Computing the Flip Distance of Triangulations Bachelor-Kolloquium

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Motivation of the Problem

- Let T_1, T_2 be binary search trees
- Operations: Left rotation, right rotation



Motivation of the Problem

- Let T_1, T_2 be binary search trees
- Operations: Left rotation, right rotation



• Task: Find a shortest sequence of rotations that lead from T_1 to T_2

Motivation of the Problem

- Let T_1 , T_2 be binary search trees
- Operations: Left rotation, right rotation



- Task: Find a shortest sequence of rotations that lead from T_1 to T_2
- There is no polynomial-time algorithm known for this problem, but NP-hardness is not proven



















Equivalent of Rotations



Equivalent of Rotations





Equivalent of Rotations





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Rotation distance between binary trees is equivalent to flip distance between triangulations

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Definition (Flip Distance)

The *flip distance* $fd(\pi_1, \pi_2)$ is the minimum number of diagonal flips required to transform π_1 to π_2 .

Rotation distance between binary trees is equivalent to flip distance between triangulations

Definition (Flip Distance)

The *flip distance* $fd(\pi_1, \pi_2)$ is the minimum number of diagonal flips required to transform π_1 to π_2 .

Upper bound for two triangulations of the *n*-gon:

 $\mathsf{fd}(\pi_1,\pi_2) \leq 2n-6$















Flip Graph \mathcal{F}_6 :



fd(start, target) = 3

Flip Graph \mathcal{F}_6 :



Runtime

Number of nodes in \mathcal{F}_{n+2} :

$$C_n=\frac{1}{n+2}\binom{2n}{n}$$

fd(start, target) = 3

Flip Graph \mathcal{F}_6 :



Runtime

Number of nodes in \mathcal{F}_{n+2} :

$$C_n = \frac{1}{n+2} {\binom{2n}{n}}$$
$$C_n \sim \frac{4^n}{\sqrt{\pi n^3}}$$
$$\Rightarrow \text{Exponential}$$
runtime

fd(start, target) = 3

Simple Improvements



Simple Improvements



Two-Sided BFS

(s) (t)

Two-Sided BFS



Two-Sided BFS


























- Start BFS from start and target at the same time
- Reduces the number of visited nodes





























• Reduces the number of visited nodes



- Reduces the number of visited nodes
- Needs lower bound for distance from an arbitrary node to target



- Reduces the number of visited nodes
- Needs lower bound for distance from an arbitrary node to target
- Easy lower bound: number of diagonals that are not common

Effects of these improvements



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Optimal flip sequence





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Optimal flip sequence





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Optimal flip sequence





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Input: start triangulation s, target triangulation t**Output:** short flip sequence from s to t
Variants

MostIntersections Choose diagonal with maximum #(Intersections before flipping)

Variants

MostIntersections Choose diagonal with maximum #(Intersections before flipping) FewestIntersectionsAfter Choose Diagonal with minimum #(Intersections after flipping)

Variants

MostIntersections Choose diagonal with maximum #(Intersections before flipping)

FewestIntersectionsAfter Choose Diagonal with minimum #(Intersections after flipping)

HighestDifference Choose diagonal with maximum $\Delta := \#(\text{Intersections before flipping}) - \\
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Variants

MostIntersections Choose diagonal with maximum #(Intersections before flipping)

FewestIntersectionsAfter Choose Diagonal with minimum #(Intersections after flipping)

HighestDifference Choose diagonal with maximum

 $\Delta := #($ Intersections before flipping) - #(Intersections after flipping).

Runtime: $O(n^2)$

Comparing the Variants



• First Heuristic by Pallo (2000):

- Works on weight sequences representing binary trees
- Constructs a lattice containing the trees
- Length of path in lattice is upper bound for rotation distance

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 - Works on triangulations
 - Local transformation to create an additional common edge
 - Provides Upper and Lower Bound for the Flip Distance

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- Runtime: $O(n^3)$

Comparing to other Heuristics

n = 50



Comparing to other Heuristics



Comparing to other Heuristics



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Conclusion

Summary

- Exact Algorithms: Improvements to BFS
- Heuristics: HighestDifference
 - Efficient compared to other heuristics
 - Easy to implement

Open Problems

- Polynomial-time algorithm
- NP-hardness proof
- Algorithms with approximation ratio < 2

References

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