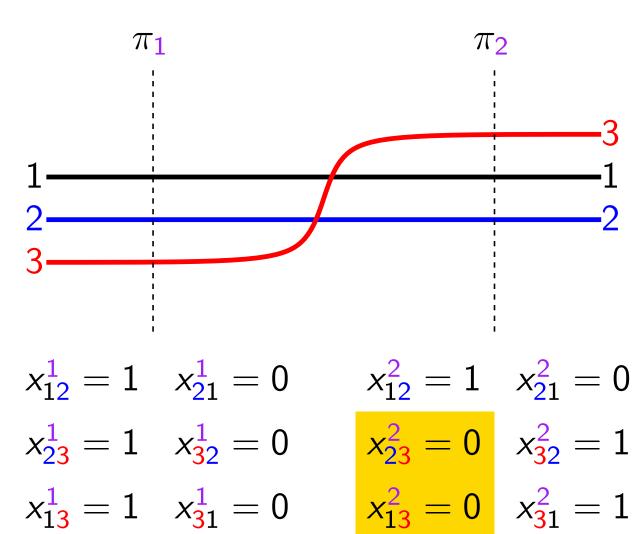
layer



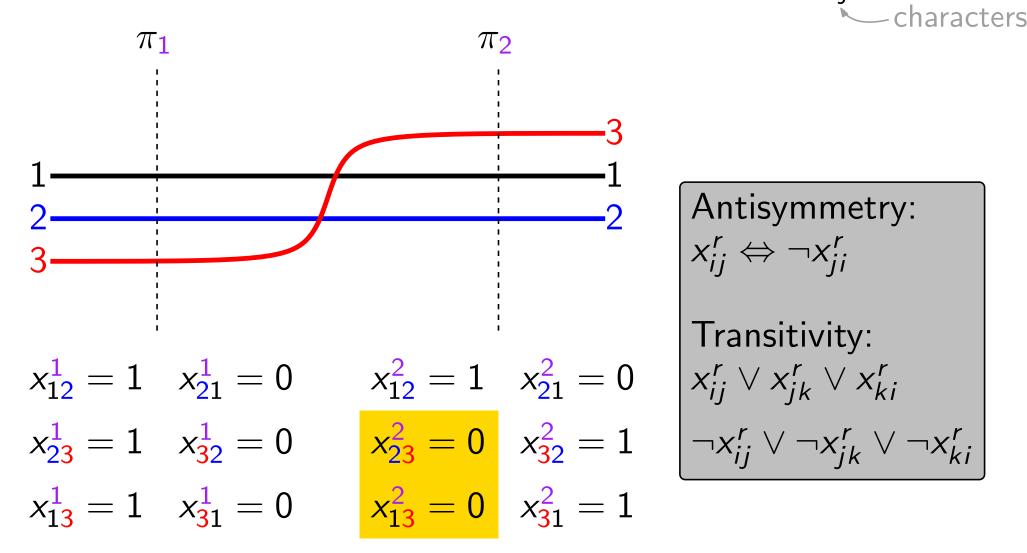
$$x_{12}^{1} = 1 \quad x_{21}^{1} = 0$$
$$x_{23}^{1} = 1 \quad x_{32}^{1} = 0$$
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layer



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Easy to count pairwise crossings using x_{ij}^r :

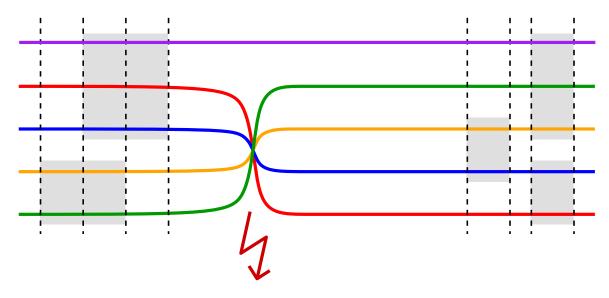
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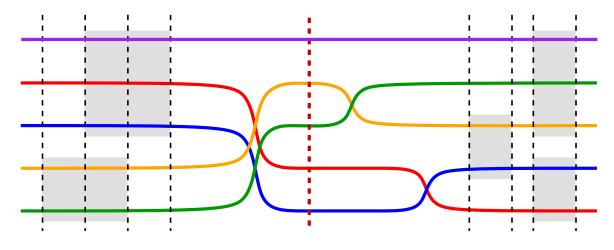


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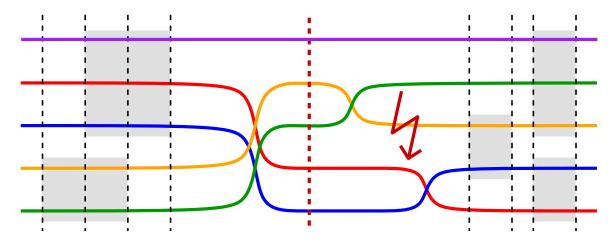
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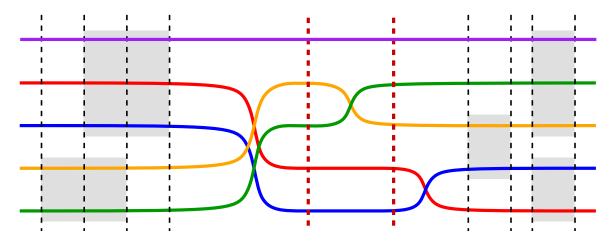
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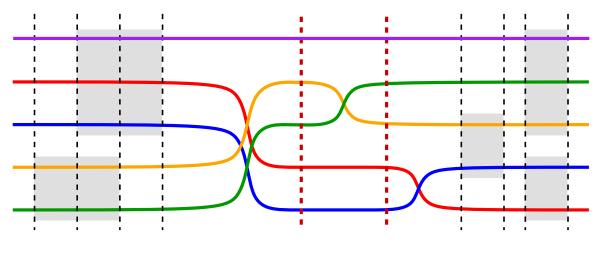
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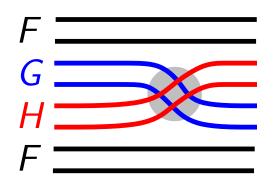
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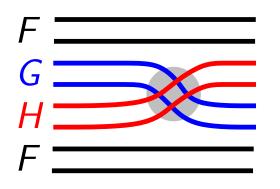


Add more permutations

Prescribe maximum number of permutations



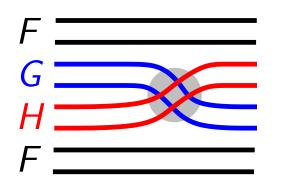
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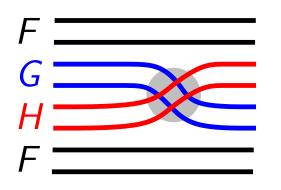
Constraints:

Exactly characters of G and H cross each other



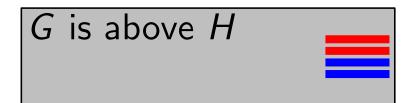
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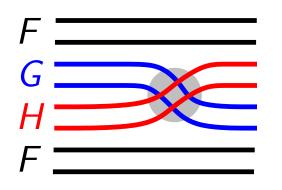
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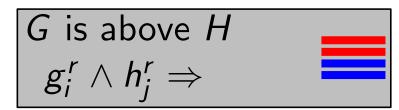
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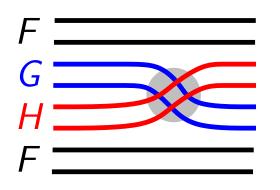




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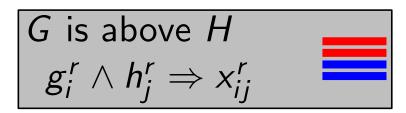
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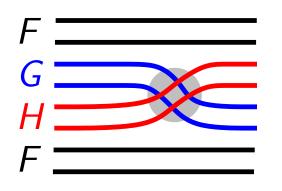




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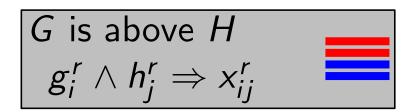


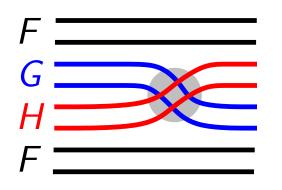
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Constraints:

Exactly characters of Gand H cross each other $\chi^{r}_{ij} \Leftrightarrow g^{r}_{i} \wedge h^{r}_{j}$ G and H are adjacent

	I

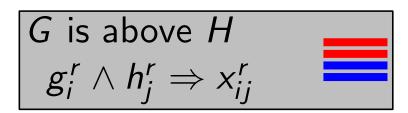


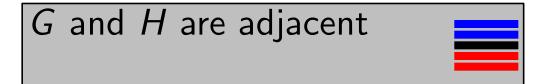


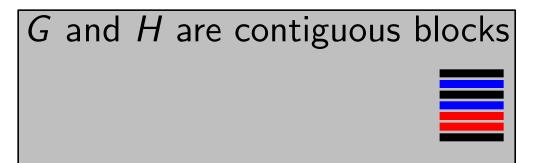
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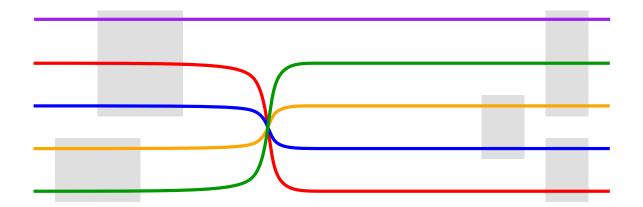
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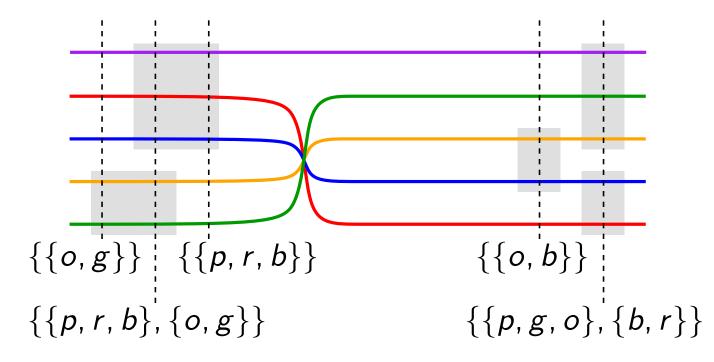
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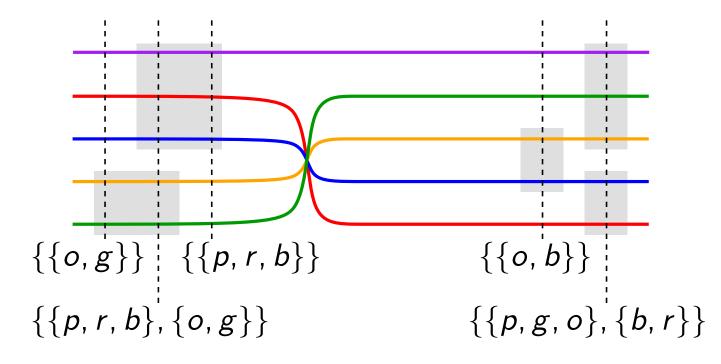


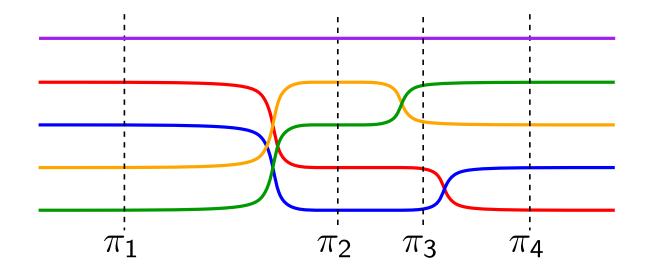


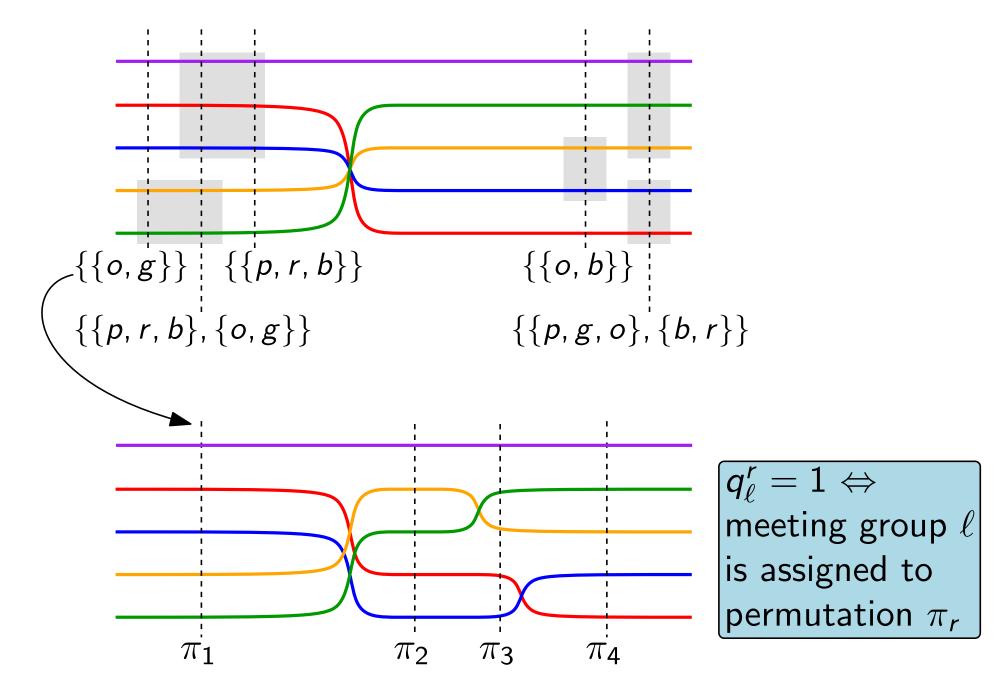


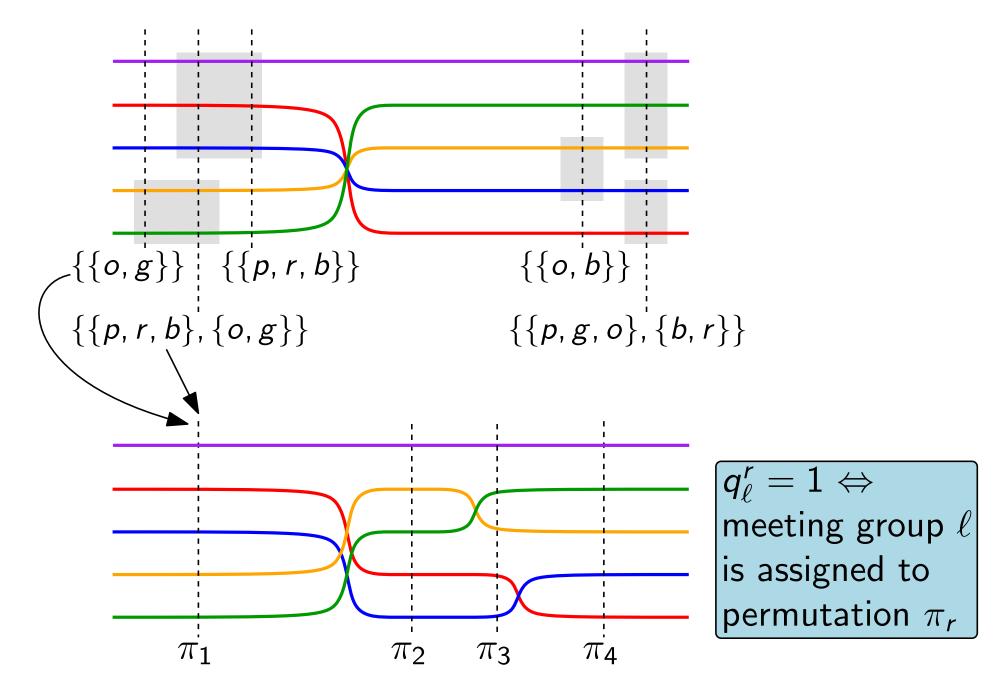


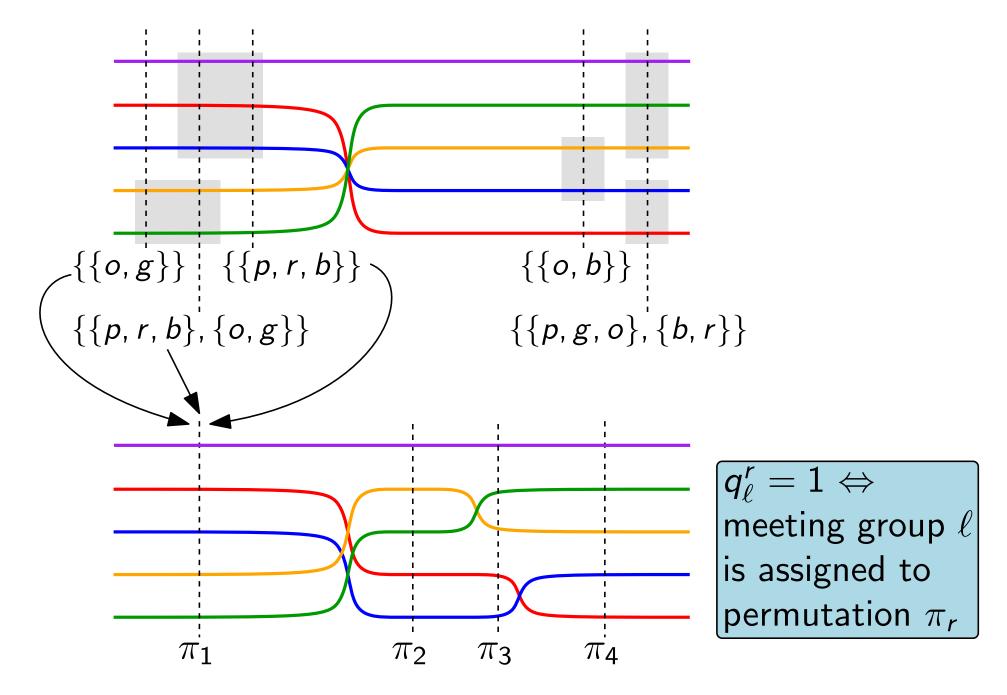


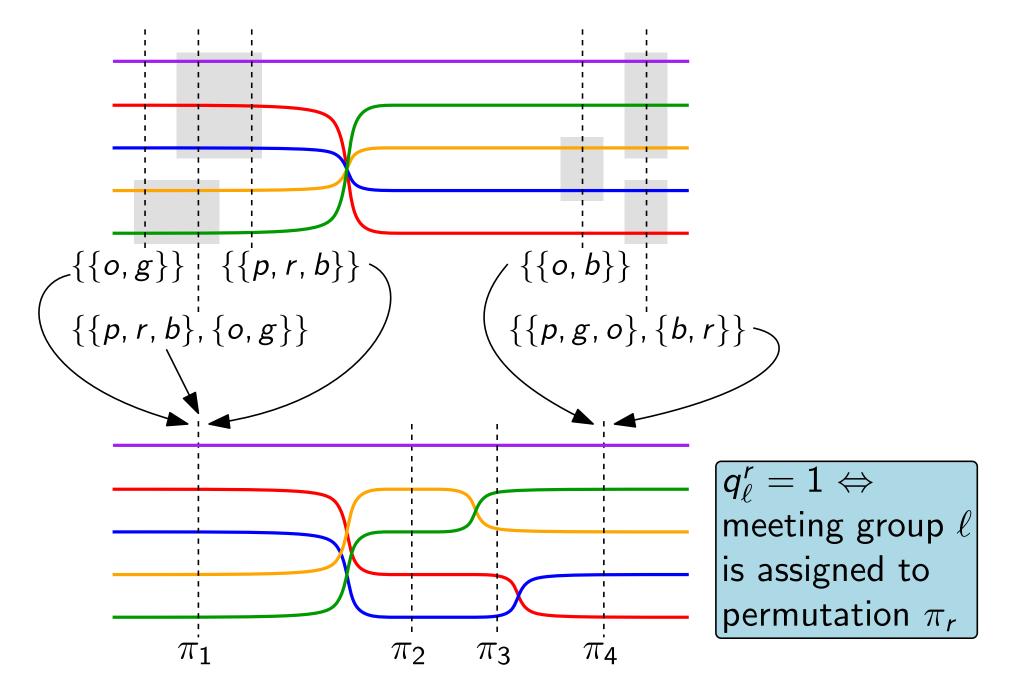












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Finding the optimum:

Repeatedly run the SAT solver with different values for λ (exponential search)

Experiments

- **FPT** Breadth-first search a smarter state space; runtime: $O(k! \cdot k^3 \cdot n)$
 - $\bullet\,$ FPT are implemented in C++
 - Concurrent meetings not implemented for FPT
 - SAT clauses generated by Python and solved using MiniSat

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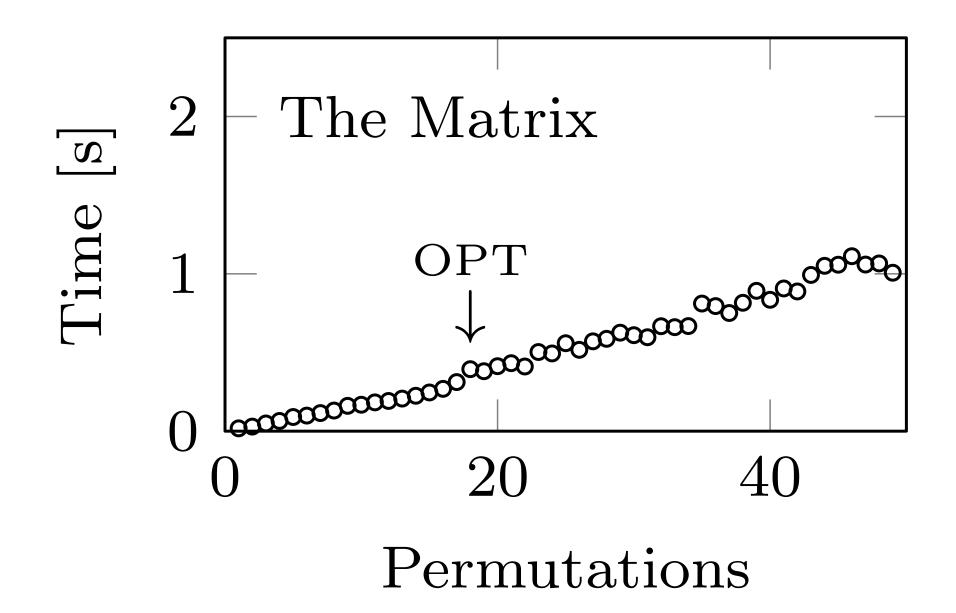
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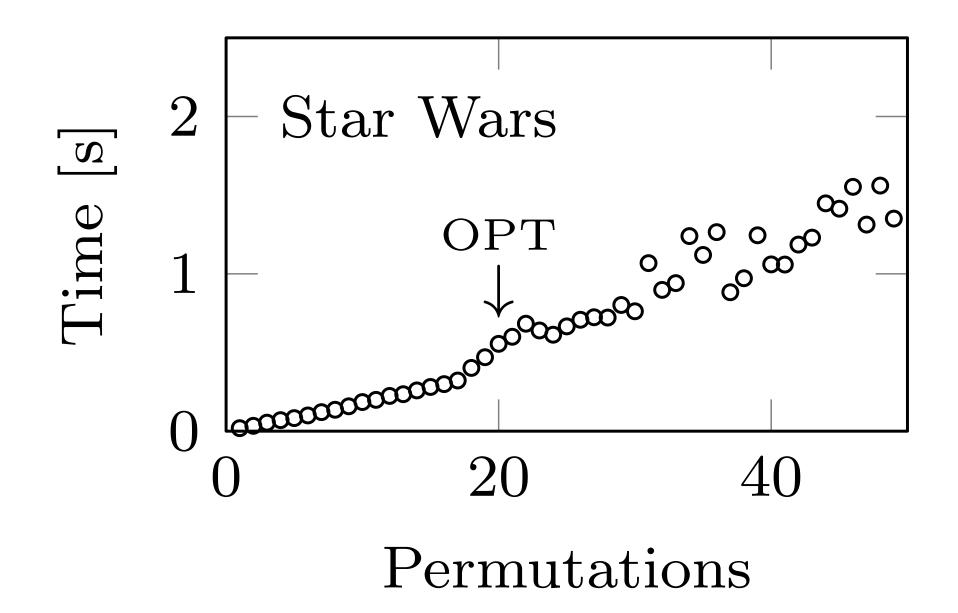
Test Data:

- Real-World instances (movies used by Gronemann et al.): The Matrix, Inception, Star Wars
- Random instances
- Random instances having a solution with few block crossings

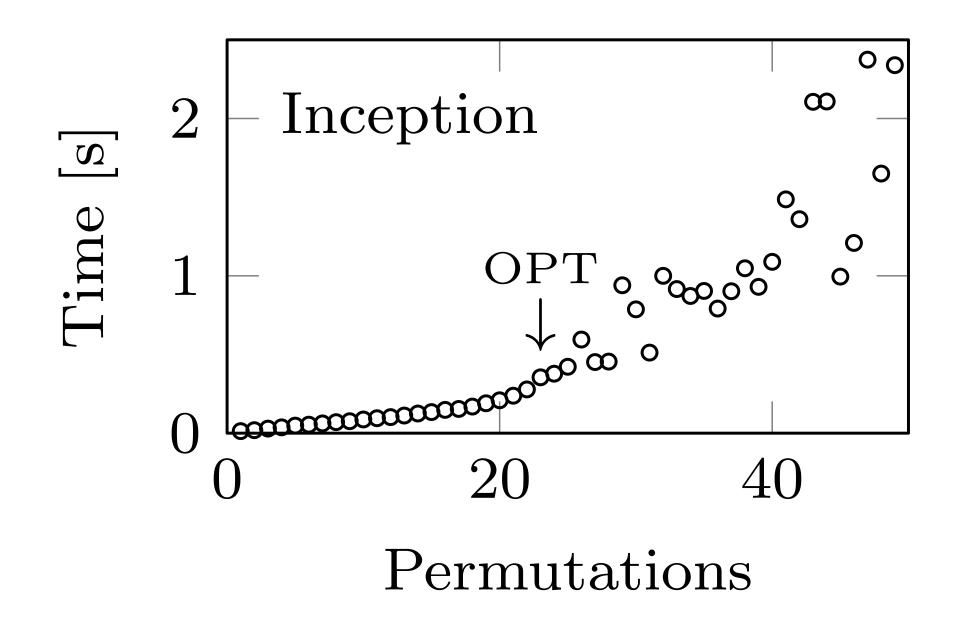
SAT: Runtime vs Number of Permutations



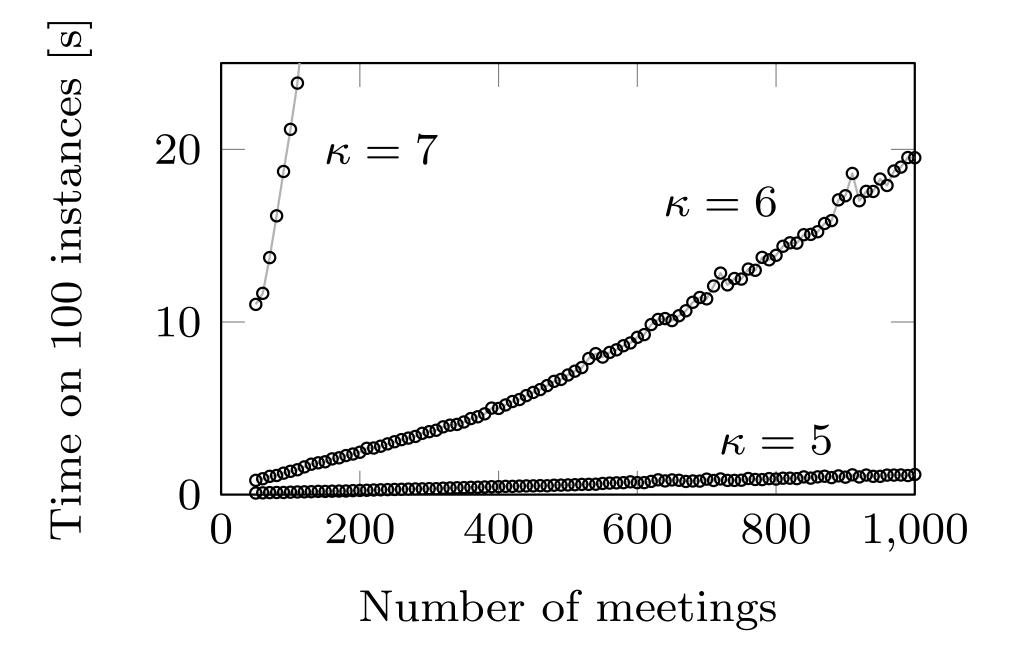
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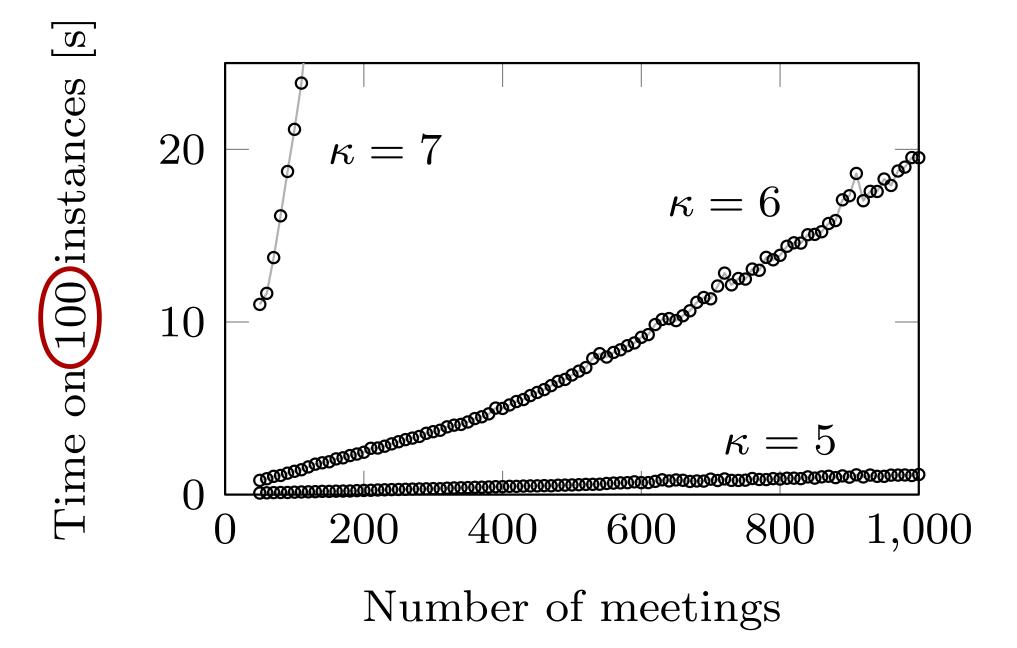
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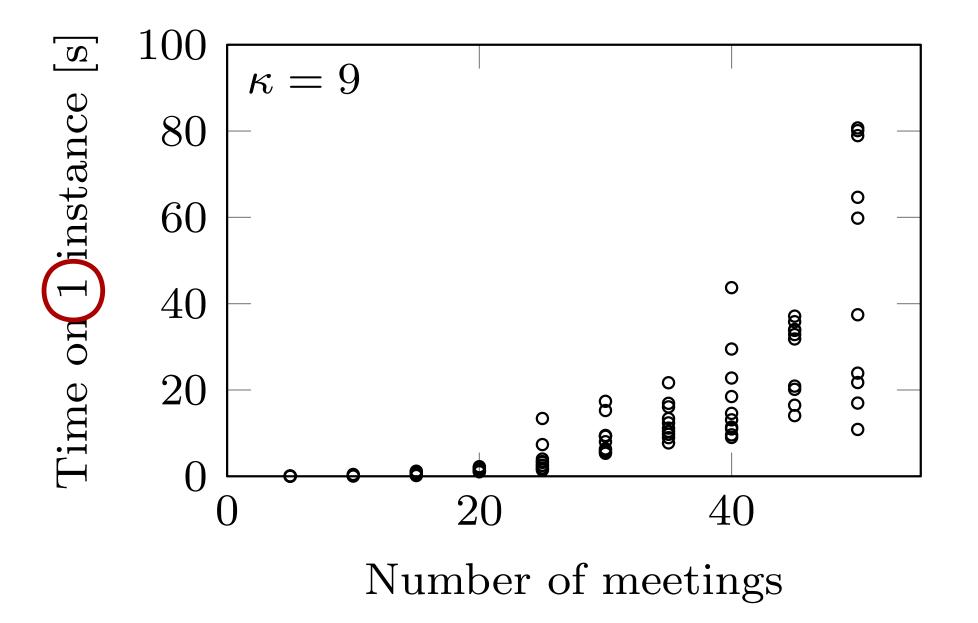
Uniform Random Instances: FPT



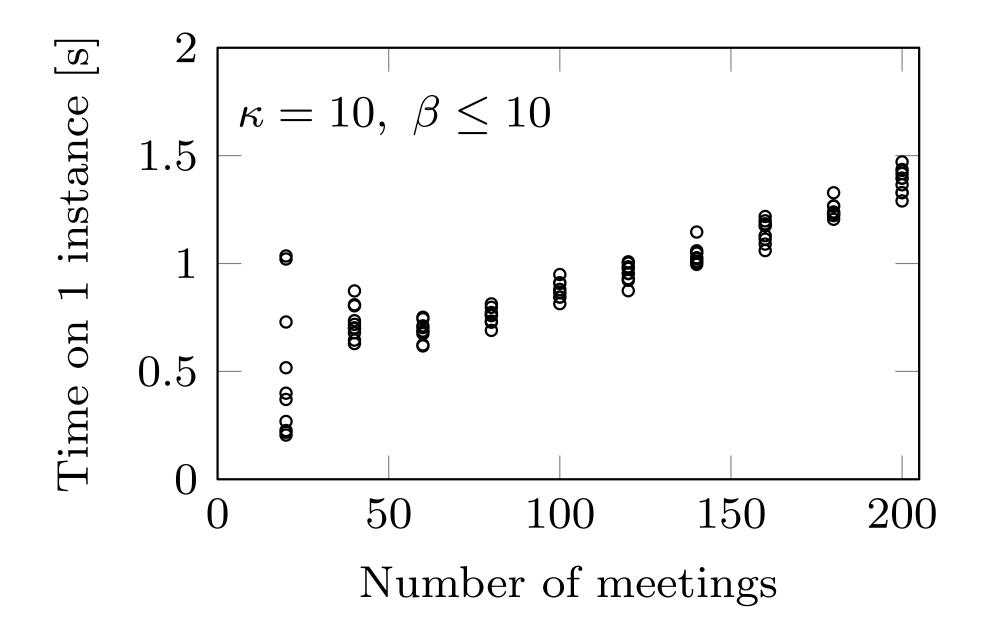
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Uniform Random Instances: SAT



Small-OPT Random Instances: SAT



Results

Movie Instances:

	Our approach			Gronemann et al.		
Instance	Cr	bс _{ОРТ}	Time [s]	cr _{OPT}	bc	Time [s]
Star Wars	54	10	3.77	39	18	0.99
The Matrix	21	4	2.86	12	8	0.77
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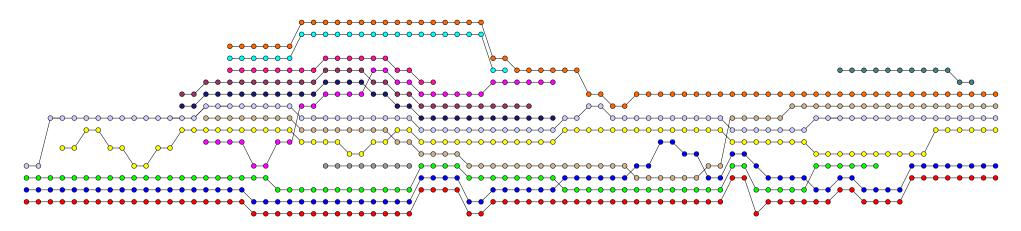
Results

Movie Instances:

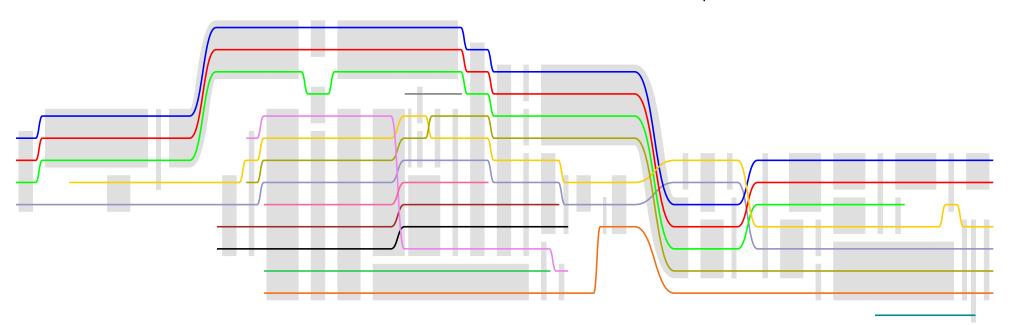
	Our approach			Gronemann et al.		
Instance	Cr	bс _{ОРТ}	Time [s]	cr _{OPT}	bc	Time [s]
Star Wars	54	10	3.77	39	18	0.99
The Matrix	21	4	2.86	12	8	0.77
Inception	51	12	1.54	35	20	2.02

Gronemann et al.

12 crossings / 8 block crossings

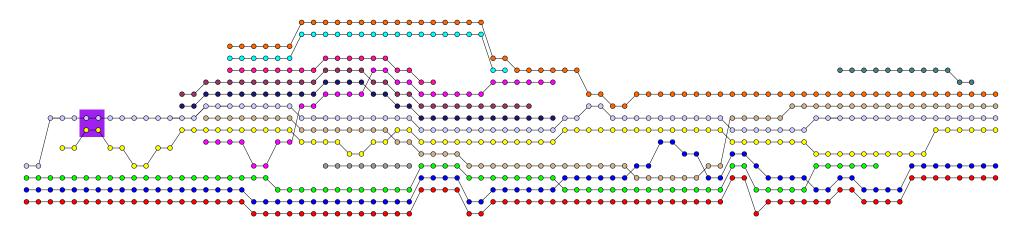


Our approach

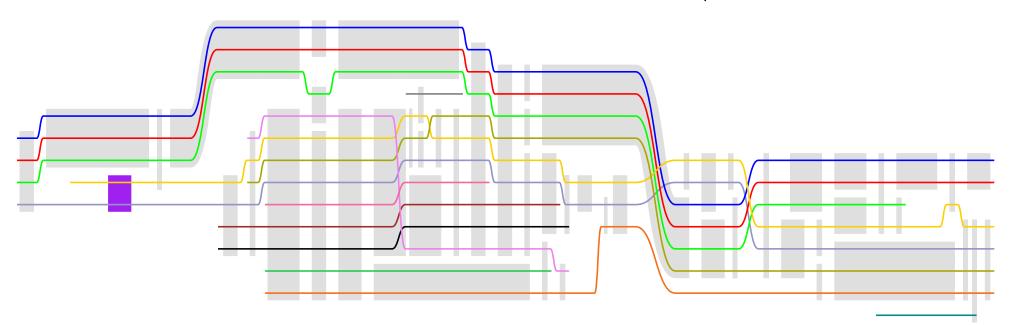


Gronemann et al.

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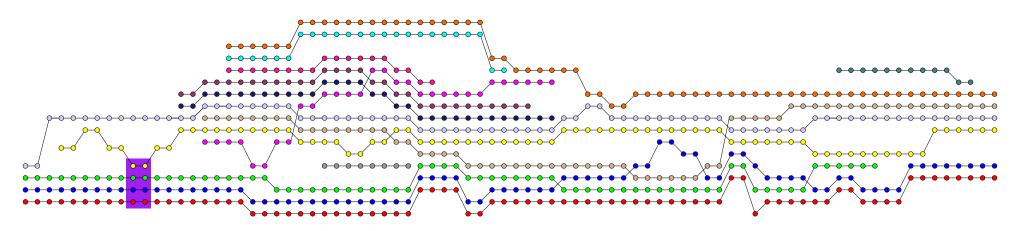


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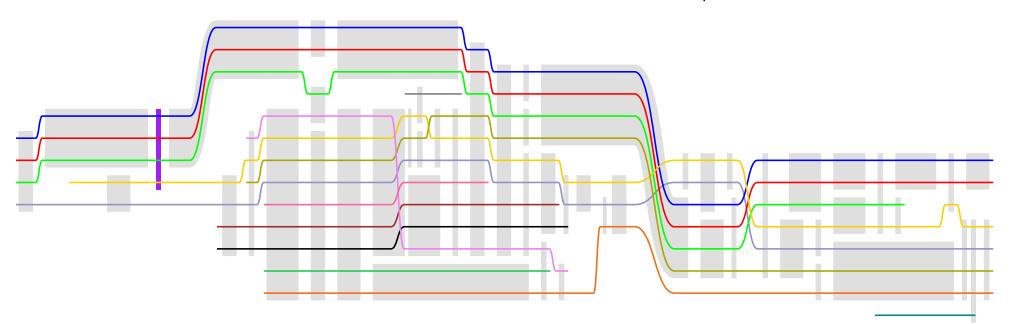


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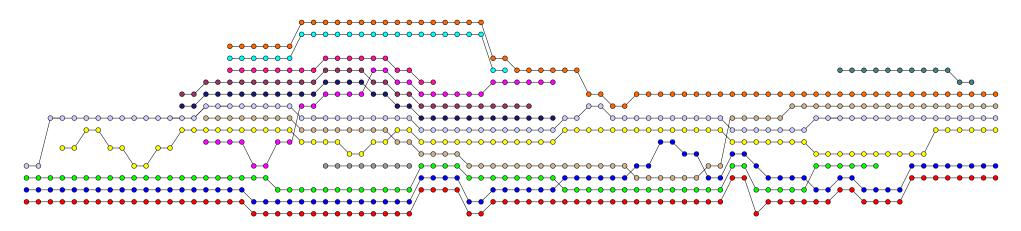


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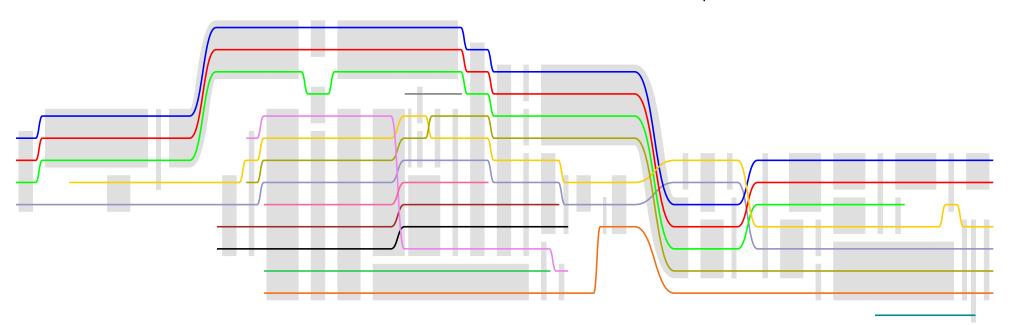


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Our approach



Conclusion

- Our SAT approach is usable for real-world instances.
- Use SAT instead of ILP turned out to be much faster!
- Source code is available online.

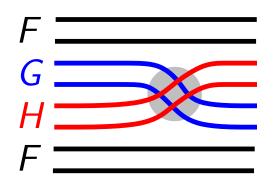
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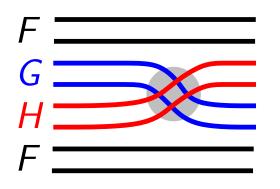
Future work

- Try other (parallel) SAT solvers.
- Find more efficient way to model lifespans.
- Consider additional quality criteria of the drawing, e.g., minimize wiggles. [Fröschl & Nöllenburg, GD17]
- Perform a user study on the effect of block crossings, especially for storyline visualizations.





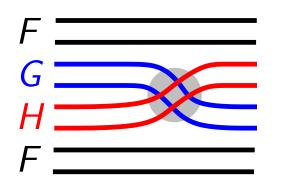
Blocks G and H cross



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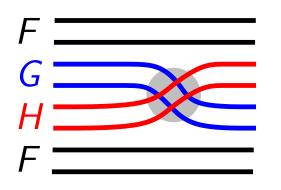
Constraints:

Exactly characters of G and H cross each other



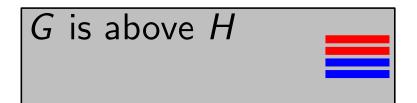
Blocks G and H cross

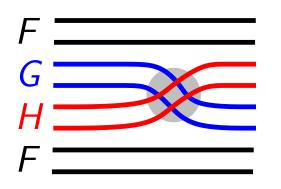
Constraints:



Blocks G and H cross

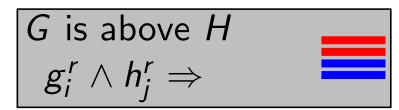
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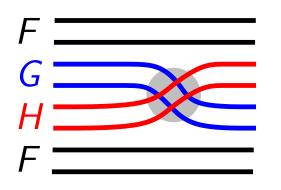




Blocks G and H cross

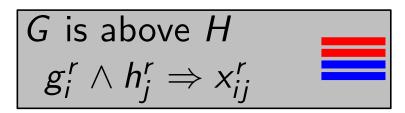
Constraints:

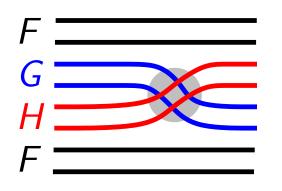




Blocks G and H cross

Constraints:



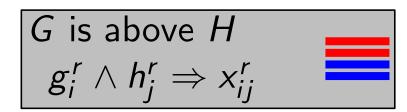


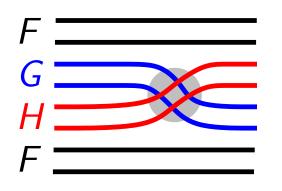
Blocks G and H cross

Constraints:

Exactly characters of Gand H cross each other $\chi^{r}_{ij} \Leftrightarrow g^{r}_{i} \wedge h^{r}_{j}$ G and H are adjacent

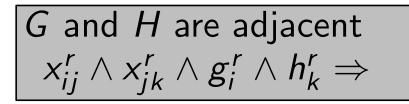
	I



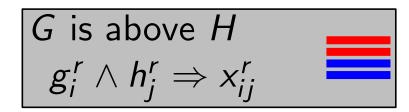


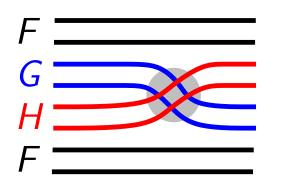
Blocks G and H cross

Constraints:



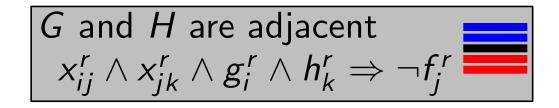


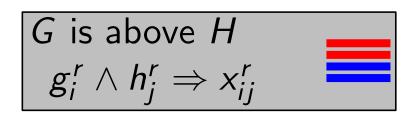


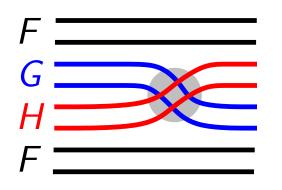


Blocks G and H cross

Constraints:



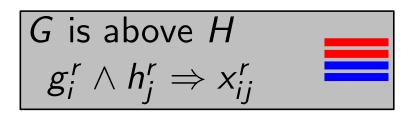


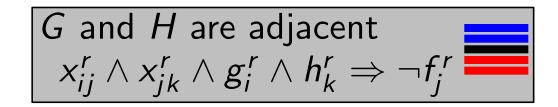


Blocks G and H cross

Constraints:

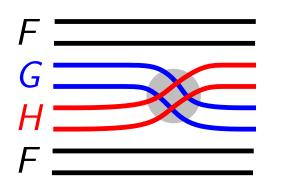
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G and H are contiguous blocks

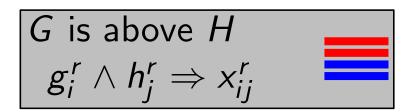




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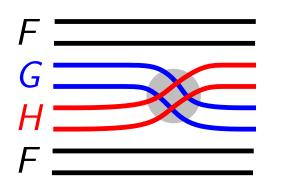
Constraints:

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G and H are adjacent $x_{ii}^r \wedge x_{ik}^r \wedge g_i^r \wedge h_k^r \Rightarrow \neg f_i^r$

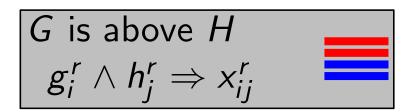
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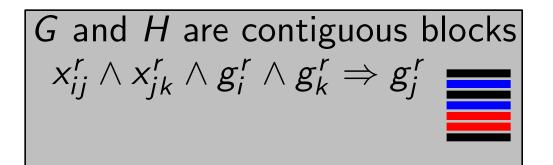
Blocks G and H cross

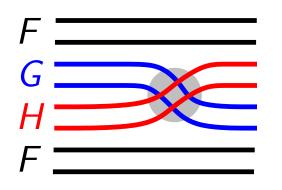
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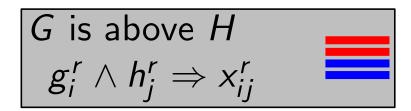




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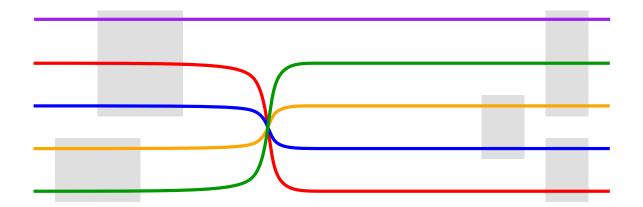
Constraints:

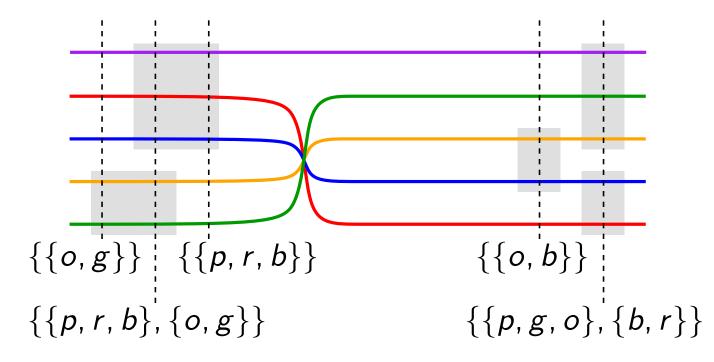
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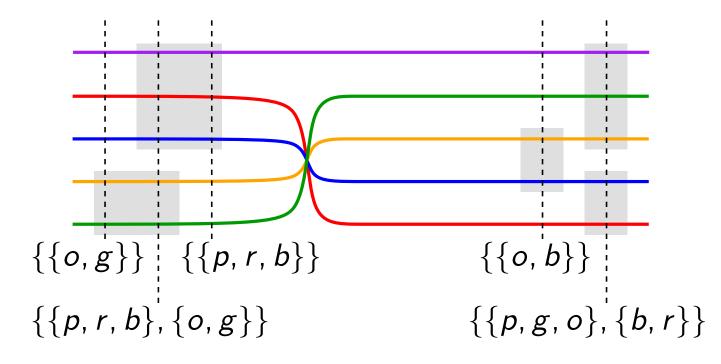


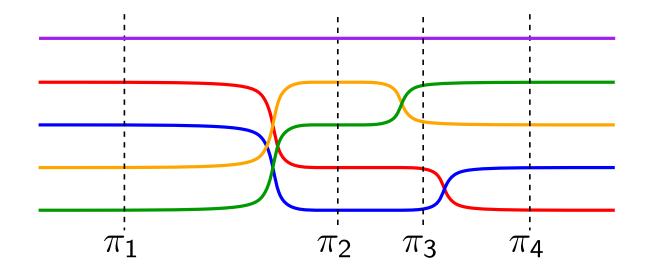
$$G \text{ and } H \text{ are adjacent} \\ x_{ij}^r \wedge x_{jk}^r \wedge g_i^r \wedge h_k^r \Rightarrow \neg f_j^r \blacksquare$$

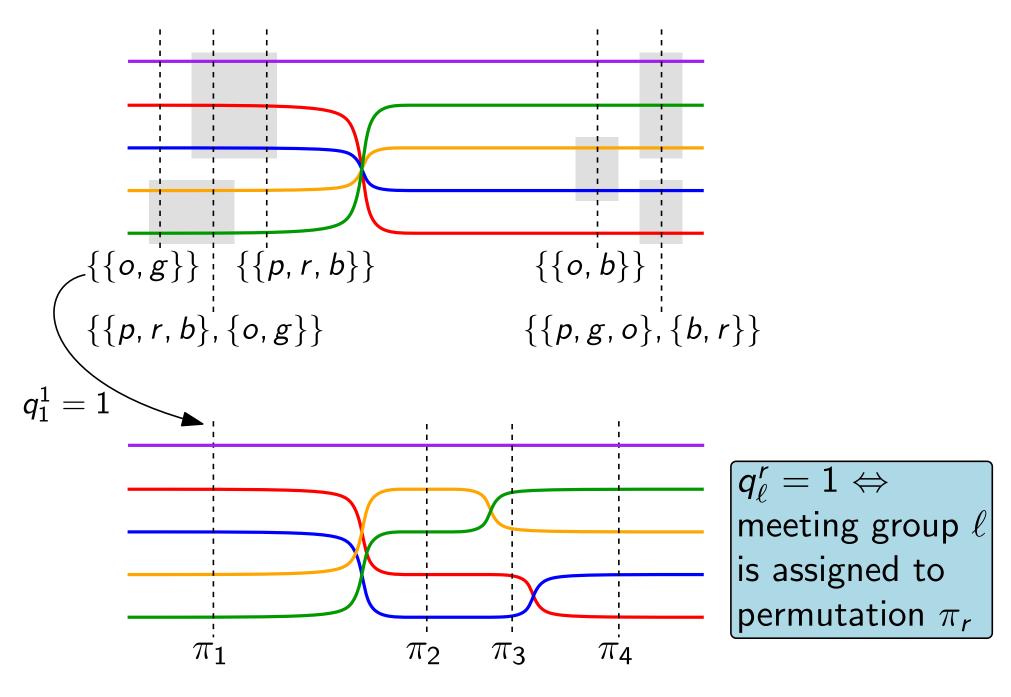
$$G \text{ and } H \text{ are contiguous blocks}$$
$$x_{ij}^{r} \wedge x_{jk}^{r} \wedge g_{i}^{r} \wedge g_{k}^{r} \Rightarrow g_{j}^{r}$$
$$x_{ij}^{r} \wedge x_{jk}^{r} \wedge h_{i}^{r} \wedge h_{k}^{r} \Rightarrow h_{j}^{r}$$

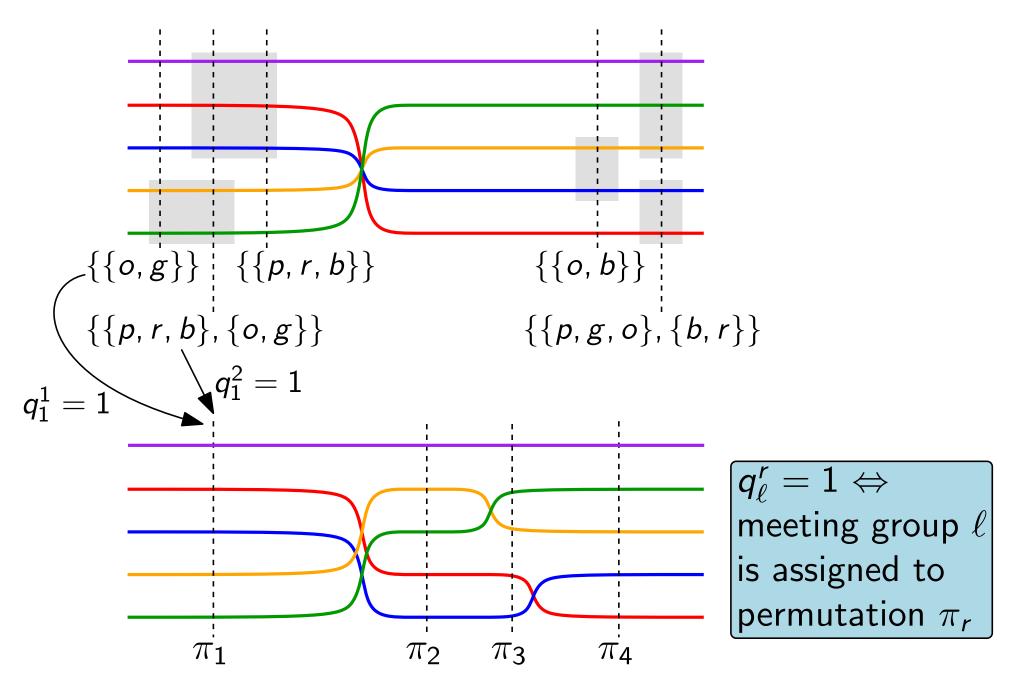


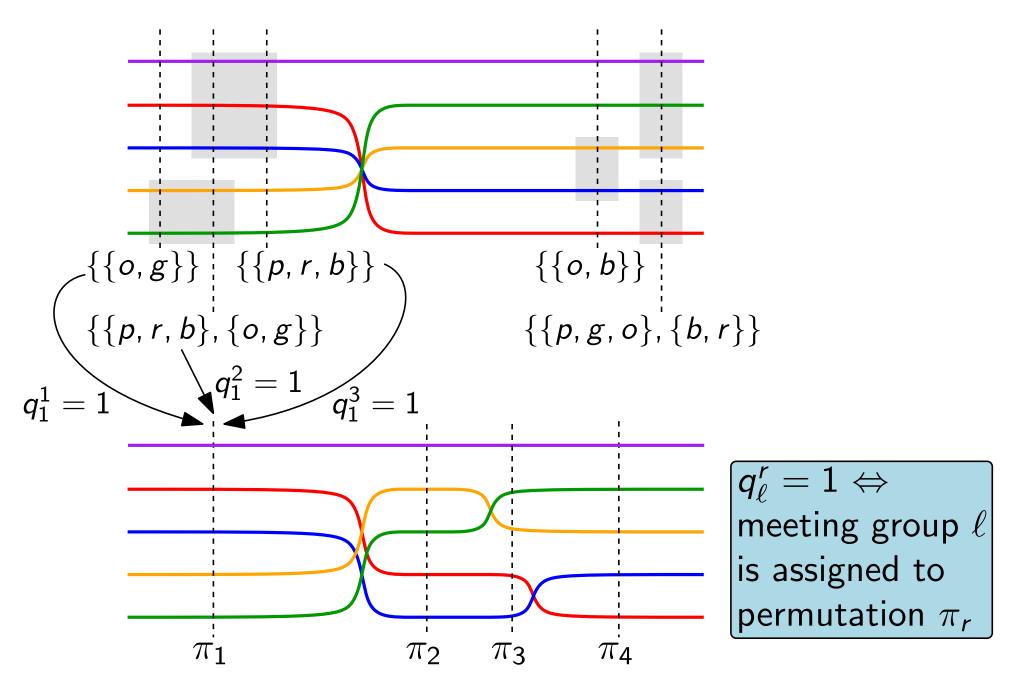


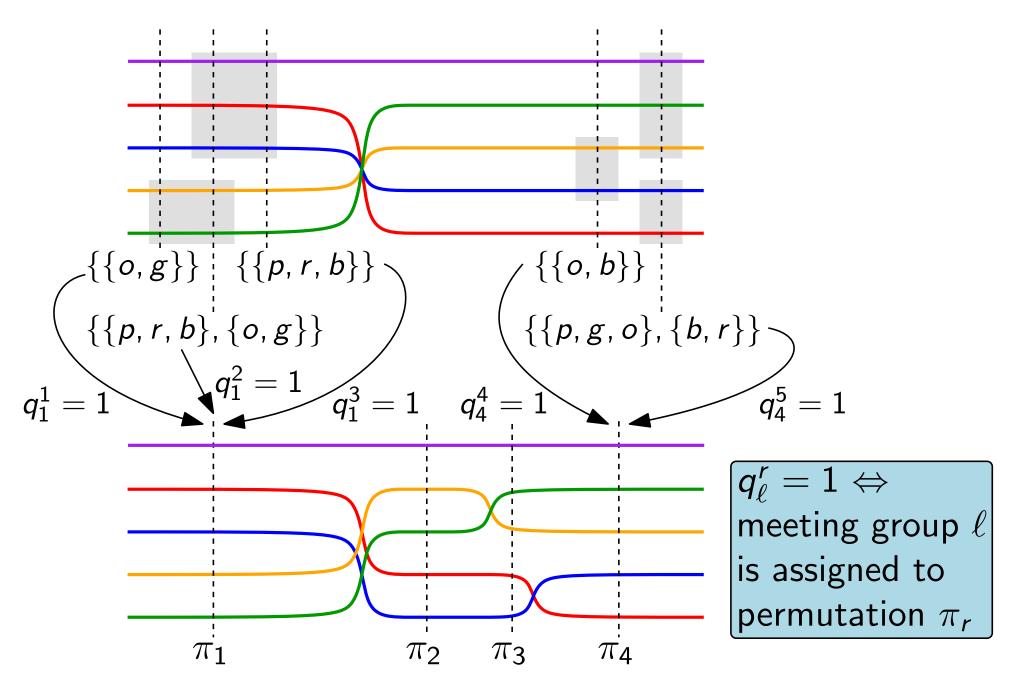












• Map the meeting groups in the right order:

• Map every meeting group exactly once:

• Force meeting characters to be next to each other:

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• Force meeting characters to be next to each other: If *i* and *k* are part of the same meeting in meeting group ℓ and *j* is not: $q_{\ell}^r \Rightarrow (x_{ij}^r = x_{kj}^r)$