

Non-Planarity Measures and Small Cycles

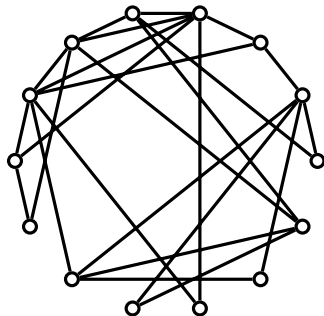
EuroCG 2020 – PhD School

Markus Chimani

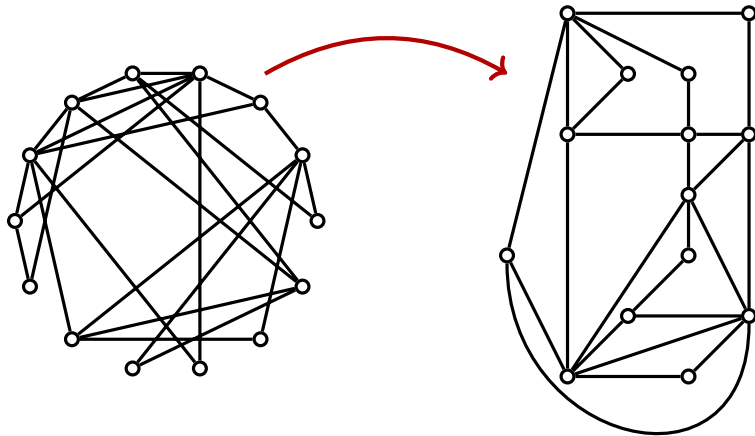
Theoretical Computer Science, Osnabrück University

March 19th, 2020

Planarity

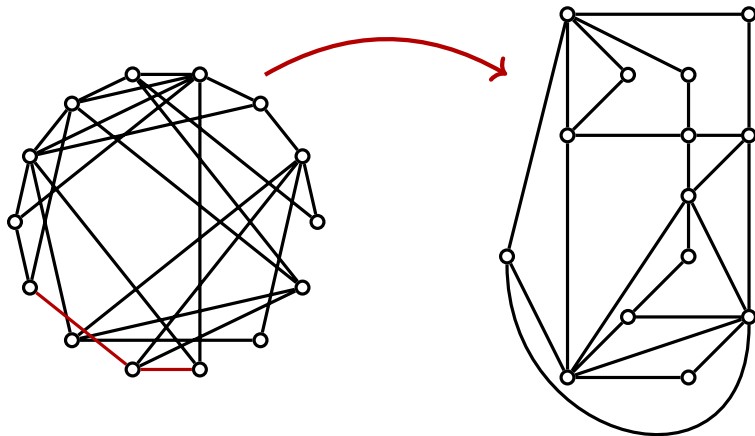


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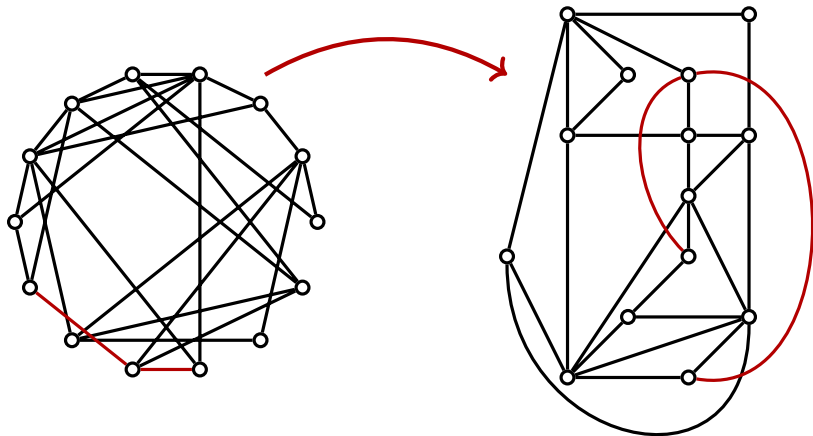


Planarity helps **a lot** algorithmically!

Planarity



Planarity

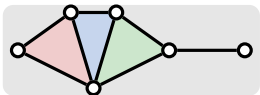


Euler

Theorem (Euler's formula)

Given a planarly drawn graph with n vertices, m edges, and f faces, then:

$$n - m + f = 2$$



Euler

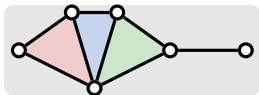
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≤ 2 faces per edge



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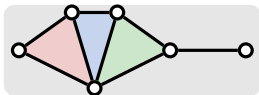
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$$\Rightarrow 3f \geq 2m \rightarrow n - m + (2/3)m \geq 2 \rightarrow m \leq 3n - 6$$



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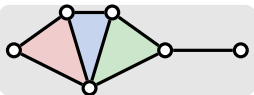
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Definition (Girth)

Girth $g(G)$ is the length of the shortest cycle in G .

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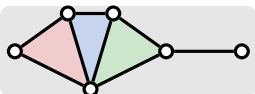
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Bipartite graphs (girth ≥ 4): ≥ 4 edges per face $\Rightarrow m \leq 2n - 4$

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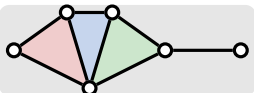
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Girth g : $\geq g$ edges per face $\Rightarrow m \leq \frac{g}{g-2}(n-2)$

high girth \rightarrow few edges

Kuratowski

Theorem (Kuratowski, 1930)

Graph G is **non-planar**



G contains a K_5 - or $K_{3,3}$ -**subdivision** as a subgraph.

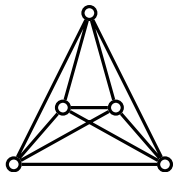
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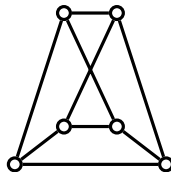
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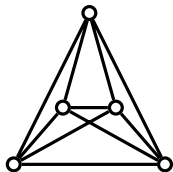
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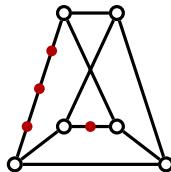
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K_5



$K_{3,3}$ -subdivision

Non-Planarity Measures

Can we gain an algorithmic advantage is graph is **close to planar**?

What does **close** mean?

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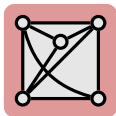
- ▶ **Crossing Number:** min. number of **crossings** in the plane $cr(G)$
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Relating Measures of Non-Planarity

Lemma

$$\text{cr}(G) \geq \text{sk}(G) \geq \gamma(G)$$

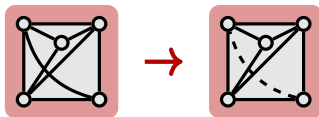


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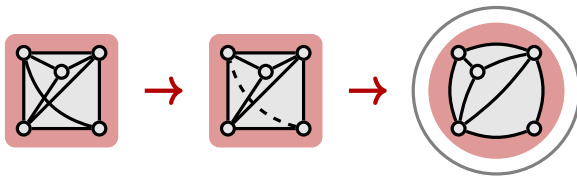


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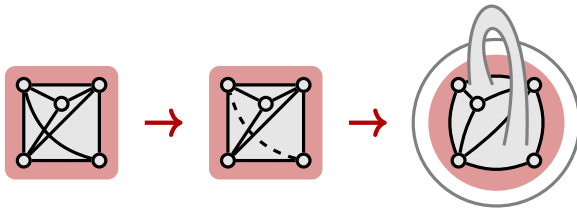


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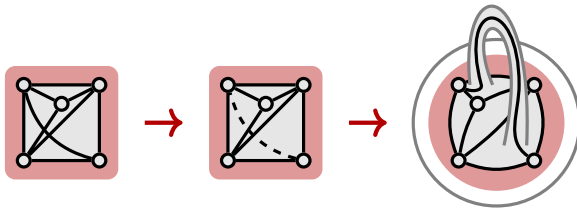


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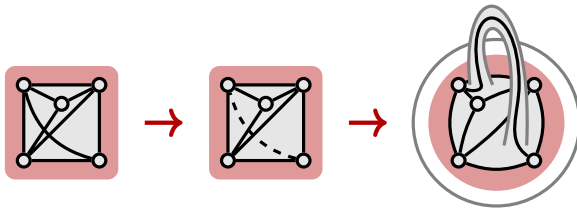


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... and the gaps can be **large**!

Exploiting Low Non-Planarity

$$\{G : \gamma(G) \leq k\} \supset \{G : \text{sk}(G) \leq k\} \supset \{G : \text{cr}(G) \leq k\}$$

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- ▶ finer-grained parameterization may be more practical
- ▶ more tractable in practice, reasonable exact algorithms & strong heuristics

How to **exactly** compute
 $\text{cr}(G)$, $\text{sk}(G)$, and $\gamma(G)$?

Integer Linear Programming

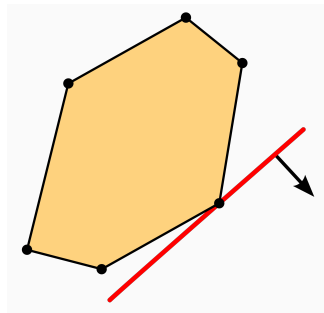
Formulate the problem as an **ILP**

$$\max \quad c^T x \quad (1)$$

$$s.t. \quad Ax \leq b \quad (2)$$

$$x \geq 0 \quad (3)$$

$$x \in \mathbb{Z}^n \quad (4)$$



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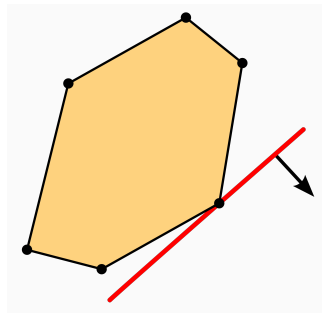
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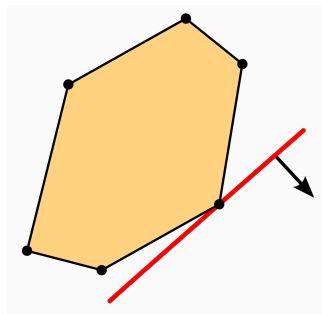
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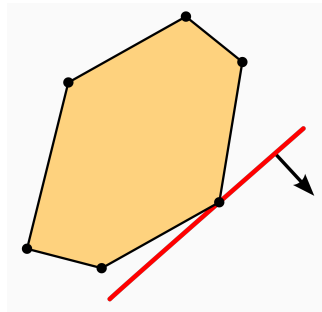
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Roadmap (of this talk)

Skewness: Original ILP \rightarrow Improvement by considering Short Cycles

Genus: Original ILP \rightarrow Improvement by considering Short Cycles

Skewness $sk(G)$

= Maximum Planar Subgraph (MPS)

Kuratowski-based Formulation

Theorem (Kuratowski, 1930)

G is non-planar $\iff G$ contains a K_5 - or $K_{3,3}$ -subdivision.

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Kuratowski-based ILP [Mutzel, 1994]

$$\begin{aligned} \min \quad & \sum_{e \in E} s_e \\ \text{s.t.} \quad & \sum_{e \in K} s_e \geq 1 \\ & s_e \in \{0, 1\} \end{aligned}$$

Variable is **1** iff edge e is **deleted**

exponentially many

\forall Kuratowski subdivisions $K \subseteq E$

$\forall e \in E$

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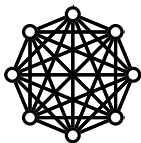
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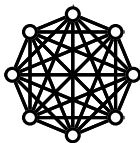
$\forall e \in E$

Solve via branch-and-cut with heuristic separation.

Generalized Euler Constraints

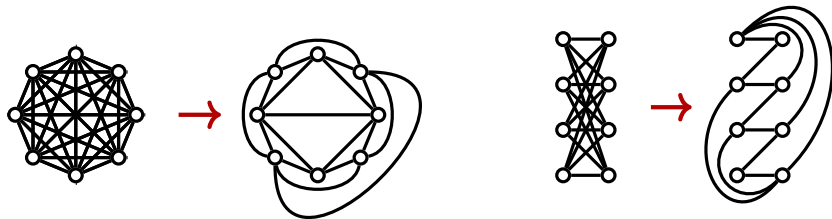


Generalized Euler Constraints



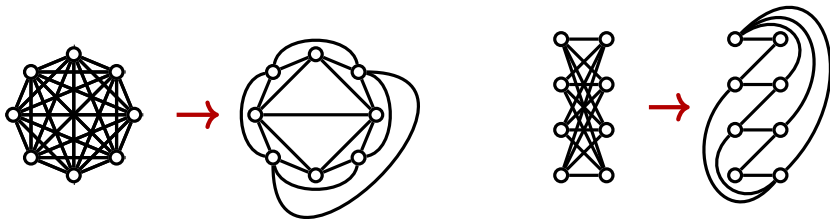
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Generalized Euler Constraints



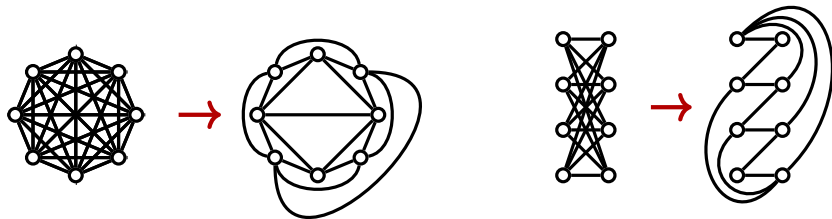
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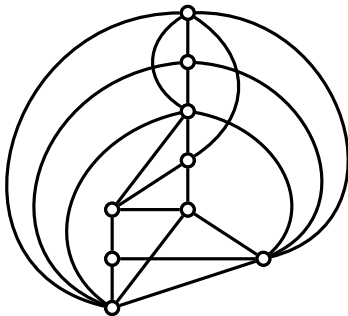
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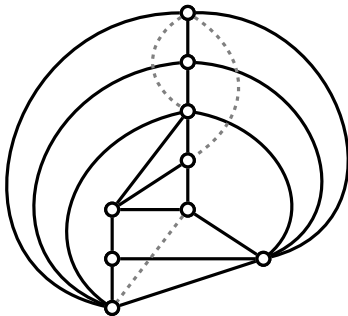
- ▶ **Kuratowski** constraints are **weak on dense** graphs
- ▶ On complete (complete bipartite) graphs, **optimality** follows directly from **Euler's formula**
⇒ no Kuratowski constraints needed
- ▶ Real-world graphs typically **neither** have large girth **nor** is their MPS tri- or quadrangulated...

Key Observations



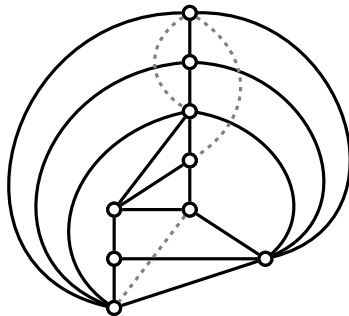
“real-world” graph

Key Observations



MPS of “real-world” graph

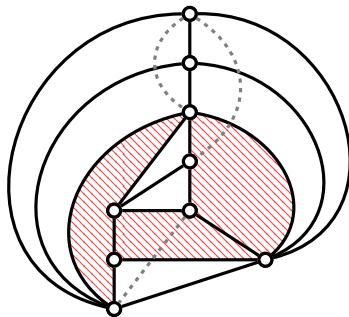
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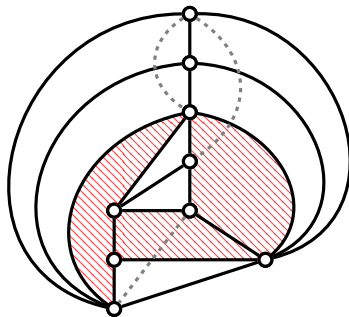
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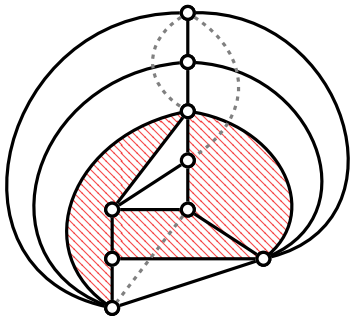
Key Observations



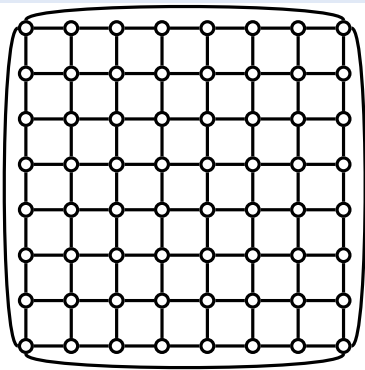
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Key Observations



MPS of “real-world” graph



grid-like graph

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A diagram of a 2D lattice structure, represented by a grid of white circles (sites) connected by black lines (bonds). The lattice is enclosed in a rounded rectangular boundary. A single site in the center of the lattice is highlighted with a red dot. Two red lines, one solid and one dotted, extend from this central red site, forming a V-shape that points towards the top-left and bottom-right corners of the lattice.

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- ▶ MPS is **typically biconnected**

Idea for Cycle Model

Assume: MPS is biconnected.

$\mathcal{C}_G :=$ set of cycles in input G .

new variable is **1** iff α is a face in the solution



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Problems:

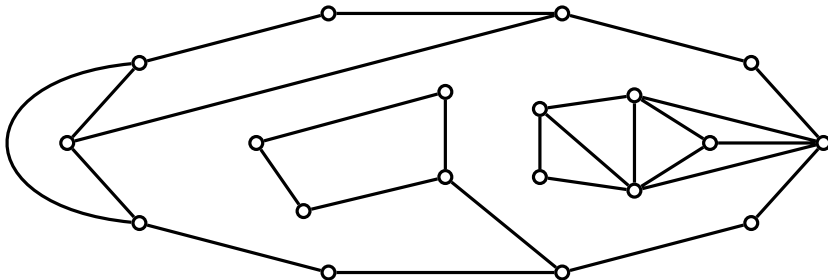
- ▶ We cannot enumerate **all** cycles in practice
- ▶ MPS is not biconnected

Obstacle: Non-Biconnectedness

Lemma

(MPS will not be outerplanar.) To each a face-walk β we can associate a sub-cycle $\alpha \subseteq \beta$ such that each cycle is used at most once.

- ▶ faces in the solution $\xleftrightarrow{1:1}$ cycles
- ▶ each edge is incident to **at most** one such cycle

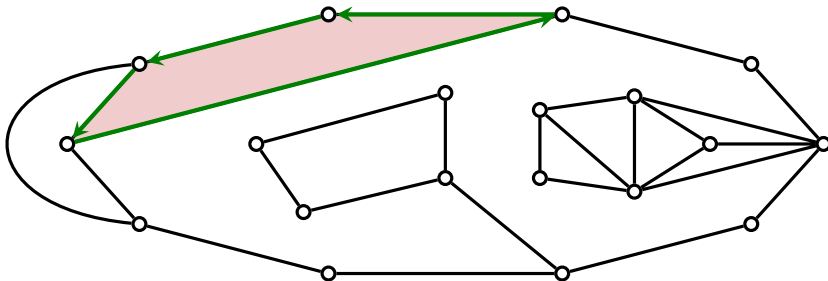


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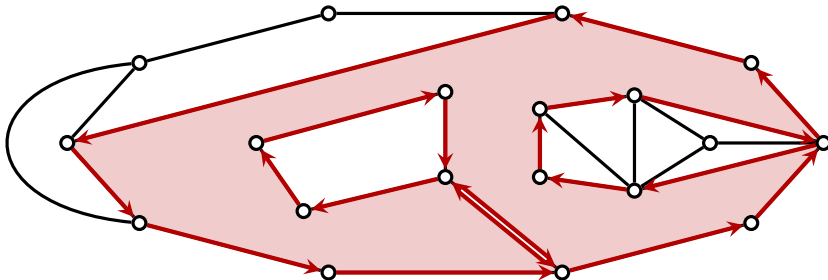


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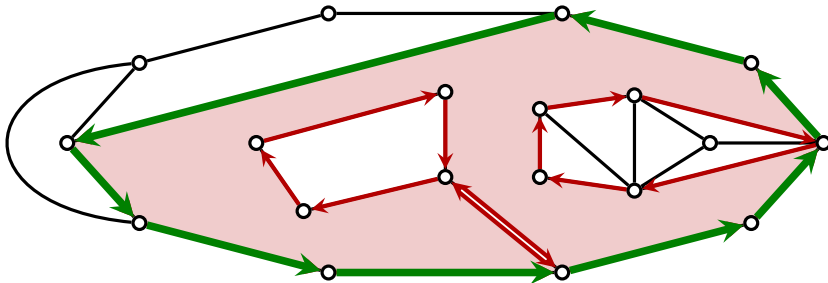


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Pick $D \in \mathbb{N}$ such that number of variables is “reasonable”.

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$$(D + 1)(|V(G)| - 2) + \sum_{d=3,4,\dots,D} (D + 1 - d) \sum_{\alpha \in \mathcal{C}_G^d} c_\alpha \geq (D - 1) \sum_{e \in E} (1 - s_e)$$

D-Hierarchy

D-Hierarchy

Theorem

The ILP formulations become strictly stronger when increasing D (but the number of variables increases drastically, as well).

D-Hierarchy

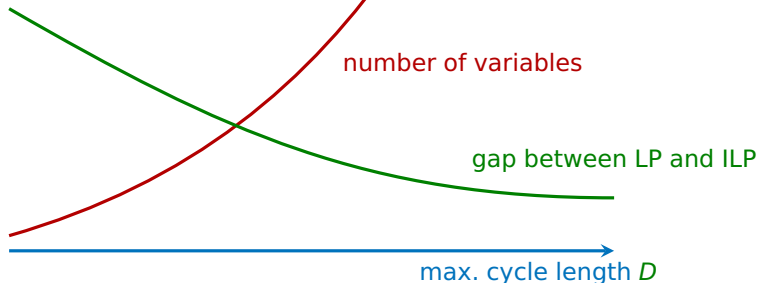
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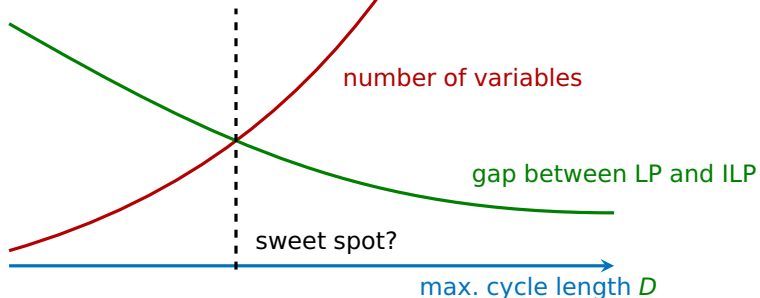
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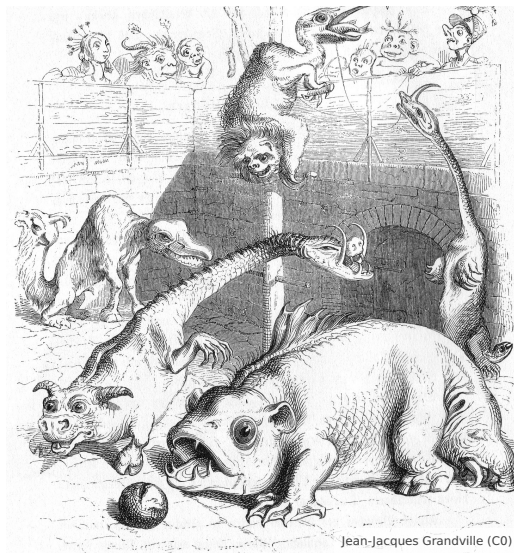
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Supplemental Constraint Zoo

Once you have cycle variables,
you can do a lot more with them!

Goal: Tightly link edge- and cycle-variables



Once you have cycle variables,
you can do a lot more with them!

For example:

- ▶ pseudo-tree extension
- ▶ cycle-edge cons.
- ▶ Kuratowski-cycle cons.
- ▶ k -cycles-path cons.
- ▶ cycle-clique cons.
- ▶ cycle-two-paths cons.



Experimental Setting

Framework

- ▶ C++, GCC 6.3
- ▶ OGDF 2018.03 [www.ogdf.net]
- ▶ SCIP 6.0 [scip.zib.de]
- ▶ CPLEX 12.8

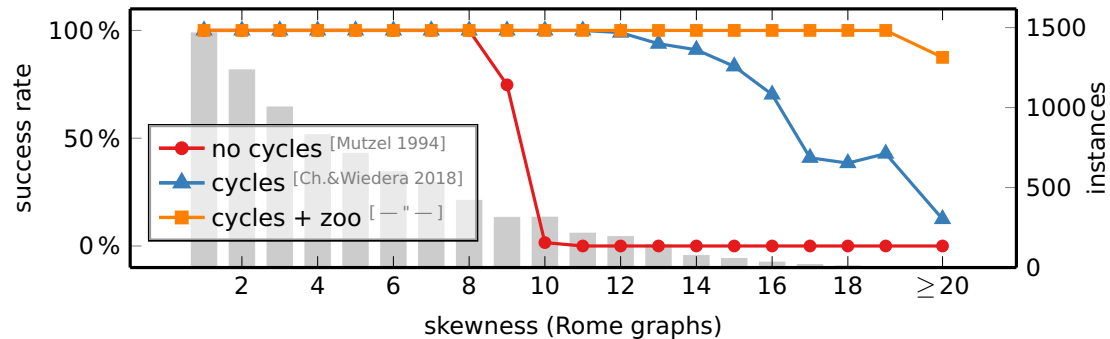
Computations

- ▶ Xeon Gold 6134
- ▶ limit: 20 minutes, 8 GB

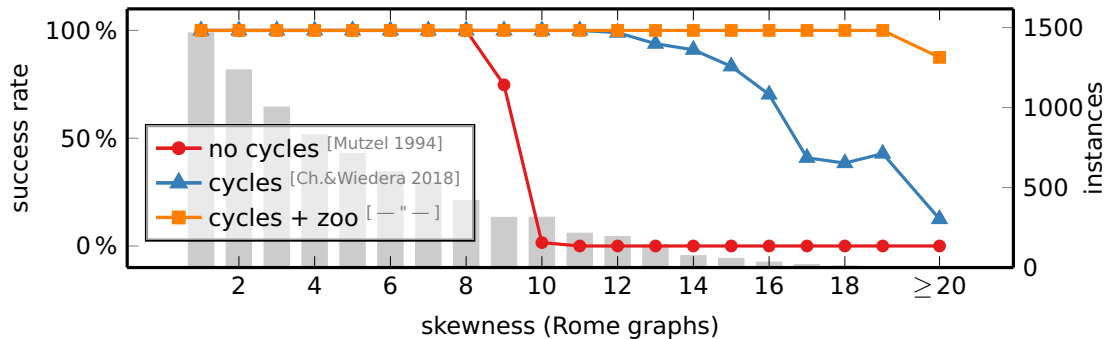
Instances

- ▶ Rome [Di Battista et al., 1995]
- ▶ North [North, 1995]
- ▶ Expander [Steger & Wormald, 1997]
- ▶ SteinLib [Koch et al., 2000]

Experimental Evaluation



Experimental Evaluation



Without vs. with cycles (+zoo)

% solved of previously unsolved

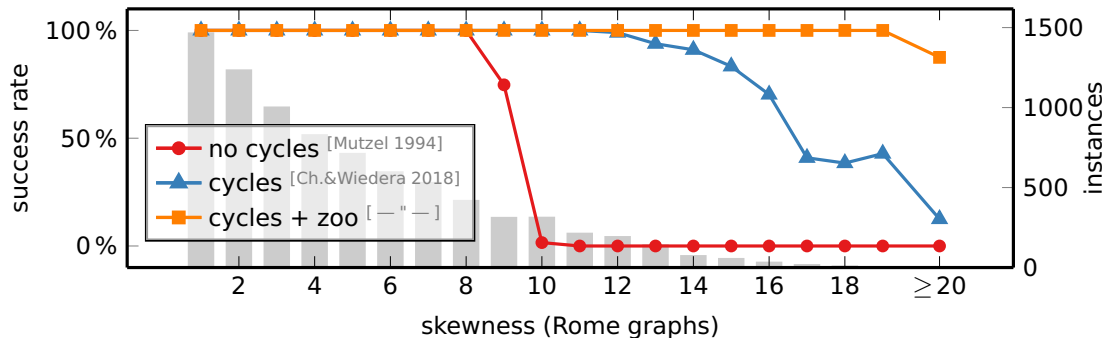
Rome
"100%"

North
75%

Expander
30%

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30%

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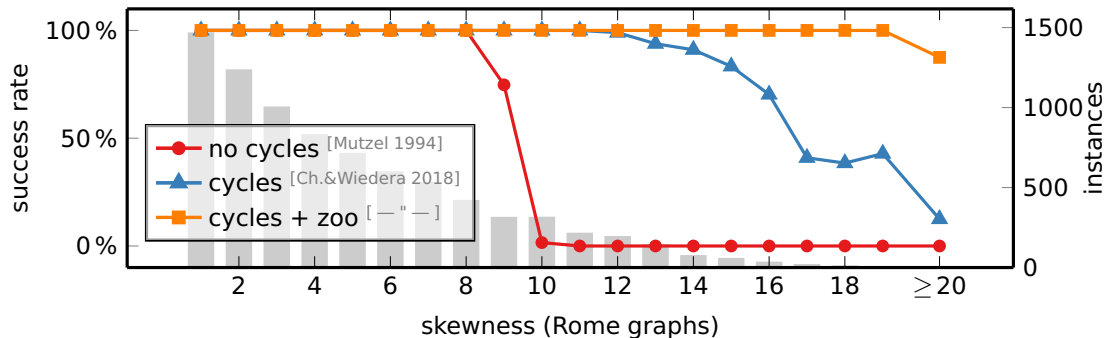


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66x	34x	20x	12x

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 D (raise until ≥ 1000 vars)

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66x	34x	20x	12x
11	8	6	7

Genus $\gamma(\mathbf{G})$



Genus $\gamma(G)$

computing it is quite hard practice...

- ▶ \exists linear time FPT-algorithm for bounded genus g [Mohar 1999], but **doubly exponential** in g and no known implementation even for toroidal case
- ▶ no (reasonable) heuristics



Faces in Embeddings of Higher Genus

Theorem (Euler's formula)

... is sensitive to the genus of the surface on which the drawing is: $n - m + f = 2 - 2\gamma$.

Faces in Embeddings of Higher Genus

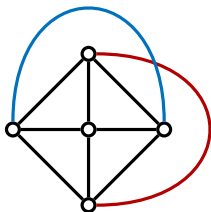
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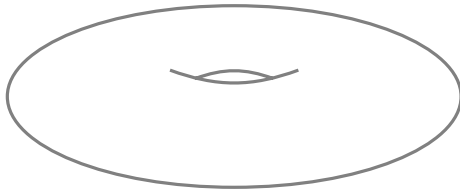
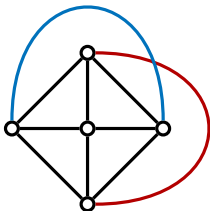
Face-Tracing-based ILP [Beyer et al. 2016]

- ▶ Minimize γ by finding an embedding (= rotation system) that **maximizes** f .
- ▶ Count faces via **face tracing**.

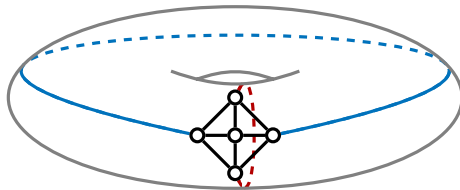
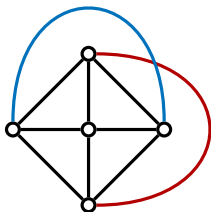
Crossing-free Non-planar Graphs



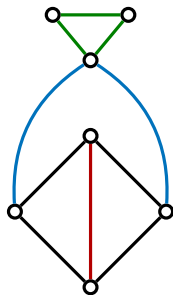
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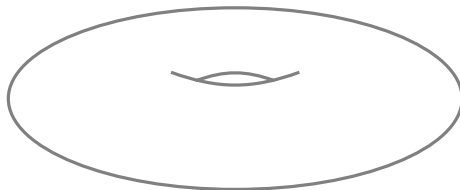
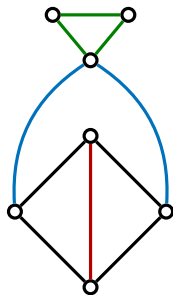
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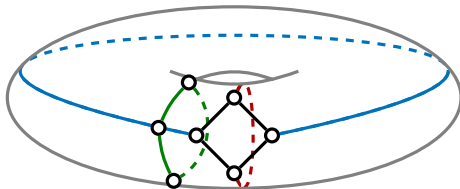
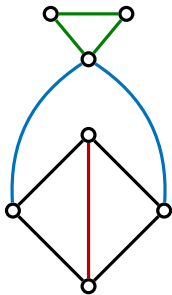
Embeddings and Face Tracing



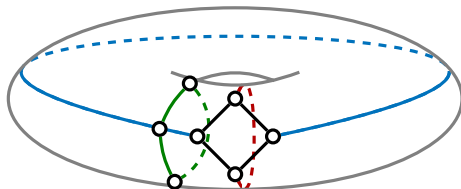
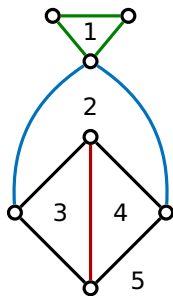
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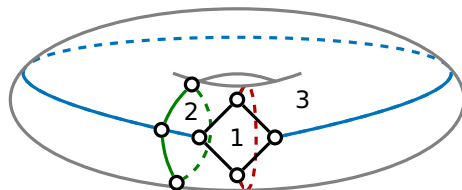
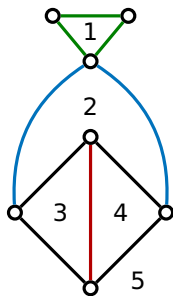
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upper bound on number of faces: $\bar{f} := \min\{m - n, 2m/3\}$

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Face-Tracing-based Formulation with small faces

upper bound on number of **large** faces: $\bar{f} := \min\{m - n, 2m/(D + 1)\}$

all **walks** of length $\leq D$: \mathcal{F}_D

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also needs amendment, no details

Hierarchie and Zoo

Analogous to before:

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The ILP formulations become strictly stronger when increasing D (but the number of variables increases drastically, as well).

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Now that we have cycle variables, we can again give additional add-ons to bind them tighter with the face-tracing (but fewer options than for skewness; no details now).

Experimental Evaluation

No cycles. [Beyer et al. 2016]

- ▶ First (at least somewhat) practical approach, but:
- ▶ only able to solve real-world graphs with $\gamma(G) = 1$.

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 - Rome 200x
 - North 100x
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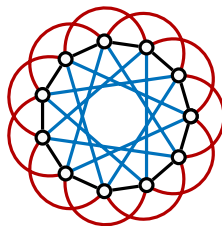
Evaluation: Genera from Literature

The cycle-based ILP can confirm results from literature (all with non-trivial dual bounds):

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hardest case: $C_{11}(1, 2, 4)$

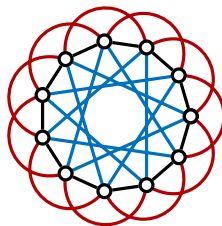
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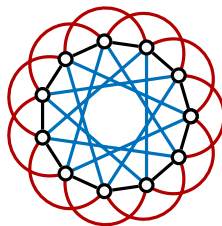
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- ▶ **Gray graph has genus 7** [Marusic et al. 2005]
full paper \Rightarrow 42 hours



Evaluation: Genera from Literature

The cycle-based ILP can confirm results from literature (all with non-trivial dual bounds):

- ▶ **Circulants with genus ≤ 2** [Conder&Grande 2015]
hardest case: $C_{11}(1, 2, 4)$
3 pages analysis, 85h \Rightarrow 180h [Beyer et al. 2016] \Rightarrow **10s**
- ▶ **Gray graph has genus 7** [Marusic et al. 2005]
full paper \Rightarrow 42 hours
- ▶ $\mathbb{Z}_9 \times \mathbb{Z}_3$ **has genus 4** [Brin et al. 1989]
full paper \Rightarrow 5 minutes



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Thank you and good health!

In particular also to the organizers Sascha, Steven and Philipp!